

Manufacturing Simulation Using Parallel Linear Solver and Contact in Adagio

B.W. Spencer^a, J.F. Dempsey^b, and K.H. Pierson^a

^aComputational Solid Mechanics and Structural Dynamics (1542)

^bSolid Mechanics (1524)

Sandia National Laboratories

Albuquerque, NM



Introduction

- Manufacturing simulations (often contact-intensive) are a key application area for the Adagio finite element code.
- Recent work has greatly improved contact robustness with Adagio's parallel linear solvers.
- This robustness has been demonstrated in simulations of the manufacturing process of a component. Adagio is being used to give insight into performance of various design alternatives under consideration.

Role of Adagio

Adagio is the implicit (quasistatic & dynamic) nonlinear solid mechanics code in Sandia's SIERRA framework.



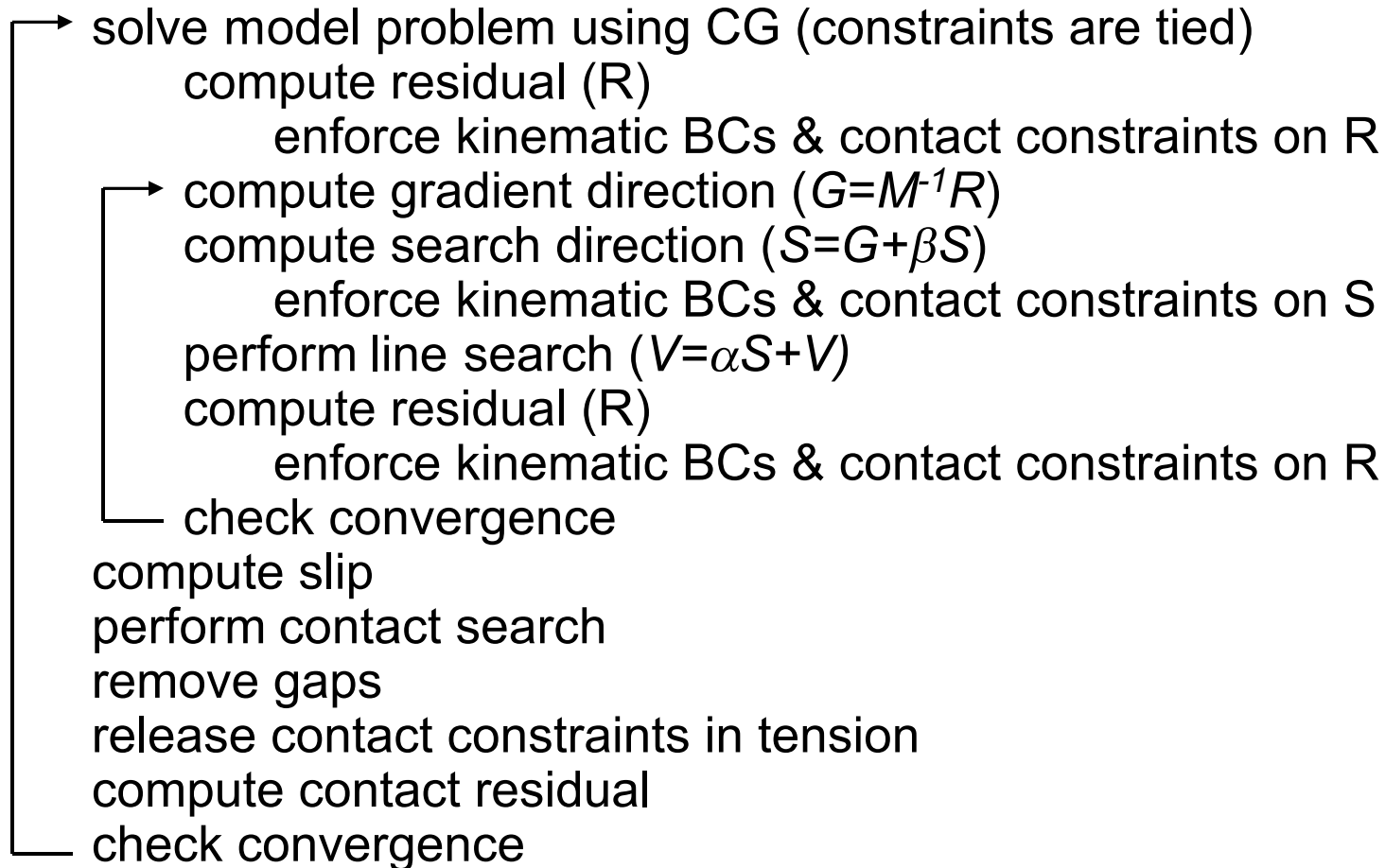


Adagio Multilevel Solver Technology

- Nonlinear preconditioned conjugate gradient core solver.
- Multilevel solver developed in JAS3D legacy code is used to improve handling of poorly conditioned systems.
 - Series of well conditioned “model problems” are solved leading up to the solution of the real nonlinear system.
 - Several types of controls are available
 - Used for contact
 - Contact is tied in model problems, search and slip calculations occur between model problems



Flowchart for Control Contact with CG





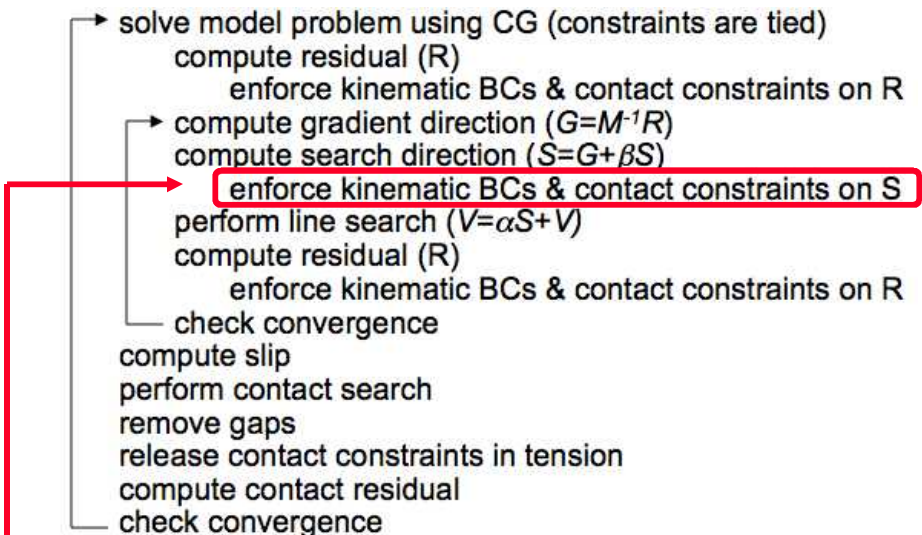
Linear Solvers in Adagio's CG Algorithm

- Legacy code (JAS3D) relied on diagonal or block diagonal (3x3) stiffness matrix for preconditioner
 - Simple, easy to invert, low cost per iteration
 - Requires many iterations
 - Performs very well on “blocky” problems, has more trouble with slender problems because system is poorly conditioned.
 - These problems are handled with constraint mesh in JAS3D.
- Linear solvers are a relatively new (~5 years) addition to Adagio
 - Uses full tangent stiffness matrix for preconditioner in nonlinear CG algorithm
 - Applied in compute gradient direction ($G=M^{-1}R$) step
 - Several iterative linear solvers are available, FETI is used most often.
 - Until recently, handling of constraints has been done in linear solver
 - Problematic in parallel, especially if contact surfaces are on processor boundary.



Alternative for Constraint Handling: Penalty Elements

- Represent constraints as penalty elements and add contributions to tangent matrix.
- No longer necessary to handle constraints in linear solver.
- Penalty constraints are usually problematic
 - Conditioning problems if stiffness is high
 - Incorrect results if stiffness is low.
- Errors introduced by compliance of penalty elements are removed in nonlinear CG algorithm.
 - Allows for low penalty stiffness to be used without affecting results.
- Has been extremely successful.

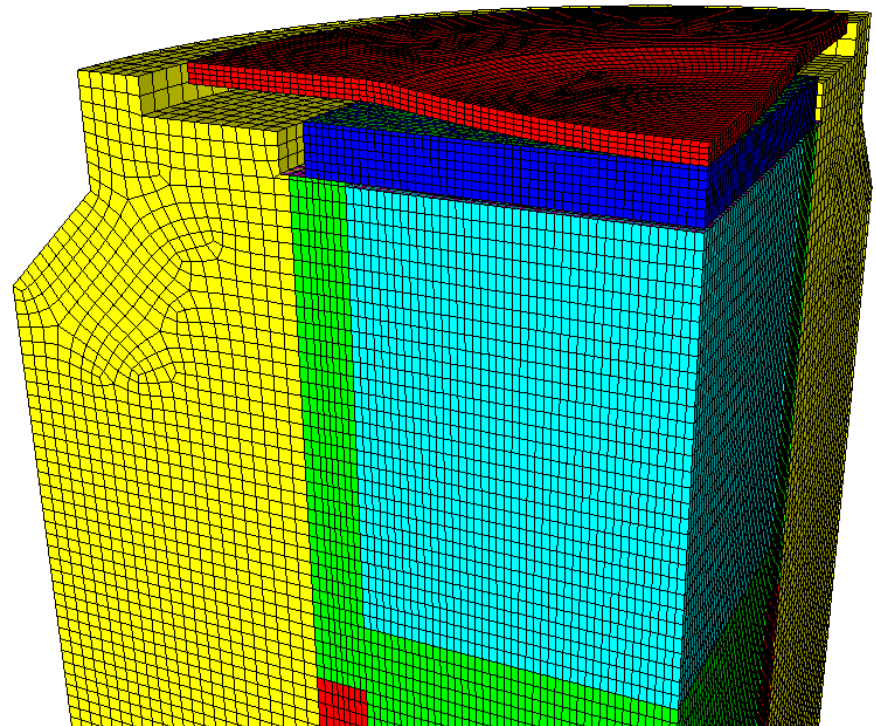


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graph TD; A[solve model problem using CG (constraints are tied)] --> B[compute residual (R)]; B --> C[enforce kinematic BCs & contact constraints on R]; C --> D[compute gradient direction (G=M^-1 R)]; D --> E[compute search direction (S=G+βS)]; E --> F[enforce kinematic BCs & contact constraints on S]; F --> G[perform line search (V=αS+V)]; G --> H[compute residual (R)]; H --> I[enforce kinematic BCs & contact constraints on R]; I --> J[check convergence]; J --> K[compute slip]; K --> L[perform contact search]; L --> M[remove gaps]; M --> N[release contact constraints in tension]; N --> O[compute contact residual]; O --> P[check convergence];
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→ solve model problem using CG (constraints are tied)
compute residual (R)
enforce kinematic BCs & contact constraints on R
→ compute gradient direction ($G=M^{-1}R$)
compute search direction ($S=G+\beta S$)
enforce kinematic BCs & contact constraints on S
perform line search ($V=\alpha S+V$)
compute residual (R)
enforce kinematic BCs & contact constraints on R
check convergence
compute slip
perform contact search
remove gaps
release contact constraints in tension
compute contact residual
check convergence

Application to Manufacturing Simulation

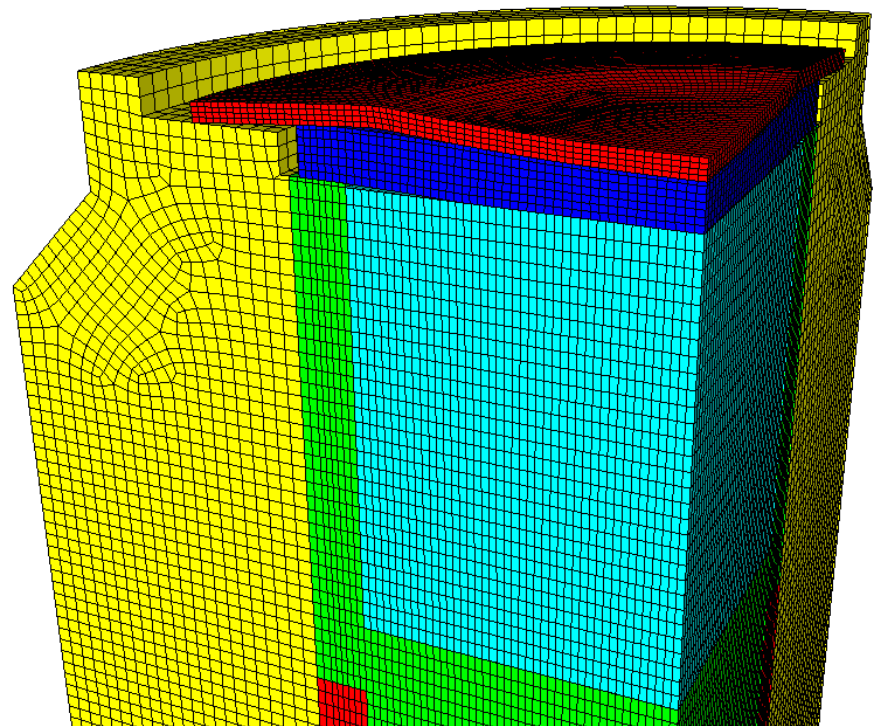
- Design alternatives for actuator are being considered
- Manufacturing process involves pushing down cap, welding around edge, and cool-down.
- Modeling is used to understand performance of part observed in tests.
- Simplifications were made for material models. Results are therefore intended to interpret trends rather than as exact representation of stress fields.





Analysis with Adagio

- One of the first real-world applications of new penalty constraint algorithm with FETI linear solver in Adagio.
- Initial attempts to use block diagonal preconditioner were unsuccessful due to poor conditioning of the problem.
- Fixes of parallel consistency bugs combined with penalty constraints allowed for robust, scalable solution of this model for production use.
- Model sizes of 100K - 300K elements on up to 100 processors.

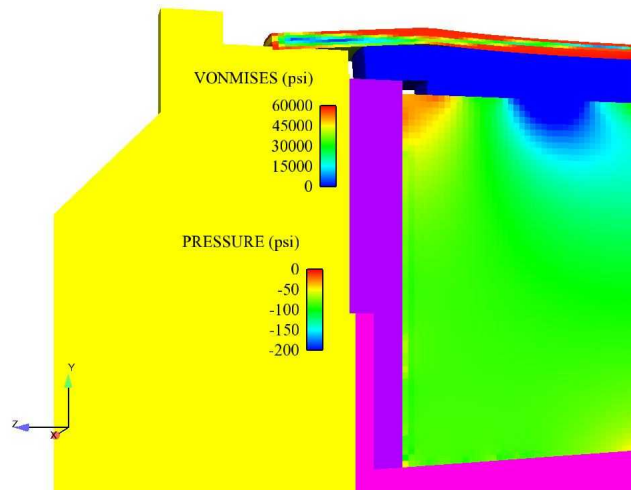
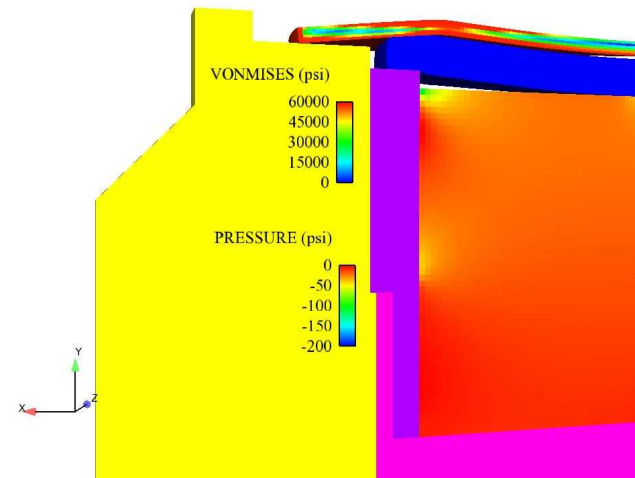
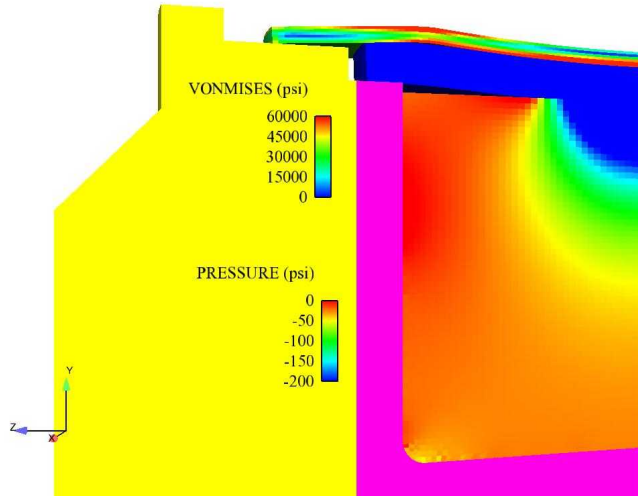




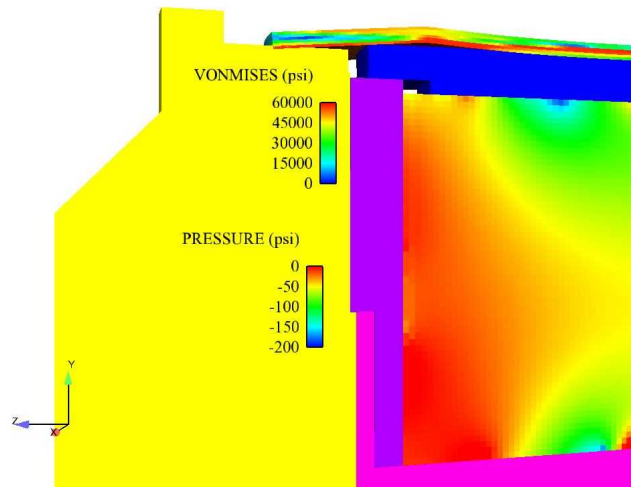
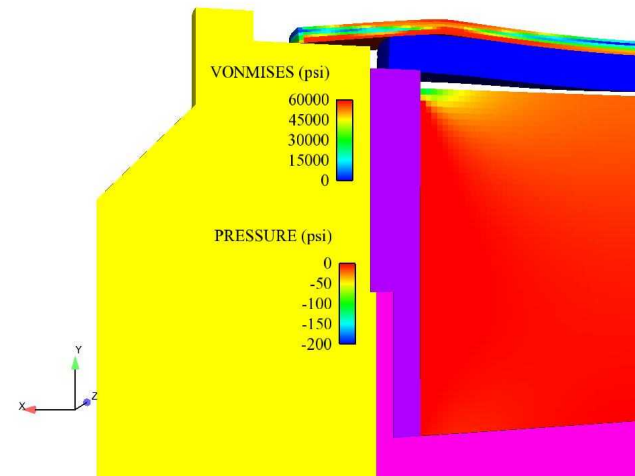
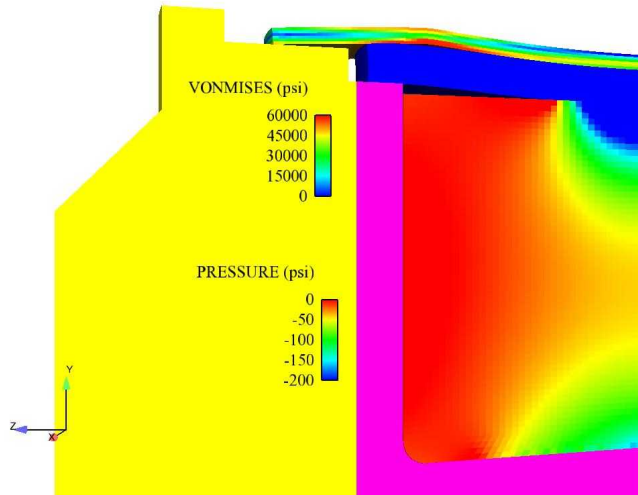
Example Animation

QuickTime™ and a
YUV420 codec decompressor
are needed to see this picture.

Results after Push-Down



Results after Cool-Down





Conclusions

- Penalty treatment of constraints in linear solver has proven to be very successful in the framework of Adagio's nonlinear preconditioned conjugate gradient algorithm.
- The robustness and scalability of this algorithm has been demonstrated in production manufacturing simulations.
- Modeling has been very helpful to designers in understanding performance of design alternatives.