



SAND2007-4988C



Heterogeneous Dynamic Behavior and Failure of a Tungsten Alloy: Experiments and Simulations

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&

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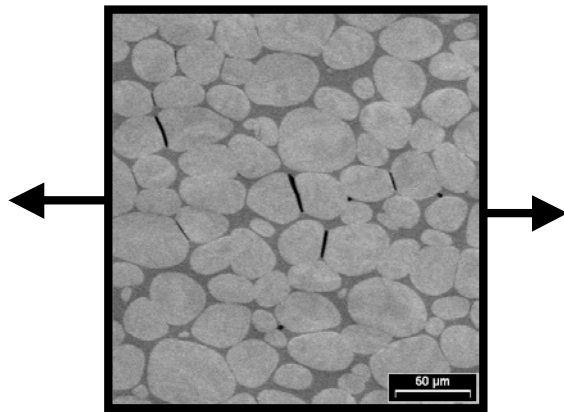
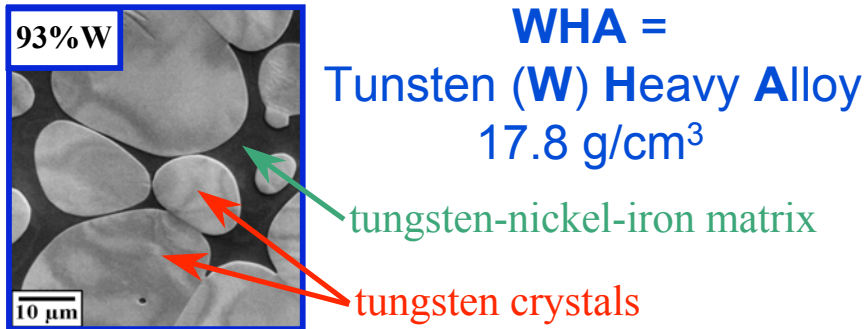
Impact Physics Branch
U.S. Army Research Laboratory

ASME Applied Mechanics and Materials Conference
Austin, Texas
June 6, 2007

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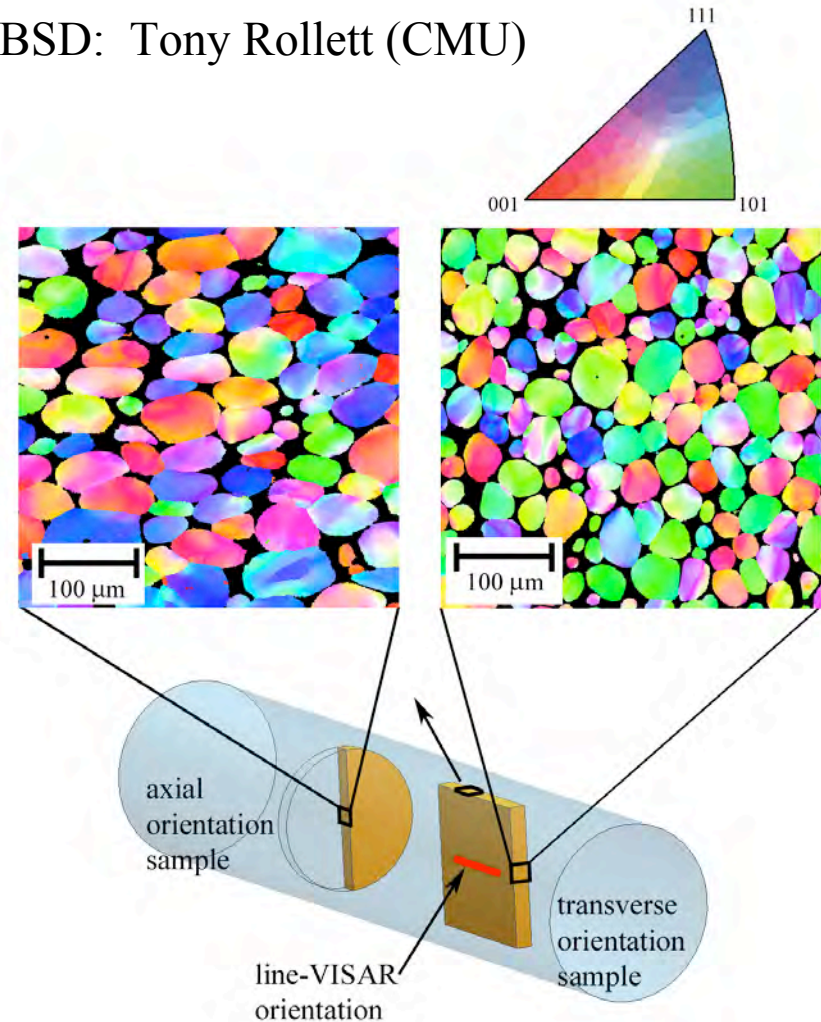
Introduction - WHA



Local failure modes

- Shear bands
- Fracture at grain-grain & matrix-grain interface

EBS: Tony Rollett (CMU)



Single crystal ballistic tests suggest important role of texture

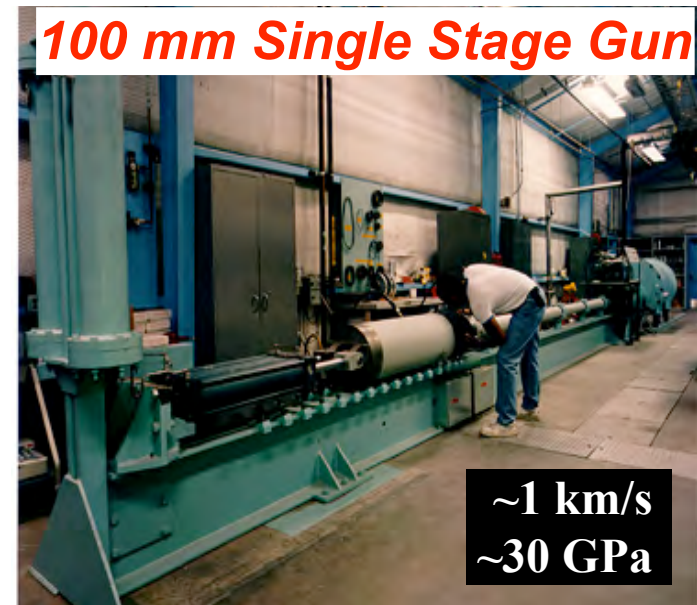


Plate Impact with Gas Guns



gas guns

- launch thin plates at high velocities
- provide well-posed initial conditions
- sample is in uniaxial strain
- used to study material behavior at high pressures and strain rates



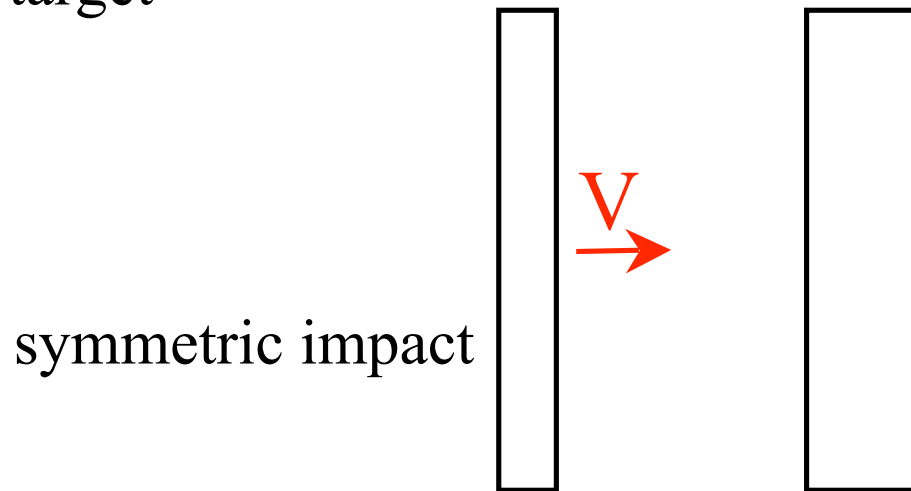
compressed helium used
to launch projectiles as
fast as 1 km/s



What is Spall?



- spall is dynamic tensile failure of a material due to interactions of waves
- failure initiates at internal flaws (triple points, voids, inclusions, etc.) rather than surface flaws
- spall strengths are typically much higher than tensile strengths measured in quasi-static experiments
- spall experiments typically involve plate impact experiments with dimensions of 1:2 for impactor and target

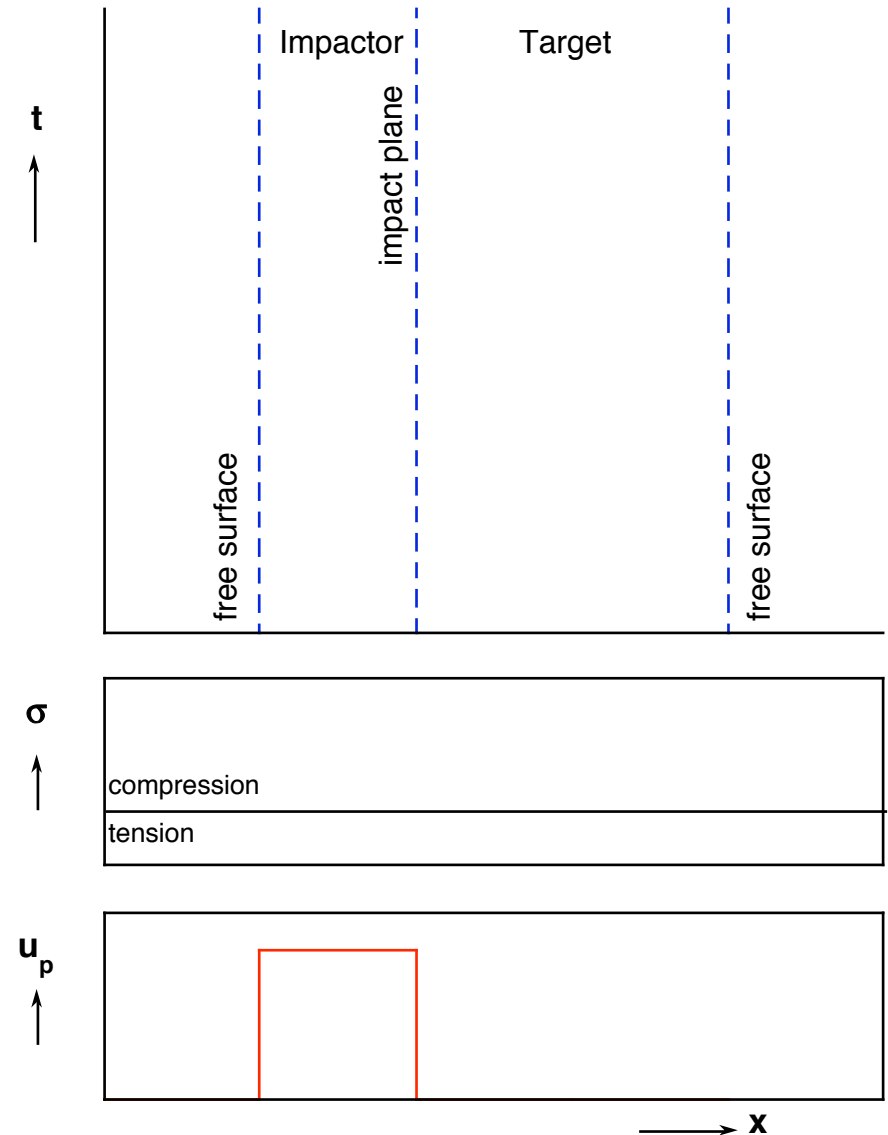




A Spall Experiment



- impactor hits stationary target at $t = 0$

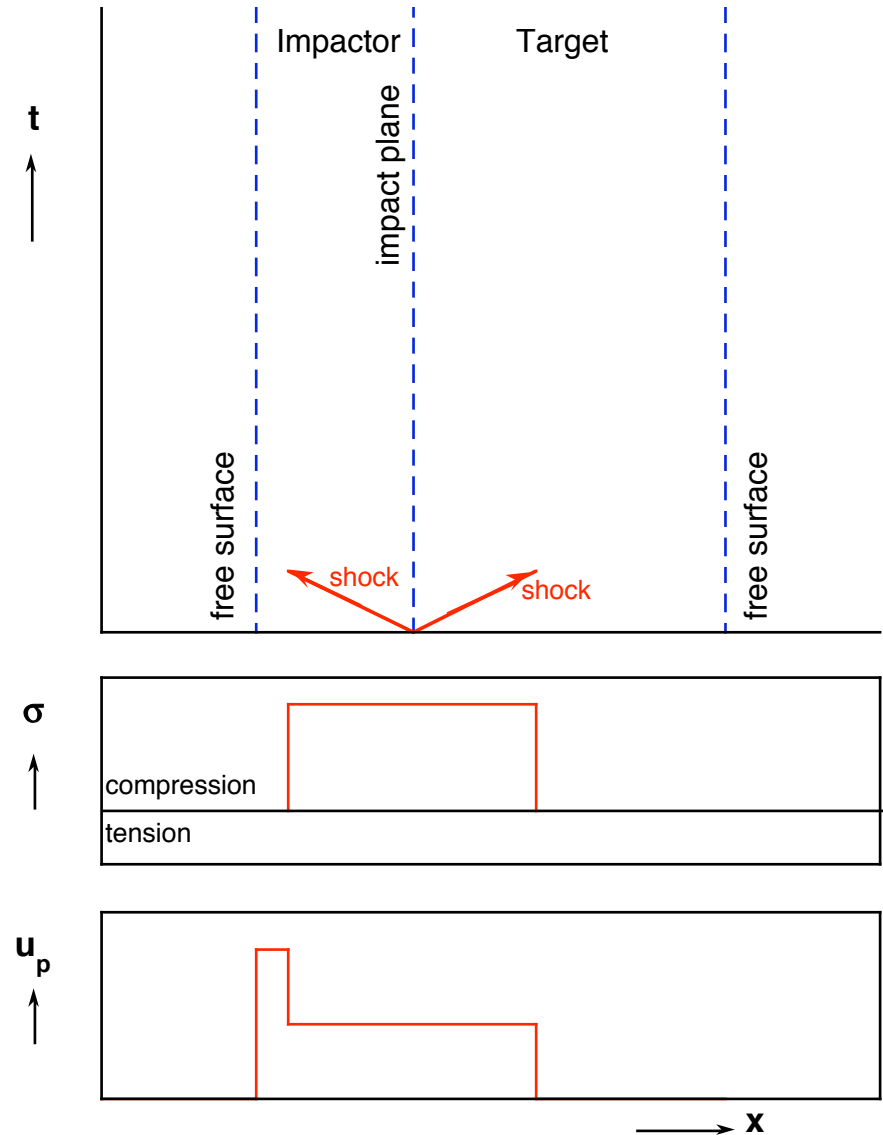




A Spall Experiment



- impactor hits stationary target at $t = 0$
- shocks travel into impactor and target

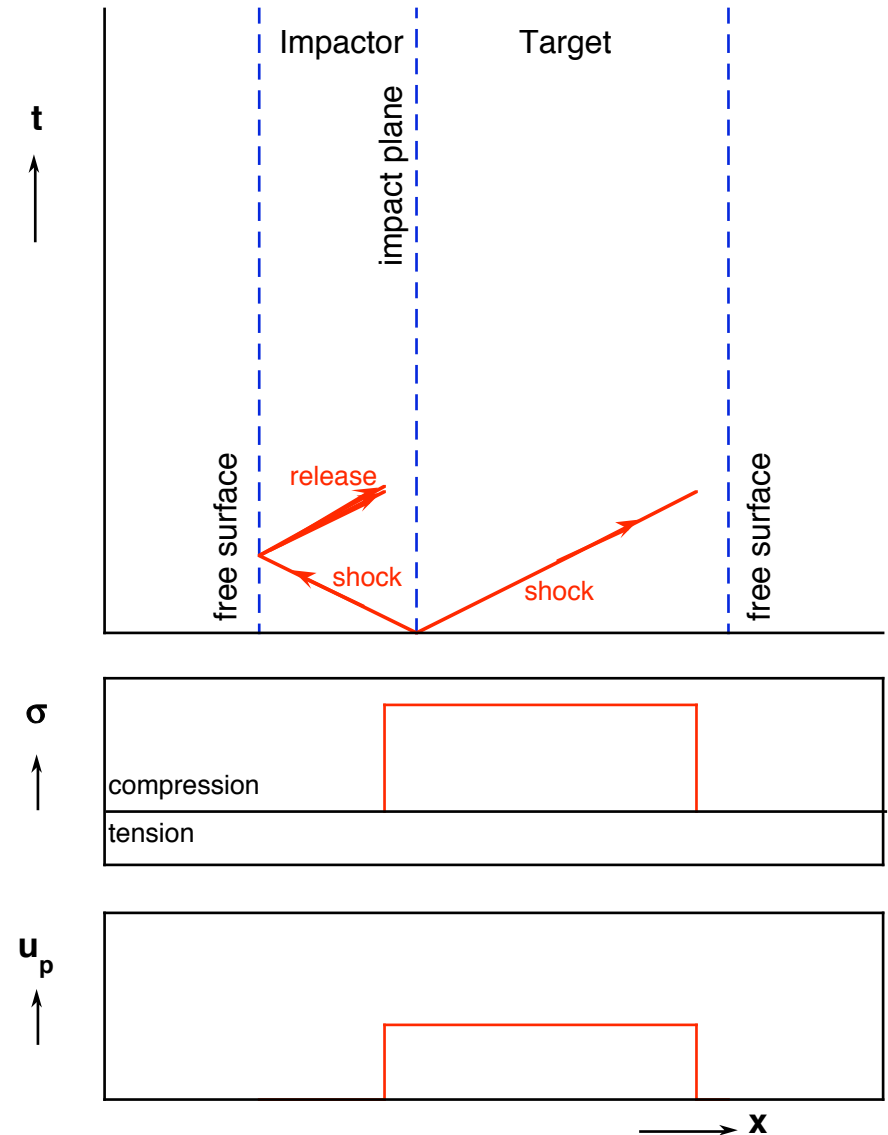




A Spall Experiment



- impactor hits stationary target at $t = 0$
- shocks travel into impactor and target
- shock in impactor reflects from free surface as release (unloading) wave (rarefaction fan)

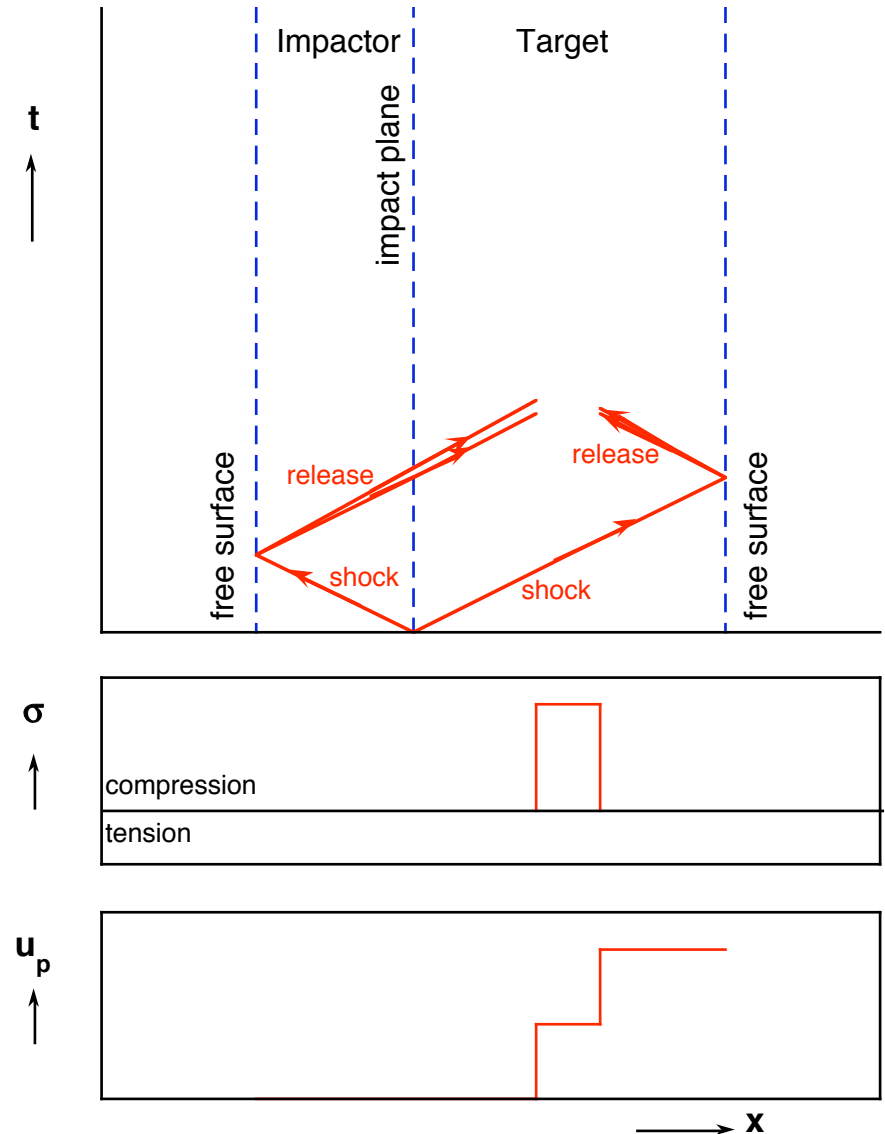




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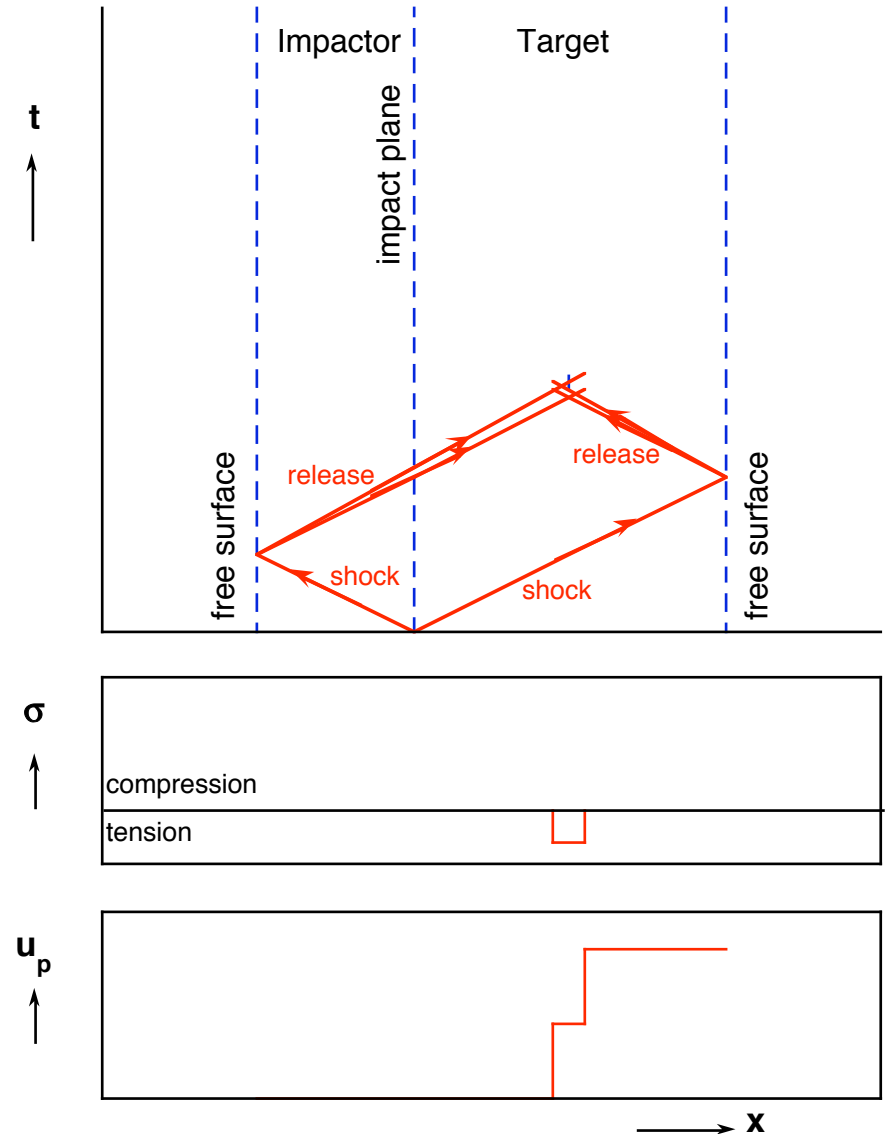




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- release waves intersect at mid-plane and cause tensile stresses to build

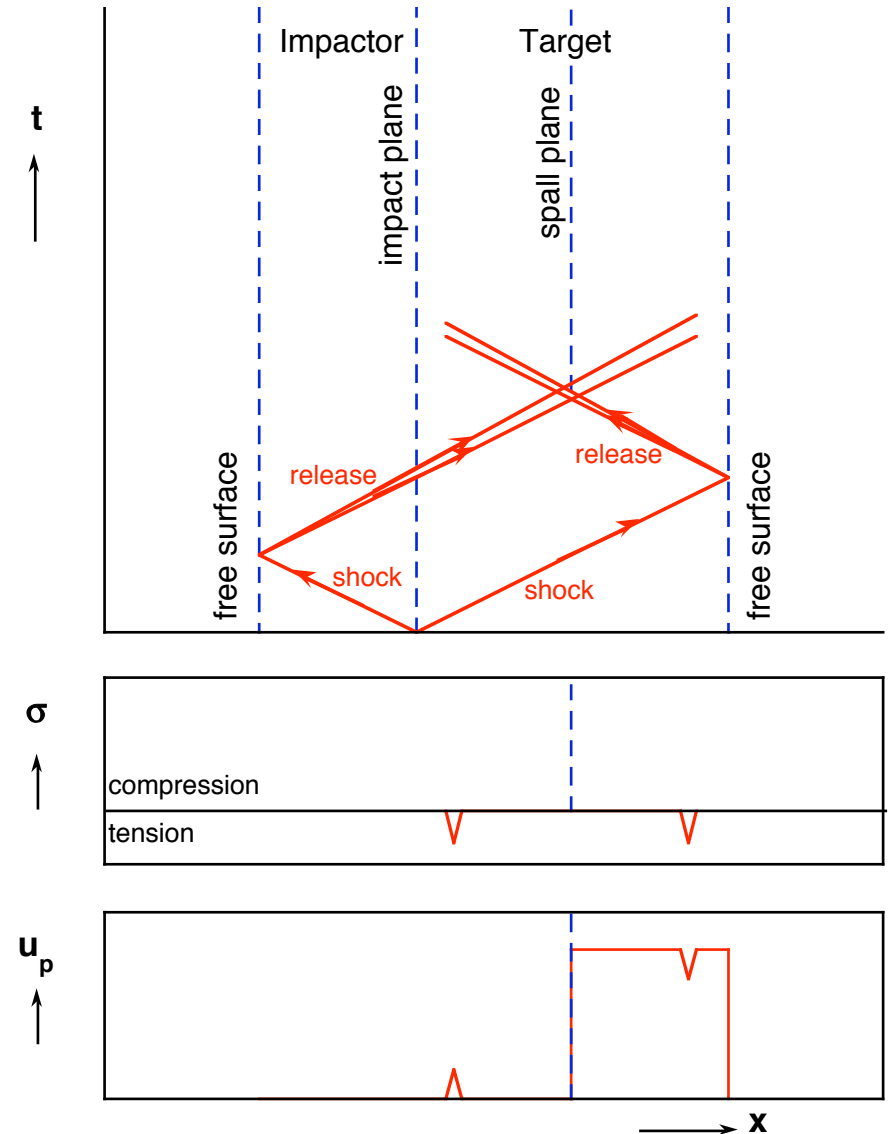




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- release waves intersect at mid-plane and cause tensile stresses to build
- if stresses are large enough, sample fails in tension and spall plane forms

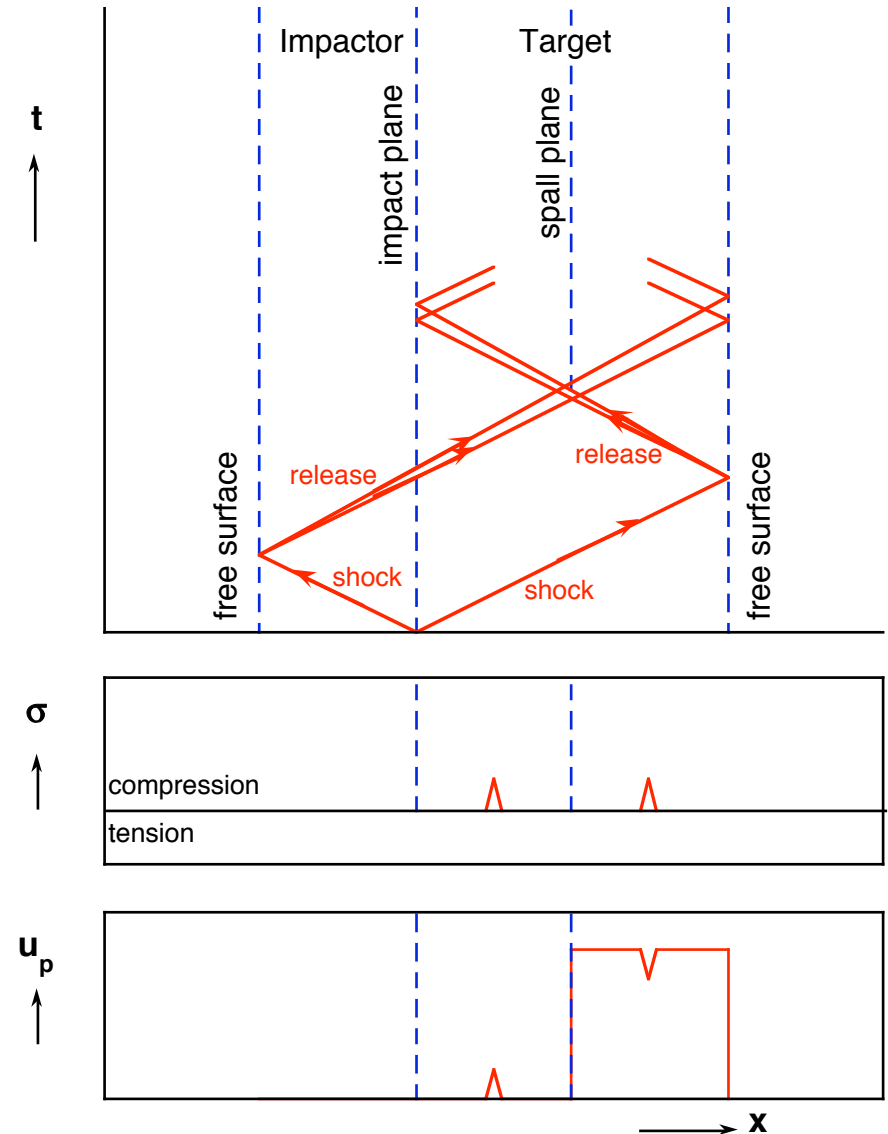




A Spall Experiment



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- same thing happens in target
- release waves intersect at mid-plane and cause tensile stresses to build
- if stresses are large enough, sample fails in tension and spall plane forms
- sample separates at spall plane; waves continue to “ring” in spalled sample

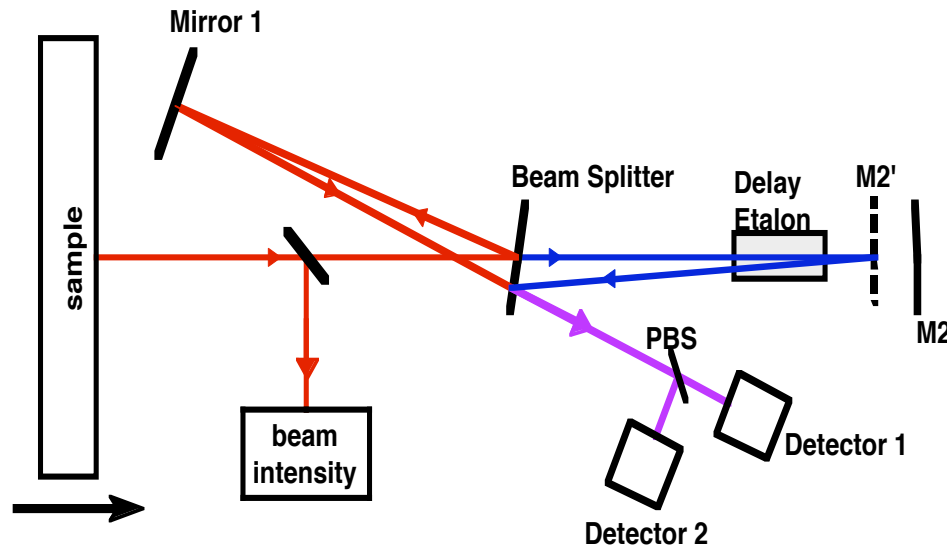




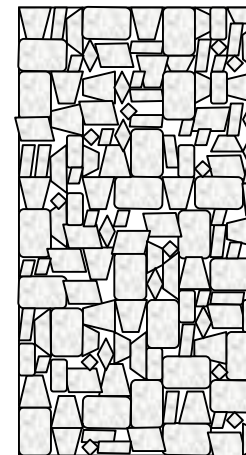
Background: VISAR Diagnostics



Velocity Interferometer System for Any Reflector
(VISAR) [Barker & Hollenbach, 1972] uses
Doppler shift to measure free surface velocity
history during spall experiment

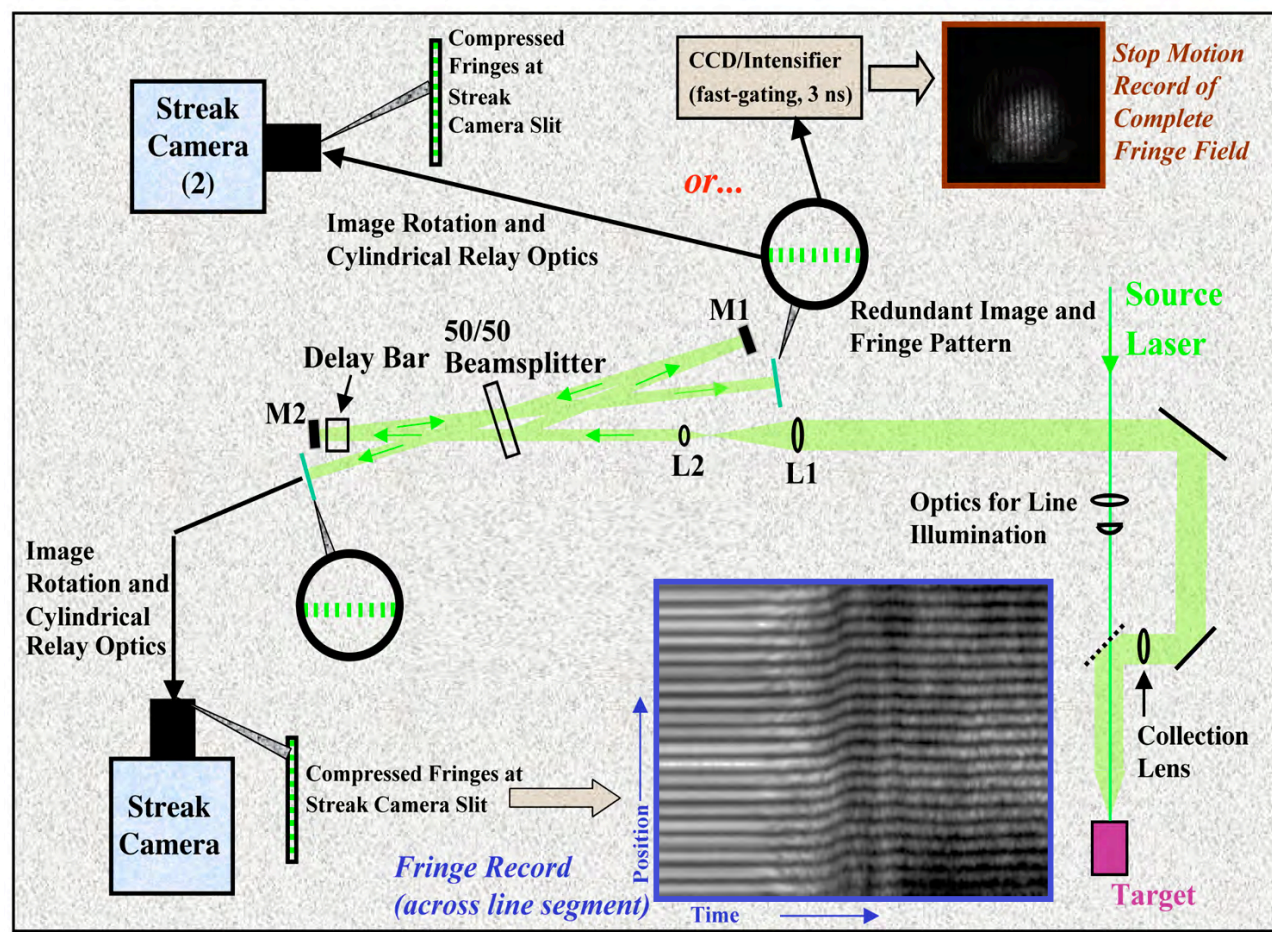


single point measurement,
typically 50-200 μm

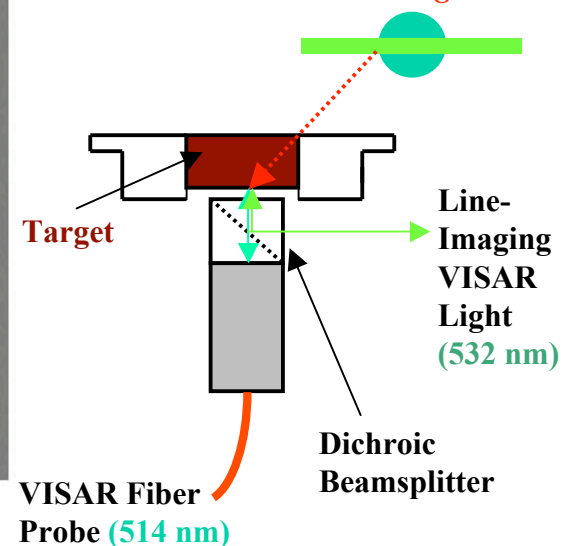


heterogeneity within the spot
diameter averaged; no
information outside this region

Background: Line-VISAR



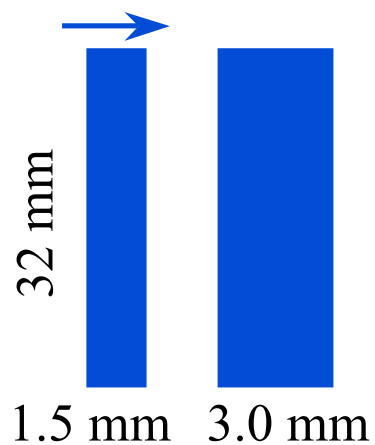
Illumination Pattern On Target



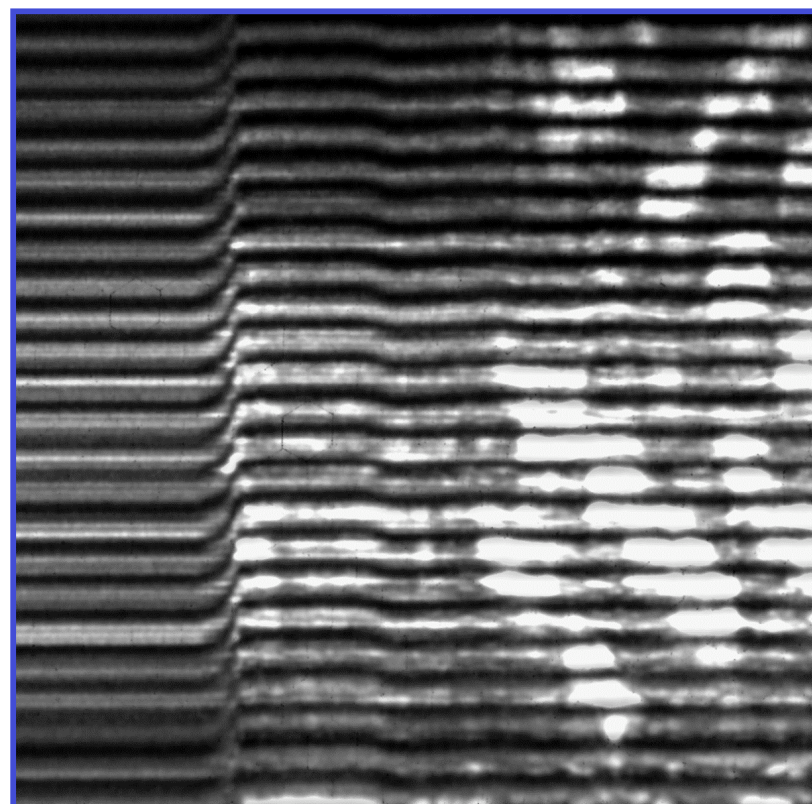
*resolution as high as $\sim 10 \mu\text{m}$ can be achieved along the line
only way to resolve this scale in dynamic experiments*



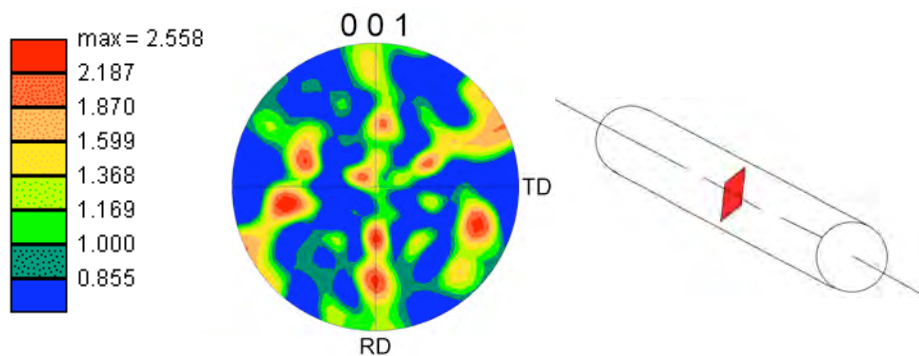
Streak Camera Record



WHA-2
 $V = 345 \text{ m/s}$, $\sigma = -13.4 \text{ GPa}$



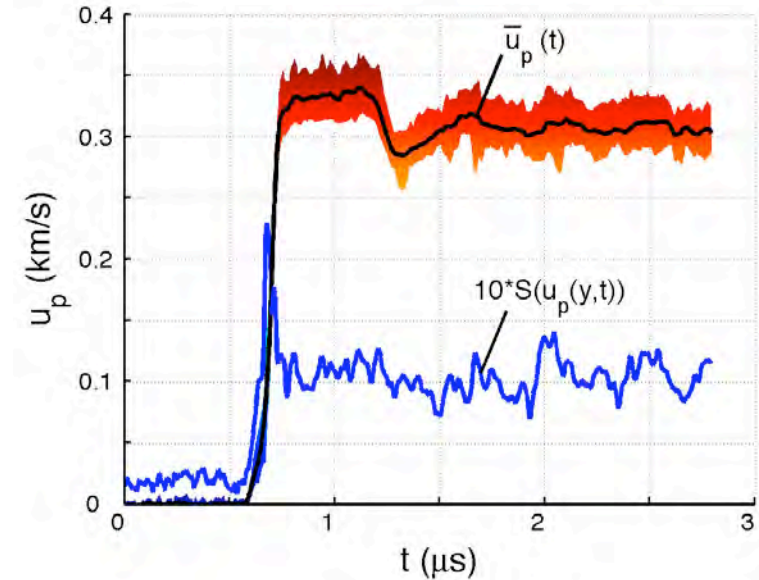
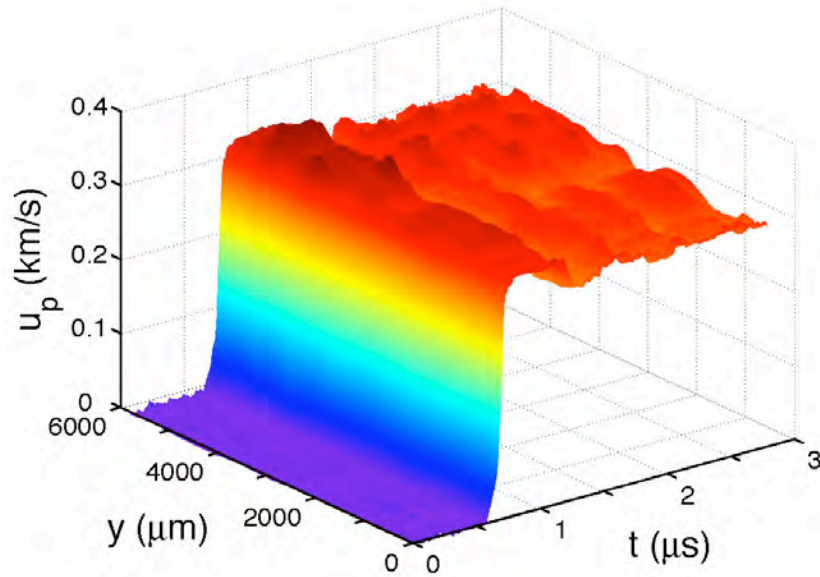
Longitudinal Section



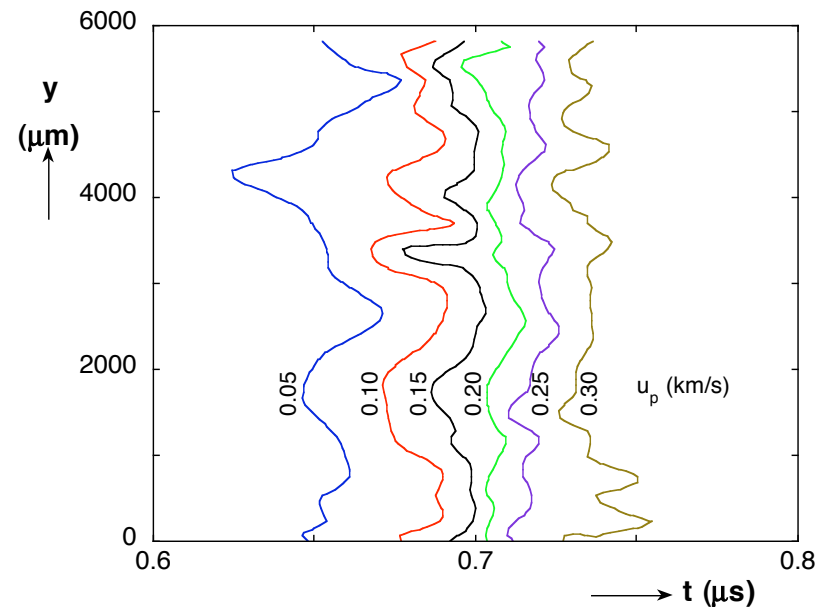


WHA-2 Results

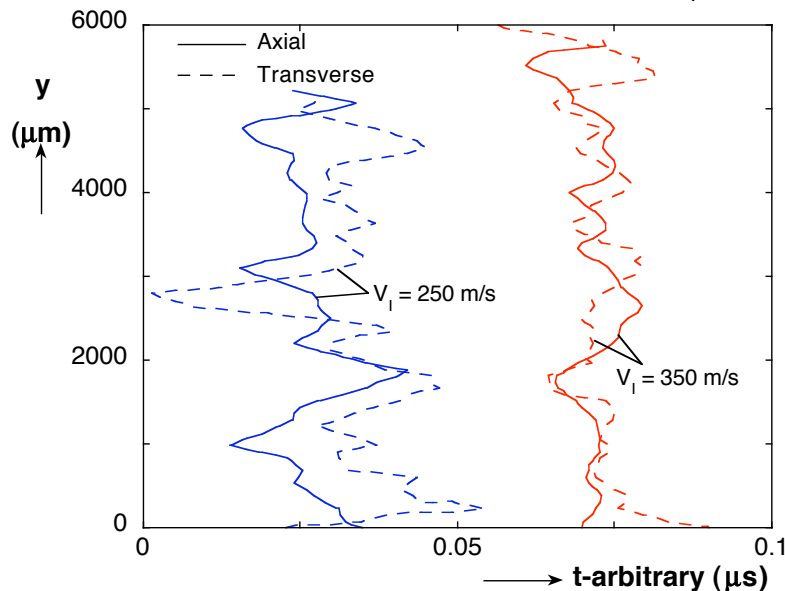
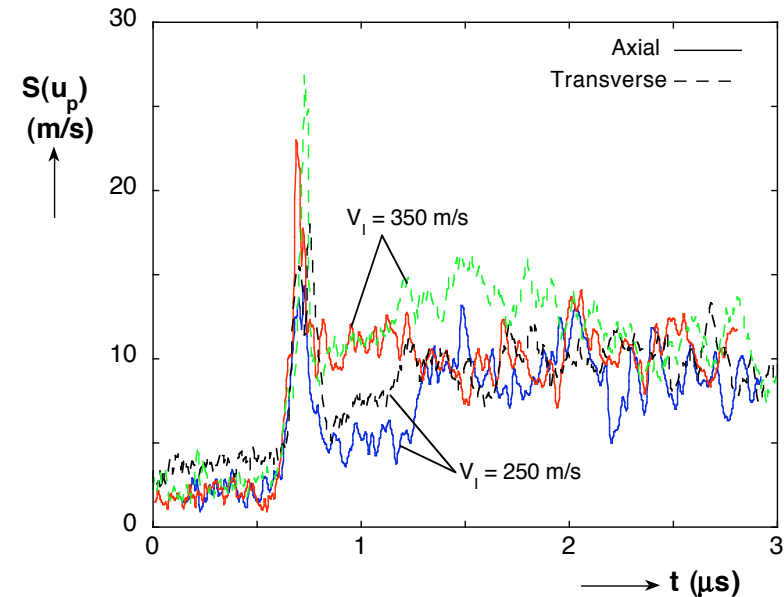
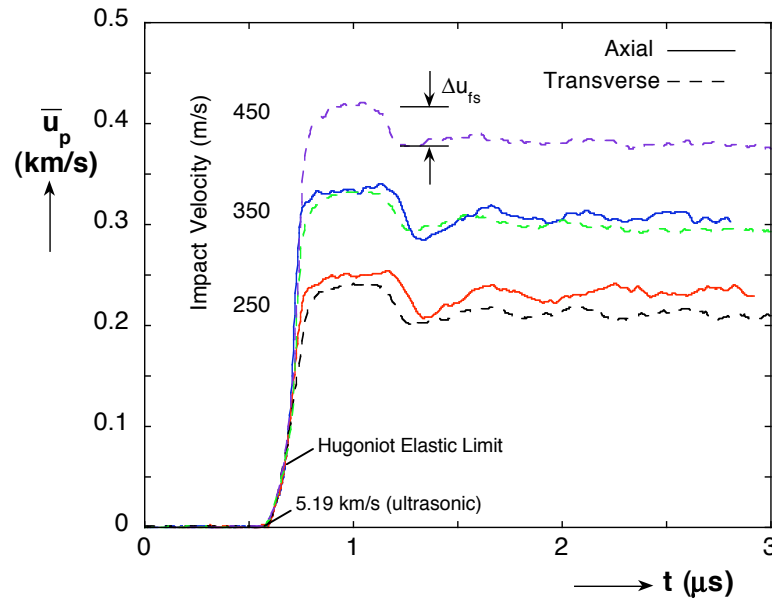
Impact Velocity = 345 m/s



- velocity fluctuations spaced 100-1000 microns (larger than grain size)
- average response similar to previous point VISAR results
- deviations nearly constant except at shock front at around 3% of mean
- period for shock arrival approximately 1 mm

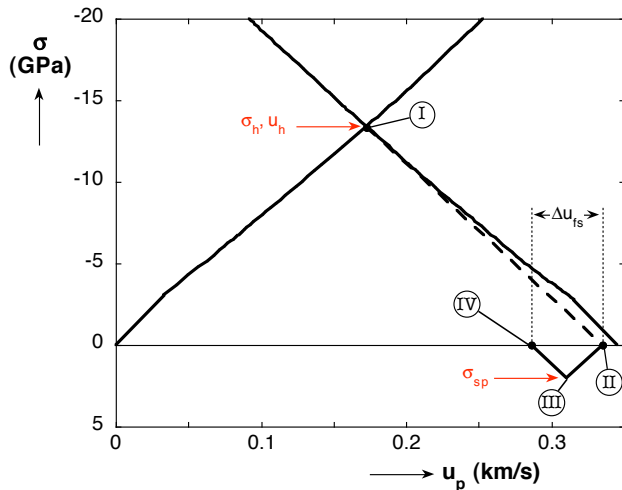
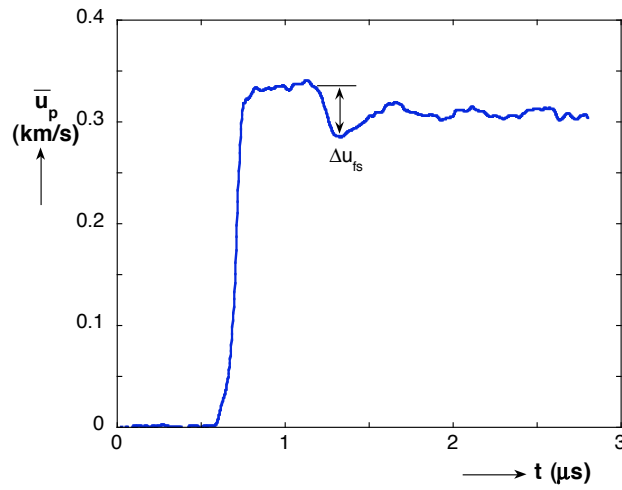


Results for Different Orientations and Velocities



- transverse response slightly softer
- ringing in spalled material less pronounced for transverse samples
- higher impact velocities give somewhat higher deviations but no apparent correlation with microstructure
- wave fronts rougher for lower velocities (ratio ~ 0.6) and for transverse vs. axial samples (ratio ~ 0.6)

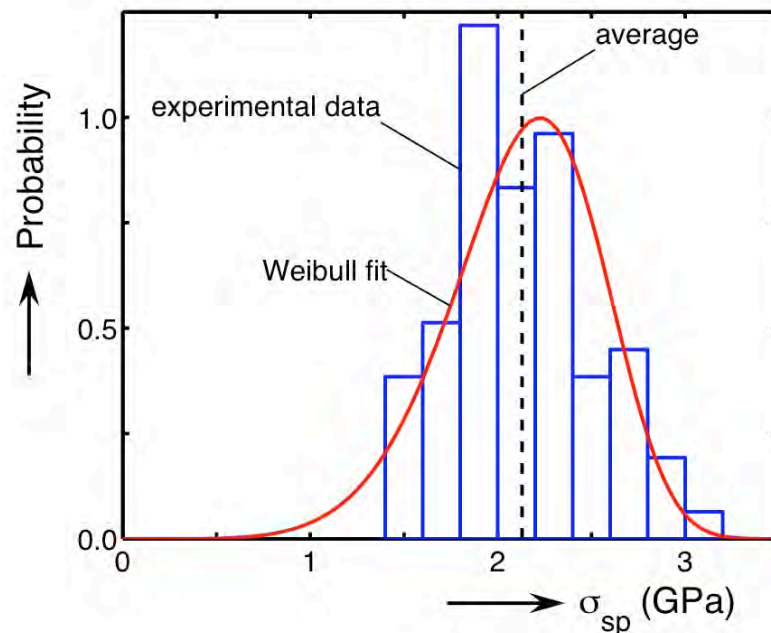
Distributions of Spall Strengths



$$\sigma_{sp} \approx \frac{1}{2} \rho_o U_t \Delta u_{fs}$$

(assuming plane waves)

- significant variation in spall strengths for a given experiment
- average strengths 0.2-0.4 GPa higher for axial
- strength increases with impact velocity
- both Weibull and normal distributions fit data
- Weibull modulus 5-7 for all experiments (slightly higher for axial samples)





Crystal Plasticity Modeling



finite crystalline thermoelastic-viscoplastic framework

$$\mathbf{f} \equiv \partial \mathbf{x} / \partial \mathbf{X} = \mathbf{f}^e \mathbf{f}^p$$

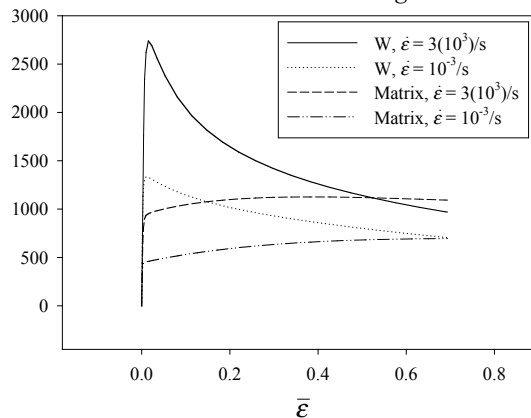
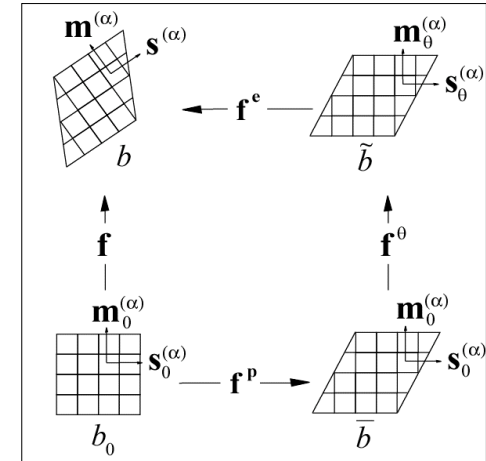
Kinematics: $\mathbf{l}^e = \dot{\mathbf{f}}^e \mathbf{f}^{e-1} = \alpha_T \dot{\mathbf{1}}$

$$\bar{\mathbf{l}}^p \equiv \dot{\mathbf{f}}^p \mathbf{f}^{p-1} = \sum_{\alpha=1}^n \dot{\gamma}^{(\alpha)} \mathbf{s}_0^{(\alpha)} \otimes \mathbf{m}_0^{(\alpha)}$$

Flow rule: $\dot{\gamma}^{(\alpha)} = \dot{\gamma}_0 \left(\tilde{\tau}^{(\alpha)} / g^{(\alpha)} \right)^m \text{sgn} \left(\tilde{\tau}^{(\alpha)} \right)$

Free energy: $\tilde{\rho} \psi = \frac{1}{2} K_0 (\theta) \vartheta^2 - \frac{1}{3} K_1 \vartheta^3 + \mu (\theta) \mathbf{e}^e : \mathbf{e}^e + \frac{1}{2} \kappa \mu (\theta) \xi^2 + y (\theta)$

Energy balance: $\underbrace{\rho \hat{c} \dot{\theta}}_{\text{temperature change}} = \underbrace{\sum_{\alpha=1}^n \tau^{(\alpha)} \dot{\gamma}^{(\alpha)}}_{\text{plastic dissipation}} - \underbrace{\rho \left(\left(\partial_{\xi} \psi \right) - \theta \left(\partial_{\theta \xi} \psi \right) \right) \dot{\xi}}_{\text{energy of lattice defects}} + \underbrace{\rho \theta \partial_{\theta \mathbf{e}^e} \psi : \dot{\mathbf{e}}^e}_{\text{thermoelastic coupling}} + \underbrace{\text{div} (k \nabla_x \theta)}_{\text{heat conduction}}$



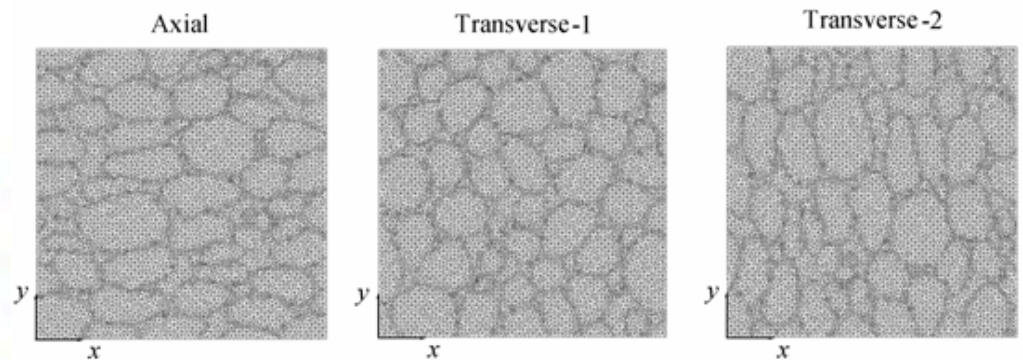
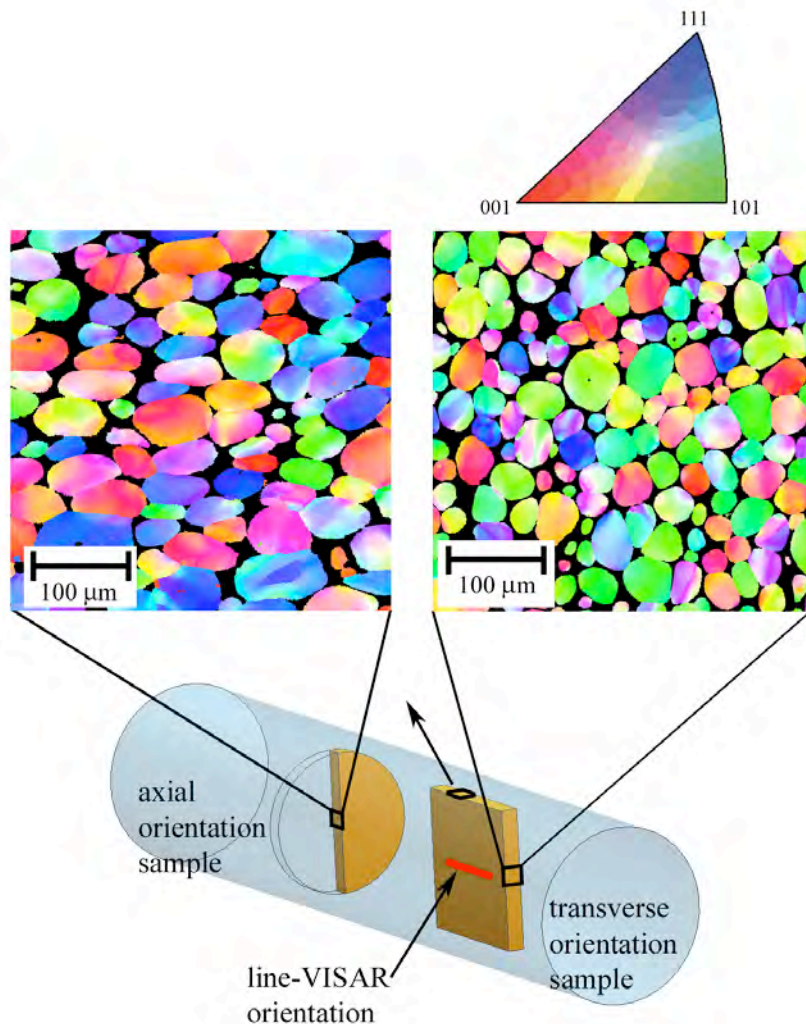
Stress-strain response for 300 random grains
(uniaxial compression, Taylor constraints)

- 24 slip systems for BCC W grains
- 12 slip systems for FCC matrix
- properties inferred from literature, mainly from static and intermediate rate experiments

Clayton, J.D., *J. Mech. Phys. Solids* **53**, 2005.

Clayton, J.D., *Int. J. Solids Structures* **42**, 2005.

Microstructure Representation

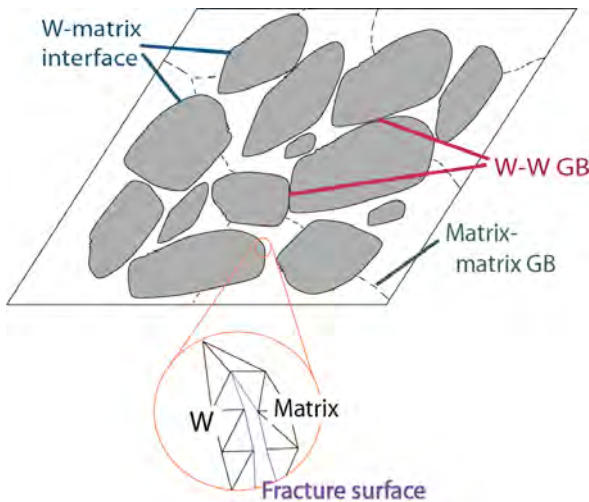


- Realistic grain shapes, sizes, volume fractions, and lattice orientations
- plane strain
- rigid upper and lower boundaries

WHA-I	axial	350 m/s
WHA-II	transverse-1	350 m/s
WHA-III	transverse-2	250 m/s
WHA-IV	transverse-2	350 m/s
WHA-V	transverse-1	450 m/s



Fracture Modeling: cohesive approach

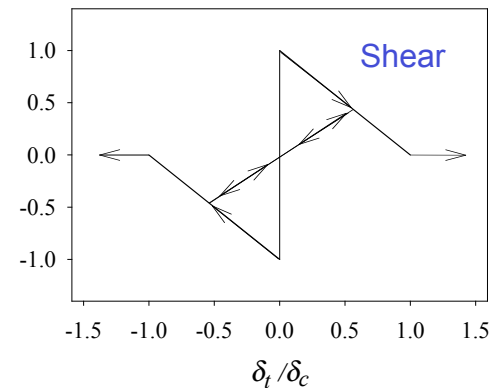
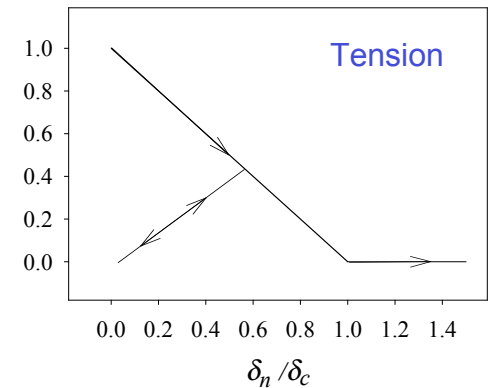
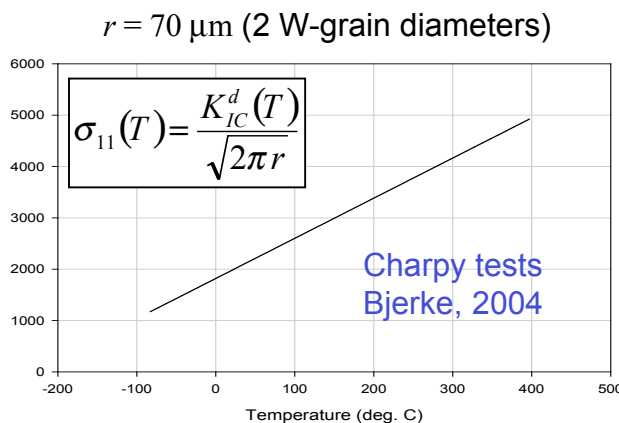


- new crack surfaces generated via traction criteria at interfaces (Camacho & Ortiz, 1996)
- focus on **intergranular fracture** at W-W and W-matrix interfaces
- nominal fracture properties: **fracture stress (300K) (Dandekar & Weisgerber, 1999; Weerasooriya, 2003; Bjerke, 2004)**

$$\hat{s}_0 = 2.0 \text{ GPa}$$

- **fracture toughness** (compromise of values from literature)

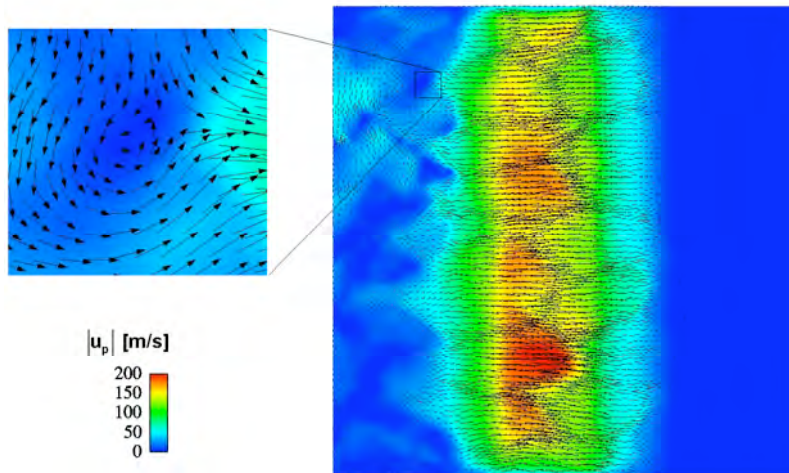
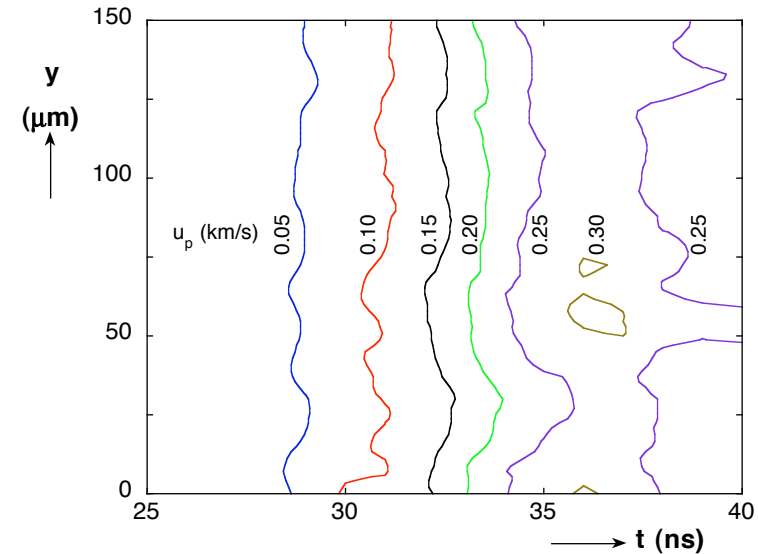
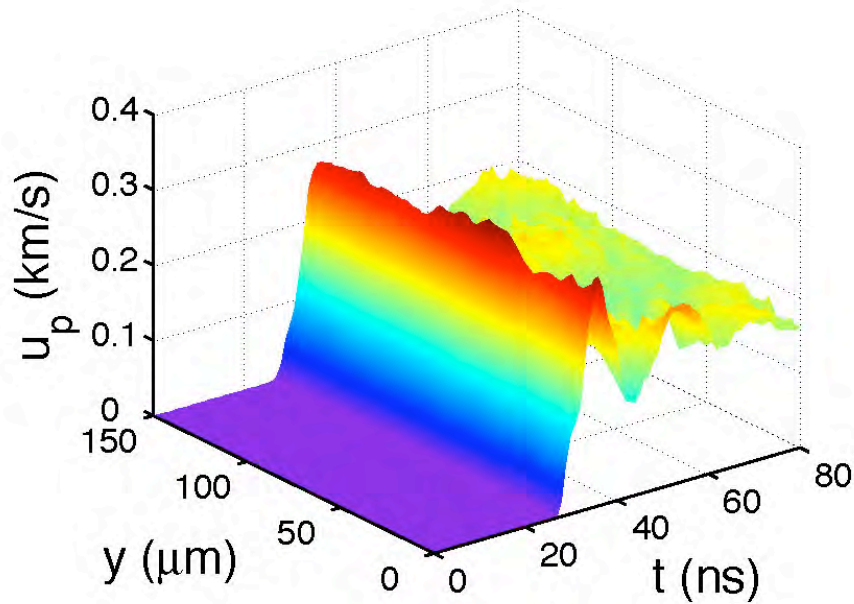
$$K_{Ic} = \sqrt{G_c E / (1 - \nu^2)} = 20 \text{ MPa}\sqrt{\text{m}}$$



- cleavage could be important, not modeled here

Model results: WHA-IV

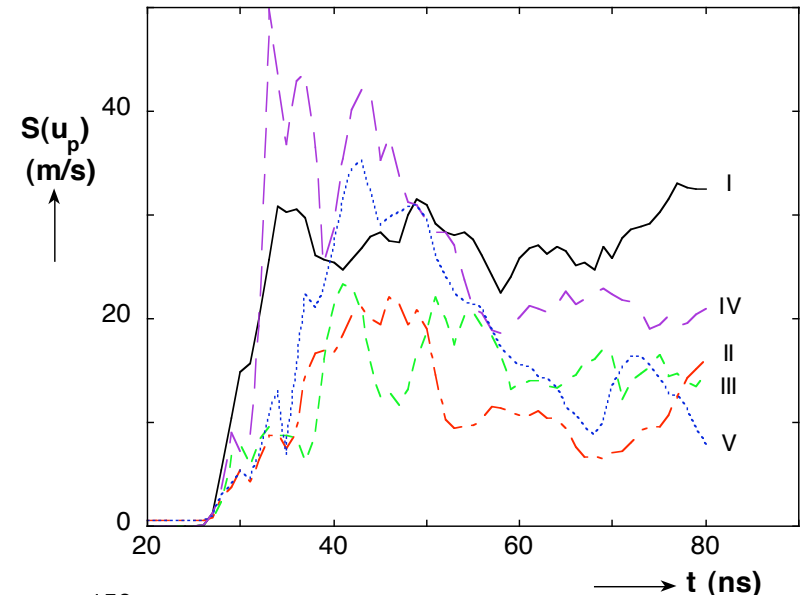
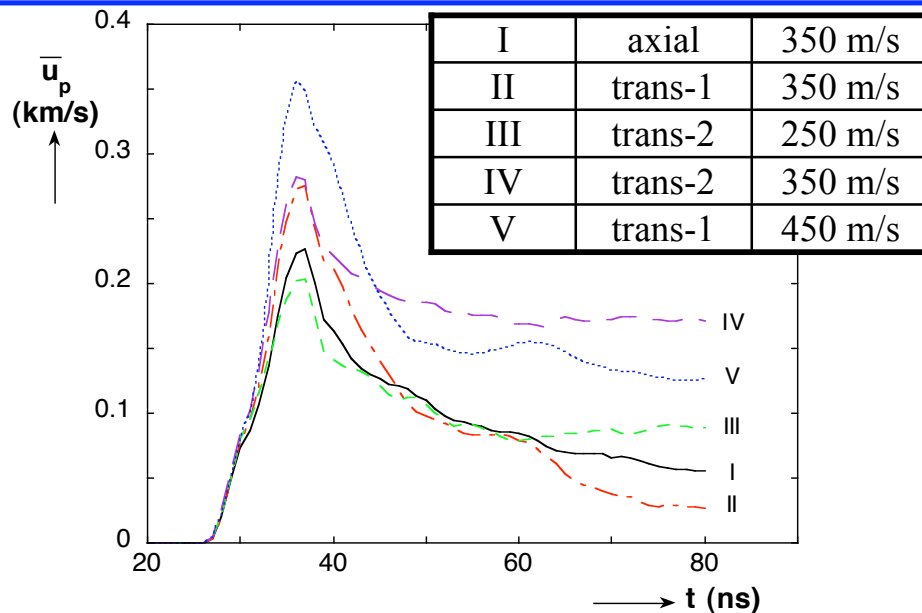
transverse-2, 350 m/s



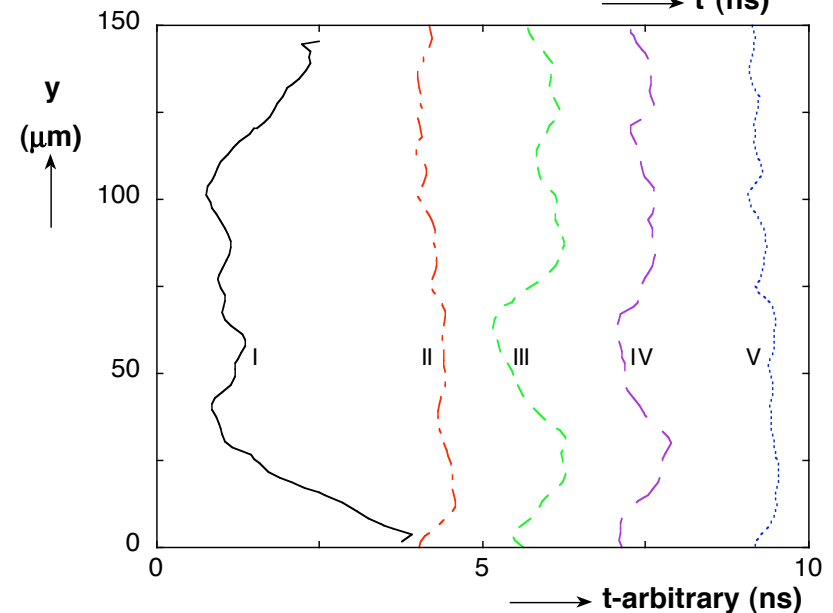
- velocity fluctuations spaced 10-30 microns
- roughness in shock front contours on order of grain size
- vortical velocity flow fields appear in wake of unloading wave



Model results: collective

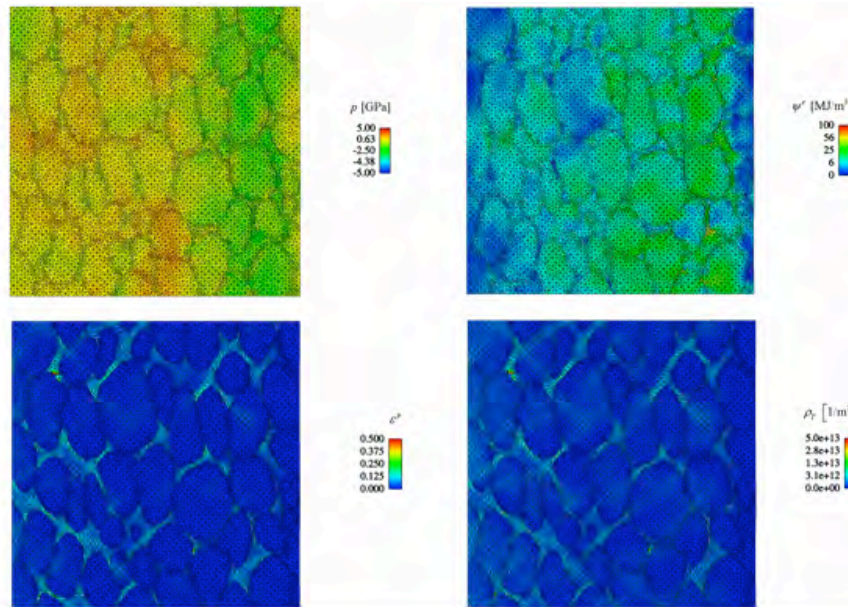


- residual velocity highest for trans-2
- no pronounced peak in deviations
- higher velocities give higher deviations
- trans-1 (equiaxed) gives lowest deviations and most uniform shock front
- ratio of roughness for 250 & 350 m/s (III and IV / trans-2) is 0.65
- ratio for axial (I) and trans-2 (IV) is 0.71

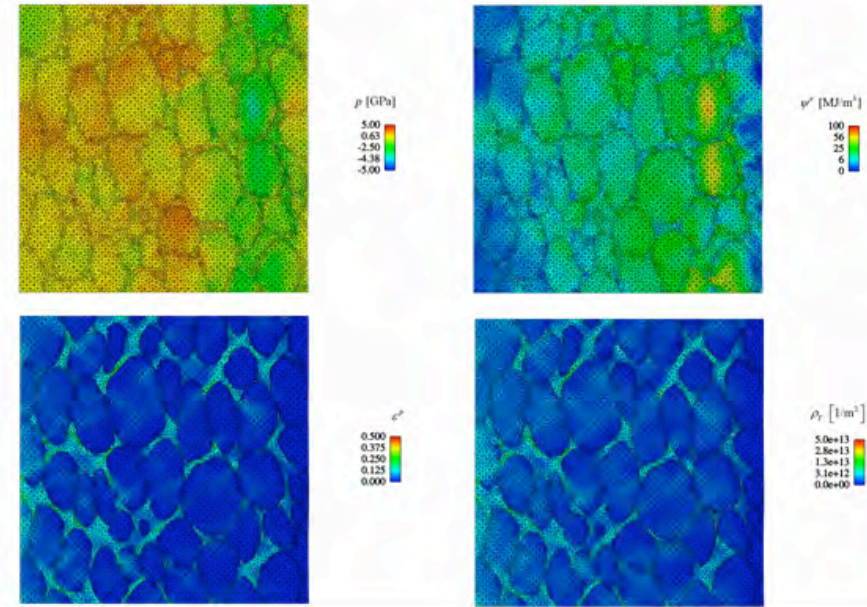


Field Variables of Model

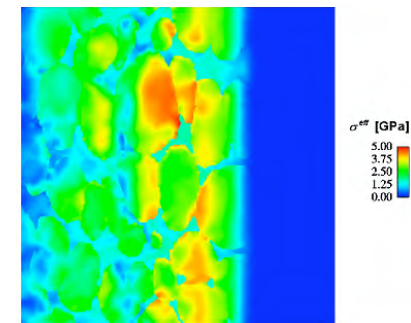
WHA-III (trans-2, $V_I = 250$ m/s, $t = 40$ ns)



WHA-IV (trans-2, $V_I = 350$ m/s, $t = 40$ ns)

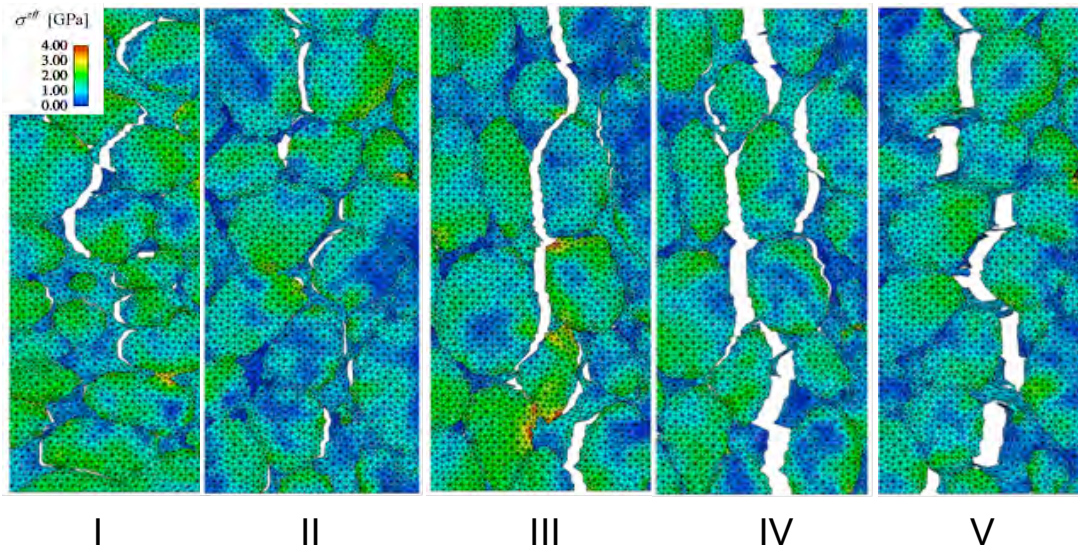


- pressure, elastic energy, plastic strain, dislocations all increase with impact velocity
- momentum conservation prevents concentration of pressure in grains vs. matrix
- strain and dislocations accumulate in matrix, local plastic strain rates reach $\sim 10^7$ s⁻¹
- deviatoric stress concentrates in stiff W grains (right, simulation WHA-IV, $t = 20$ ns)



Model results: spall fracture

Effective stress at spall planes, $t = 80$ ns



			σ	β
I	axial	350 m/s	2.01	8.7
II	trans-1	350 m/s	2.88	18.8
III	trans-2	250 m/s	1.57	11.3
IV	trans-2	350 m/s	1.50	7.8
V	trans-1	450 m/s	2.69	14.9

- failure surface more torturous for axial and trans-1
- “spall strength” decreases with increased impact velocity
- trans-2 orientation has lowest “spall strength” since it presents the greatest GB area perpendicular to tensile loading
- ligaments remain since failure can only occur on W grain boundaries
- differences among microstructures not distinguishable by Weibull modulus
- Weibull moduli higher than in experiments - strength variability arises from both microstructure (grains and anisotropy) and flaw distributions



Comparison of results



Noteworthy observations

- heterogeneous wave profiles observed in both simulations and experiments
- fluctuations of 10-30 microns in simulations (grain size) and ~500 microns in experiments (several grains)
- shock roughness affected by velocity and morphology in about the same way for experiments and simulations
- deviations of 10-30 m/s for simulations, ~10 m/s for experiments
- spike in deviations seen in experiment; absent in simulation
- spall strengths lower for grains elongated perpendicular to loading direction
- deviations in spall strengths ~0.2 GPa for simulations and ~0.3-0.4 GPa for experiments
- Weibull moduli higher for simulations than experiments
- higher velocities give larger spall strengths in experiments, but not in simulations



Conclusions



-
- shock roughness decreases with increased velocity and is higher for transverse orientations (**expt. and sim.**)
 - velocity deviations increase with velocity but not affected by orientation (**expt.**) or are lower for equiaxed grains (**sim.**); magnitudes are similar for expt. and sim.
 - spall strength lowest for orientations with elongated grains perpendicular to loading (**expt. and sim.**), supporting hypothesis that failure controlled by W grain boundaries
 - β higher for sim. than for expts., indicating that β is controlled by microstructure/anisotropy and nonuniform flaw distributions; no strong correlation with velocity or orientation
 - proper method for comparison of model and experiments remains unclear, but standard deviation of velocity, shock front roughness, and Weibull modulus show promise



Future Work



-
- verify repeatability of behavior and statistics
 - determine effect of measurement resolution
 - investigate effect of variations in geometry
 - experimental validation of plastic flow rules at higher rates
-
- larger domain for calculations
 - multiple realizations
 - 3-D simulations
 - transgranular fracture criteria
 - shock-induced grain boundary strengthening