

Measurement Results for a Hybrid Dimensional Artifact

Meghan Shilling
Sandia National Laboratories
kmshill@sandia.gov

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Co-Authors:
John Stoup and Theodore Doiron, NIST
Andre Claudet and Hy Tran, SNL

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Research Objective

- Mesoscale metrology commonly uses video probing
- Accuracy of video systems are typically limited by calibration artifact, not resolution
 - Calibration artifact accuracy $\sim 1\mu\text{m}$
 - System resolution $\sim 0.1\mu\text{m}$

Objective: To create a calibration artifact for a video-based measurement system which can be certified to better than $0.1\mu\text{m}$ accuracy.



Outline

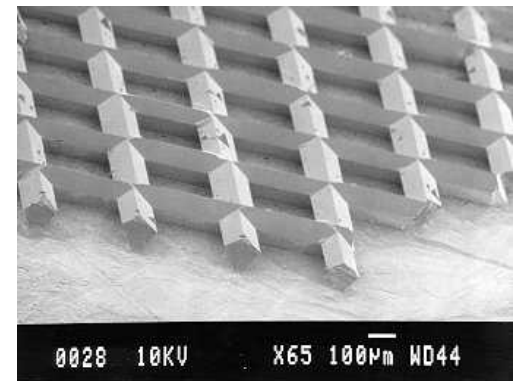
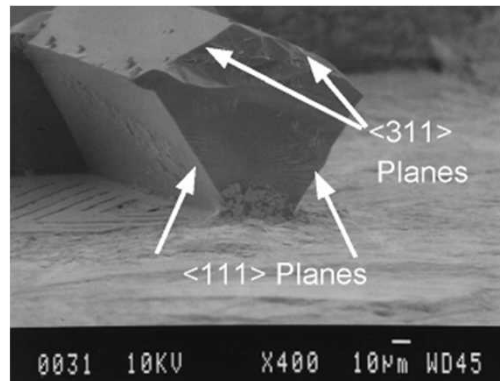
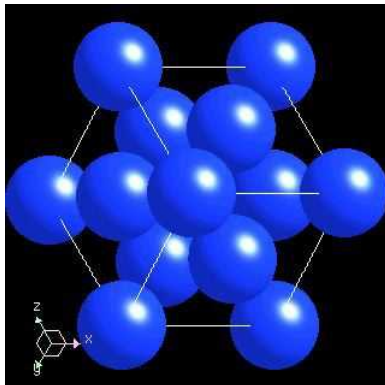
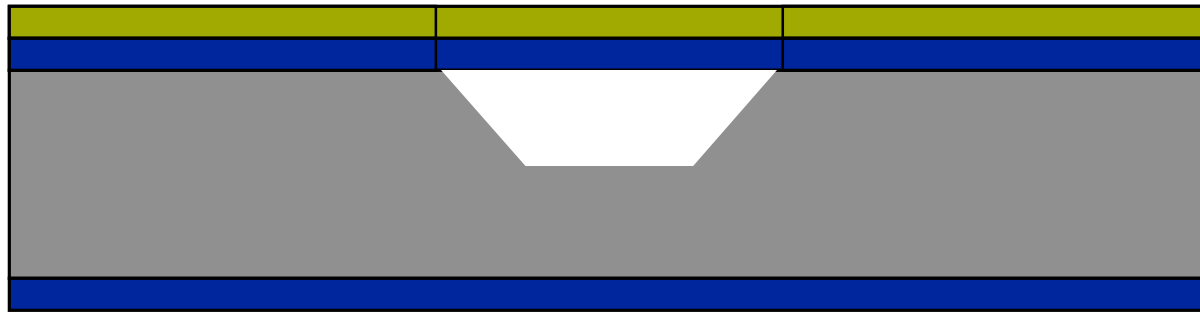
- **Hybrid Dimensional Artifact**
 - Design
 - Manufacturing
- **Edge Measurement with UMAP**
- **Comparison of Pitch Measurements made by CMM and Video Probes**
- **Discussion and Conclusions**

Geometric Design

- Fabricate artifact which contains miniature versions of “macro” metrology
- Step gage
 - 2D performance evaluation
- Ball plate
 - 3D performance evaluation
- Other objects for investigation



Si Bulk Micromachining



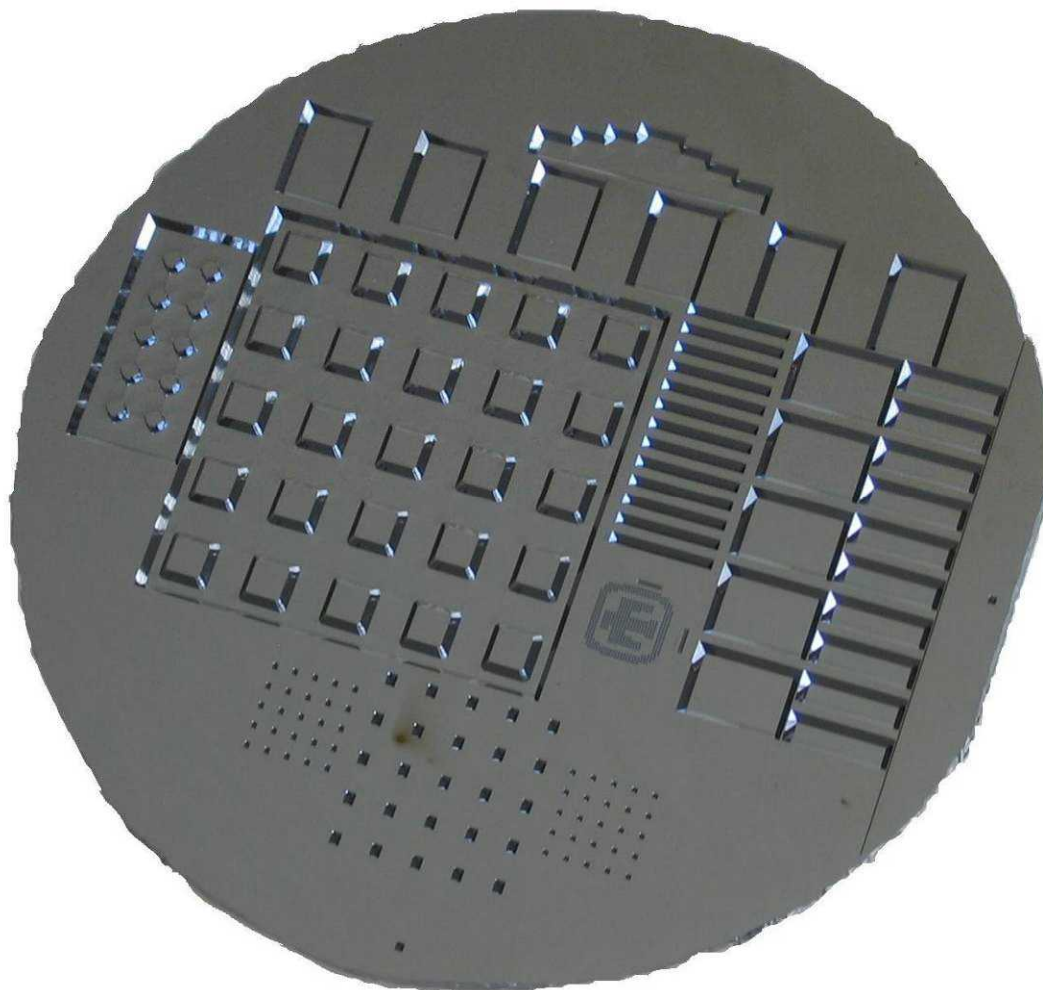


Manufacturing Design Details

- **<100> silicon with KOH etchant**
 - Gives sidewalls at 54.74 degrees
 - Yields etch planes flat to 50 nm
 - Edges are sharp and straight to nm level
 - Bottom of trenches not perfectly flat
- **1.5 mm thick wafer, polished on both sides**
 - Flat to 50-70 nm over 20-30 mm
 - Etch depth can be varied

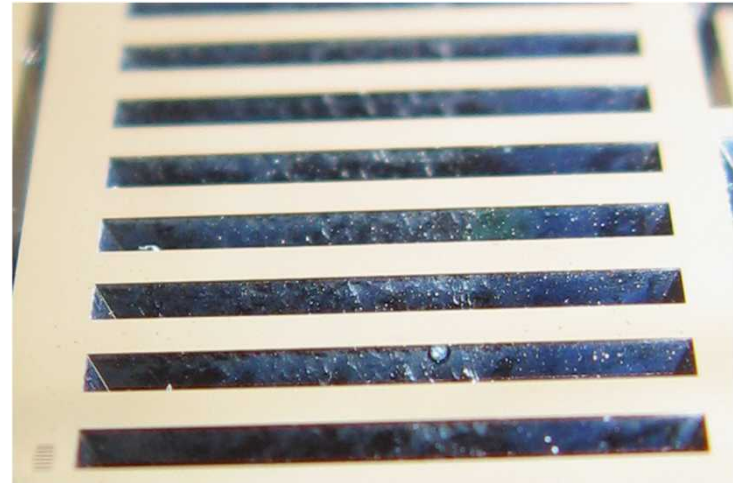
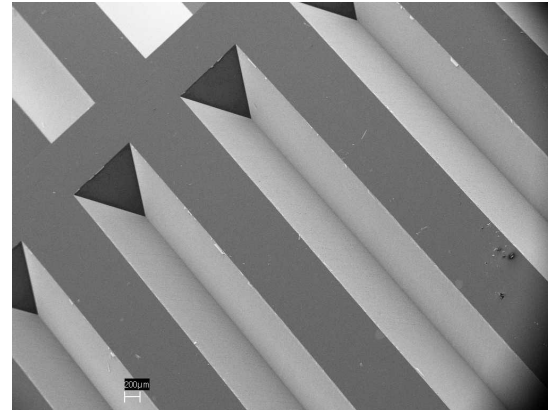


Artifact



Manufacturing Issues

- Nitride removal process attacked silicon sidewalls
- Effects of alternative nitride removal processes are being studied
- Multiple crystal planes being etched



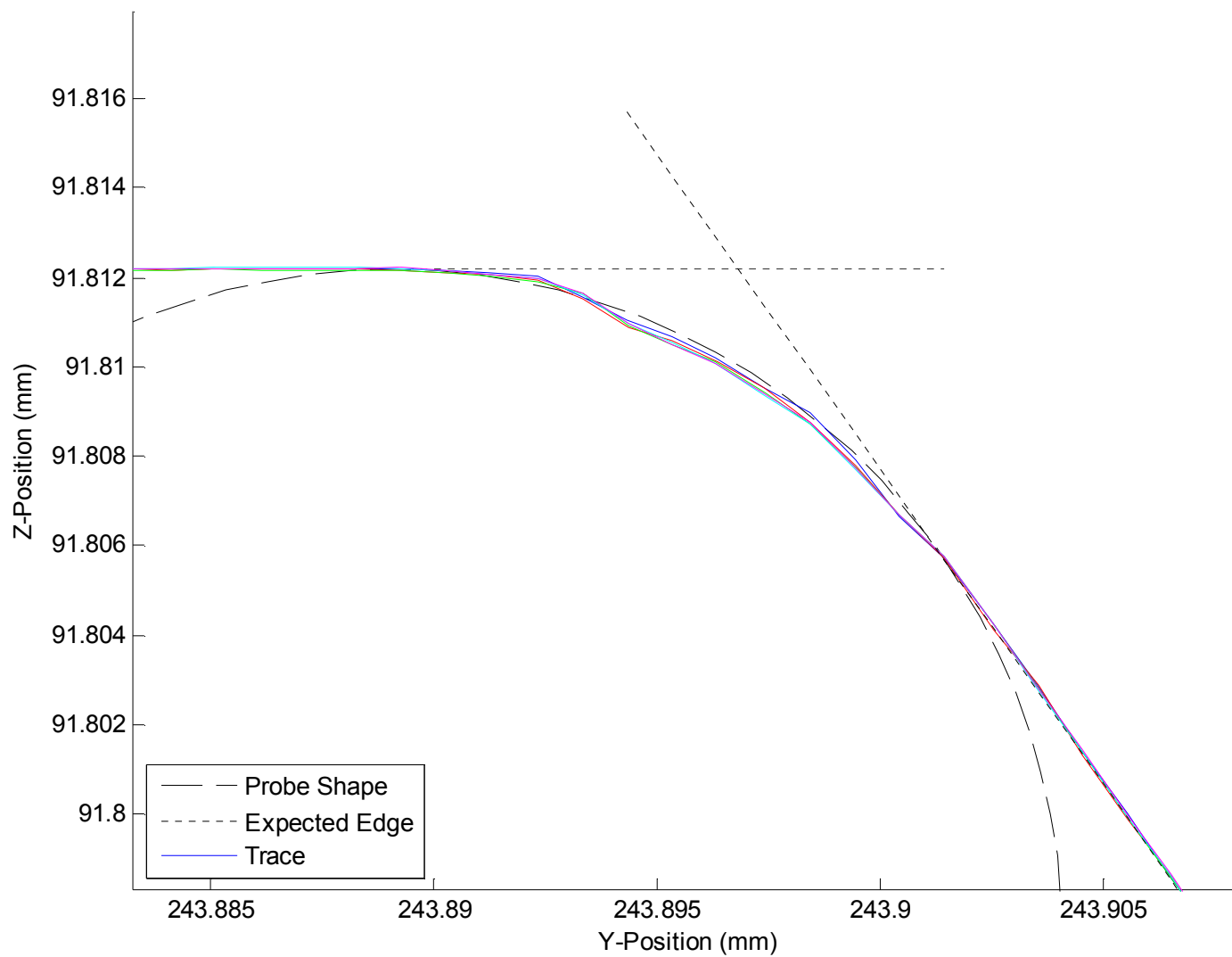
Edge Measurement with UMAP

- Mitutoyo UMAP Ultra
- Contact measurements with probe
 - 30 μm diameter
 - 2 mm stylus length
- Accuracy
 - $(1.2 + 3L/1000) \mu\text{m}$
- Repeatability
 - $S < 0.1 \mu\text{m}$



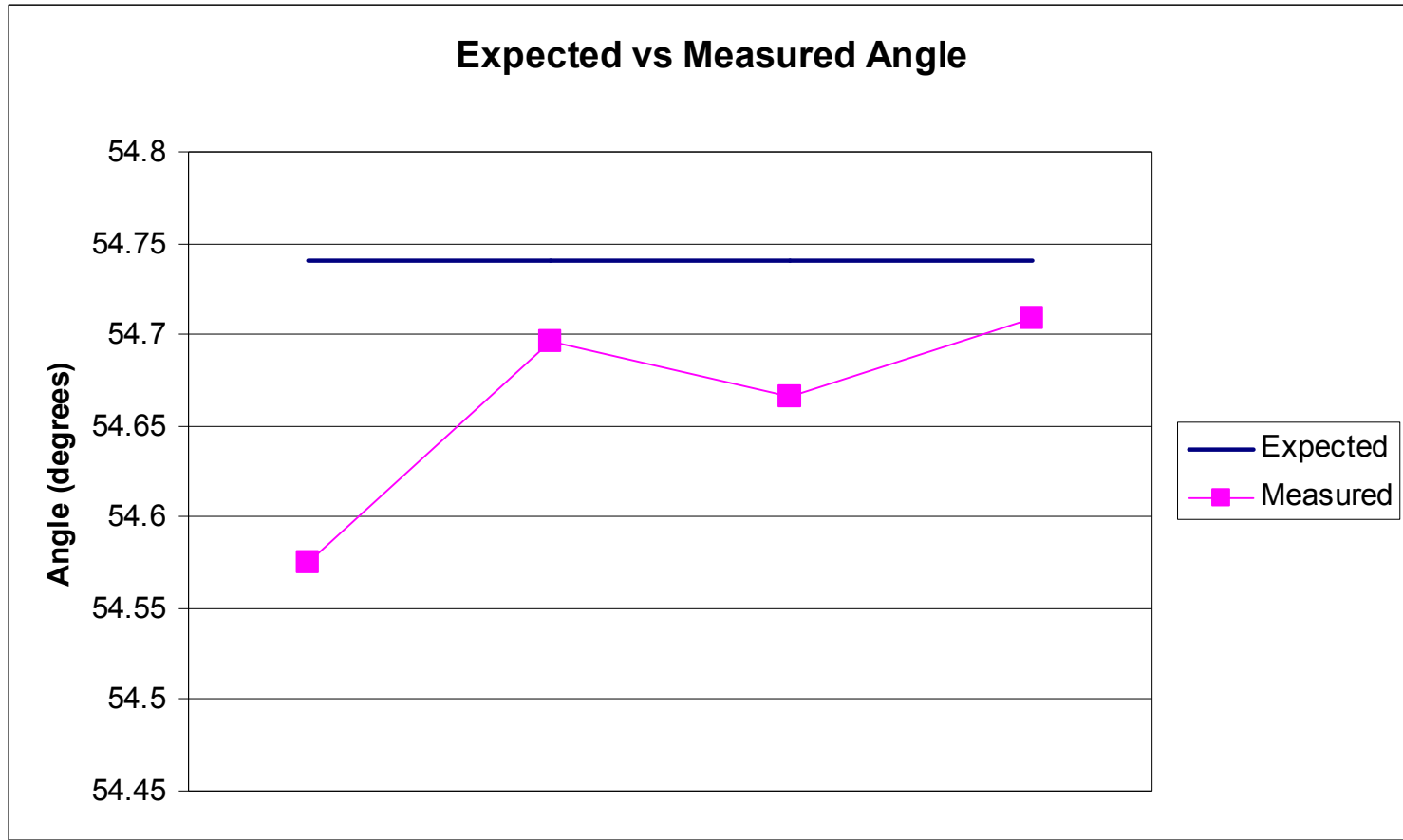


UMAP Edge Measurement



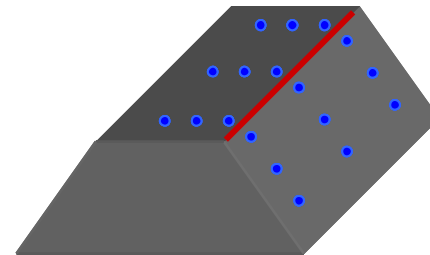
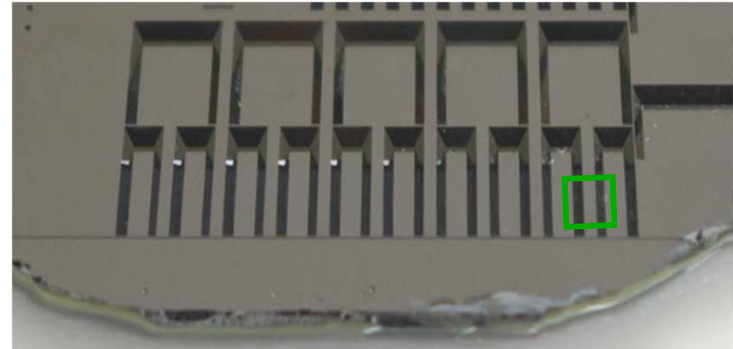


UMAP Angle Measurement



Comparison

- Compared single step bar (3mm trench, 4mm pitch)
 - Touch Probe (Moore M48)
 - Optical Probes (Werth Video-Check HA, OGP)
- CMM will probe top and etch planes and calculate intersection line
- Vision systems will locate edge formed by intersection of top and etch planes (top lighting used)



Coordinate Measurement Machine



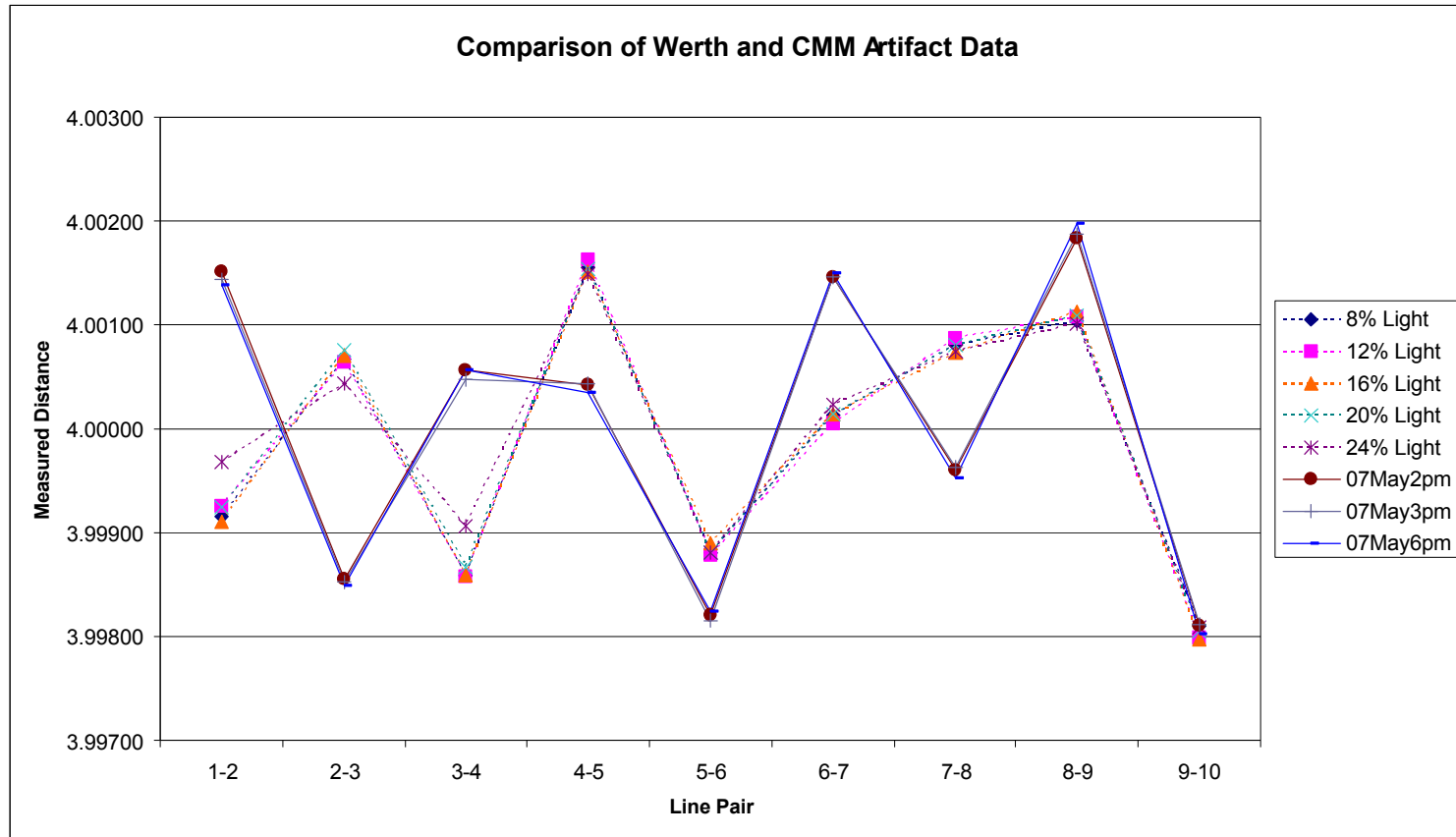
- Moore M48 CMM
- Movomatic analog probe head
- Temperature controlled environment
- Volumetric performance $0.3 \mu\text{m} + L/300$
- Repeatability $\sim 15 \text{ nm}$

Werth

- Video-Check HA
- High-accuracy vision measurement system
- Resolution
0.01 μm
- XY Accuracy
(0.5 + L/900) μm



Werth Results

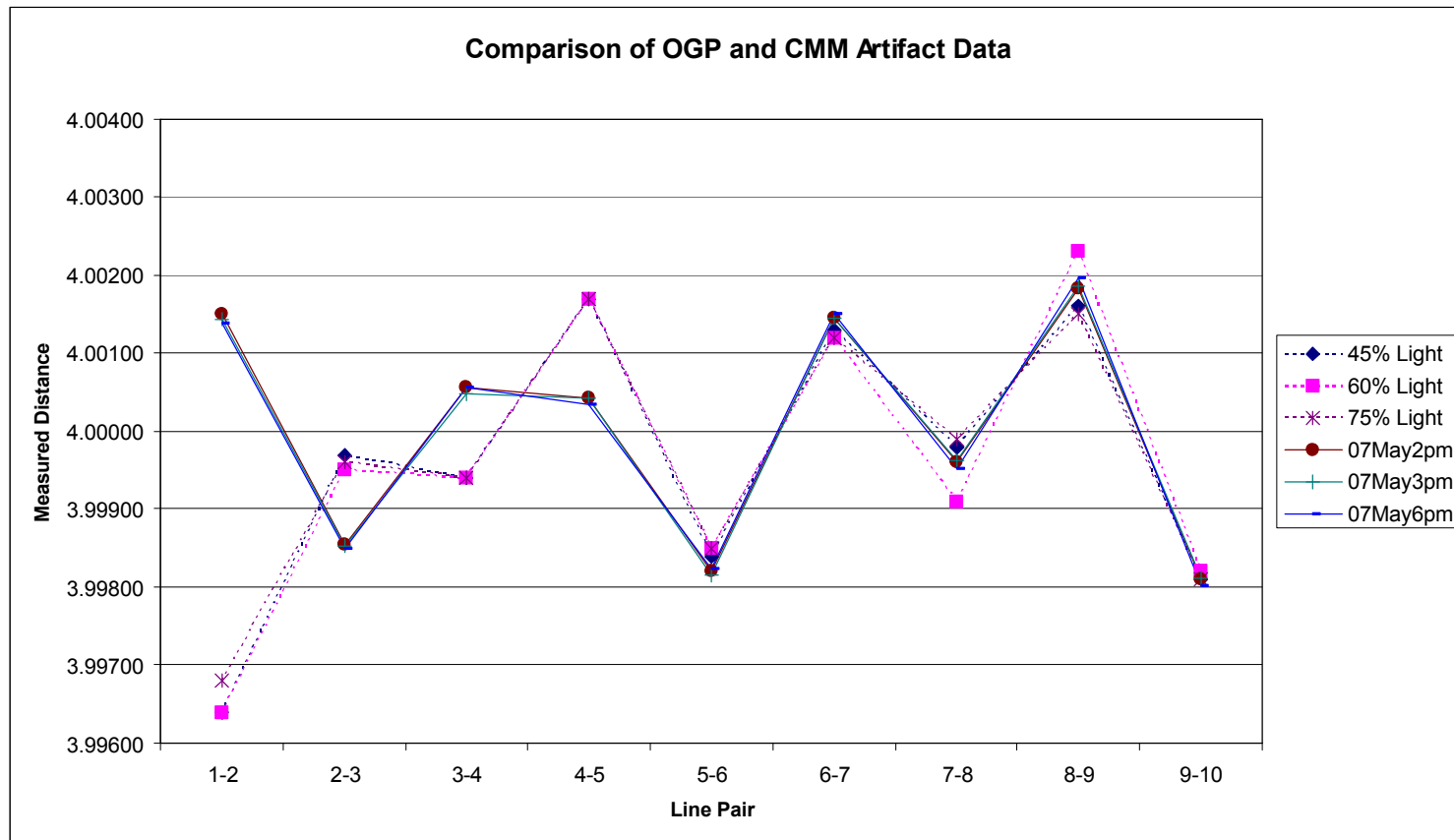


OGP



- **Smartscope APEX**
- **High-accuracy vision measurement system**
- **Scale Resolution**
 $0.10 \mu\text{m}$
- **XY Accuracy**
 $(1.2 + 2L/1000) \mu\text{m}$

OGP Results



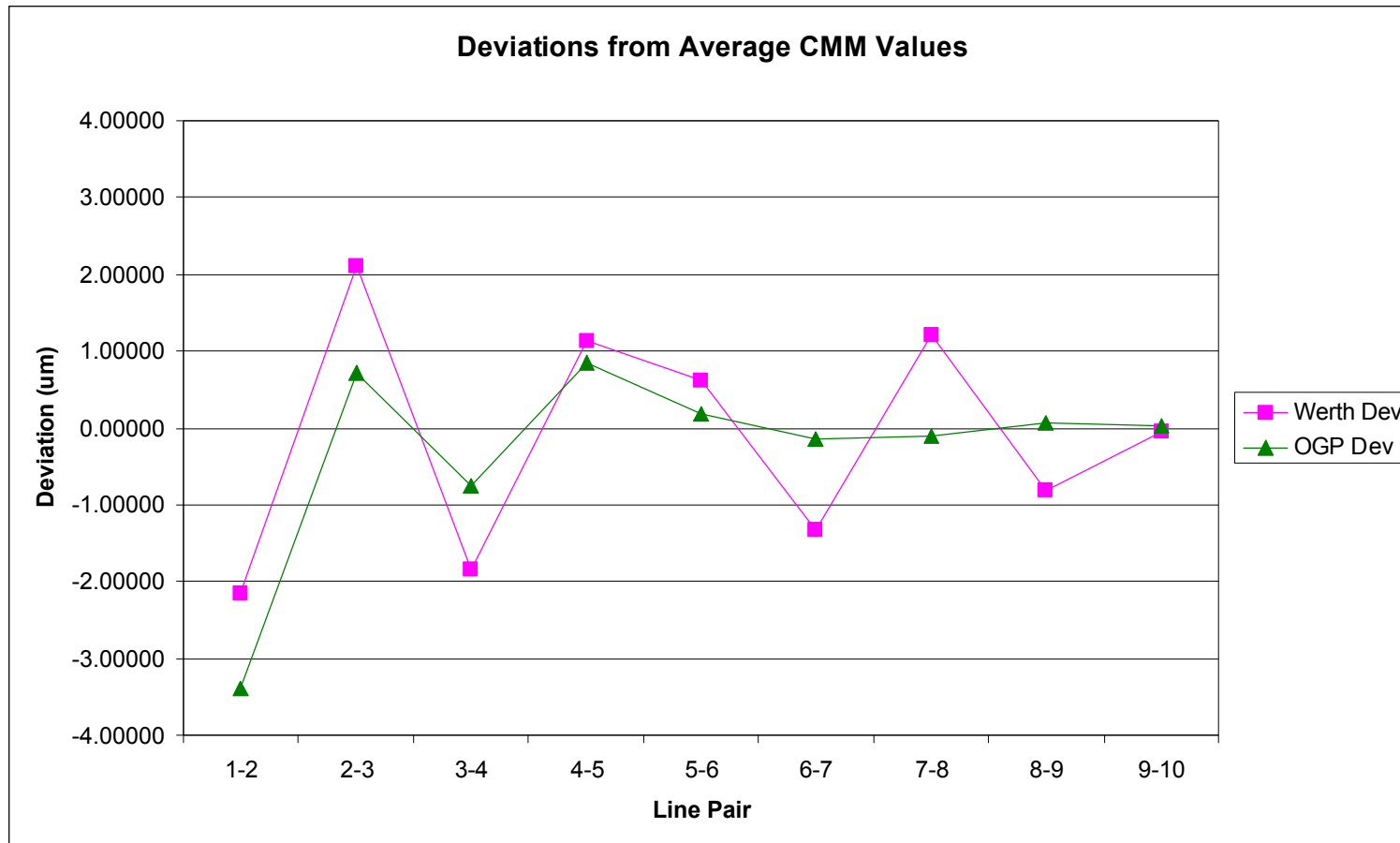


Comparison





Comparison





Discussion

- **Manufacturing process needs to be studied and improved to eliminate**
 - Etching on multiple planes (better alignment)
 - Roughness on sidewalls (nitride removal process optimization)
- **Light level change has little effect on pitch measurement**
- **Multiple runs on same measurement machine are repeatable**



Conclusions

- **Manufacturing process requires optimization**
- **Artifact can be used on vision systems with little concern for lighting conditions**
- **Repeatability implies that the machine errors can be corrected for**