

Modeling Plastic Deformation of Steel Plates in Hypervelocity Impact Experiments

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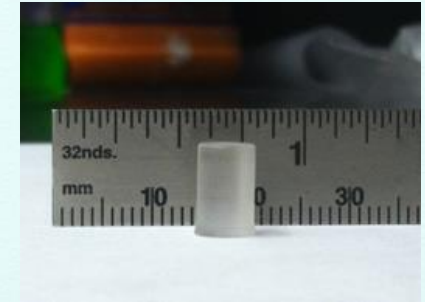
- ☐ Objective
- ☐ Experimental Setup
- ☐ Results & Discussion
- ☐ Computational Simulation
- ☐ Simulation Comparison
- ☐ Conclusion
- ☐ Future Work

Objective

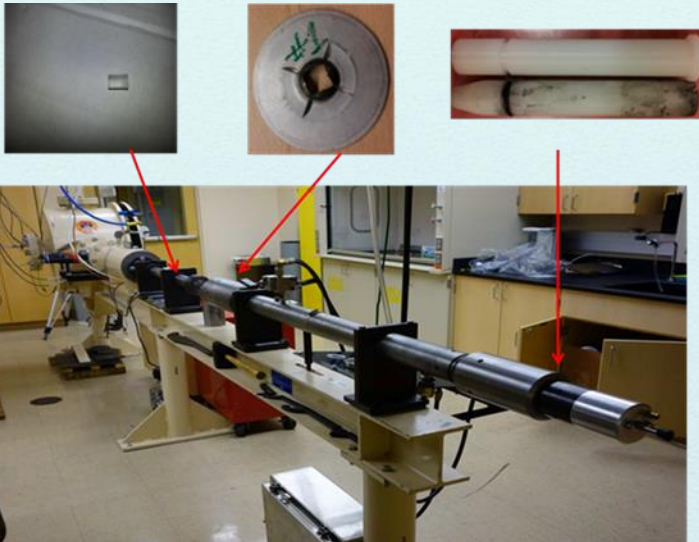
- ❑ A common technique to perform hypervelocity impact research in laboratory settings: gas gun experiments.
- ❑ Metallic plates experience tremendous amounts of shockwave and pressure within a short time, which results large localized plastic deformation.
- ❑ Characterizing materials under this type of dynamic experiment often poses multiple challenges in terms of experimental design and computational modeling.
- ❑ Most of the time, gas gun experiments include expensive instrumentation and high-fidelity diagnostic systems.
- ❑ Therefore, predictive modeling is an alternate way to simulate this type of experiment.
- ❑ Computational tools developed to simulate these experiments must consider the complexities and nonlinearities arising from such projectile-target interactions.

Experimental: Two-Stage Light Gas Gun

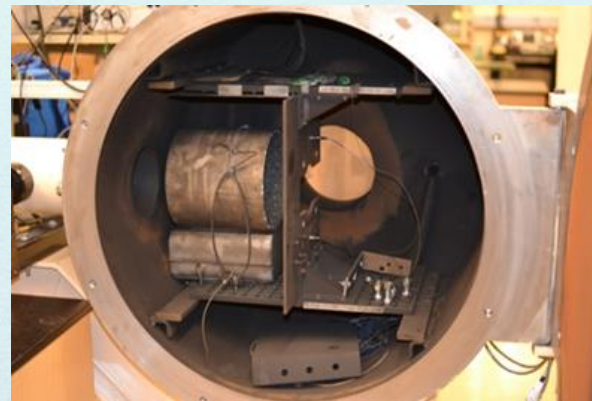
- ❑ A two-stage light gas gun is used to launch a cylindrical projectile into a target plate at a velocity from 4.5 to 6 km/s
- ❑ The gun uses either hydrogen or helium
 - Projectile: Lexan (5.6 mm diameter)
 - Target: A36 steel plate (152.4 × 152.4 × 12.7 mm)
- ❑ The target is bolted on a mounting plate during the experiment
- ❑ A laser intervalometer system is used to measure projectile velocity



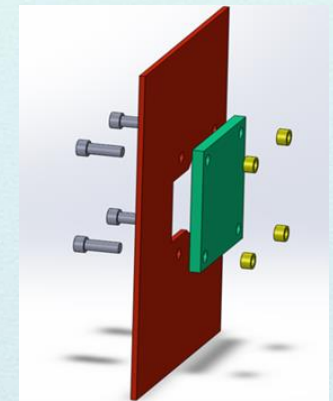
Lexan projectile



UNLV two-stage light gas gun



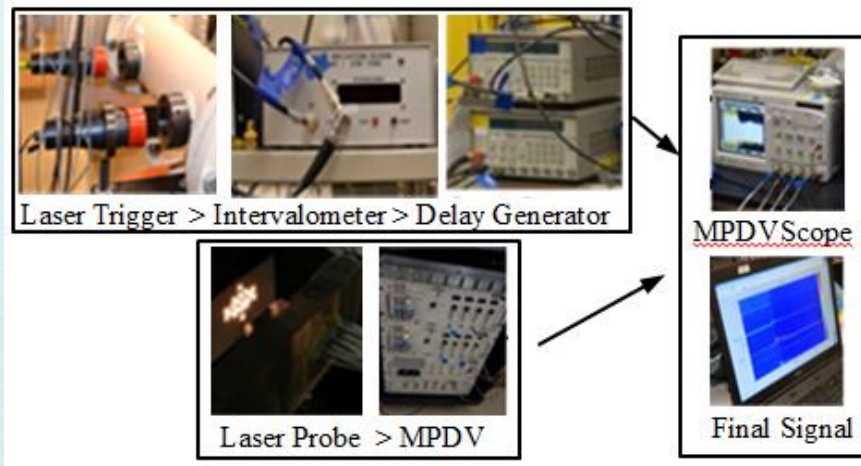
Target chamber assembly



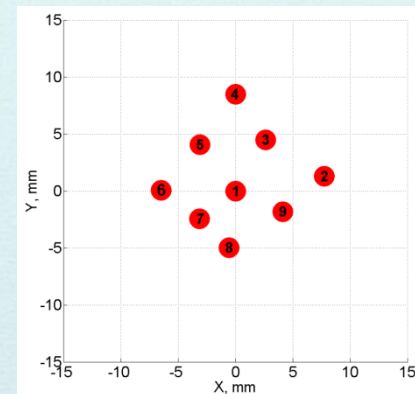
Target mounting plate

Multiplexed Photonic Doppler Velocimetry

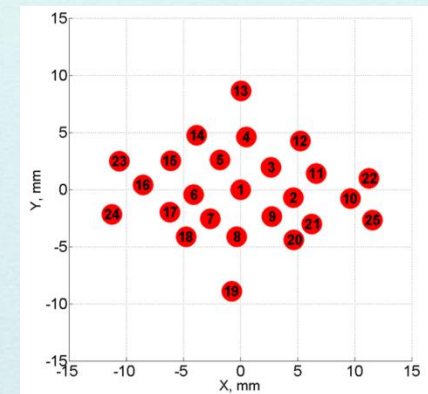
- ❑ A Multiplexed Photonic Doppler Velocimetry (MPDV) system has been used as a diagnostic tool to collect the velocimetry data
- ❑ PDV is a heterodyne interferometric technique that can record velocity data in terms of displacement using Doppler shift of reflected light frequency from a moving surface
- ❑ In the case of the MPDV system, data are collected from multiple points with multiple optical fiber probes
- ❑ So far, 9-probe and 25-probe arrangements have been used with the MPDV system in gas gun experiments



Schematic of MPDV data acquisition



Typical 9-probe pattern



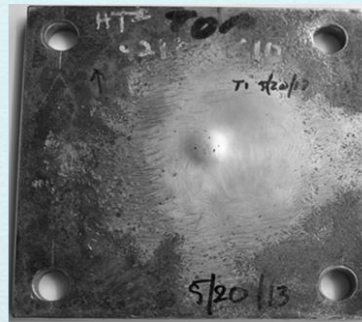
Typical 25-probe pattern

Results & Discussion

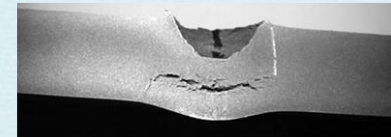
- ❑ In all experiments, the Lexan projectiles disintegrated due to the enormous stress and the heat generated upon impact with the target surface
- ❑ A small crater with a bulge on the back side of the target plate is created as a result of impact
- ❑ **Spall failure**
 - Spalling happens close to the rear side of the target
 - Shock waves reach a free surface end and reflect back, resulting in tensile pressure in the material
 - The material fails when the tensile pressure is above the material strength



Crater (front side)



Bulge (back side)



Spall (Sectioned)

Typical target plate after experiment

Results & Discussion

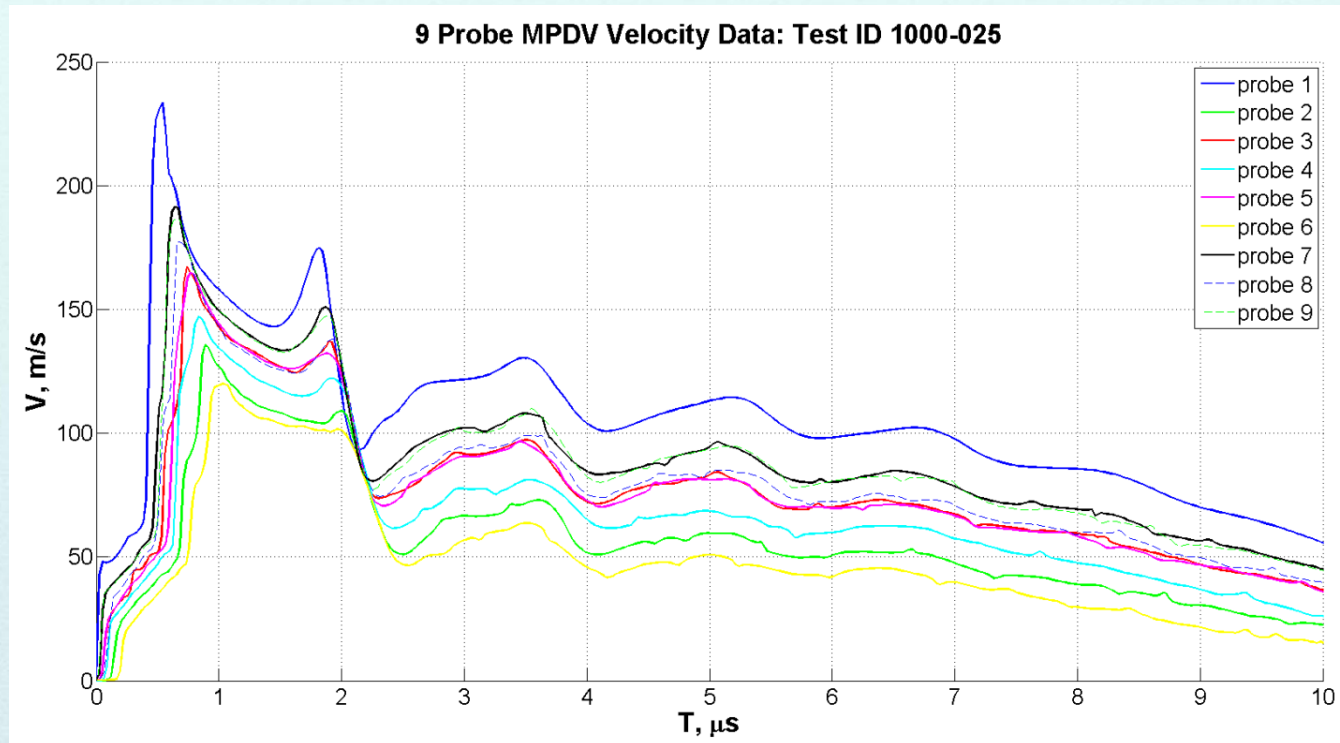
- Physical measurements of crater and bulge are taken typically after every experiment.

Test ID	MPDV system details	Impact velocity, km/s	Crater diameter, mm	Penetration depth, mm	Bulge, mm	Spall crack details	
						Diameter, mm	Width, mm
1000-024	9 probe	5.708	17.2 ± 0.3	7.7 ± 0.3	3.1 ± 0.3	21.4 ± 0.2	1.9 ± 0.1
1000-025	9 probe	4.763	15.4 ± 0.3	6.5 ± 0.3	1.4 ± 0.1	14.5 ± 0.2	0.2 ± 0.1
1000-026	25 probe	4.823	15.1 ± 0.2	6.5 ± 0.5	1.5 ± 0.1	n/a	n/a
1000-027	25 probe	5.088	16.9 ± 0.8	7.0 ± 0.4	2.3 ± 0.2	n/a	n/a
1000-028	25 probe	5.157	15.9 ± 0.4	6.5 ± 0.5	1.7 ± 0.2	18.5 ± 0.1	0.7 ± 0.1

- Damage trends seem reasonable: Higher impact velocity results in larger crater and bulge. (Although some minor discrepancies in damage dimensions still exist!)
- All the values listed above are an average of typical physical measurements of crater and the bulge on the back side

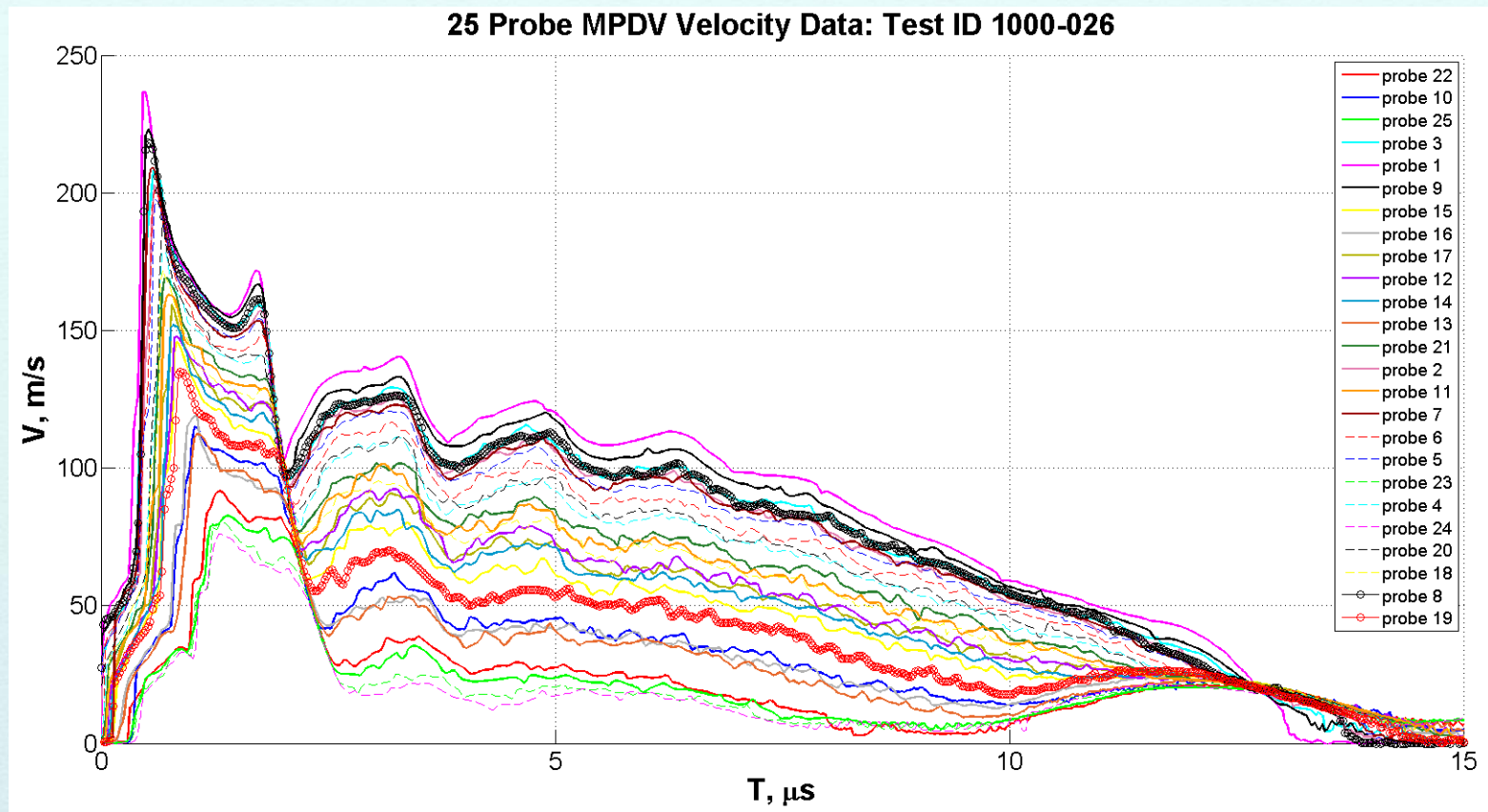
Results & Discussion

- ❑ Free surface velocity is measured by MPDV systems
- ❑ Probe locations and velocity signal arrival time are very important for MPDV systems



Typical 9-probe MPDV data

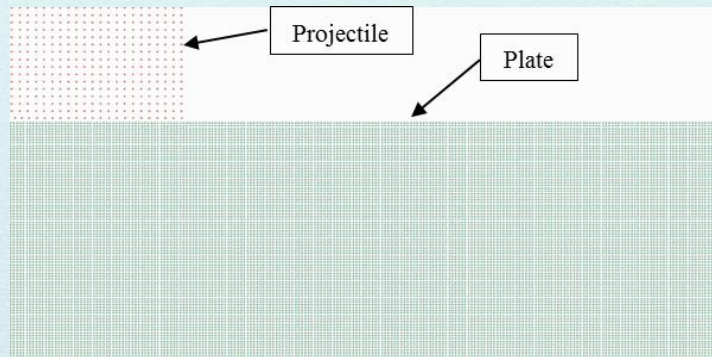
Results & Discussion



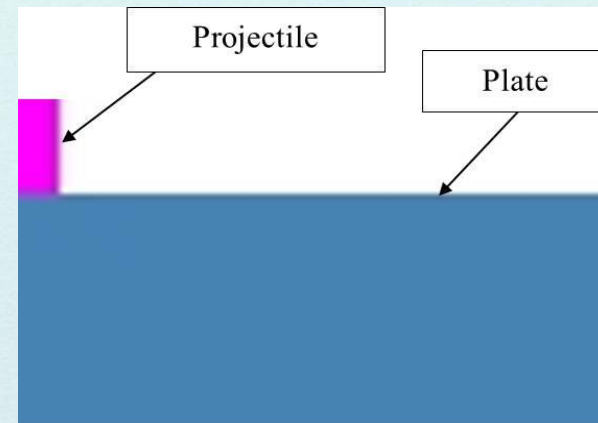
Typical 25-probe MPDV data

Computational Simulation

- ❑ Two finite element methods are used to simulate the impact phenomena computationally:
 - Lagrangian-based Smooth Particle Hydrodynamics (SPH) in LS-DYNA
 - Eulerian-based Hydrocode in CTH
- ❑ 2-D axi-symmetric models are developed
- ❑ Both models have no boundary conditions
- ❑ An extensive parametric study has been performed in both models
- ❑ For LS-DYNA model, a general SPH particle spacing of 0.05 mm is chosen
- ❑ For CTH, a zone size of 0.05×0.05 mm is chosen



LS-DYNA SPH Model (zoomed in)



CTH Model (zoomed in)

Computational Simulation: Material Model

- ❑ Both LS-DYNA and CTH models use Johnson-Cook material model for both Lexan projectiles and A36 steel target plates
- ❑ Parameters of Johnson-Cook material model are taken from the available literature

Material	A, MPa	B, MPa	C	M	N	T _{melt} , °K
Lexan (Littlewood)	75.8	68.9	0	1.85	1.004	533
A36 Steel (Seidt)	286.1	500.1	0.022	0.917	0.2282	1811

Littlewood, D.J., “Simulation of dynamic fracture using peridynamics, finite element modeling, and contact,” *ASME 2010 International Mechanical Engineering Congress & Exposition*, Vancouver, British Columbia, Canada, November 12–18, 2010.

Seidt, J.D. et al., “High strain rate, high temperature constitutive and failure models for EOD impact scenarios,” *Proceedings of the 2007 SEM Annual Conference and Exposition on Experimental and Applied Mechanics*, Springfield, MA, June 2007.

Computational Simulation: Equation of State

- ❑ Both LS-DYNA and CTH models use a Grüneisen equation of state for both Lexan and A36 steel
- ❑ EOS parameters are also taken from the available literatures

Material	ρ , kg/m ³	C_0 , m/s	S_1	Υ
Lexan (Steinberg)	1190	1933	1.42	0.61
A36 Steel (Seidt)	7890	4569	1.49	2.17

Steinberg, D. J., *Equation of State and Strength Properties of Selected Materials*, UCMRL-MA-106439; Lawrence Livermore National Laboratory: Livermore, CA, 1996.

Seidt, J.D. et al., “High strain rate, high temperature constitutive and failure models for EOD impact scenarios,” *Proceedings of the 2007 SEM Annual Conference and Exposition on Experimental and Applied Mechanics*, Springfield, MA, June 2007.

Computational Simulation: Spall Parameter

- ❑ In both LS-DYNA and CTH, spall failure is defined as a pressure cut-off (i.e., P_{\min}) value in Johnson-Cook material model
- ❑ Spall happens in both models if tensile stress exceeds a certain P_{\min} value
- ❑ P_{\min} value is also taken from literature:

Lexan: $P_{\min} = -160$ MPa (Steinberg)

A36 steel: $P_{\min} = -1200$ MPa (calculated based on 1-D assumption)

Steinberg, D. J., *Equation of State and Strength Properties of Selected Materials*, UCMRL-MA-106439; Lawrence Livermore National Laboratory: Livermore, CA, 1996.

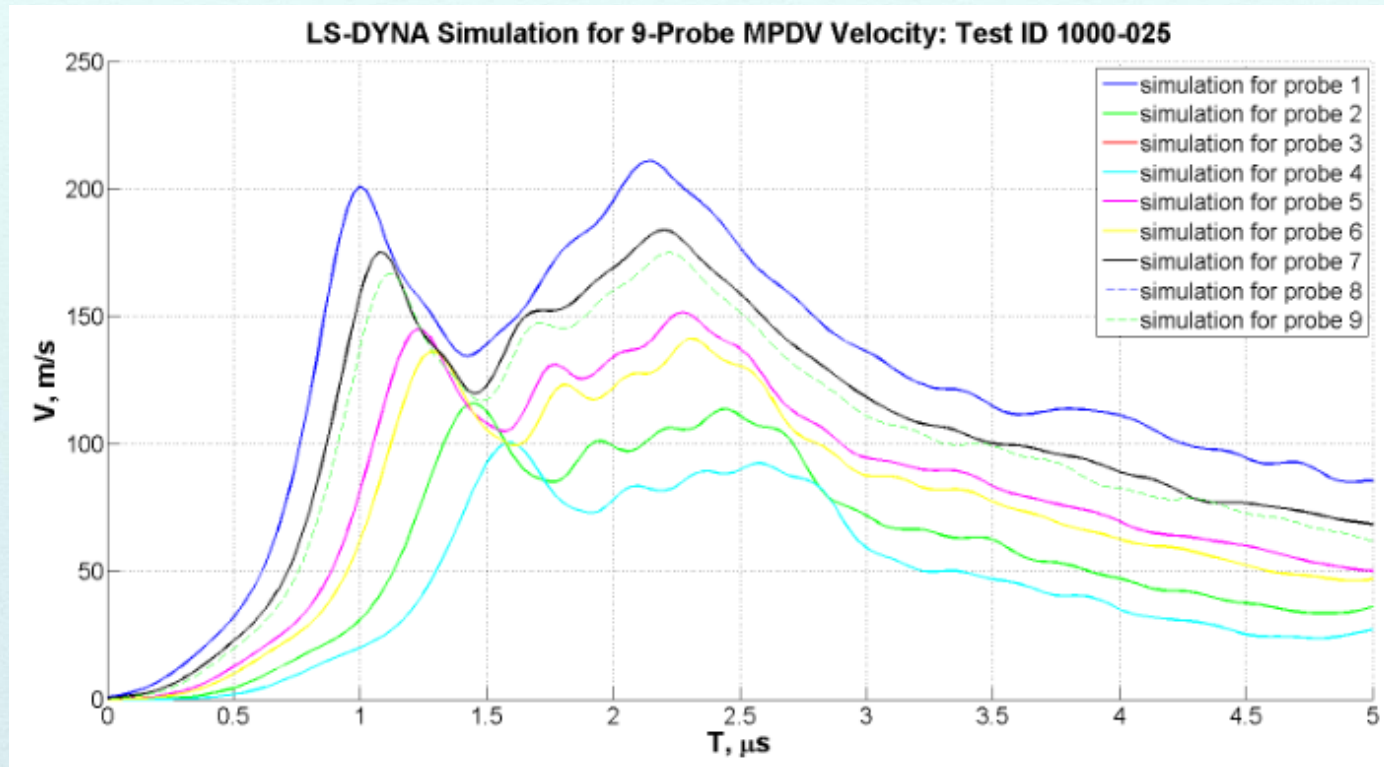
Simulation Comparison: Crater Details

- Both LS-DYNA and CTH simulations have been able to capture the deformation progression due to impact.

Material	Crater diameter, mm	Difference (%)	Penetration, mm	Difference (%)	Bulge, mm	Difference (%)
Experiment	15.37	N/A	4.83	N/A	1.42	N/A
LS-DYNA (SPH)	16.20	-5.4	4.44	8.07	1.39	2.11
CTH	16.20	-5.4	4.50	6.83	1.40	1.41

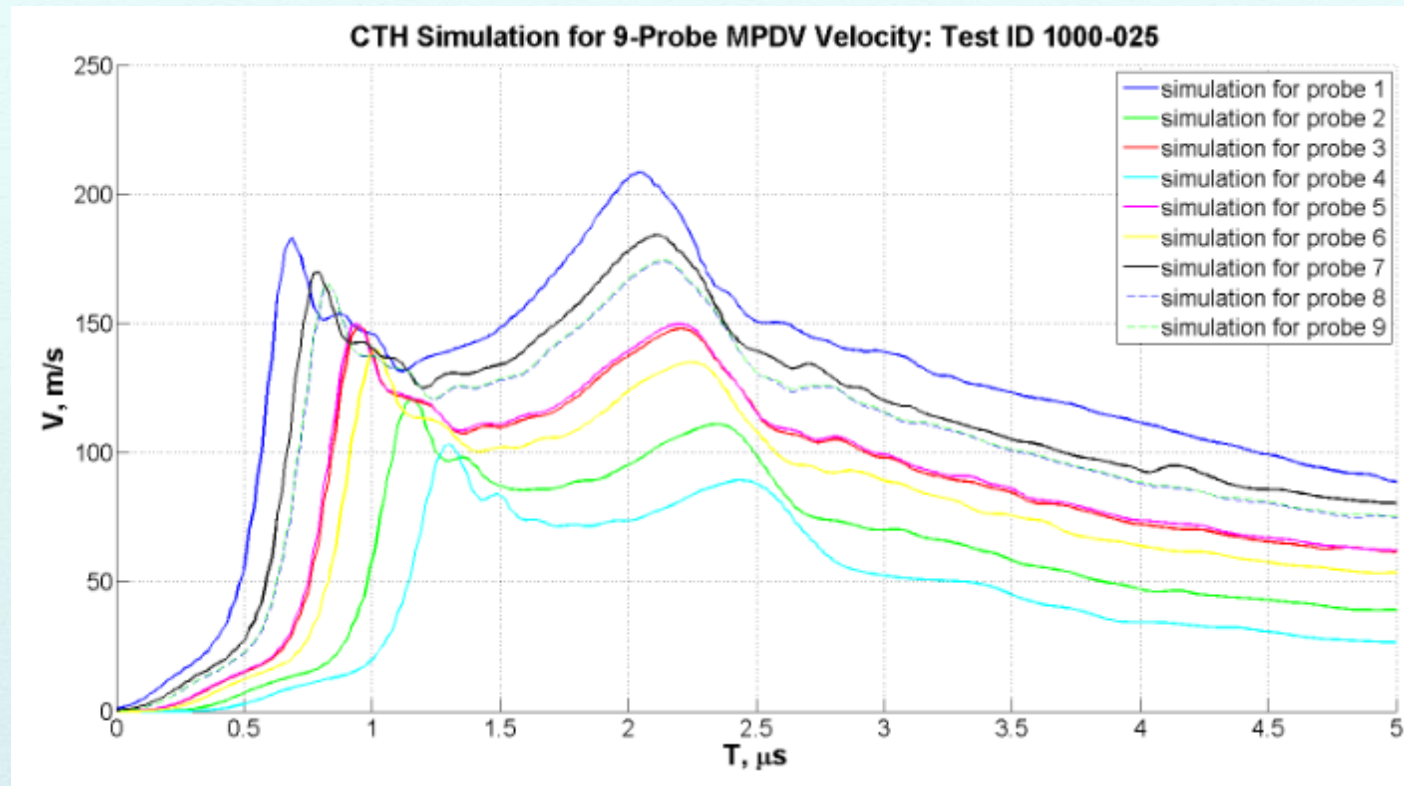
Simulation Comparison: Free Surface Velocity

- ❑ Free surface velocity profiles are also in reasonable agreement
- ❑ Further refinement of the models is still in progress



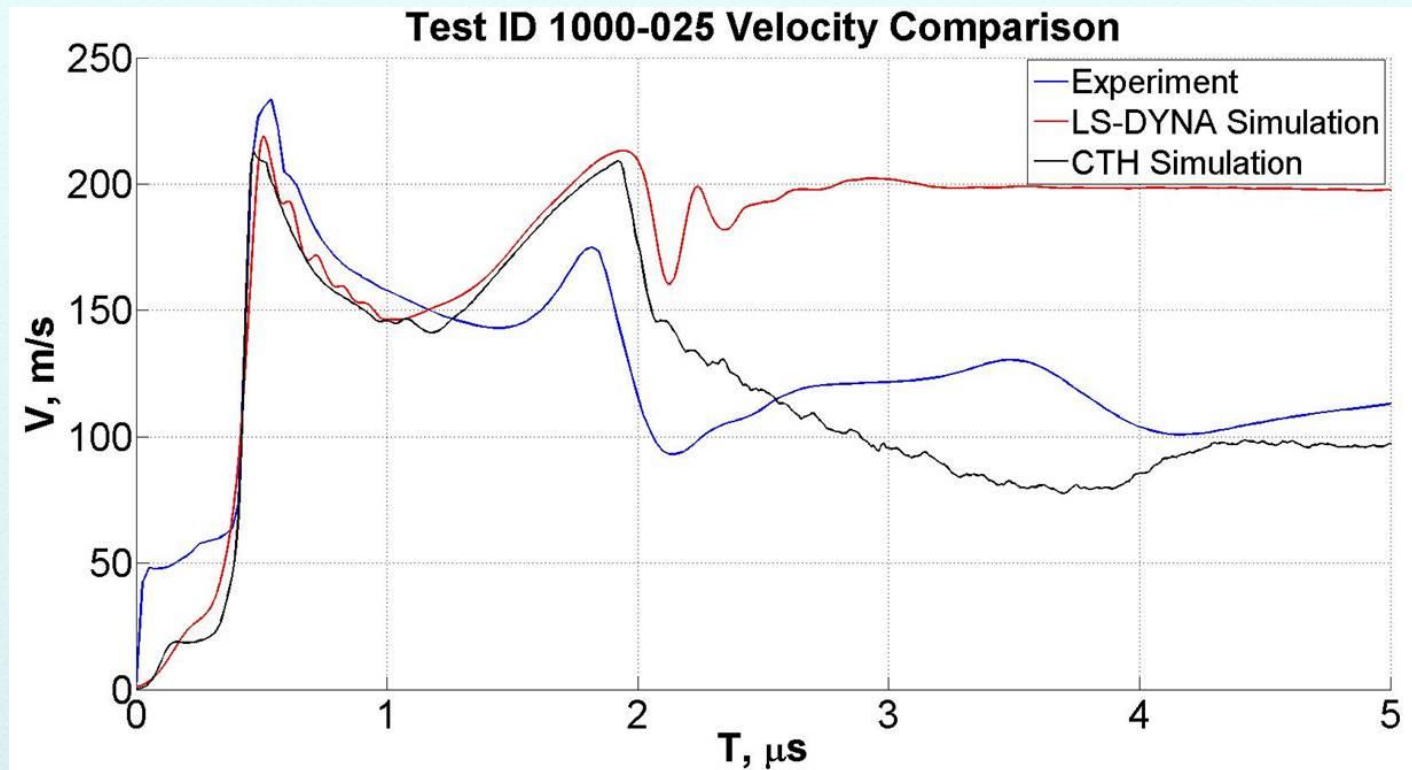
Typical free surface velocity from LS-DYNA simulation

Simulation Comparison: Free Surface Velocity



Typical free surface velocity from CTH simulation

Simulation Comparison: Free Surface Velocity



- ❑ Both simulation models capture the overall trend of the free surface velocity in terms of HEL, plastic wave rise, peak velocities, and spall signature
- ❑ However, the magnitude of these features vary in the process of further tuning

Conclusion

- ❑ A series of two-stage light gas gun experiments were performed to study the plastic deformation of steel plates during hypervelocity impact.
- ❑ Free surface velocity from back of the plate was measured using MPDV system during these experiments.
- ❑ Simulation models developed in LS-DYNA SPH solver and CTH hydrocode reasonably simulated the experiments.
- ❑ The results of this study may be used to conduct a parametric study of the material models and the equation of the state to determine their sensitivities in accurately predicting the behavior of metallic materials during dynamic penetration events.

Future Work

- ❑ Representation of MPDV data
- ❑ Benchmark MPDV data with high-speed camera data
- ❑ Tuning of parameters in simulation models to get better match

THANK YOU!



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