



# Integration Techniques for Extended Finite Element Methods

David R. Noble and David J. Holdych

Sandia National Laboratories

Albuquerque, New Mexico

This work was performed at Sandia National Laboratories. Sandia is a multiprogram laboratory operated by Sandia Corporation, a Lockheed Martin Company, for the United States Department of Energy under Contract DE-AC04-94AL85000.



# XFEM Integration - Motivation

## Modified Element Quadrature

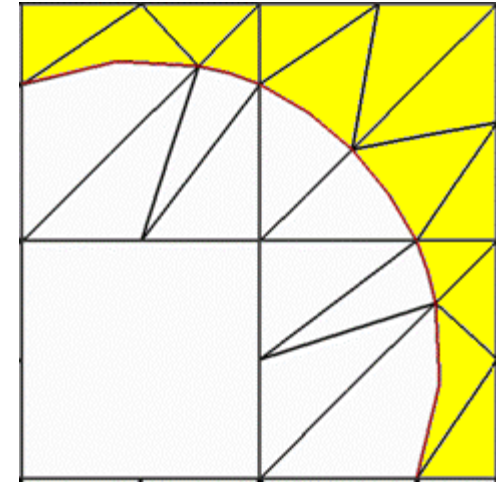
- Basis and trial functions are now discontinuous
- For XFEM-Level set methods, functions become generalized functions of the level set variable
  - Heaviside and Dirac delta functions

## Moderately Invasive Feature in XFEM Codes

- Quadrature rule depends on level set variable
- Coupling issues, time derivative evaluation

## Several Solutions

- Diffuse integration
  - Smoothed generalized functions
- Subelement integration
  - Subdivide elements into conformal subelements
  - Implementation issues
- Develop new integration rules for generalized functions
  - Derive new integration rules that account for generalized functions





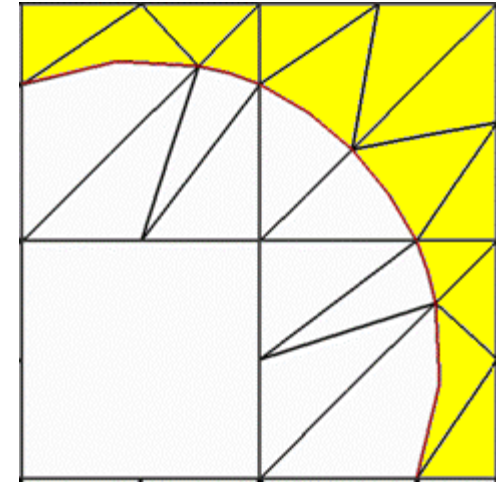
# XFEM Subelement Integration - Issues

## Basics

- Decompose non-conformal element into conformal subelements
- Perform standard Gauss integration over subelements

## Important Implementation Details

- What is definition of subelements?
  - Option 1: Coordinates of subelements are parametric coordinates for owning element
  - Option 2: Coordinates of subelements are real coordinates
- Consequences
  - Option 1
    - Gauss point locations in parent element are directly known
    - Pathological errors for low order subelements
  - Option 2
    - Gauss point locations are unknown and must be solved for using nonlinear iteration
    - Optimal accuracy obtained for low order subelements





# Integration Rules for Elements with Generalized Functions - Motivation

## Philosophical

- Integration rules designed to exactly integrate finite element functions
  - Enriched functions need modified quadrature rules

## Pragmatic When Compared with Alternatives

- Diffuse methods
  - Simple but inaccurate, inconsistent
- Subelement methods
  - Must be carefully implemented
  - Can be expensive when having to solve nonlinear system for parametric coordinates
  - Must specifically account for degenerate cases

## Allows Advanced Capabilities

- Provides analytical Jacobian information
  - Required by full Newton codes
  - Make interfacial optimization possible

## Possible Disadvantages

- Possibly increases number of quadrature points for same element
- Difficult, if not impossible to derive for higher order elements



# Generalized Quadrature - Method

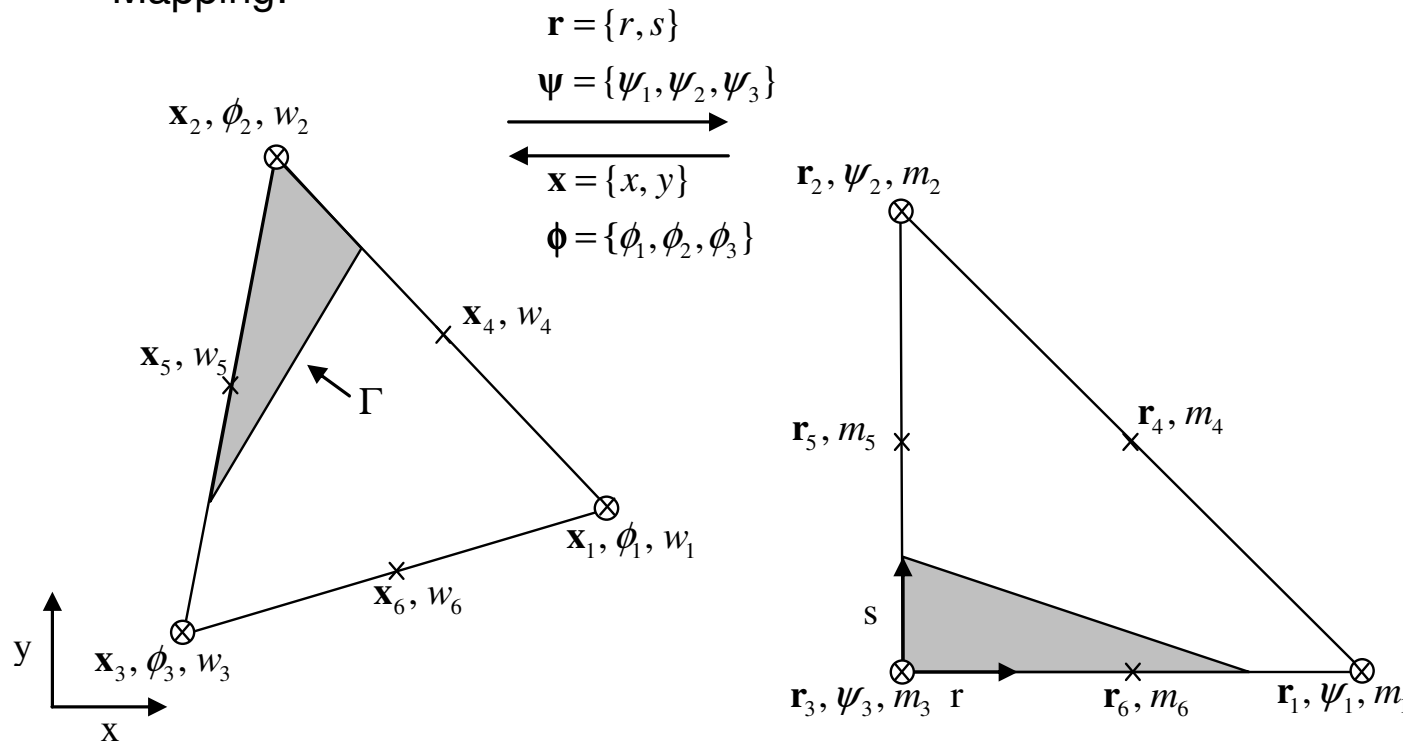
## Approach

- Develop quadrature rules capable of exactly integrating finite element functions including a generalized function of the level set variable
  - Piecewise polynomial times Heaviside or Dirac delta function

- Form:

$$\int_{\Omega^+} g(\mathbf{x}) d\Omega_{\mathbf{x}} = \sum_{i=1}^6 w_i^+(\phi) g(\mathbf{x}_i) J(\mathbf{x}_i) \quad \int_{\Gamma} g d\Gamma_{\mathbf{x}} = \sum_{i=1}^6 w_i^{\Gamma}(\phi) |\nabla \phi(\mathbf{x}_i)| g(\mathbf{x}_i) J(\mathbf{x}_i)$$

- Mapping:





## Generalized Quadrature - Method

- Form linear system for weights

$$I_f^\Delta(\psi) \equiv \int_{\Delta} f(\mathbf{r}) d\Omega_{\mathbf{r}} = \sum_{i=1}^6 m_i^\Delta(\psi) f(\mathbf{r}_i)$$

$$\mathbf{A} \mathbf{m}^\Delta(\psi) = \mathbf{I}^\Delta(\psi)$$

- Require all monomials in a quadratic function be exactly integrated

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ r_1 & r_2 & r_3 & r_4 & r_5 & r_6 \\ s_1 & s_2 & s_3 & s_4 & s_5 & s_6 \\ r_1 s_1 & r_2 s_2 & r_3 s_3 & r_4 s_4 & r_5 s_5 & r_6 s_6 \\ r_1^2 & r_2^2 & r_3^2 & r_4^2 & r_5^2 & r_6^2 \\ s_1^2 & s_2^2 & s_3^2 & s_4^2 & s_5^2 & s_6^2 \end{bmatrix} \begin{bmatrix} m_1^\Delta(\psi) \\ m_2^\Delta(\psi) \\ m_3^\Delta(\psi) \\ m_4^\Delta(\psi) \\ m_5^\Delta(\psi) \\ m_6^\Delta(\psi) \end{bmatrix} = \begin{bmatrix} I_1^\Delta(\psi) \\ I_r^\Delta(\psi) \\ I_s^\Delta(\psi) \\ I_{rs}^\Delta(\psi) \\ I_{r^2}^\Delta(\psi) \\ I_{s^2}^\Delta(\psi) \end{bmatrix}$$

- Select quadrature point locations
  - Valid quadrature rules yield nonsingular matrix,
  - Normally quadrature point locations considered unknowns select so that integration achieves desired order with minimal number of points
  - Arbitrary interface location makes fortuitous point selection impossible
  - Simplest valid quadrature rules involve points on the nodes and edges



## Generalized Quadrature - Method

- Form linear system for weights, cont'd
  - Analytically evaluate integrals as function of nodal level set values

$$\begin{aligned}
 I_1^\Delta(\psi) &= \frac{\psi_3^2}{2\Delta_{31}\Delta_{32}} & I_{rs}^\Delta(\psi) &= \frac{\psi_3^4}{24\Delta_{31}^2\Delta_{32}^2} \\
 I_r^\Delta(\psi) &= \frac{\psi_3^3}{6\Delta_{31}^2\Delta_{32}} & I_{r^2}^\Delta(\psi) &= \frac{\psi_3^4}{12\Delta_{31}^3\Delta_{32}} & \Delta_{31} &\equiv \psi_3 - \psi_1 \\
 I_s^\Delta(\psi) &= \frac{\psi_3^3}{6\Delta_{31}^2\Delta_{32}} & I_{s^2}^\Delta(\psi) &= \frac{\psi_3^4}{12\Delta_{31}\Delta_{32}^3} & \Delta_{32} &\equiv \psi_3 - \psi_2
 \end{aligned}$$

- Solve for weights as functions of nodal level set values

$m_i^\Delta(\psi)$	functional form
$m_1^\Delta(\psi)$	$-I_r^\Delta(\psi) + 2I_{r^2}^\Delta(\psi)$
$m_2^\Delta(\psi)$	$-I_s^\Delta(\psi) + 2I_{s^2}^\Delta(\psi)$
$m_3^\Delta(\psi)$	$I_1^\Delta(\psi) - 3I_r^\Delta(\psi) - 3I_s^\Delta(\psi) + 4I_{rs}^\Delta(\psi) + 2I_{r^2}^\Delta(\psi) + 2I_{s^2}^\Delta(\psi)$
$m_4^\Delta(\psi)$	$4I_{rs}^\Delta(\psi)$
$m_5^\Delta(\psi)$	$4(I_s^\Delta(\psi) - I_{rs}^\Delta(\psi) - I_{s^2}^\Delta(\psi))$
$m_6^\Delta(\psi)$	$4(I_r^\Delta(\psi) - I_{rs}^\Delta(\psi) - I_{r^2}^\Delta(\psi))$

## Results

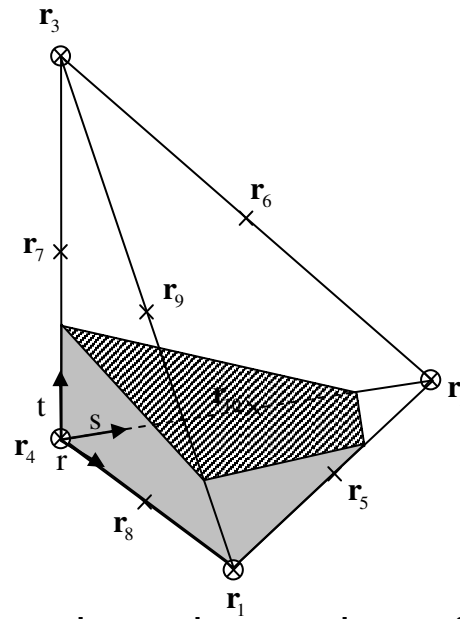
- Weights are continuous functions of nodal level set values
  - Allows analytical Jacobian formation
  - All degenerate cases handled without special consideration
- Weights are not positive definite



# Generalized Quadrature – Other Elements

## 3D Tetrahedra

- Mapping:



- Analytically evaluate integrals as function of nodal level set values
  - Case 1: 1 node on opposite side from other 3
  - Case 2: 2 nodes on opposite side from other 2

## Higher Order Elements (Including quads/hexes)

- Analytically evaluate integrals as function of nodal level set values
  - Integrals difficult, if not impossible, to evaluate in general





# Generalized Quadrature – Test Problem

## Conduction in Annulus and Spherical Shell

- Poisson equation,  $k = 1$ ,  $q = 1$   
 $\nabla \cdot k \nabla T + q = 0$
- Boundary conditions
  - Insulated inner surface
  - Robin-type output surface,  $h = 10$   
 $-\mathbf{n}_{outer} \cdot k \nabla T = h(T - 0)$

## Discretization

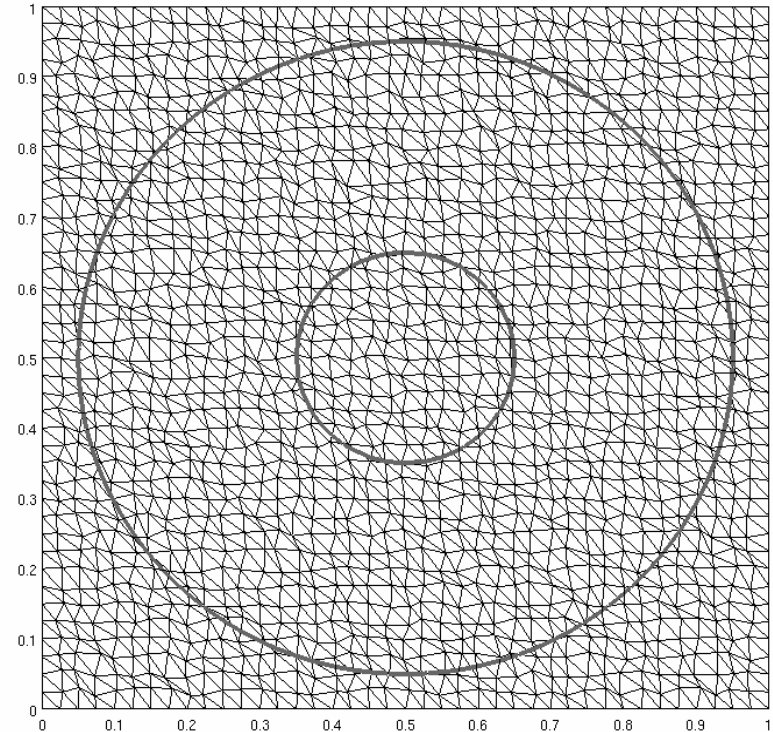
- Linear triangle and tetrahedral elements, linear temperature, linear level set function
- Randomly perturbed nodes of structured mesh
  - Rigorous test for deformed meshes

## Validation

- Compare against exact solutions

$$T^{2D}(r) = \frac{q}{4k}(R_o^2 - r^2) + \frac{q}{2hR_o}(R_o^2 - R_i^2) - \frac{qR_i^2}{2k}(\log(R_o) - \log(r))$$

$$T^{3D}(r) = \frac{q}{3hR_o^2}(R_o^3 - R_i^3) - \frac{q}{6kr}(r^3 + 2R_i^3) + \frac{q}{6kR_o}(R_o^3 + 2R_i^3)$$

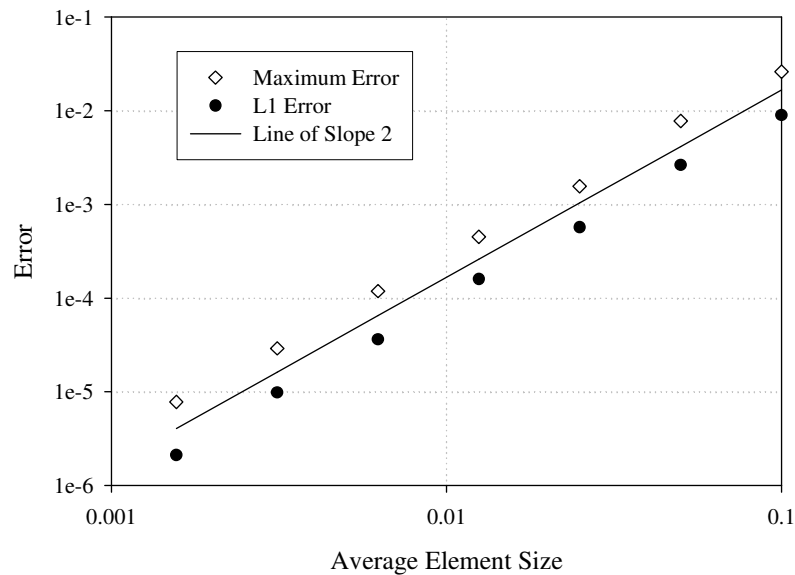
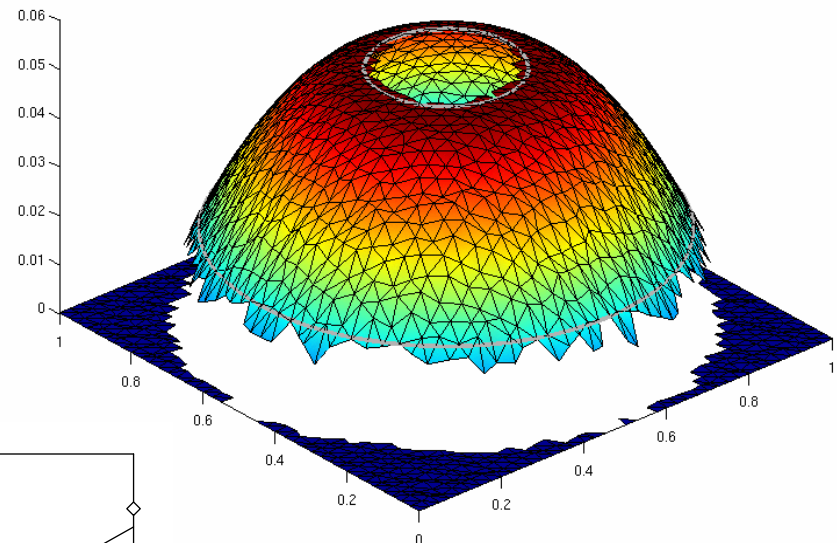




# Generalized Quadrature – 2D Test

## Results

- Visualization - Elements that use ghost nodes and exterior nodes are removed
- Sharp discontinuities captured along inner and outer surfaces
- 2<sup>nd</sup> order accuracy demonstrated over multiple decades

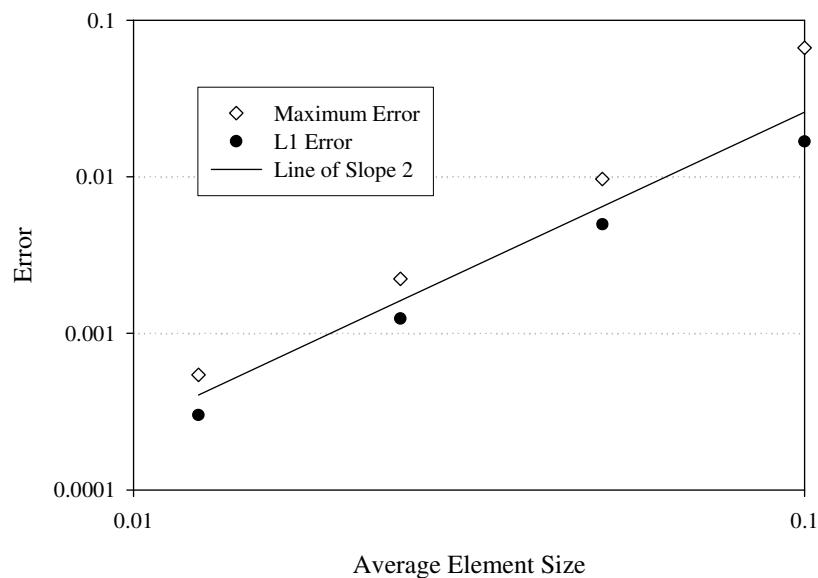
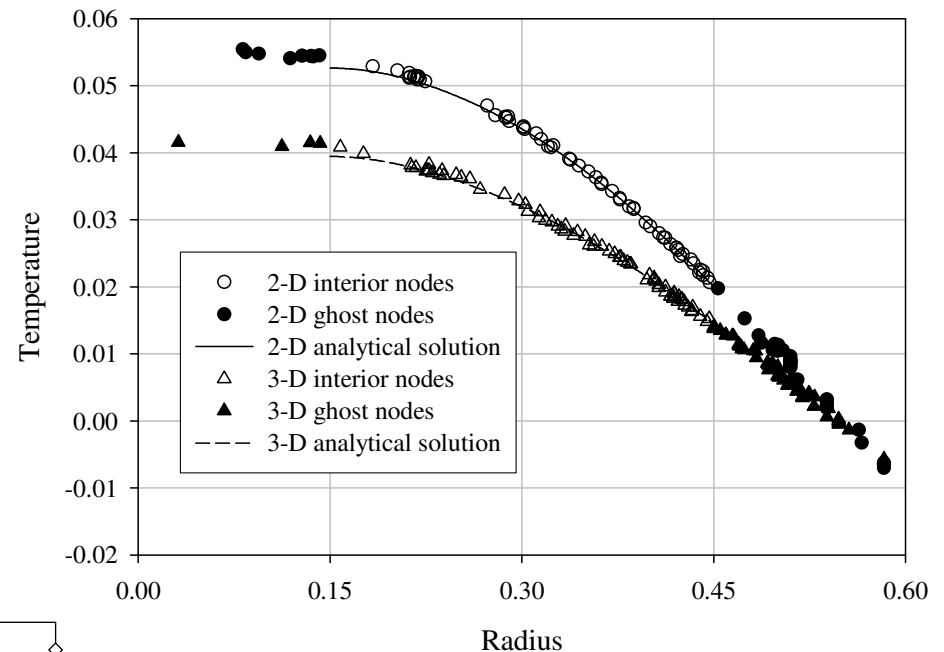




# Generalized Quadrature – 3D Test

## Results

- 2<sup>nd</sup> order accuracy
- Successfully integrates discontinuous function using fixed gauss point quadrature rule
- Successfully handles degenerate cases without special consideration





## Summary and Conclusions

### Care Must be Taken When Using Subelement Integration

- Definition of subelements – Parametric or real coordinates?
- Performance issues – Quadrature point location inversion
- Low order subelements can lead to suboptimal convergence

### Analytic Integration with Generalized Functions

- Can be used to formulate fixed point integration rules with weights that depend continuously on nodal level set values
- Provides analytic Jacobian information
- Handles degenerate cases smoothly without special consideration

### Hybrids are Possible

- Subelement methods could be used to form fixed point integration rules

$$I_f^\Delta(\psi) \equiv \int_{\Delta} f(\mathbf{r}) d\Omega_{\mathbf{r}} = \sum_{i=1}^6 m_i^\Delta(\phi) f(\mathbf{r}_i)$$
$$\mathbf{A} \mathbf{m}^\Delta(\psi) = \mathbf{I}^\Delta(\psi)$$



# Implementation – Applying XFEM to Laser Welding

## Problem Discretization

- Fixed unstructured mesh
- Solid-liquid interface described by enthalpy method
  - Specific heat is temperature dependent to account for latent heat
  - Viscosity sharp function of temperature around between solidus and liquidus
- Liquid-vapor interface described by level set method

## Variable Enrichment

- Variables allowed to be discontinuous across liquid-vapor interface

## Subelement Integration

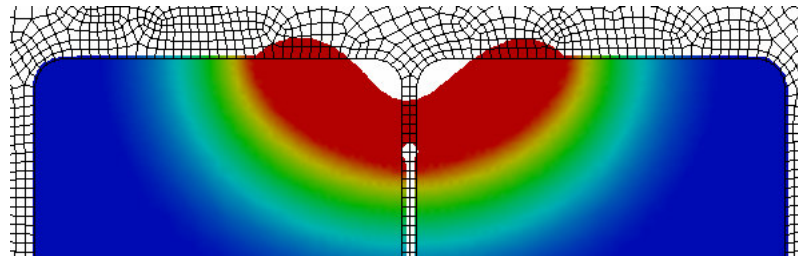
- Required to integrate discontinuous quantities resulting from discontinuous variables and trial functions

## Interfacial conditions

- XFEM approach produces natural mechanism for applying interfacial fluxes
- Several options discussed in literature for handling surface tension

## Coupling

- Implemented in code designed for fully coupled, Newton's method
- Choice of surface tension application made this impossible
  - Final algorithm involves loosely coupling the level set evolution to the mass, momentum, and energy evolution

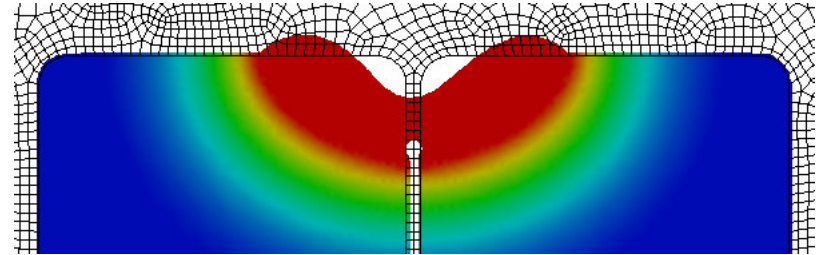




# Implementation – Interfacial Conditions

## Complex Interfacial Conditions

- Laser heat flux
  - Gaussian or flat radial distribution
  - Highly dependent on surface normal
  - Weakly applied to energy equation along interface
- Radiative heat flux
  - Highly dependent on surface temperature
  - Weakly applied to energy equation along interface
- Latent heat due to vaporization
  - Vaporization rate assumed to be function of surface superheat
  - Highly dependent on surface temperature
  - Weakly applied to energy equation along interface
- Vapor recoil pressure
  - Vaporization rate assumed to be function of surface superheat
  - Highly dependent on surface temperature
  - Weakly applied to momentum equation along interface
- Surface tension
  - Weakly applied to momentum equation along interface

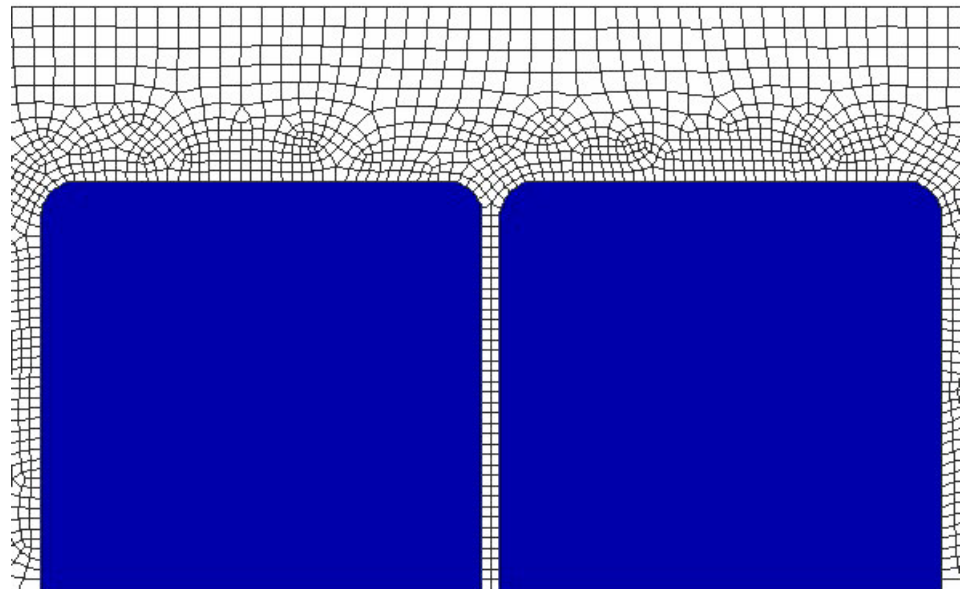




## Results – XFEM Simulations of Laser Welding

Full physics simulations in realistic geometries

- Previous ALE capability limited to non-joining simulations of welding
- XFEM capturing important surface discontinuities
- XFEM framework amenable to varied interface conditions
- Not just prettier pictures, revealing new insight into process and failure mechanisms







# Implementation – Applying eXtended Finite Elements (XFEM) to Foam Decomposition

## Problem Discretization

- Fixed unstructured mesh
- Solid-liquid interface described by enthalpy method
  - Specific heat is temperature dependent to account for latent heat
  - Viscosity sharp function of temperature around between solidus and liquidus
- Liquid-vapor interface described by level set method
  - Level set evolution described by evolution equation
  - 2 components of interfacial motion: flow and reaction

## Variable Enrichment

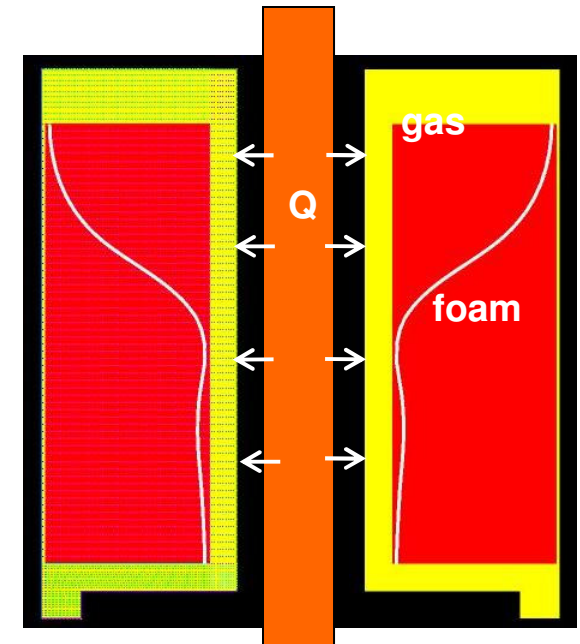
- Variables allowed to be discontinuous across liquid-vapor interface

## Subelement Integration

- Required to integrate discontinuous quantities resulting from discontinuous variables and trial functions

## Interfacial Conditions

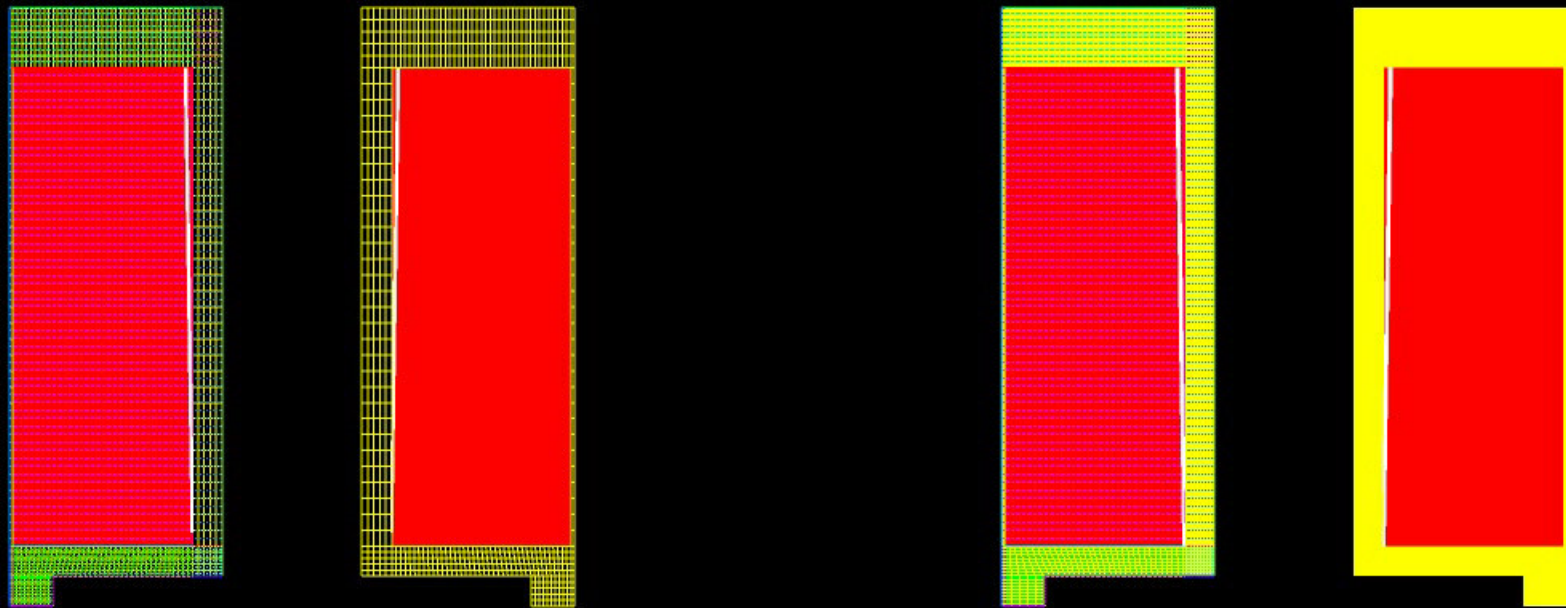
- XFEM approach produces natural mechanism for applying interfacial fluxes including surface reaction and surface tension







## Results – XFEM Simulations



- XFEM capturing important surface discontinuities, fluxes
- As expected, viscosity of fluid phase plays critical role in dynamics
  - Experimental effort to determine viscosity of decomposing foam