

Extended and Conformal Decomposition Finite Elements for 3D Compatible Discretizations

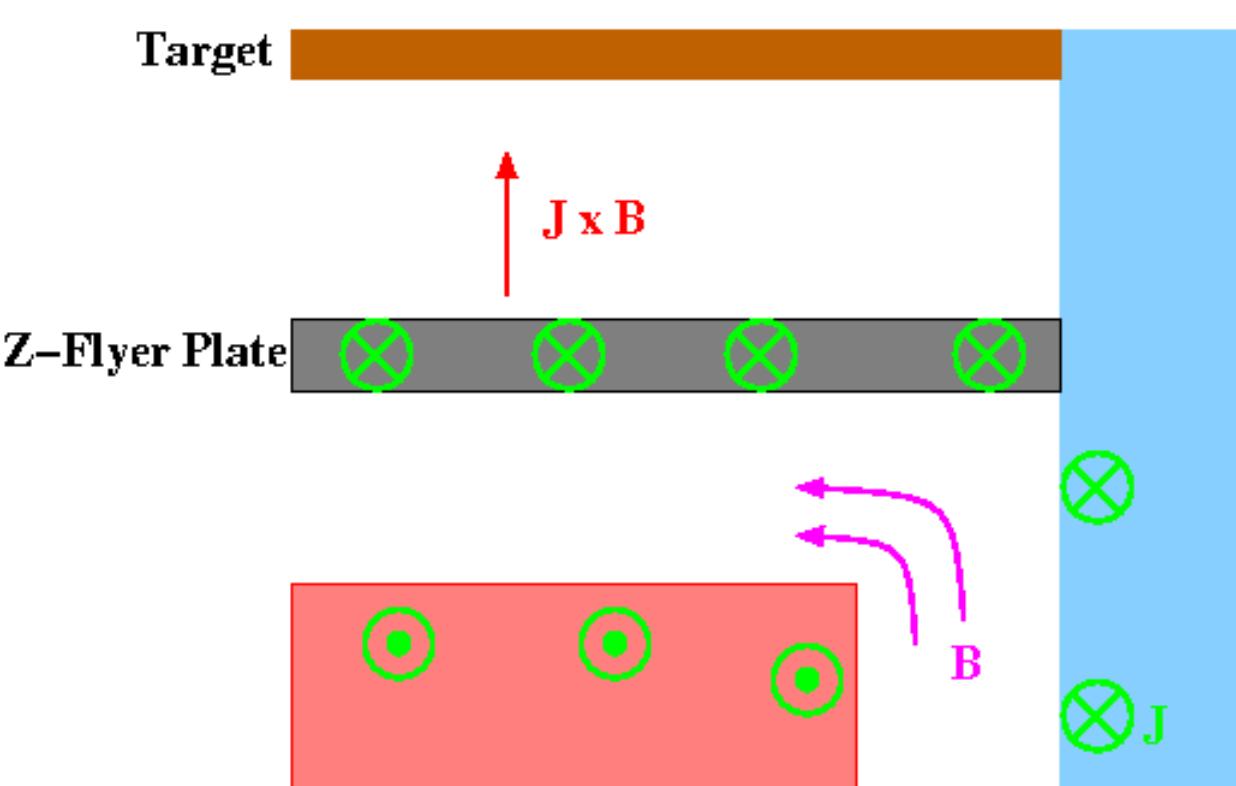
Chris Siefert, Richard Kramer, Pavel Bochev and Tom Voth

Sandia National Laboratories

Motivating Application

Motivating application: Z-flyer plate

- Lorentz force accelerates plate towards target
- Goal: Shape current pulse to ensure plate is flat and solid as possible on impact.



Current concentrates on material surfaces

- Material/void interfaces "count" for EM as voids must be meshed.
- Lagrangian only works for small deformation.
- Eulerian mixture models underdeveloped for EM.
- Solution: Interface tracking + local mesh or basis refinement.
- Basis refinement: eXtended Finite Element Method (XFEM).
- Mesh refinement: Conformal Decomposition Finite Element Method (CDFEM).

Governing PDEs

Nodes (2D/3D): $\tau \frac{\partial u}{\partial t} + \nabla \cdot \sigma \nabla u = 0$

Edges (2D/3D): $\sigma \frac{\partial E}{\partial t} + \nabla \times \nu \nabla \times E = 0$

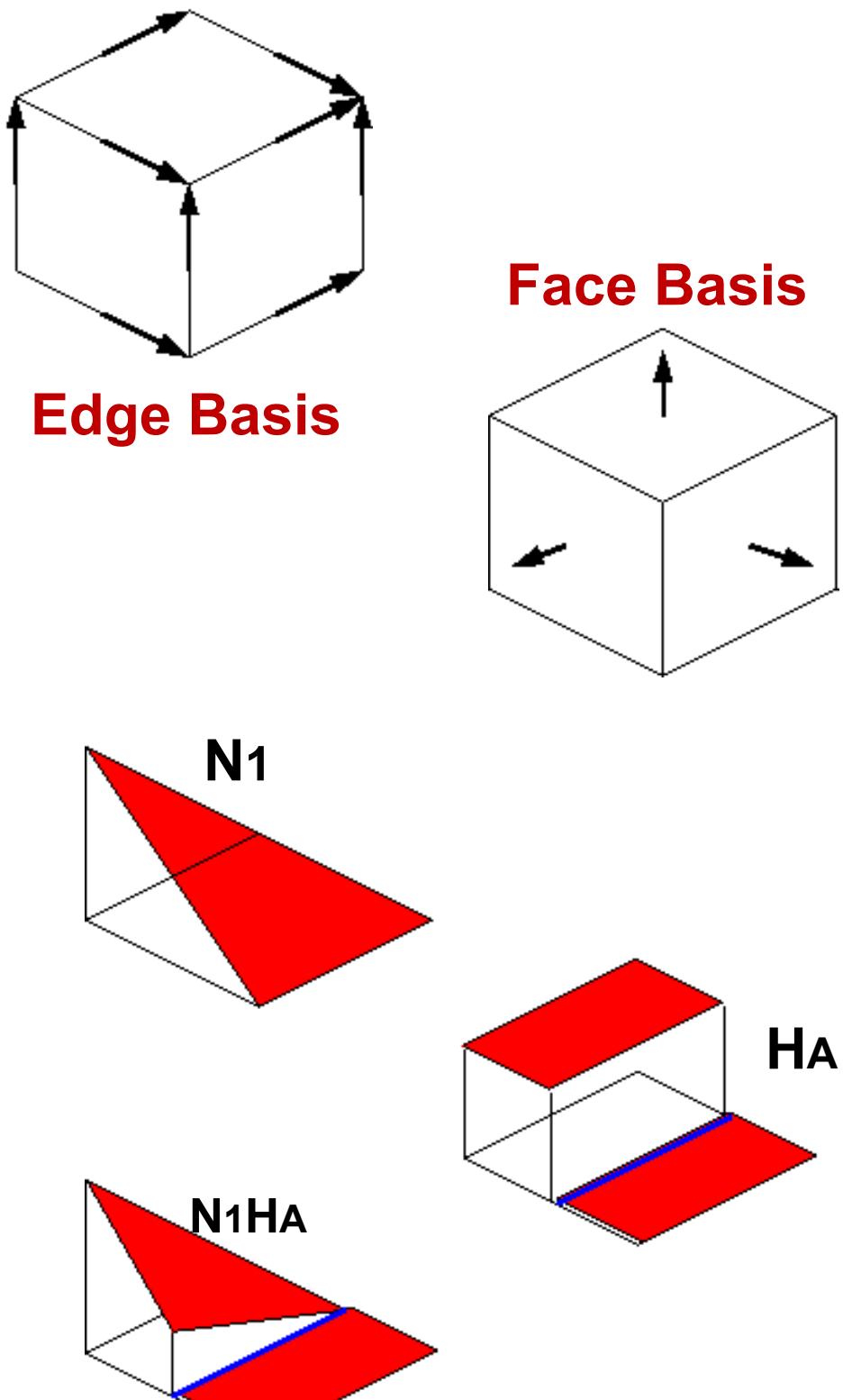
Faces (3D): $\nu \frac{\partial F}{\partial t} + \nabla \kappa \nabla \cdot F = 0$

These PDEs capture electrostatics, magnetic diffusion and thermal diffusion (both nodal and flux-based).

Approach

Edge and Face Element Discretizations

- Preserves $\operatorname{div} \operatorname{curl} = 0$ and $\operatorname{curl} \operatorname{grad} = 0$ discretely.
- Fact: Lowest order edge basis functions on simplices (tris, tets) have a *constant tangential component* along any line.
- Fact: Lowest order face basis functions on simplices (tris, tets) have a *constant normal component* along any plane.



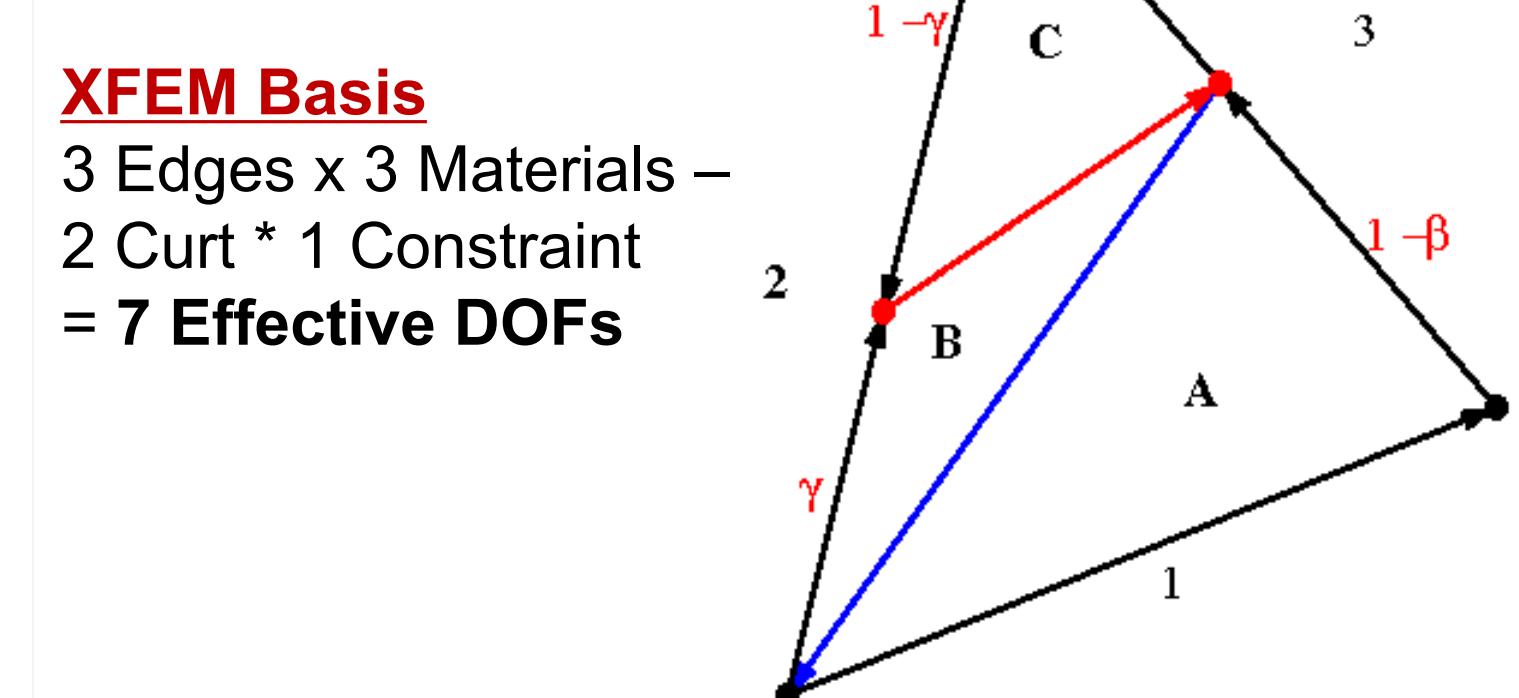
eXtended Finite Element Method (XFEM)

- Add intra-element discontinuities w/o changing mesh.
- Used here for **weak** (bonded materials) discontinuities.
- Uses Partition of Unity to preserve convergence:

$$u^h(x) = \sum_A \sum_I N_i(x) H_A(x) u_{I,A}$$

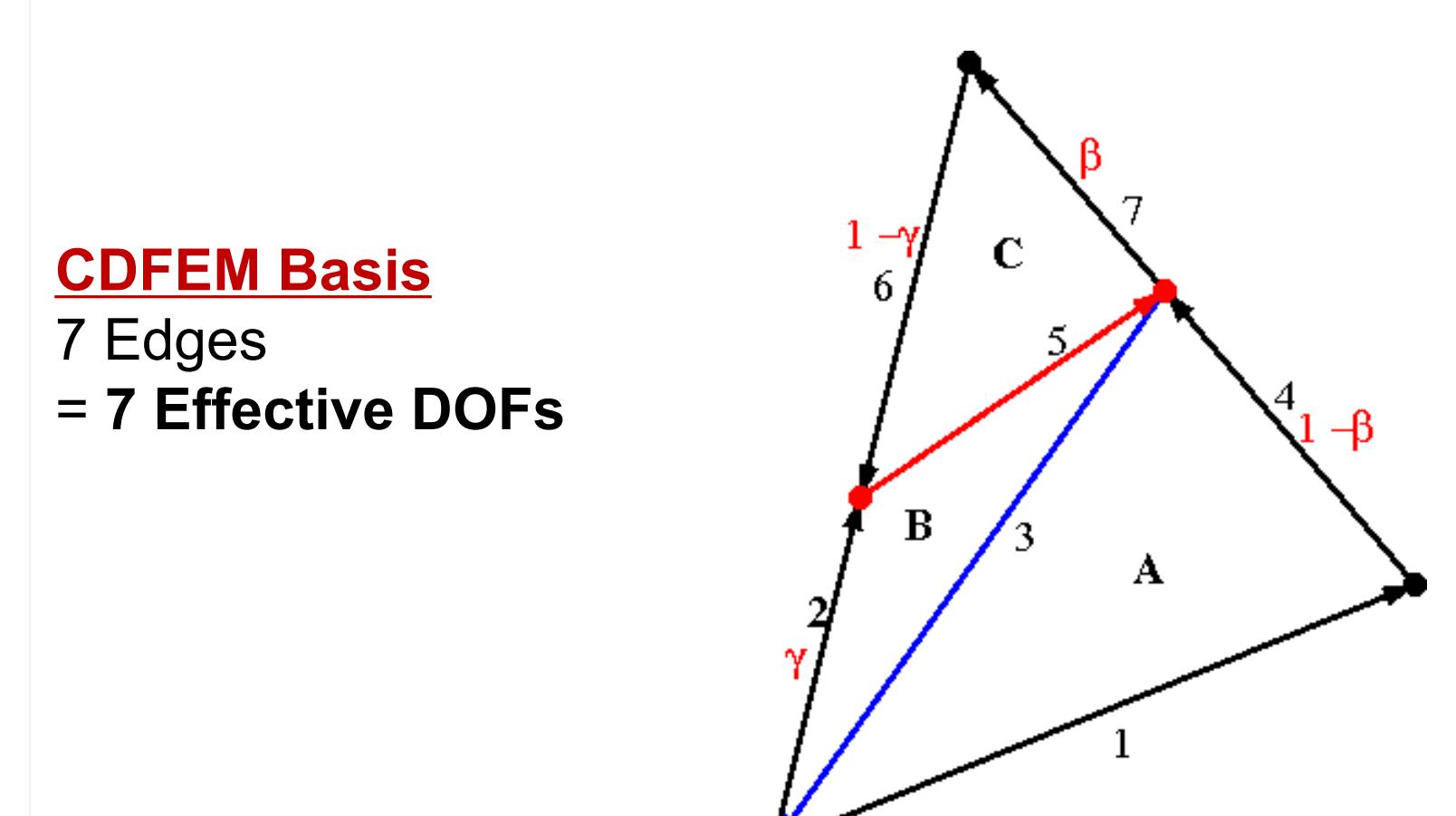
where the constant is in the span of the F_i 's

- Tie solution together w/ *virtual algebraic constraints*.
- Idea #1: Start w/ simplices, decompose into simplices.
- Idea #2: Apply just enough constraints to tie everywhere.



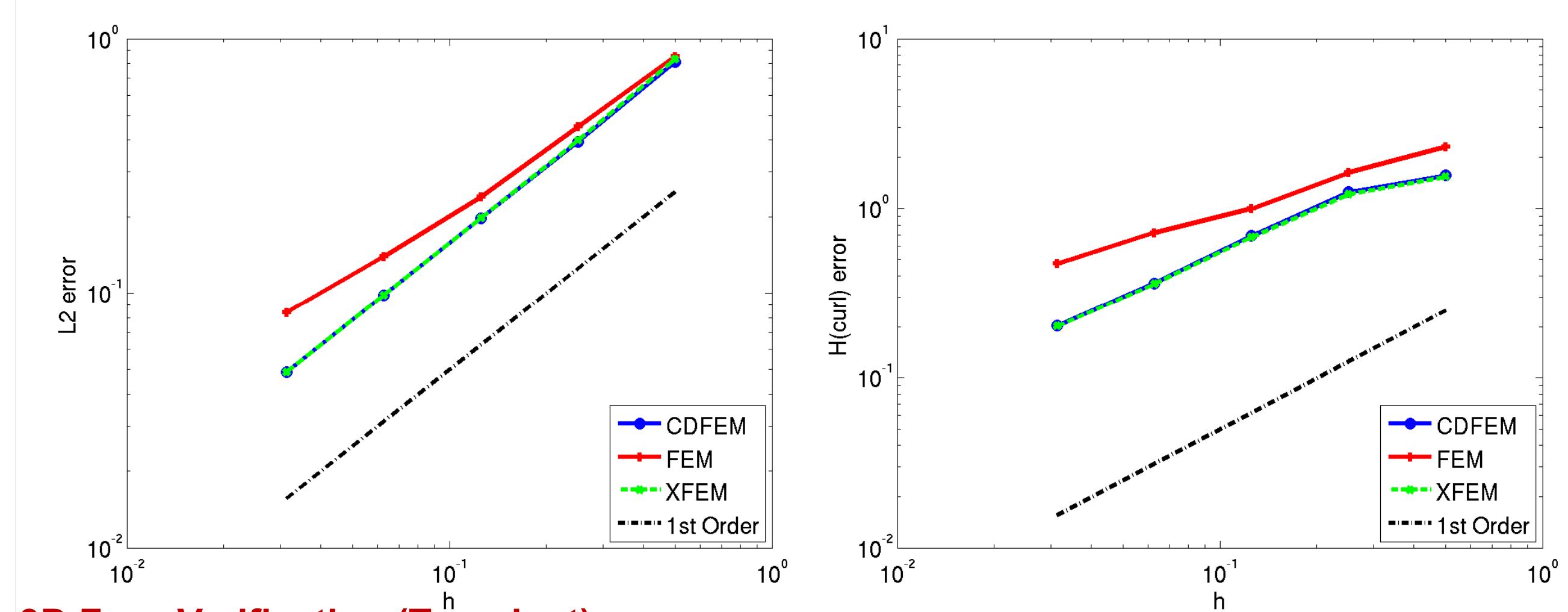
This allows us to prove **exact** equivalence to...

Conformal Decomposition Finite Element Method (CDFEM)

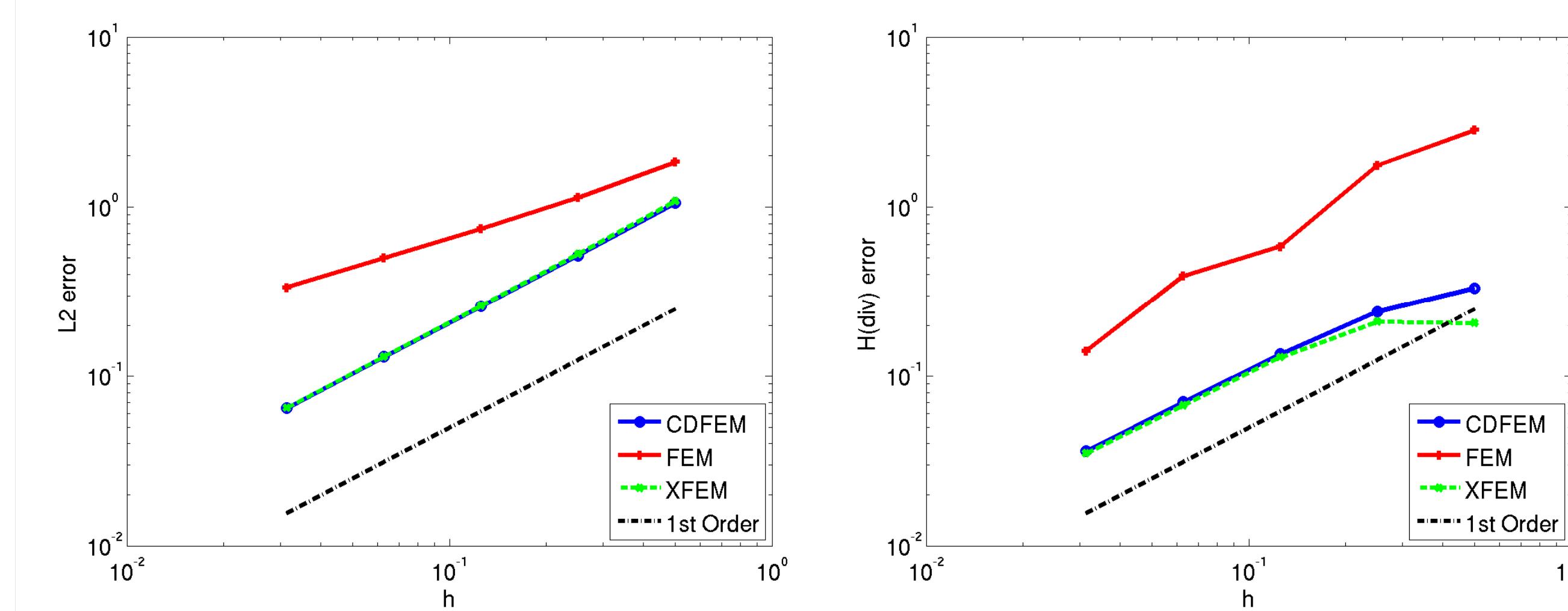


3D Verification Results

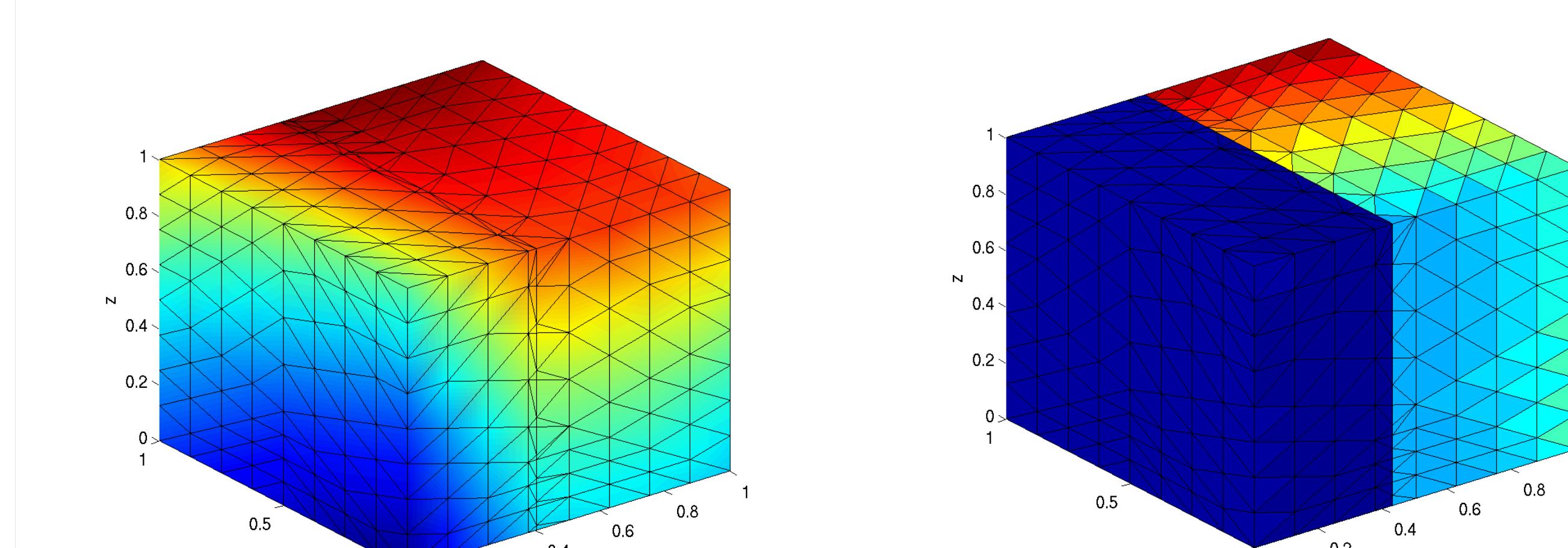
3D Edge Verification (Transient)



3D Face Verification (Transient)



3D Visualizations



Remap Algorithms

The starting point for our remap method is:

P. Bochev and M. Shashkov. Constrained interpolation (remap) of divergence-free fields. *Comput. Methods Appl. Mech. Engrg.*, 194:511–530, 2005.

The key: Think about remap as a method to transfer a representation of a field from one mesh to another.

Given the source field \mathbf{B}^0 ,

$$\lambda_{\text{opt}}^e = \operatorname{argmin} \left\| \mathbf{B}^0 \right\|_e^2 - \left\| \mathbf{B}^n(\lambda^e) \right\|_e^2 \quad \forall e \in T^n.$$

where (element-wise)

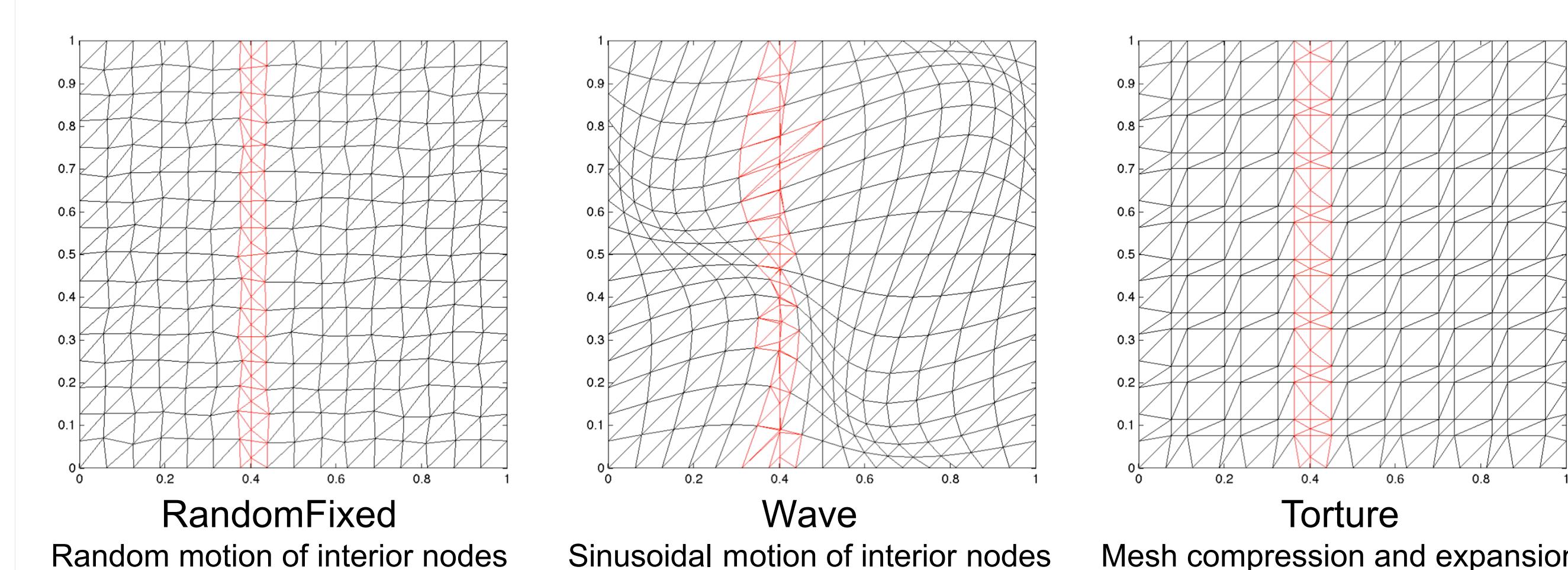
$$\begin{array}{c} \text{Low order (dissipative) field approximation} \\ \mathbf{B}_{\text{lo}}^n \end{array} + \begin{array}{c} \text{High order (accurate) field approximation} \\ \mathbf{B}_{\text{hi}}^n \end{array} = \begin{array}{c} \text{Accurate and conservative remapped field} \\ \mathbf{B}^n = \lambda_{\text{opt}} \mathbf{B}_{\text{lo}}^n + (1 - \lambda_{\text{opt}}) \mathbf{B}_{\text{hi}}^n \end{array}$$

on the destination mesh T^h .

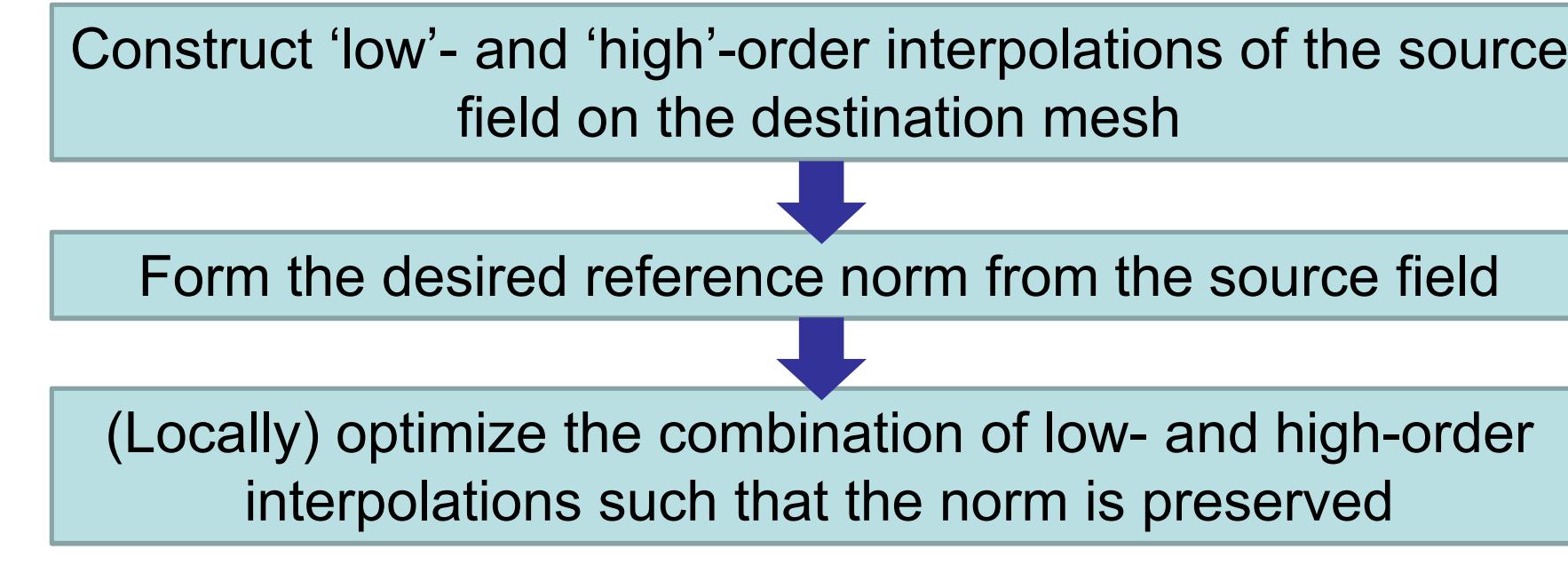
Remap Tests

Remap testing uses three different mesh motions, shown below.

A fixed material interface is located at $x = 0.4$; elements cut by the interface are enriched and shown in red. Each mesh increment is independently enriched.



Remap Algorithm Overview



Patch recovery

Nodal: Standard procedure to extract element-wise quadratic approximations from linear FEM over element neighbors.

Edge: Extract coefficients for 2nd-order Nédélec edge shape function polynomials from the 1st order approximation.

Respects material interfaces.

Reference Norm

Perfect remap idealization: Integrate the known analytic solution over each destination element to define the reference norm.

Practical alternatives:

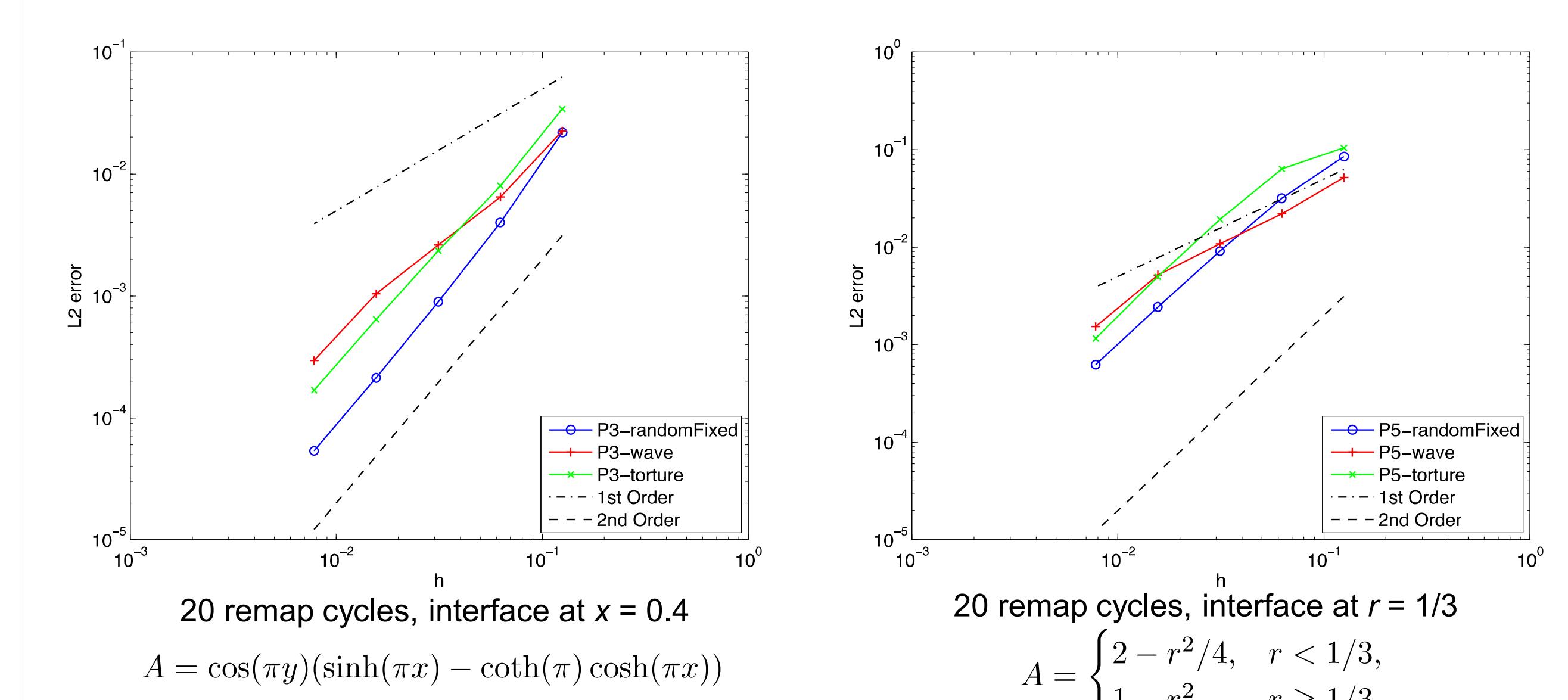
- Intersection remap of element quantities from source to destination elements.
- Approximate integration of source field on the dest mesh.

Optimization
Each element generates a simple squared quadratic objective function: roots at which local minima and maxima occur can be evaluated analytically (minimizes computational cost and improves accuracy).

2D Remap Results

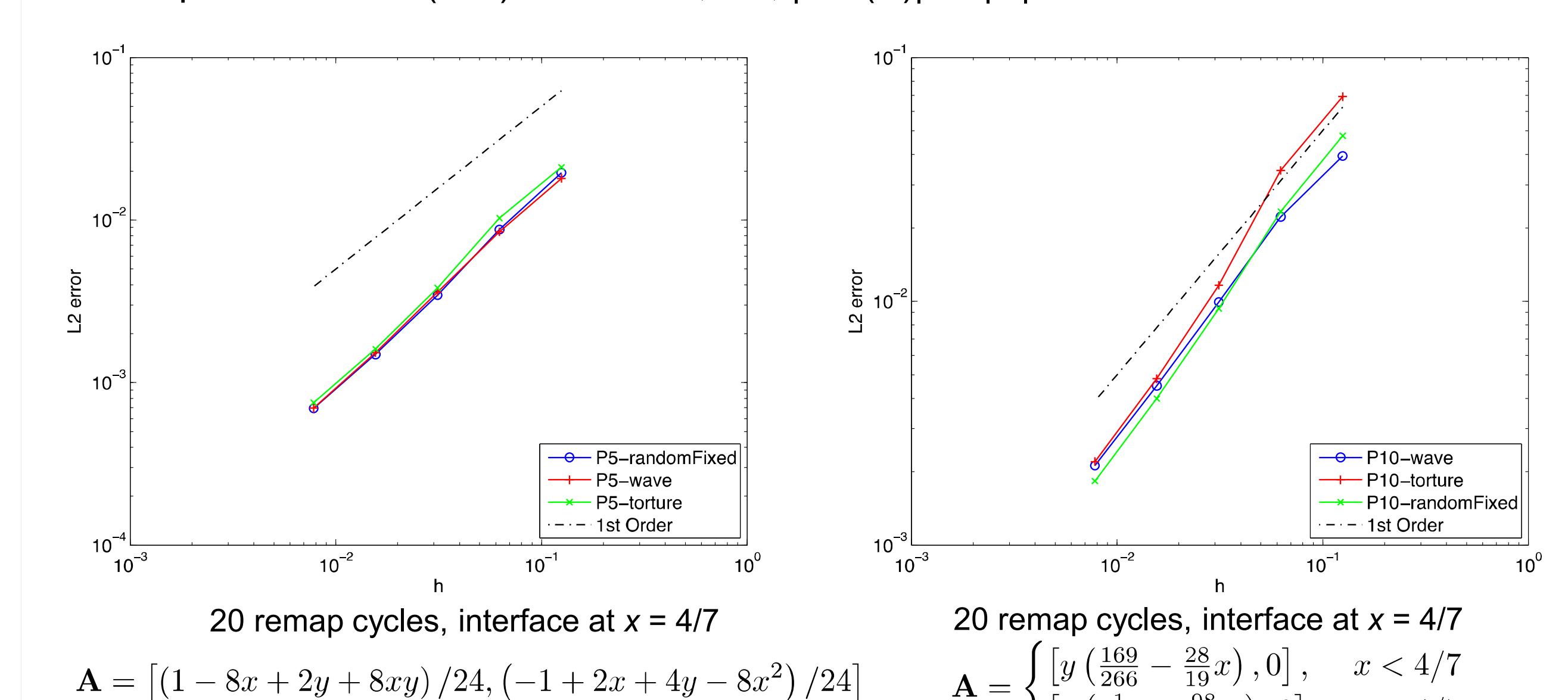
Nodal A-form (transverse magnetic):

Equation (1) solved assuming $A = A(x, y)$, with a nodal compatible discretization, where A is a scalar potential of the \mathbf{B} field such that $\mathbf{B} = \operatorname{grad}(A)$. Norm preserved is H^1 seminorm of the field, i.e., $|\operatorname{grad}(A)|^2 = \|\mathbf{B}\|^2$.



Compatible transverse electric:

Equation (1) solved assuming $\mathbf{A} = [A_x, A_y, 0]$, with an edge-based compatible discretization, where \mathbf{A} is a vector potential of the \mathbf{B} field such that $\mathbf{B} = \operatorname{curl}(\mathbf{A})$. Norm preserved is $H(\operatorname{curl})$ of the field, i.e., $|\operatorname{curl}(\mathbf{A})|^2 = \|\mathbf{B}\|^2$.



Current and Future Work

- Improved (piecewise linear) interface reconstruction.
- Mixed meshes (quad/tri and hex/pyramid/prism/tet).
- Extending remap algorithms to 3D.
- Improved patch recovery for edge element discretizations.
- References:
 - R. Kramer, P. Bochev, C. Siefert and T. Voth. An extended finite element method with algebraic constraints (XFEM-AC) for problems with weak discontinuities. *Computer Methods in Applied Mechanics and Engineering*, Volume 266, pp. 70–80, 2013.
 - R. Kramer, P. Bochev, C. Siefert and T. Voth. Algebraically constrained extended edge element method (eXFEM-AC) for resolution of multi-material cells. *Journal of Computational Physics*, Volume 276, Pages 596–612, 2014.

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