

# Modeling and Input Optimization Under Uncertainty for a Collection of RF MEMS Devices.

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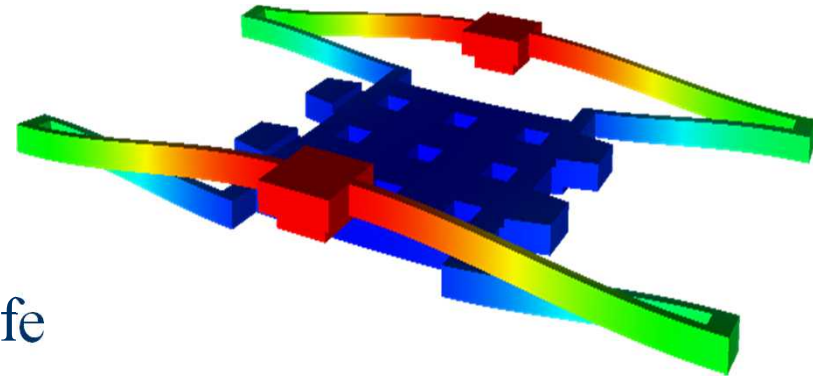
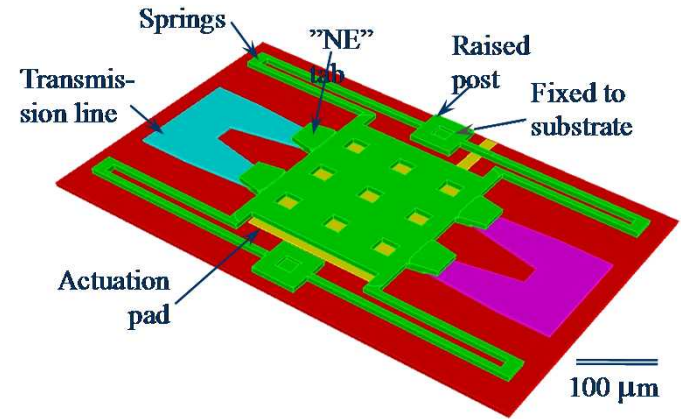
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# Introduction

- ◆ There has been significant interest in RF MEMS switches because they can potentially provide:
  - very low power consumption
  - high isolation
  - excellent linearity
  - contained in a compact package
- ◆ On significant challenge is obtaining the high reliability required.
  - Previous studies have observed orders of magnitude increase in life when the impact velocity of the switches is reduced.



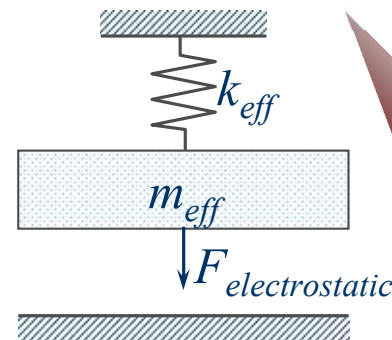
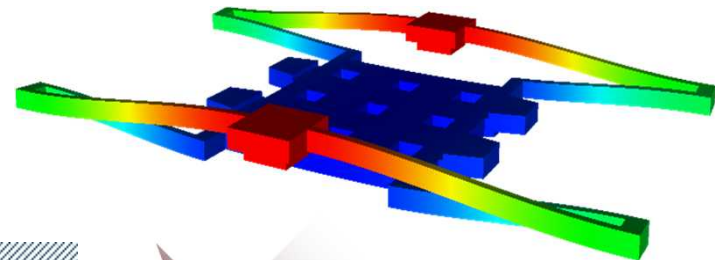
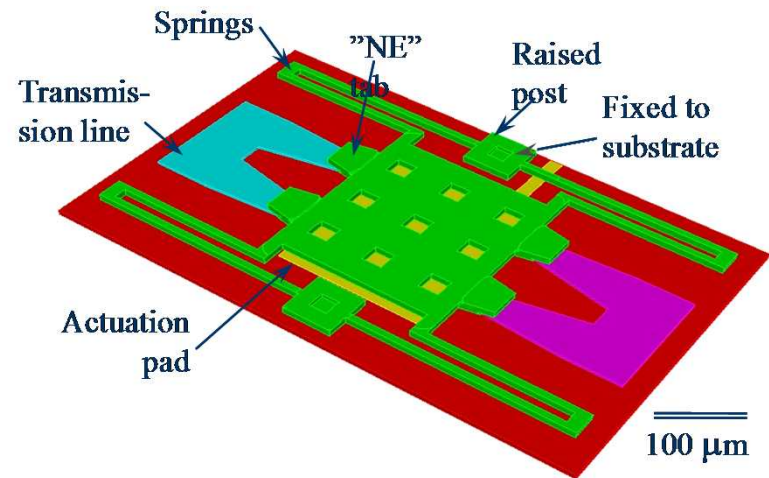


# Outline

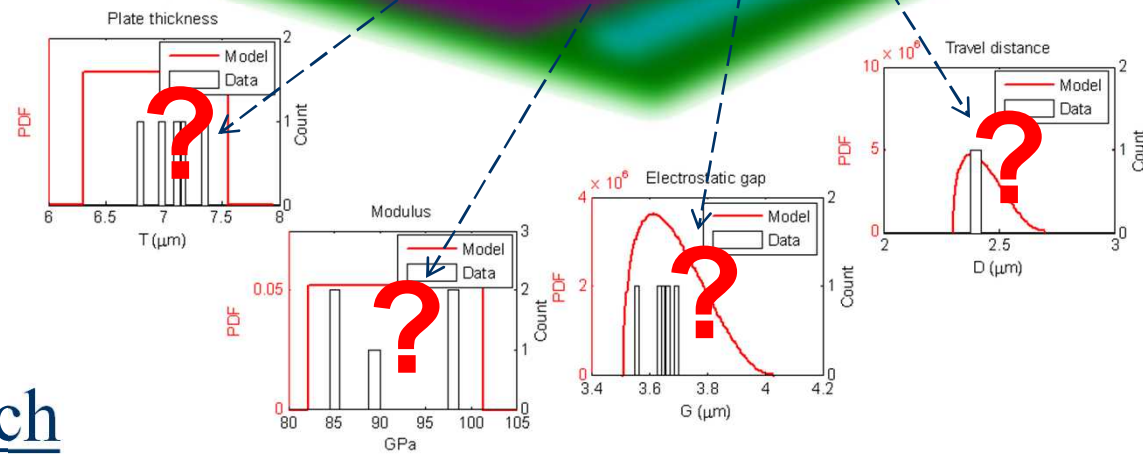
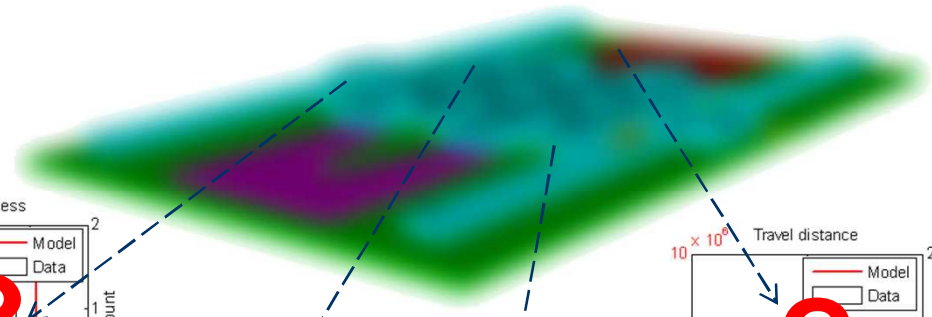
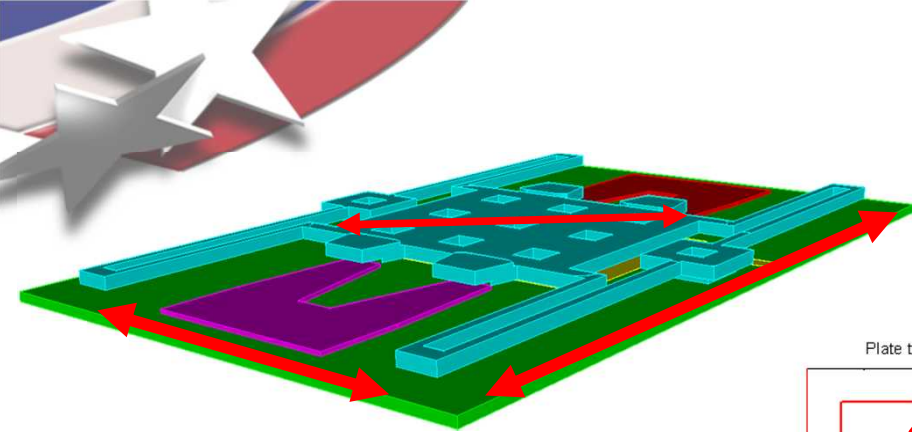
- ◆ Switch design and uncertainty model
- ◆ Unshaped waveform
- ◆ Deterministic optimization
- ◆ Optimization Under Uncertainty (OUU)
  - Waveform for current design OUU
  - Effect of a design change and OUU
  - Effect of process improvement and OUU
- ◆ Conclusions
- ◆ Wild cheering and applause

# Switch Design

- ◆ RF Switch consists of a stiff plate suspended by four folded leaf springs.
- ◆ A voltage is applied to a pad under the plate resulting in an electrostatic force that closes the switch.
- ◆ The switch is well approximated by a single-degree of freedom model.
  - The input is shaped to limit excitation to higher modes to assure that this assumption is valid.



SDOF Model



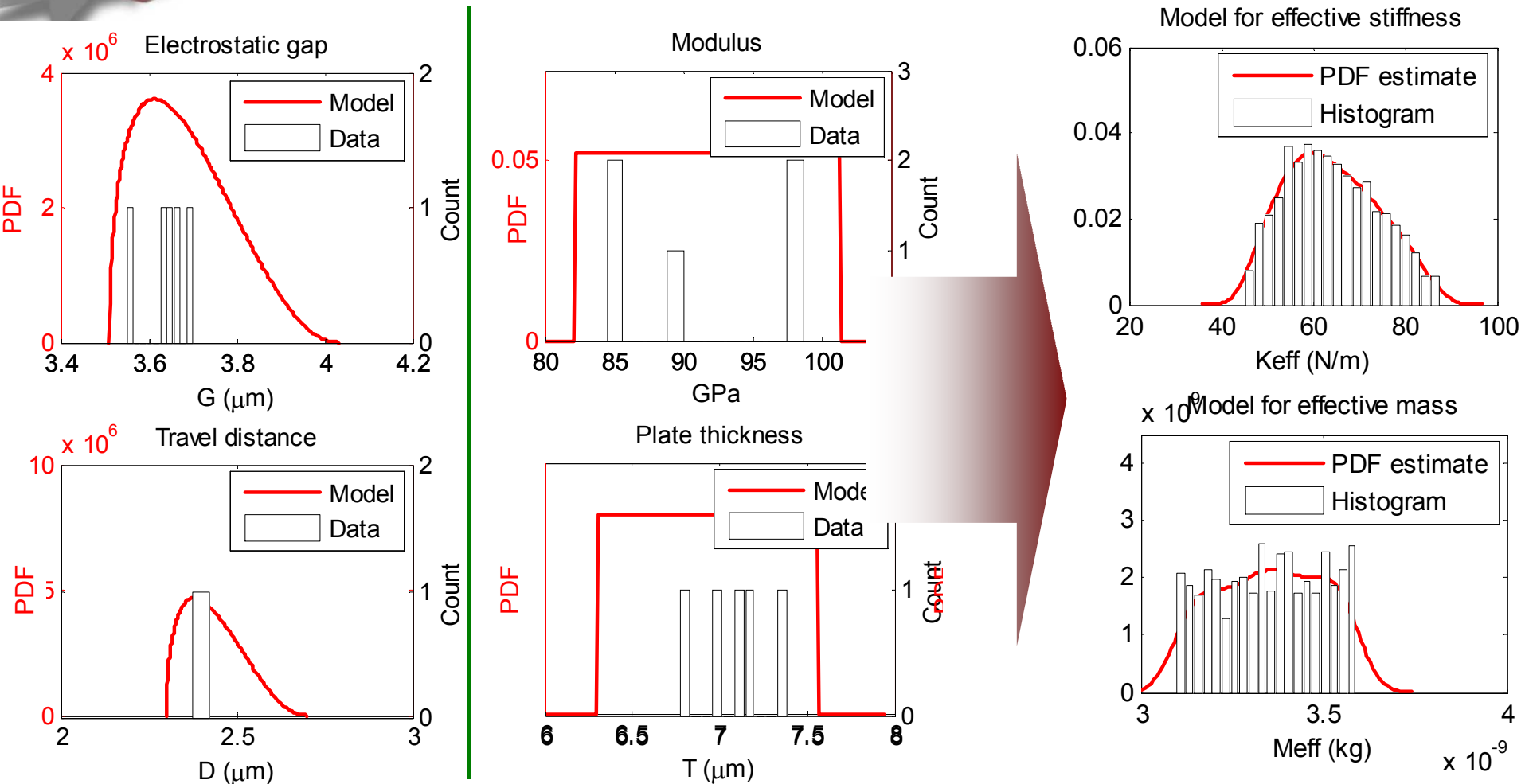
## Deterministic Approach

- ◆ Variation in switch parameters is ignored.
- ◆ Waveform designed semi-analytically to satisfy the switch with average parameters.
- ◆ Succeeds only if:
  - The parameters of the switches don't vary too much or
  - If the optimum is insensitive to variation.

## OUU Approach

- ◆ Random variation in switch parameters described by probability density functions (PDFs).
- ◆ Waveform optimized numerically to minimize impact velocity over the ensemble of switches.

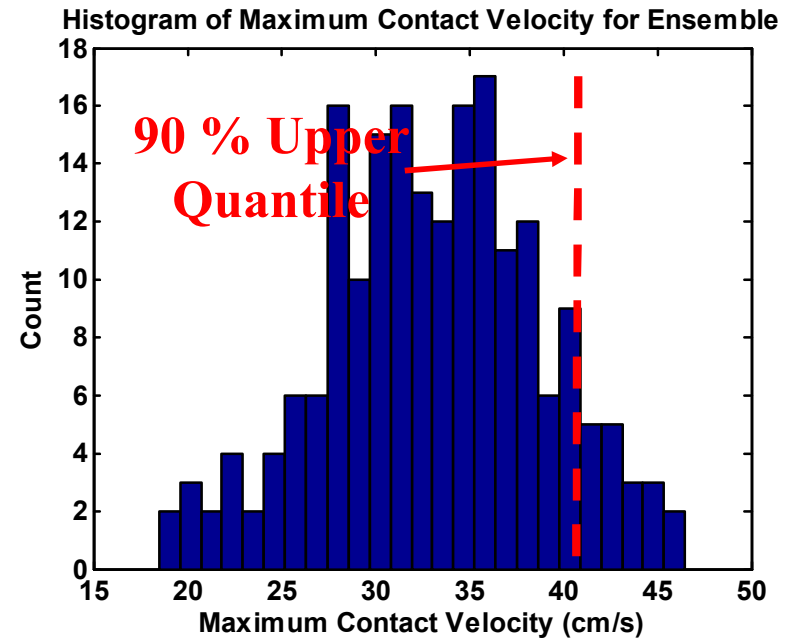
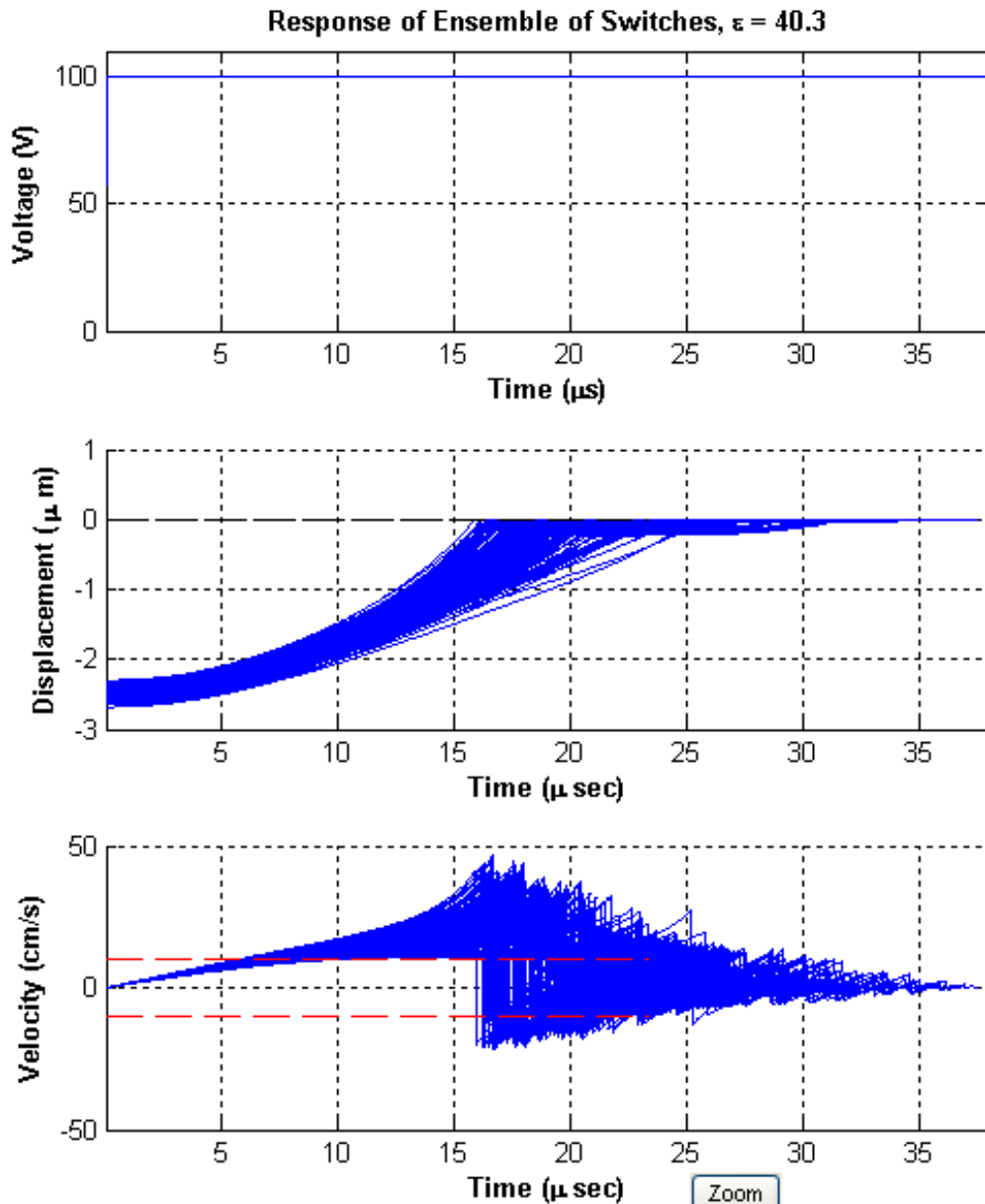
# Uncertainty Model



- ◆ Plate thickness, electrostatic gap, travel distance and elastic modulus were measured and fit to uniform and Beta Probability Density Functions (PDFs).
  - Expert opinion was used to augment the data since few samples were available.
  - Modulus and Thickness were used to deduce effective mass and stiffness.

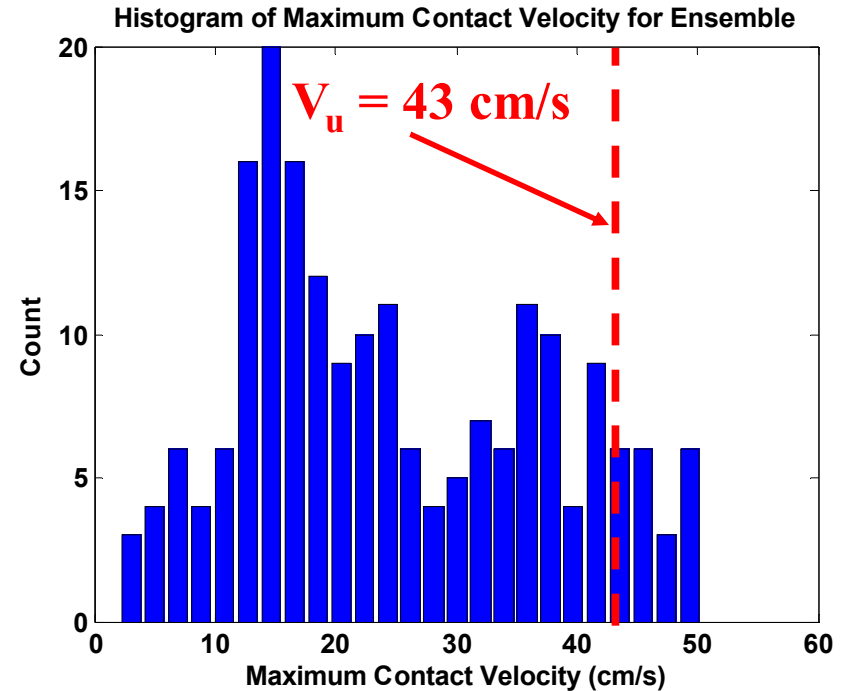
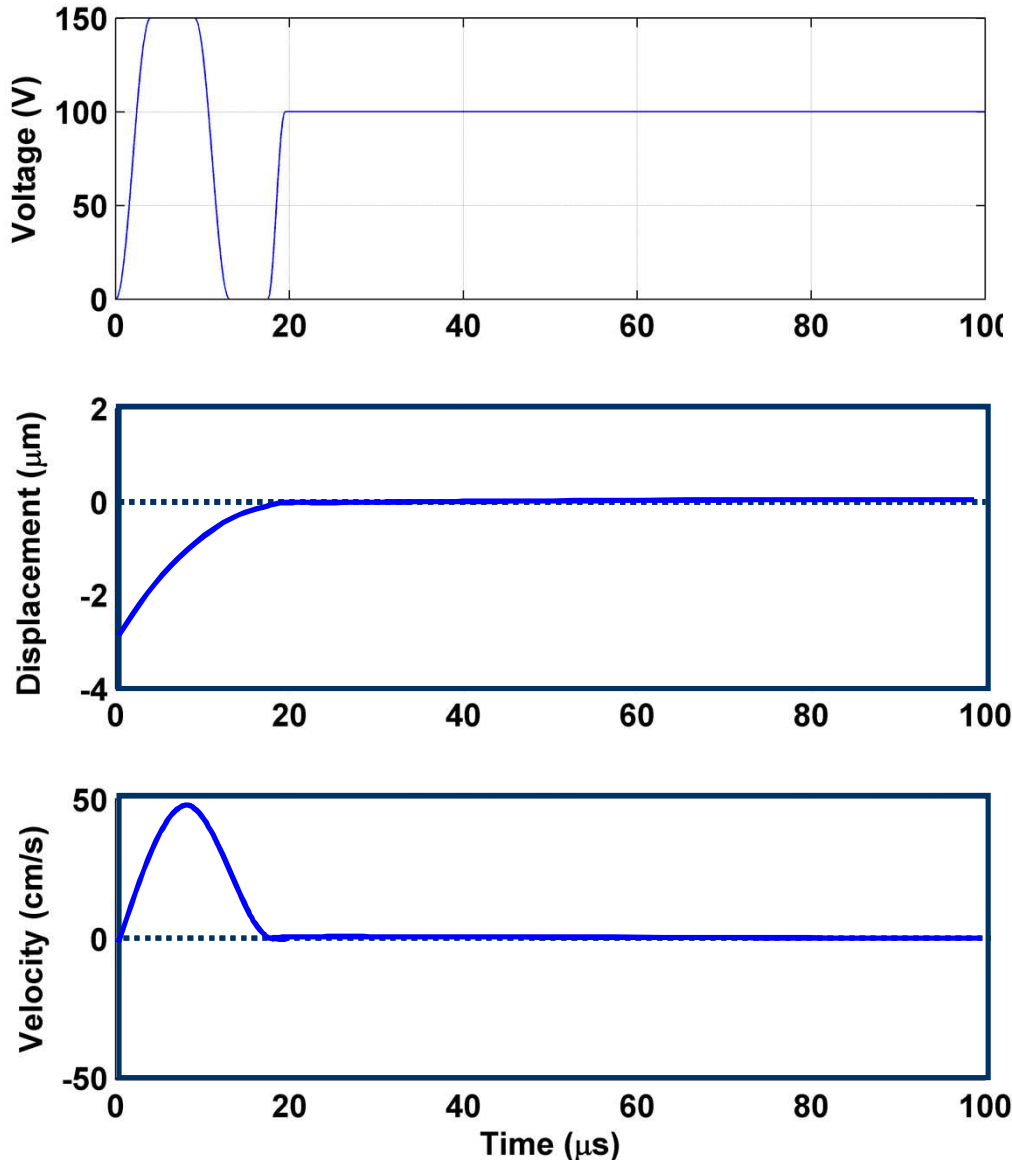


# Response without Input Shaping



- ◆ 90% of the switches experience maximum contact velocities below 40.3 cm/s

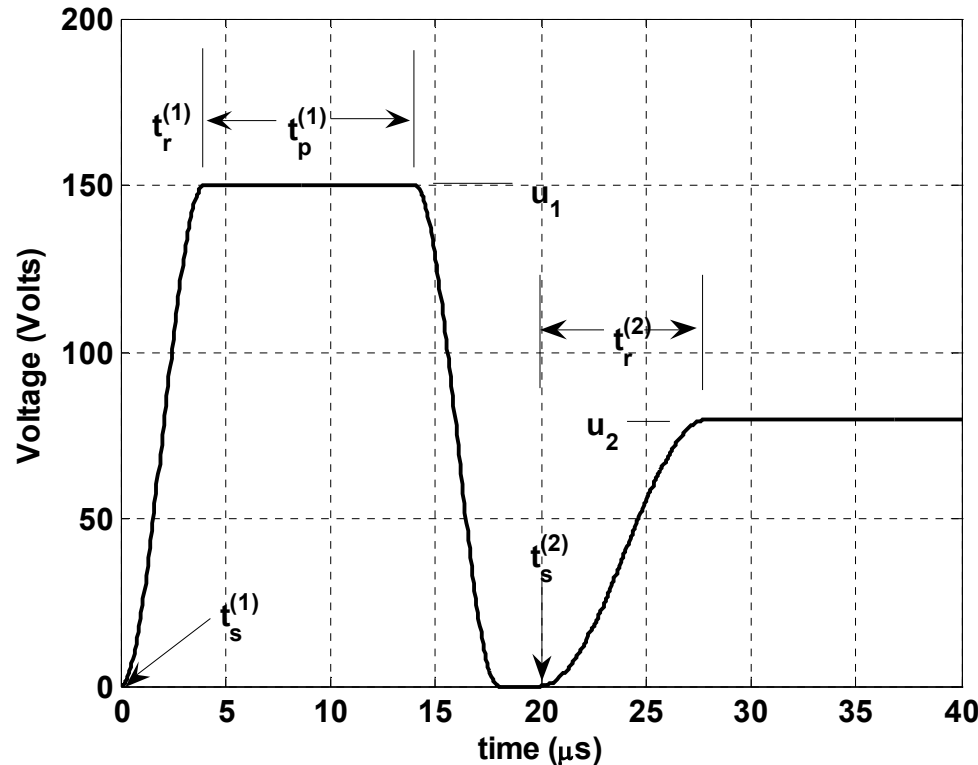
# Deterministic Waveform Design



- ◆ A waveform that is optimum in a deterministic sense gives higher contact velocities than an unshaped waveform when applied to the ensemble of switches.



# Optimization Objective & Strategy



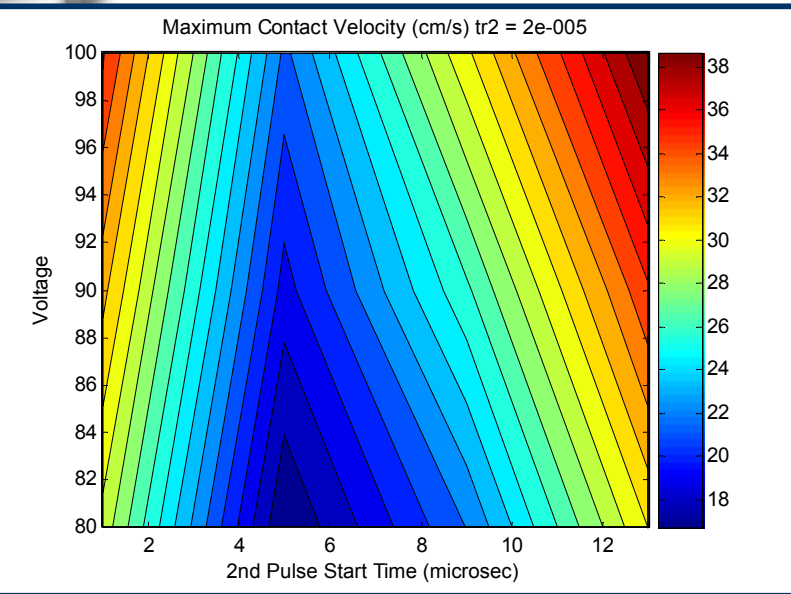
## ♦ Optimization Objective:

- $g(t_s^1, \dots) = v_u + c_{nc} * p_{nc}$ 
  - 90% of the switches experience contact velocities lower than  $v_u$ 
    - ♦ (i.e.  $P(V_{max} > v_u) = 0.10$ )
  - $p_{nc}$  is the probability that a switch doesn't close in 250  $\mu s$
  - $c_{nc}$  is a constant to weight the relative importance of the two

## ♦ Optimization Strategy:

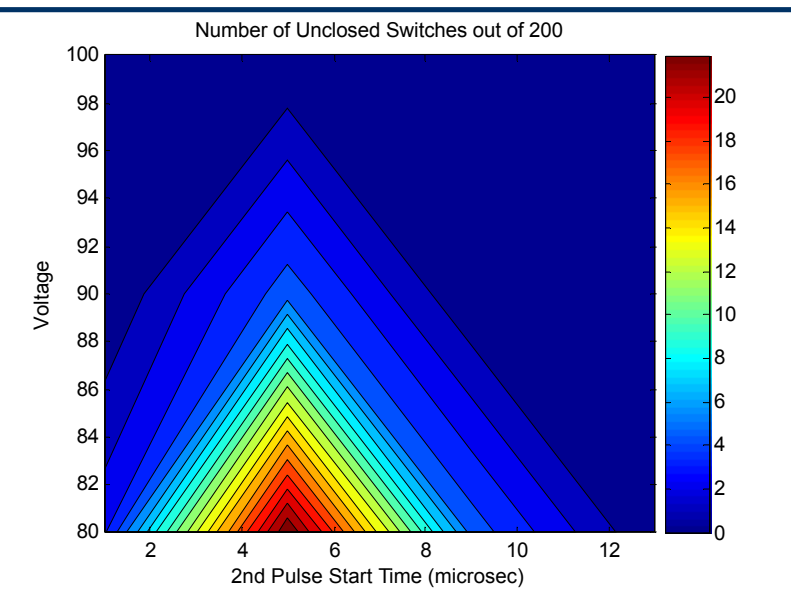
- Set  $u_2 = 0$  and adjust  $t_p^{(1)}$  (duration of first pulse) until the maximum contact velocity for the ensemble of 200 switches is  $\sim 10$  cm/s.
- Use exhaustive search to find starting values for  $t_s^{(2)}$  (start time of second pulse),  $t_r^{(2)}$  (rise time of second pulse) and  $u_2$  (maximum voltage of second pulse).
- Refine using Nelder-Mead Simplex algorithm.

# Optimization Strategy

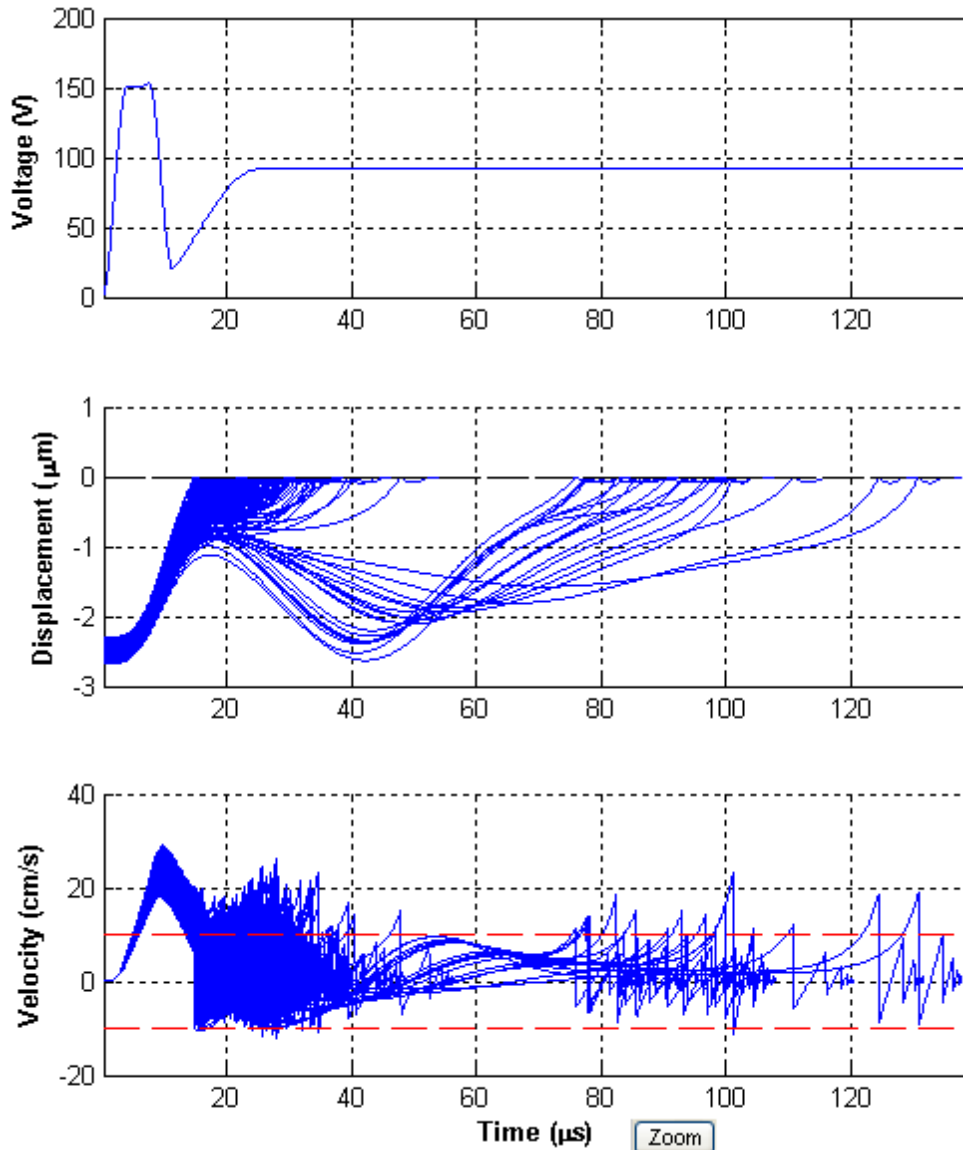


## ◆ Comments:

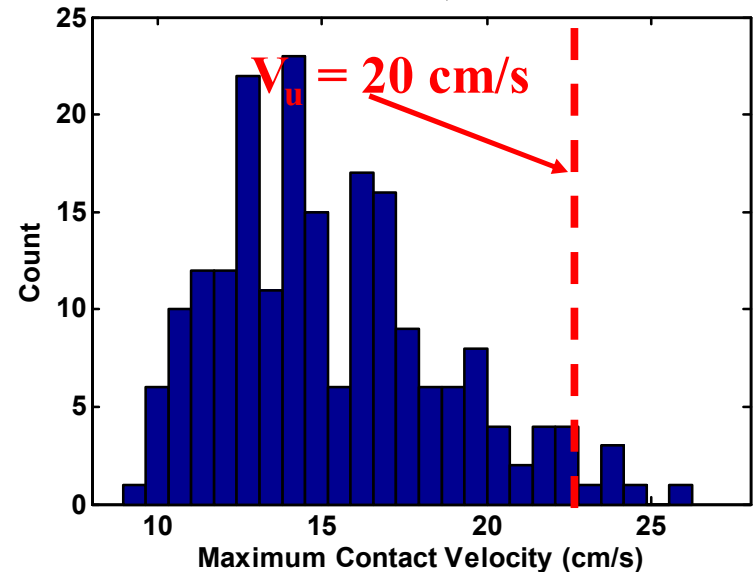
- Exhaustive search used to find starting values for Nelder-Mead.
- Nelder-Mead Simplex used to refine initial estimates, typically resulting in a 1 cm/s reduction in the maximum contact velocity from that found by exhaustive search.
- Also attempted using the DIRECT (global) optimization algorithm, yet many iterations were required to obtain reasonable results.



# O UU Waveform Design



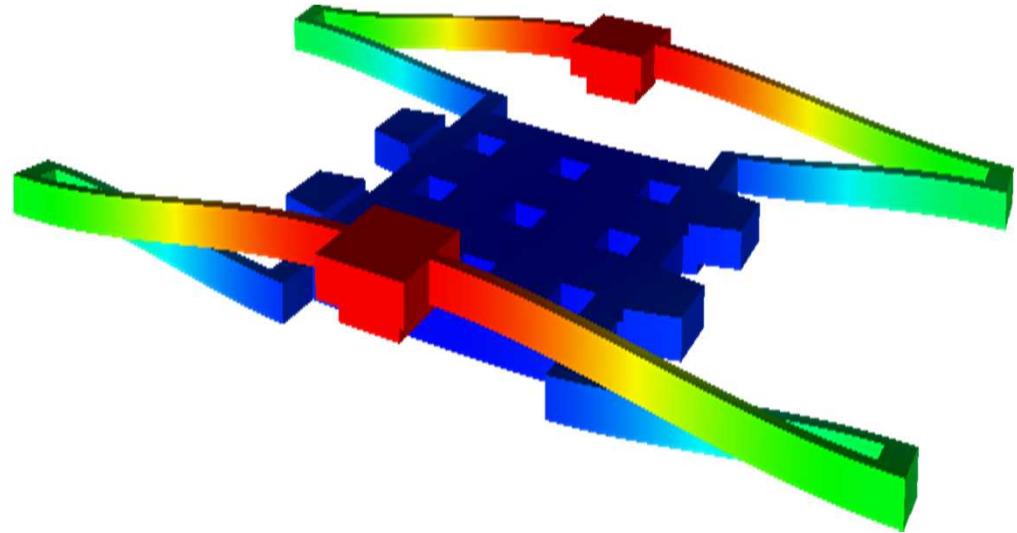
Histogram of Maximum Contact Velocity  
for Ensemble,  $\mu = 15.2653$



- ◆ Results:
  - 90% have maximum contact velocities below 19.7 cm/s
  - The mean maximum contact velocity is 15.3 cm/s
  - These represent improvements of more than 50% compared to the unshaped waveform or the deterministically designed waveform.
- ◆ None of the switches have a contact velocity near zero.

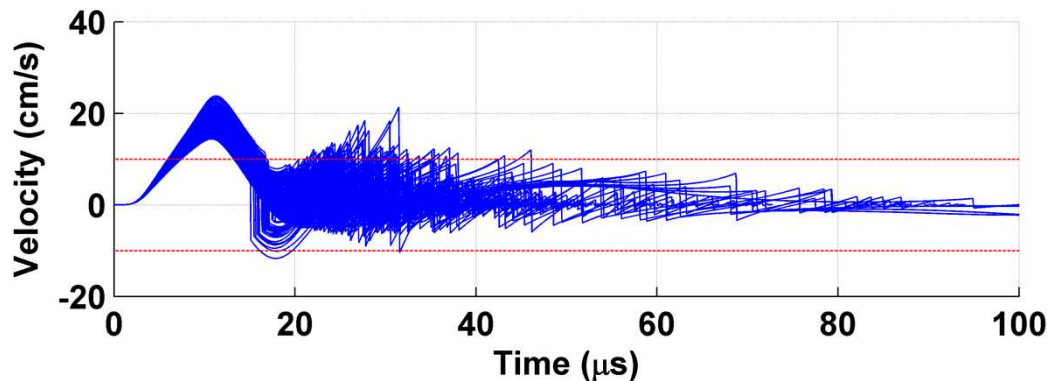
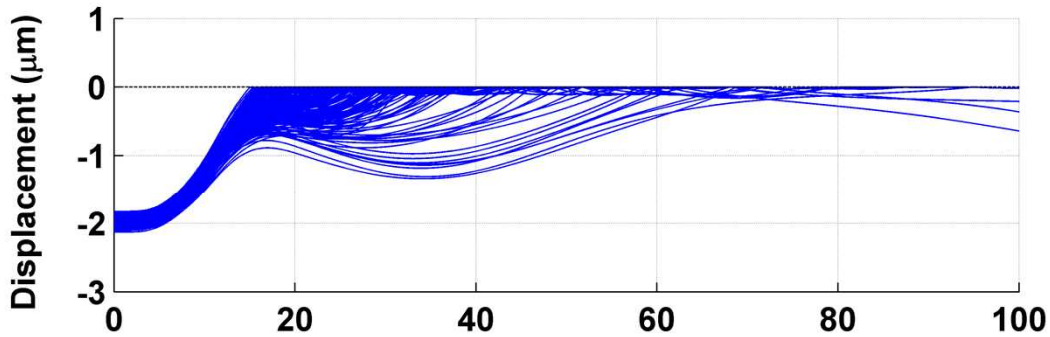
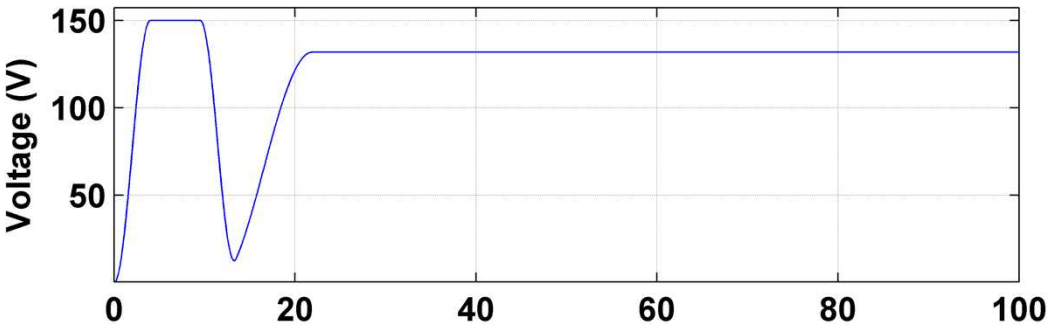
# Design Change

- ◆ Electrostatic force varies with the inverse square of the electrostatic gap (G) minus the switch displacement (X).
- ◆ The displacement must be less than the travel distance (D).
- ◆ The system is unstable for:
  - $X > G/3$ .
- ◆ Currently:
  - $0.59 \cdot D/G \cdot 0.75$
- ◆ The design was modified to reduce this ratio resulting in
  - $0.41 \cdot D/G \cdot 0.52$ .
- ◆ This design does not venture as far into the unstable region as the previous did.

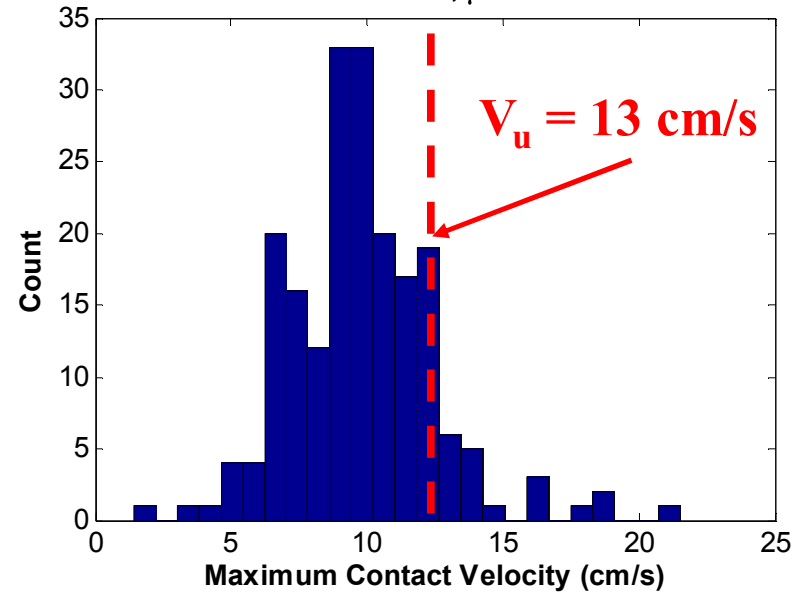


$$F_{electrostatic} = \frac{\alpha u^2}{(G-X)^2}$$
$$X \leq D$$

# Design Change and OUU



Histogram of Maximum Contact Velocity  
for Ensemble,  $\mu = 9.7822$

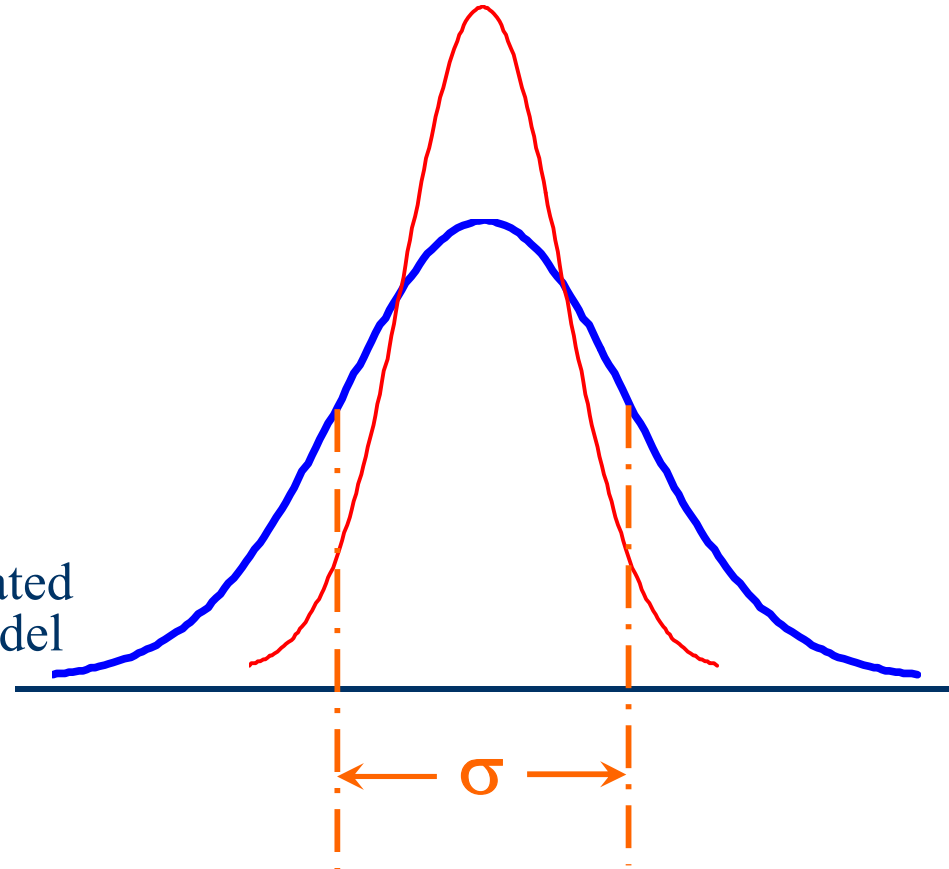


◆ 35 % reduction in upper and mean contact velocities.

- Upper 12.5 cm/s from 19.7 cm/s
- Mean 9.8 cm/s from 15.3 cm/s

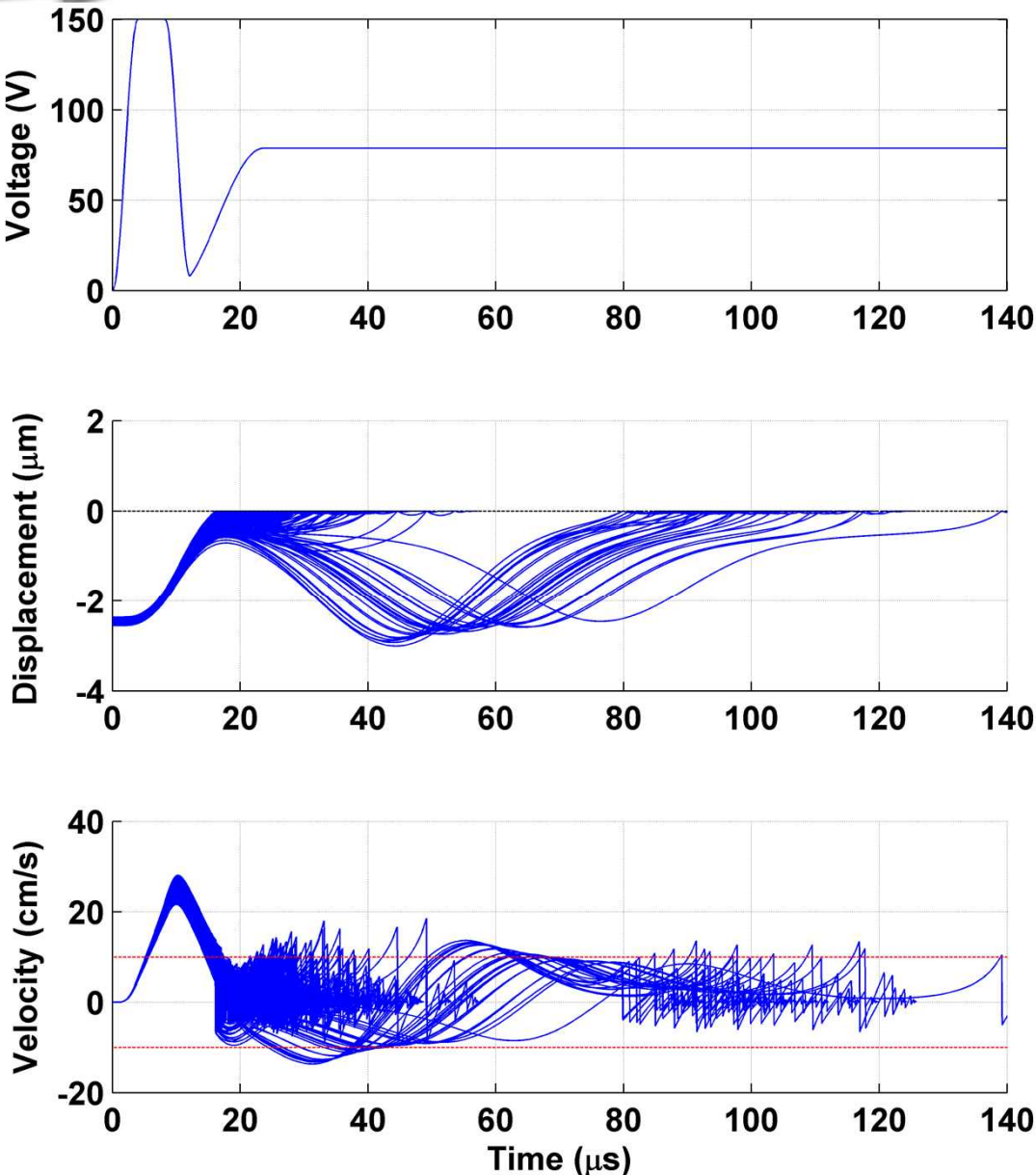
# Process Improvement

- ◆ How much would the performance improve if the process repeatability were improved by 50%?
  - Coefficient of Variation of:
    - Gap Distance
    - Travel Distance
    - Thickness
  - were decreased by 50%. (COV = standard deviation / mean).
  - Optimization procedure was repeated with this modified uncertainty model for the switch.
- ◆ This level of improvement may not be feasible, but this type of analysis can provide motivation for allocating resources to process improvement.

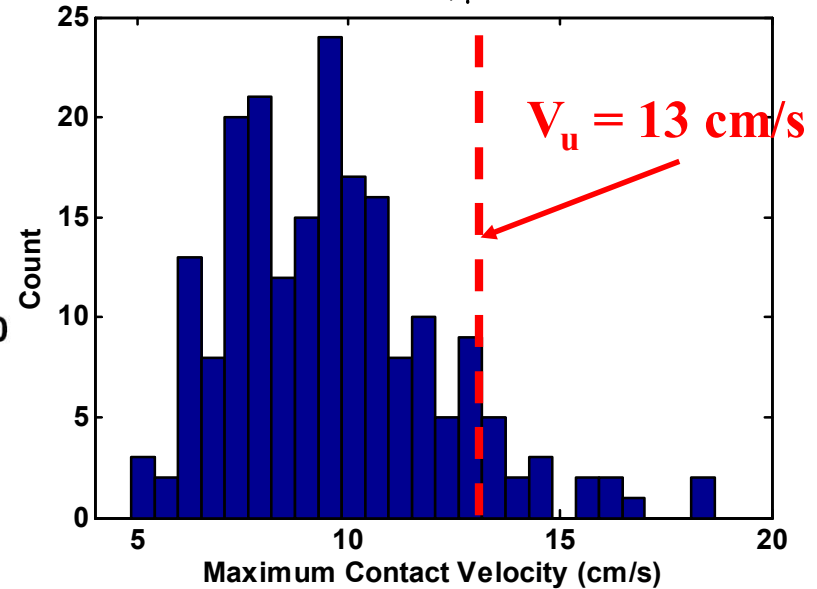




# Process Improvement and OUU



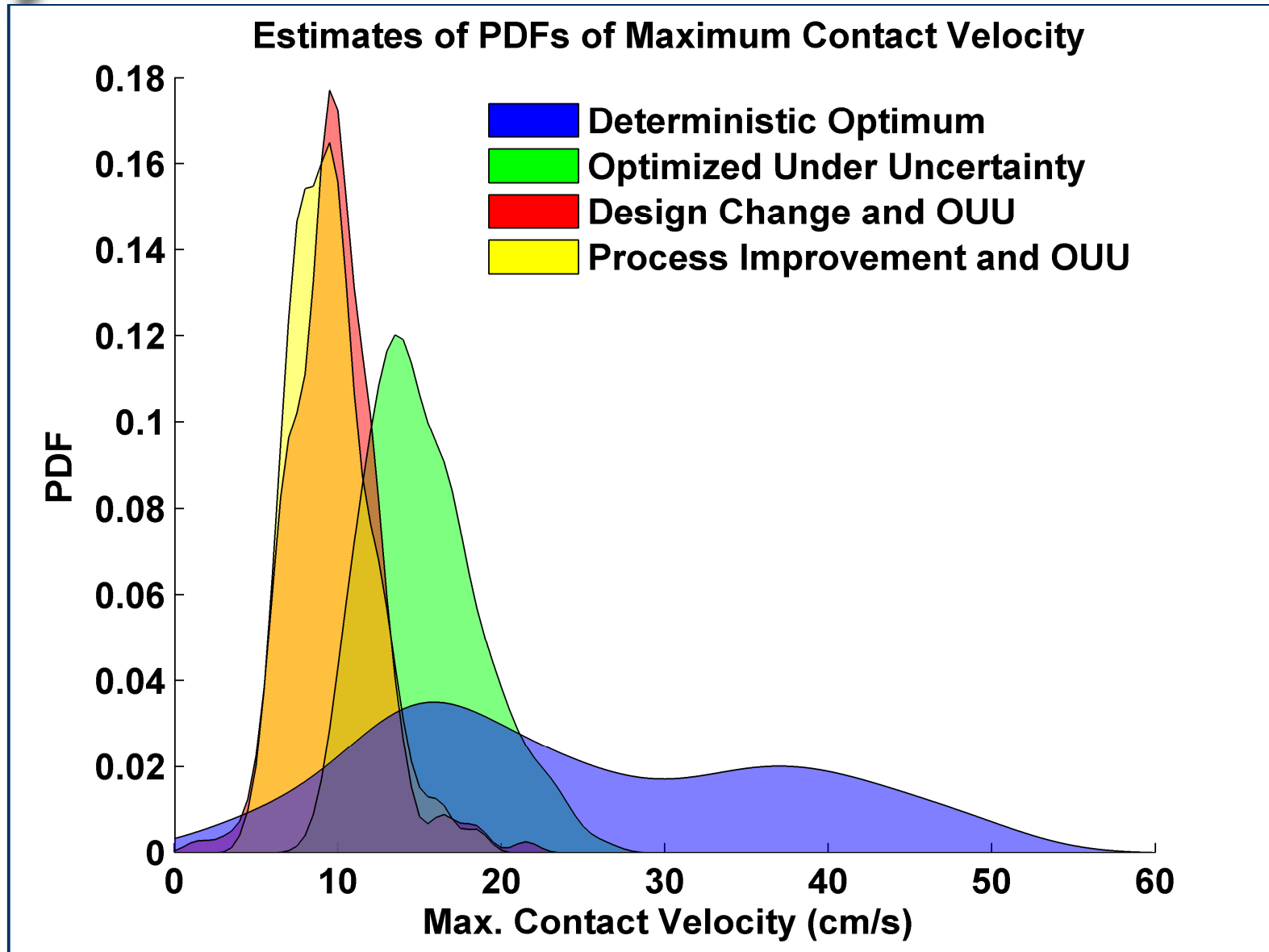
Histogram of Maximum Contact Velocity  
for Ensemble,  $\mu = 9.6232$



- ◆ Simulated the effect of process improvement:
  - Reduced the COV of gap, travel and thickness by 50%
- ◆ >35% reduction in upper and mean contact velocities
  - Upper 12.8 cm/s vs 19.7 cm/s
  - Mean 9.6 cm/s vs. 15.3 cm/s



# Summary





# Conclusions

- ◆ Shaped waveforms can reduce the impact velocity that an ensemble of switches experiences.
- ◆ The contact velocity was reduced by 50% using the waveform that was optimized under uncertainty.
- ◆ Further reductions of 35% were demonstrated after modifying the switch design or reducing process variability. (Net reduction of 70%)
- ◆ Uncertainty must be accounted for when designing shaped waveforms.
  - A waveform that was optimum for the average switch actually increased the impact velocity when applied to the ensemble of switches.