

Review of IEA Smart Structures Meeting & Review of Sandia Active Aerodynamic Flow Control Efforts

Dale E. Berg

Sandia National Laboratories

Albuquerque, NM USA

May 12-14, 2008

Sandia is a multiprogram laboratory operated by Sandia Corporation, a Lockheed Martin Company, for the United States Department of Energy's National Nuclear Security Administration under contract DE-AC04-94AL85000.



Outline

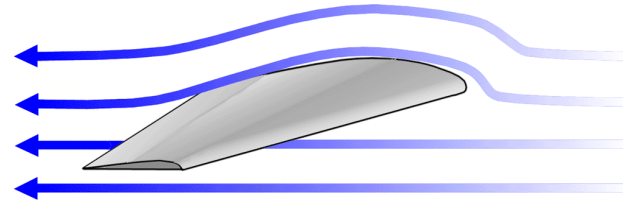
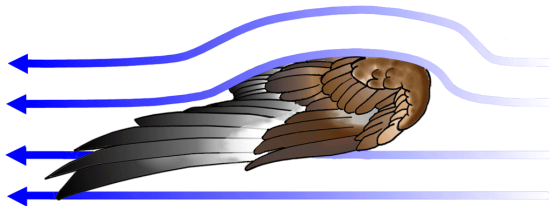
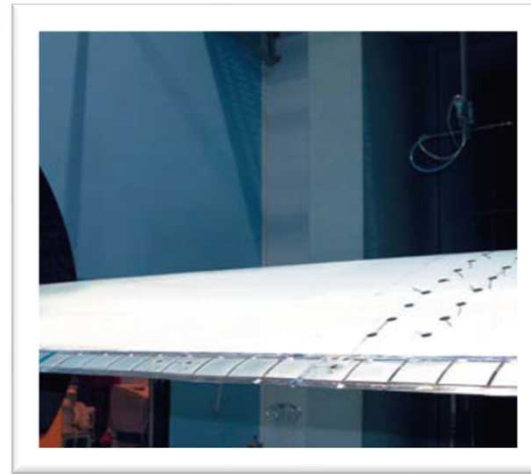
- **Brief Review of IEA Expert Meeting on Smart Structures**
 - objectives
 - why investigate local load control
 - areas of concern
 - trailing edge flap results
 - blade integration issues
 - sensor investigation efforts
- **Sandia Active Aero Control Efforts**
 - microtab concept
 - system modeling
 - cooperative efforts

Objectives of Smart Structure Concept

- **Significantly reduce blade loads**
 - vary with position on blade
 - vary with time scale of a few seconds
- **Increase energy capture**
- **Flow control utilizing distributed**
 - sensors
 - intelligence
 - small, fast-acting control devices
- **Modify local aerodynamics of the blade**
- **Maintain reliability**
- **Minimize additional cost**

Why Look at Local Control?

RISO



Why Local Load Control?

- **Large size means loads vary quickly & dramatically along blade**
- **Active pitch control can only control “average” load on blade**
- **Passive load control cannot respond to local load variations**
- **Fatigue loads can drive the lifetime of all turbine components**



What Benefits do We Expect to Gain?

- **Lower fatigue loads**
- **Increased energy capture**
- **Actively suppress vibration (certain modes)**
- **Control noise?**
- **To fully realize the potential benefits, may need to design a machine from scratch that integrates local flow control**

Key Areas of Concern

- **Aerodynamics of airfoils with distributed control elements**
 - Multiple devices available to adjust lift & drag
 - Need CFD(?) tools to determine device performance characteristics
 - Need aero/CFD(?) tools to determine control effects on entire system
- **Actuators**
 - Control device must be deployed, retracted, moved
 - Bi-stable or multi-stable devices are interesting
- **Sensors**
 - Many types are available today
 - What do we need to measure?
 - loads
 - state of flow
 - deflection
 - acceleration
 - ????

Key Areas of Concern

- **Controls**
 - **Major development required**
 - **Needs:**
 - fast
 - real-time load identification
 - fault tolerant
 - improved energy capture
 - site and condition adaptive (self learning)
 - failsafe
 - predictive?
 - multiple time scales, multiple impact levels

Key Areas of Concern

- **Communications and power supply**
 - Not usually considered high tech problem
 - immune to lightning
- **New blade materials and construction**
 - Incorporate control devices/actuators/sensors
 - Preserve integrity of blade interior
 - Replaceable control elements
- **Blade design and analysis tools**
 - Increase capability
 - Accommodate
 - innovative blade construction
 - distributed control

Why Focus on Trailing Edge Devices?

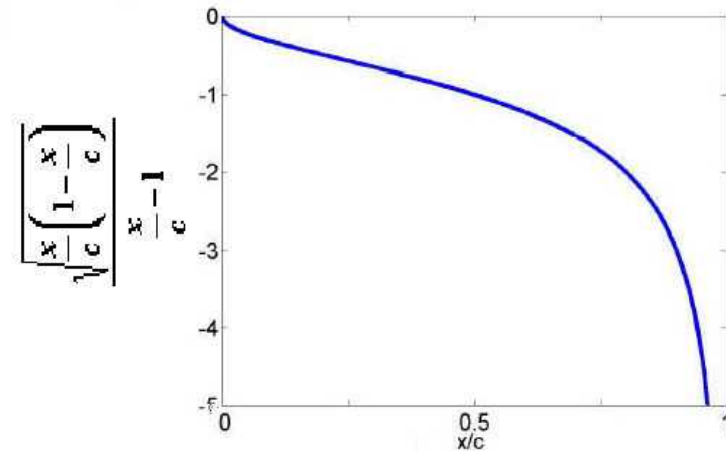
- **From Thin Airfoil Theory**

$$C_l = C_{l\alpha} + C_{lc}$$

Where

$C_{l\alpha} = 2\pi\alpha$ is lift due to airfoil angle of attack

$$C_{lc} = 4 \int_{x/c=0}^1 \frac{d(y_c/c)}{d(x/c)} \frac{\sqrt{\frac{x}{c} \left(1 - \frac{x}{c}\right)}}{\frac{x}{c} - 1} d(x/c) \text{ is lift due to airfoil camber}$$

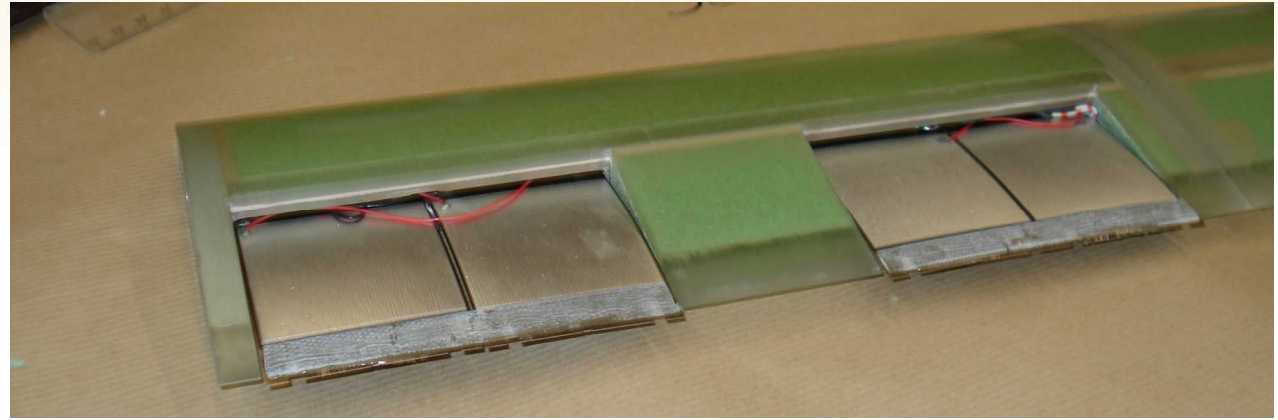


–effect of camber is greatest at trailing edge

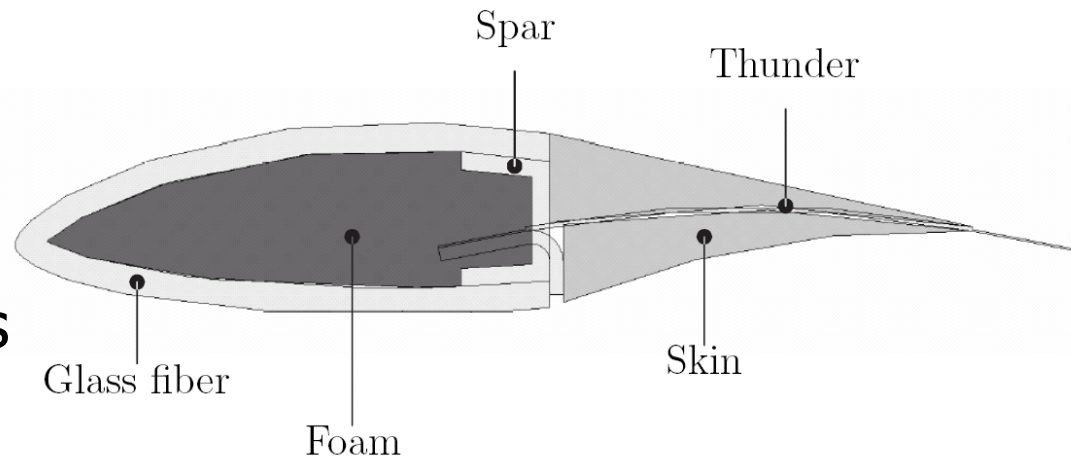
- **Aerodynamic Loads are Low at Trailing Edge**

Experimental Design

- Wind tunnel
- Blade
- Pitch system
- Trailing edge flap
- Sensors
- Real-time system



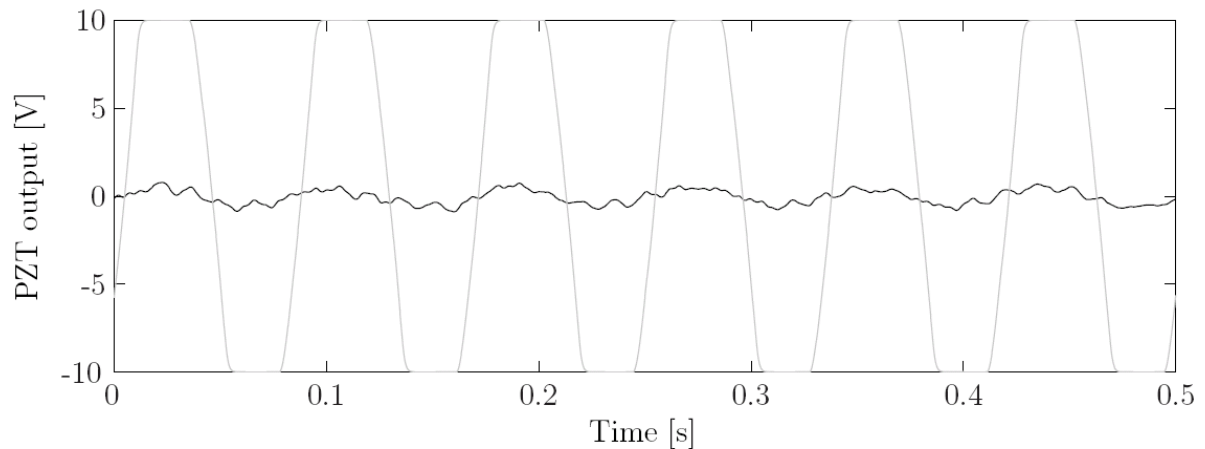
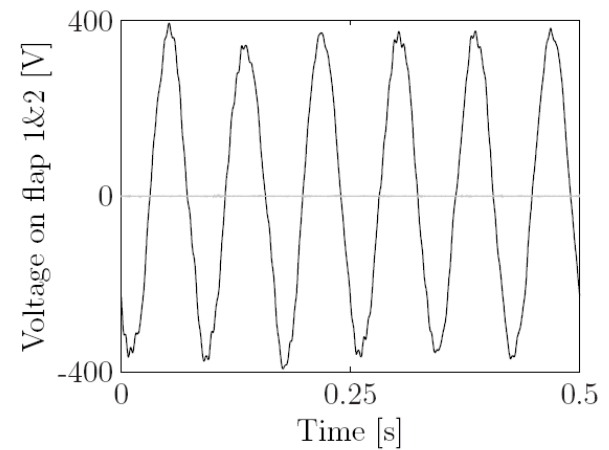
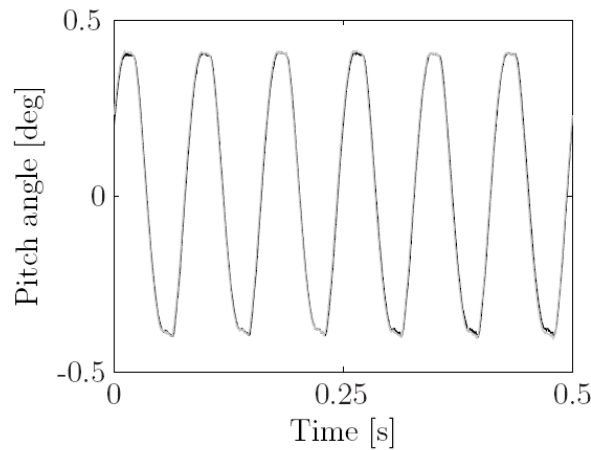
- Flexible trailing edge flap
- Piezo bender (Thunder)
- High voltage requirements



Experimental Results

- Feedforward control
- Feedback control
 - Periodic disturbance
 - Step disturbance (gust)
 - Random disturbance (turbulence)

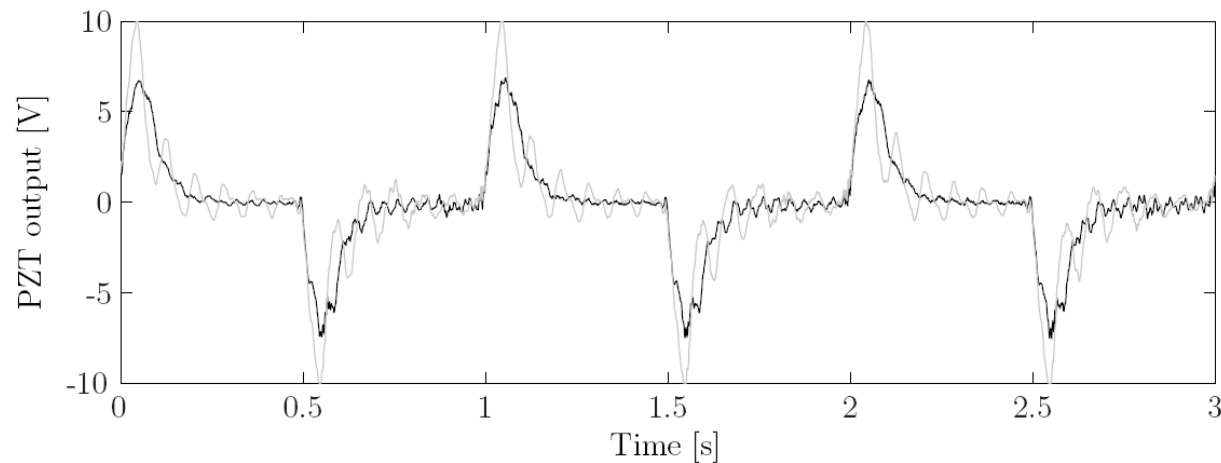
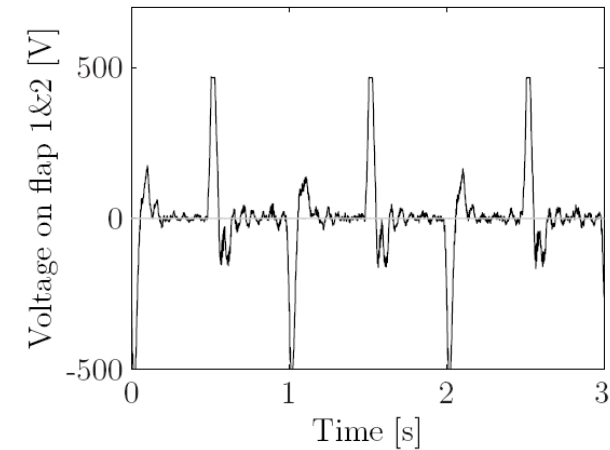
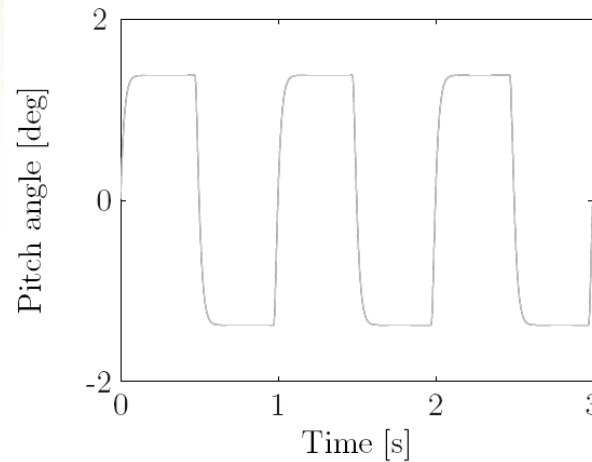
$V = 30 \text{ m/s}$
 $\alpha = 6 \text{ degrees}$
Eigenfrequency



Experimental Results

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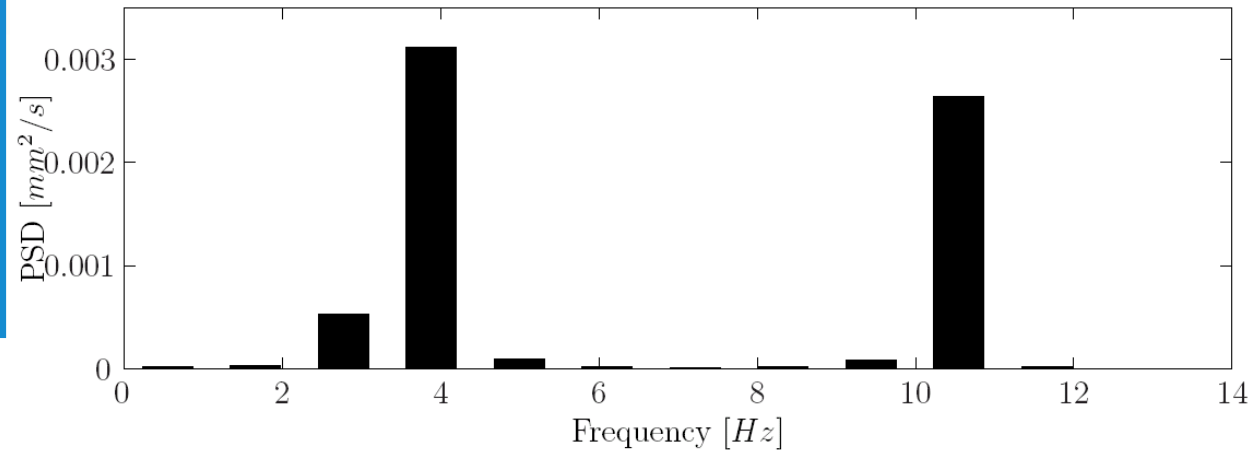
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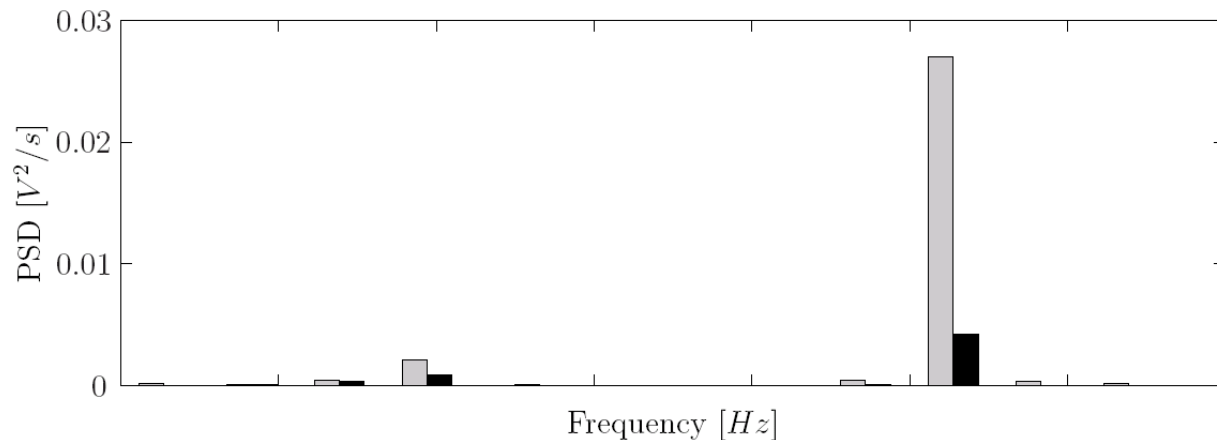
Experimental Results

Input spectrum

- Feedforward control
- Feedback control
 - Periodic disturbance
 - Step disturbance (gust)
 - Random disturbance (turbulence)



Output spectrum



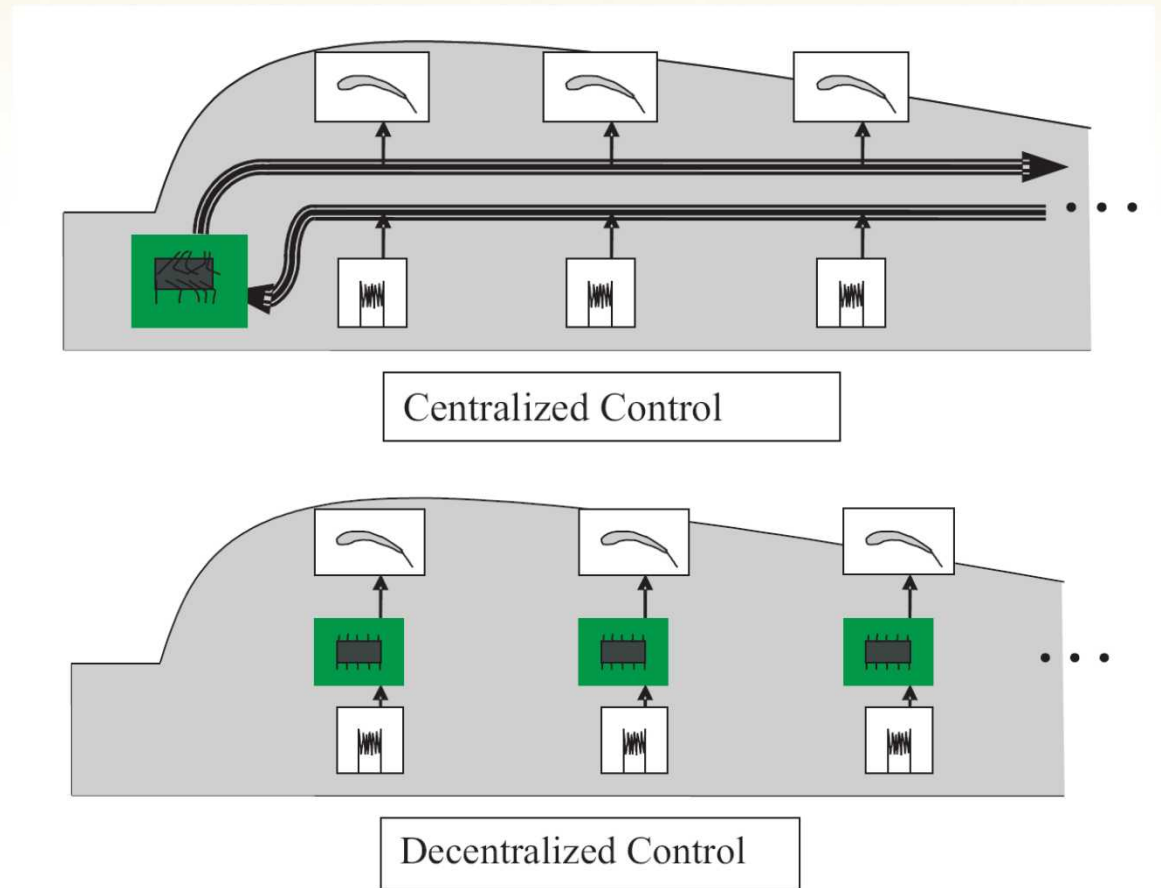
$V = 30 \text{ m/s}$

$\alpha = 6 \text{ degrees}$

Challenges: Distributed Control

Control for distributed systems

- Large number of actuators and sensors
- Centralized vs Decentralized control
- Or....

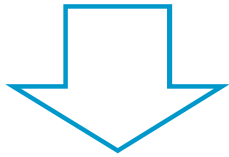


Rice

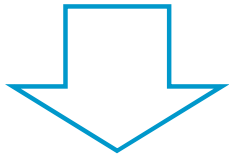
Device Integration

Utilize Thermoplastic Material

Adding elements



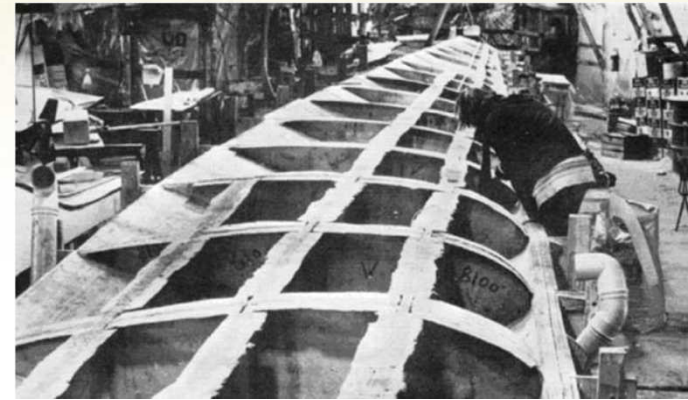
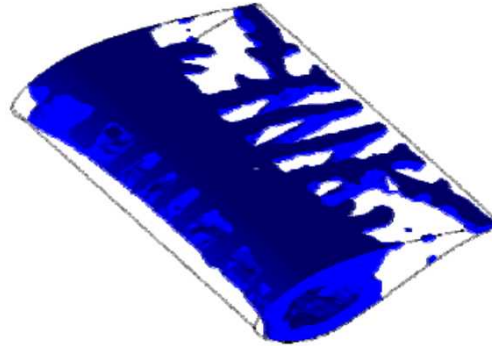
Adding ribs



Rib-spar design,

in combination with TPC material system

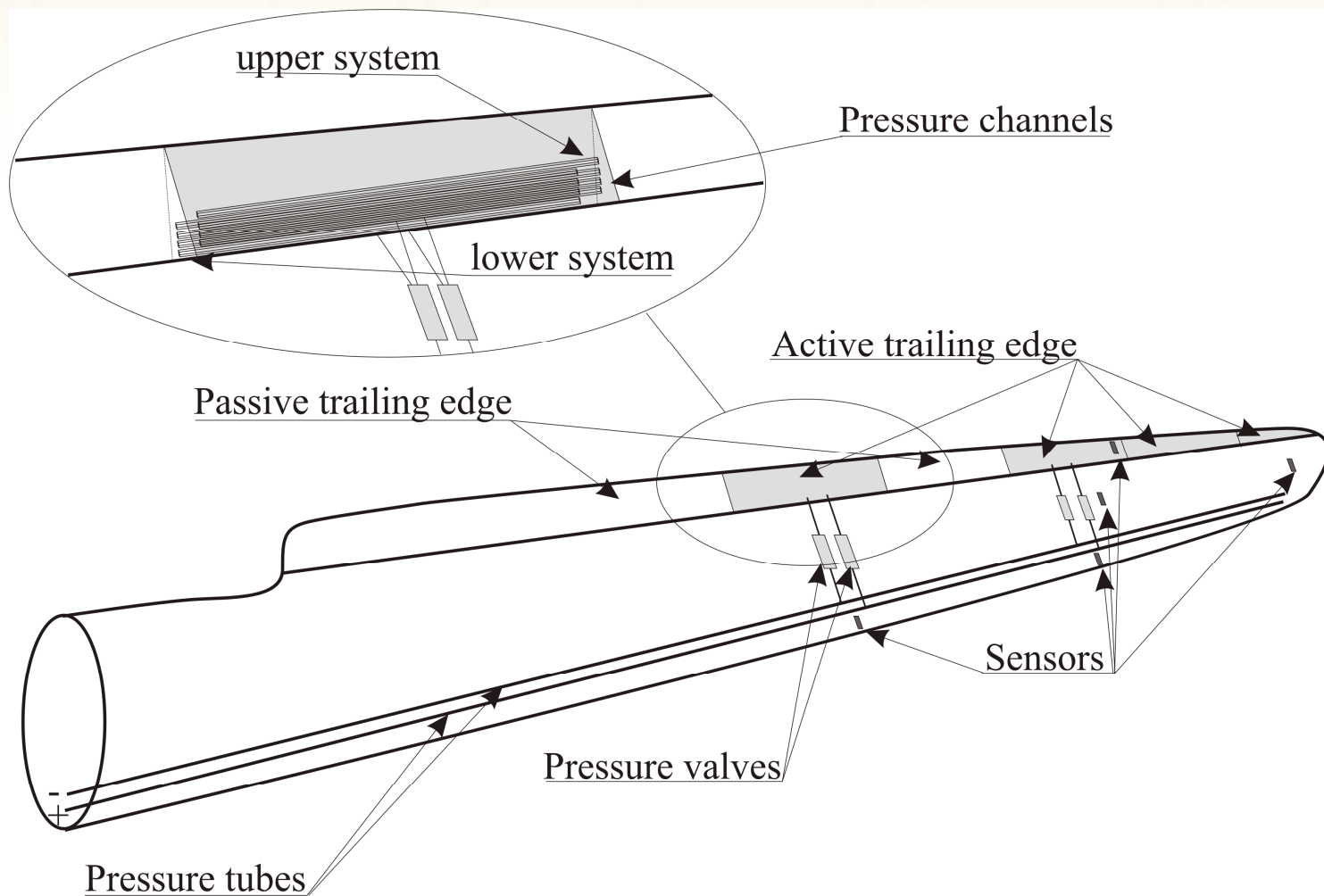
Through-out the whole blade: structurally more feasible??

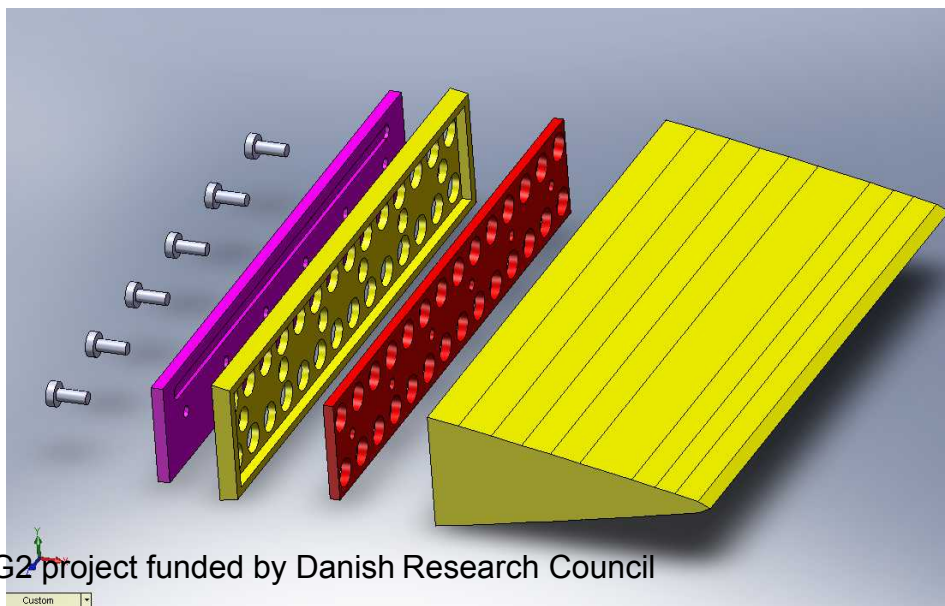
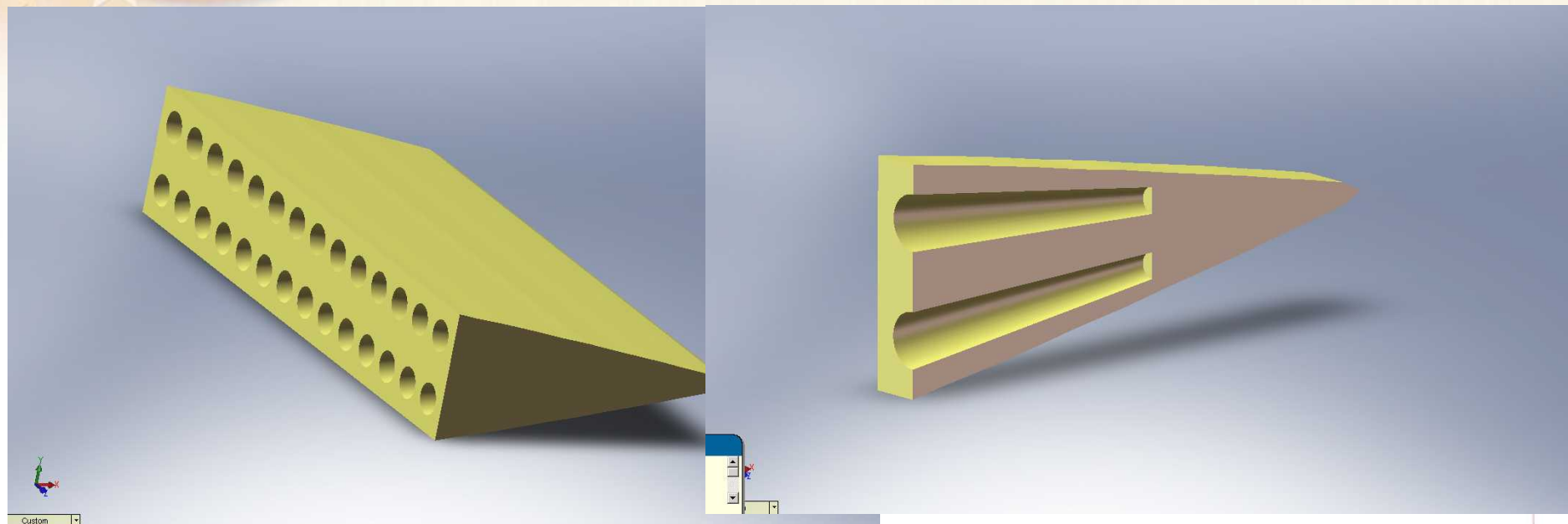


Device Integration

Rib-spar, TPC design through-out the whole blade: structurally more feasible?

- 1. (100%?) reduction in foam/balsa,**
- 2. Ease assembling through welding,**
- 3. Load paths,**
- 4. Possibly added value for sectional blades.**





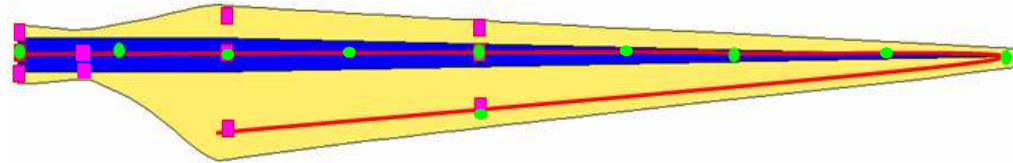
From the ADAPWING2 project funded by Danish Research Council

Development Process Stages

- **Research**
 - analysis
 - laboratory testing
- **Proof of Concept**
 - small/medium scale prototype testing
- **Commercial Viability**
 - large scale prototype field testing
- **Commercial application**

Sensor Tasks at Sandia Labs

- **Fully anticipate advanced control strategies**
- **Address Sensor-in-Blade Issues**
 - **Incorporation** (material compatibility, egress/ingress, surface-mount/embed, manufacturing, maintenance accessibility, costs)
 - **Reliability** (long-term aging, robustness)
- **Sensor Blade (SBlade) Project**
- **Sensor and Active Flow/Load Control Lab**
 - **Model and validate sensor/actuation performance**
 - **Determine sensor requirements** (accuracy, reliability, cost)
 - **Evaluate various sensing technologies**
 - **Build and test subscale structures**



Sensor Blade (SBlade) Project

- **Build a Sensor Blade**
 - **Incorporate sensors in a blade during blade manufacture**
 - **Sensor list:**
 - Embedded FBG sensors (strain and temperature, blade shape)
 - Inner-surface mounted FBG sensors (strain and temperature, loads)
 - Inner-surface mounted accelerometers (blade shape, loads, SHM)
 - Metal foil strain gages (strain, loads)
 - RTD temperature
 - Streaming video on rotor (blade shape)
- **Field Test Sensor Blade**
 - **On-the-ground checkouts and calibrations**
 - **In-the-air checkouts and calibrations**
 - **Measure loads and blade deflections during turbine operation**
 - **Real-time video monitoring**
- **Static and Fatigue Test Sensor Blade)**
 - **Static Proof Test**
 - **Fatigue test to SBlade failure**
 - **AE NDT, SHM (Impedance-based, Virtual Forces, Residual Force, ...)**
- **Analyze datasets and report results**



Sandia Active Load Control Effort

- **Effort will investigate the use of active load control for turbine blades and evaluate its impact on cost of energy**
- **Aerodynamic loading on blade can be modified through:**
 - **Blade incidence angle**
 - **Flow velocity**
 - **Blade size**
 - **Blade aerodynamic characteristics**
- **Focus is on small fast-acting systems that change sectional aerodynamic characteristics to alleviate load spikes due to gusts and to reduce blade tip deflections during high load conditions**

Innovative Concepts

Goal & Impact

- **Goal:**

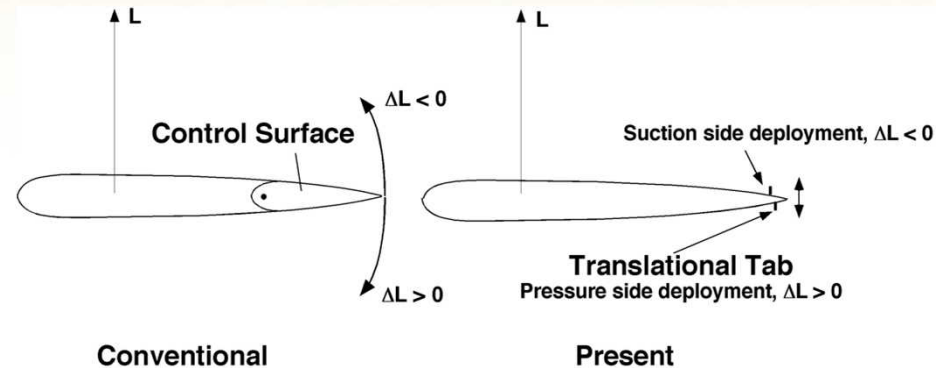
- Develop small, light-weight control devices & systems to attenuate fatigue loads on turbine blades and enable increased energy capture

- **Current Status:**

- **Devices**
 - Investigating micro tabs, morphing trailing edge, and micro flaps
 - Building wind-tunnel model with integrated devices and actuators
- **Actuators**
 - Researching durable/low-power, simple designs
- **Controls**
 - Developing appropriate control algorithms

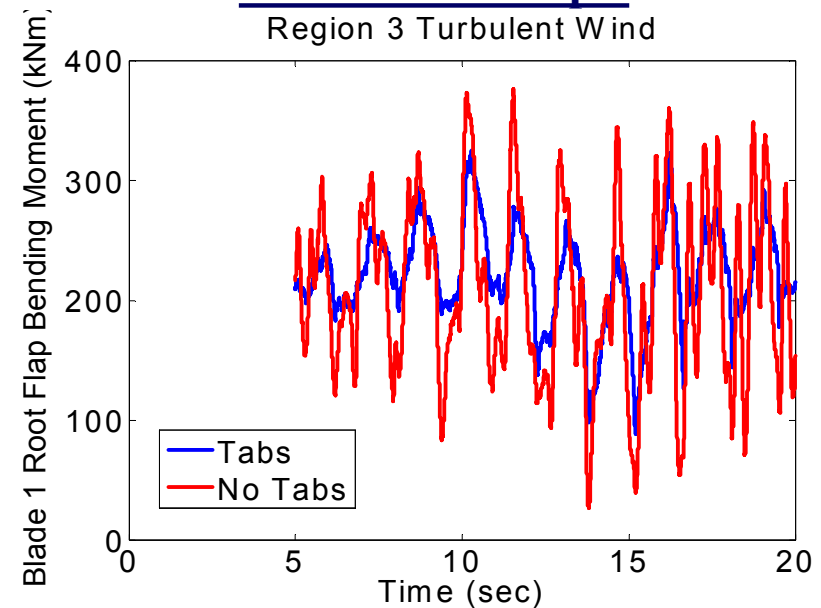
- **Industry Impact:**

- Weight reductions
- Lower cost of energy



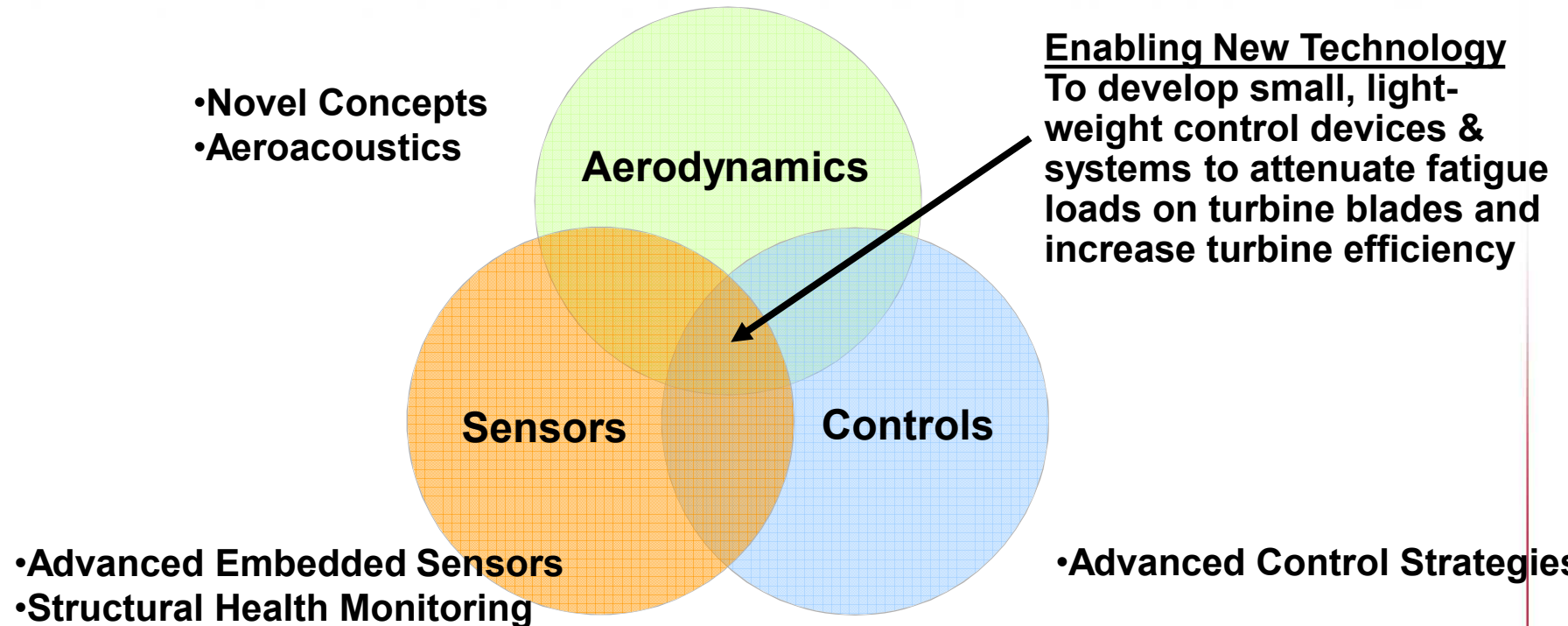
Microtab Concepts

Region 3 Turbulent Wind



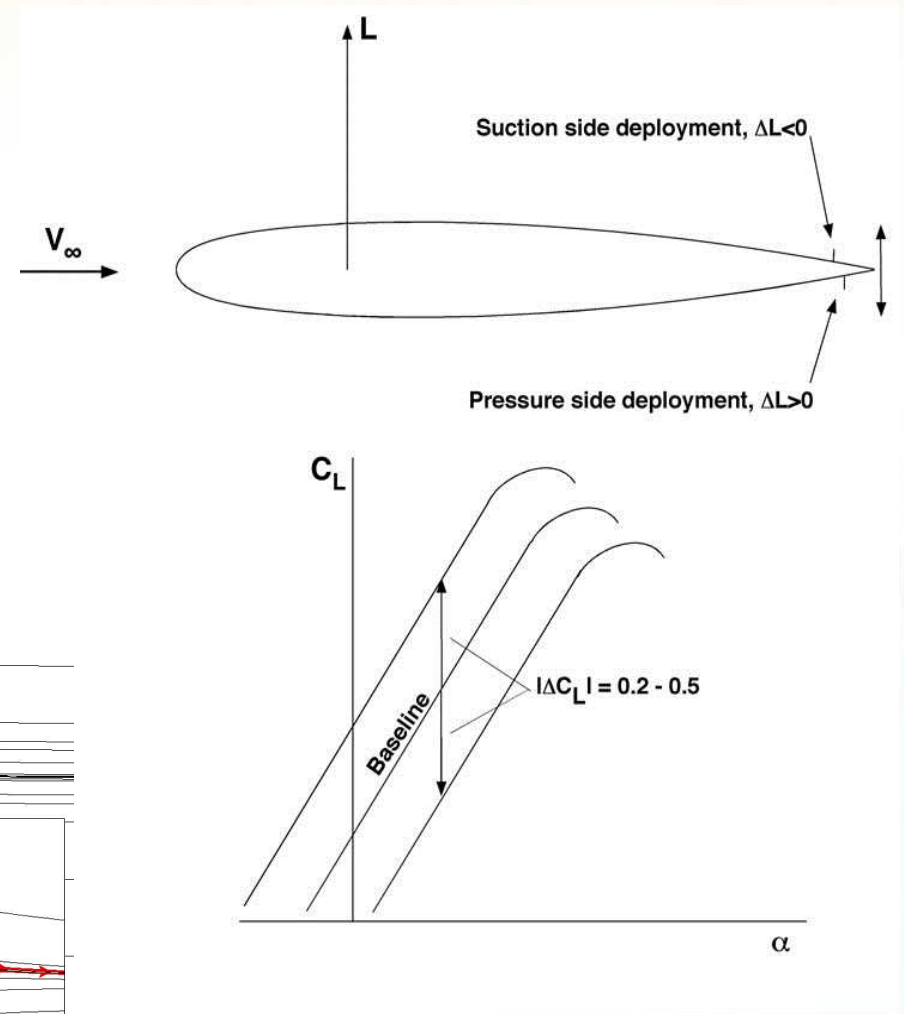
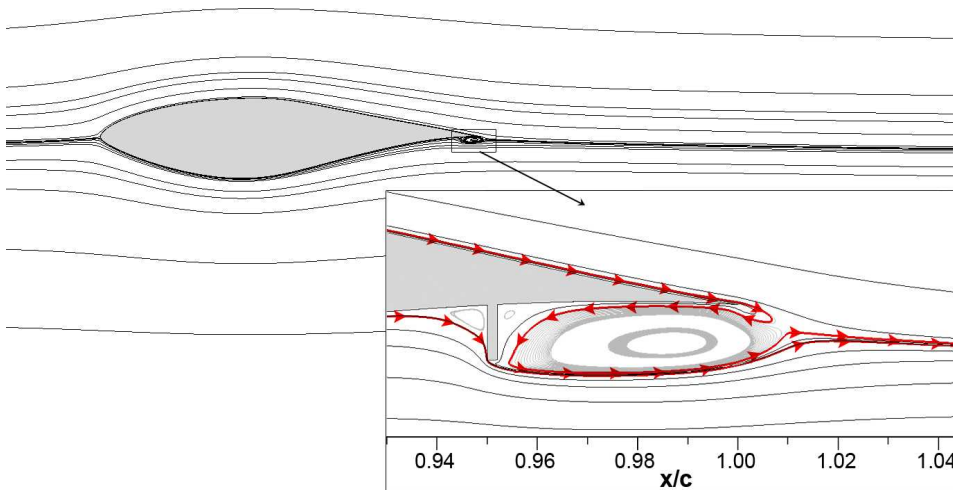
Enabling Smart Blades

Future Design Needs



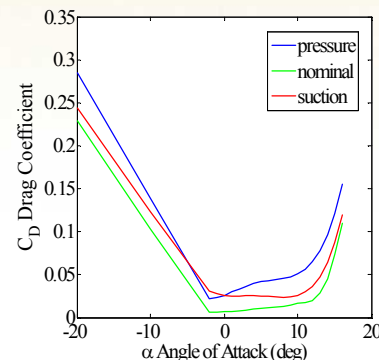
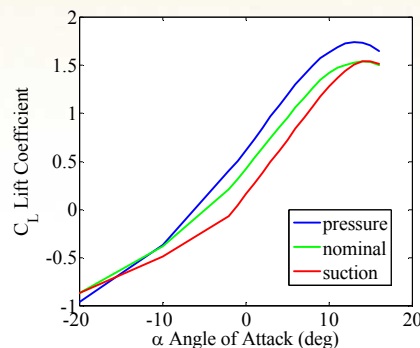
Microtab Concept

- Conceptualized in 1998
- Tabs deploy (near-)normal to flow direction
- Forward of the trailing edge
 - Upper or lower surface
- Hinge-less device
 - Small actuation forces
- $h_{\text{tab}} \sim$ boundary layer thickness
- Trailing-edge flow condition is altered

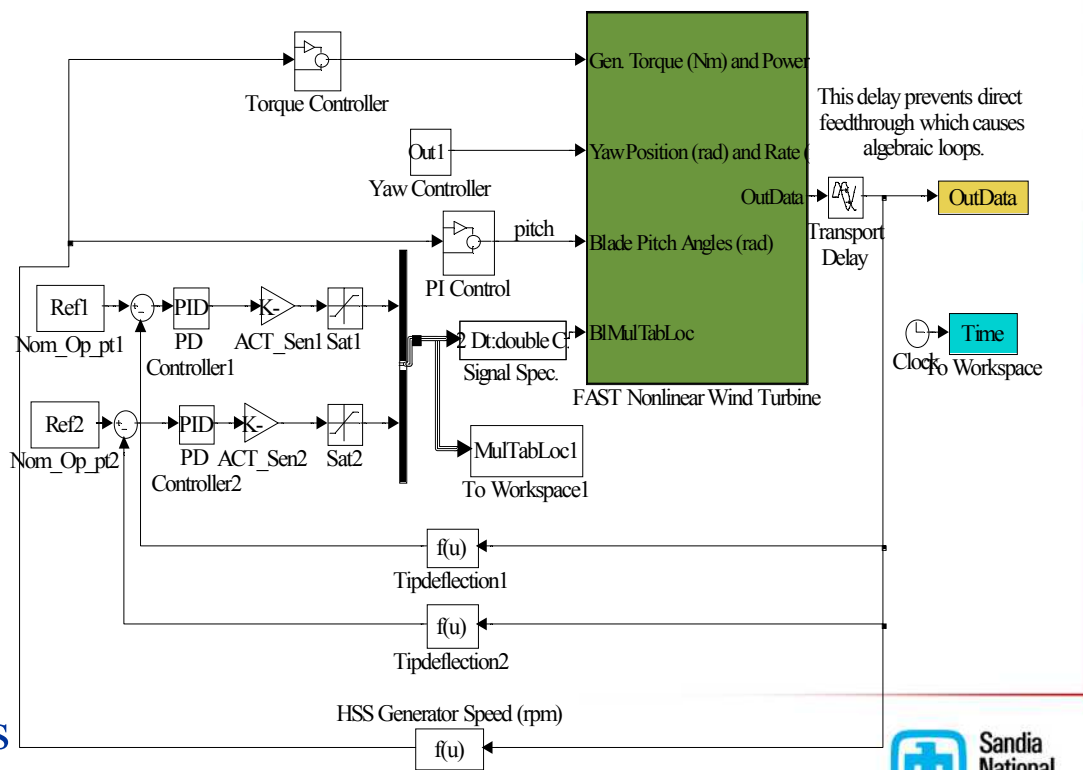


System Modeling - Analysis

- **Controls Advanced Research Turbine (CART):** utilized as simulation testbed with 600kW rated power @ 42 RPM
- **Dynamic Simulation Environment:** FAST (Fatigue, Aerodynamics, Structures, and Turbulence) run within Matlab/Simulink
- **Hybrid Controller:** Proportional-Integral (PI) Blade Pitch Control with Proportional-Derivative (PD) Microtab Control for above rated wind speed conditions, Region III
- **Microtab PD Control:** Uses tip deflection feedback and nominal reference tip deflection as set point

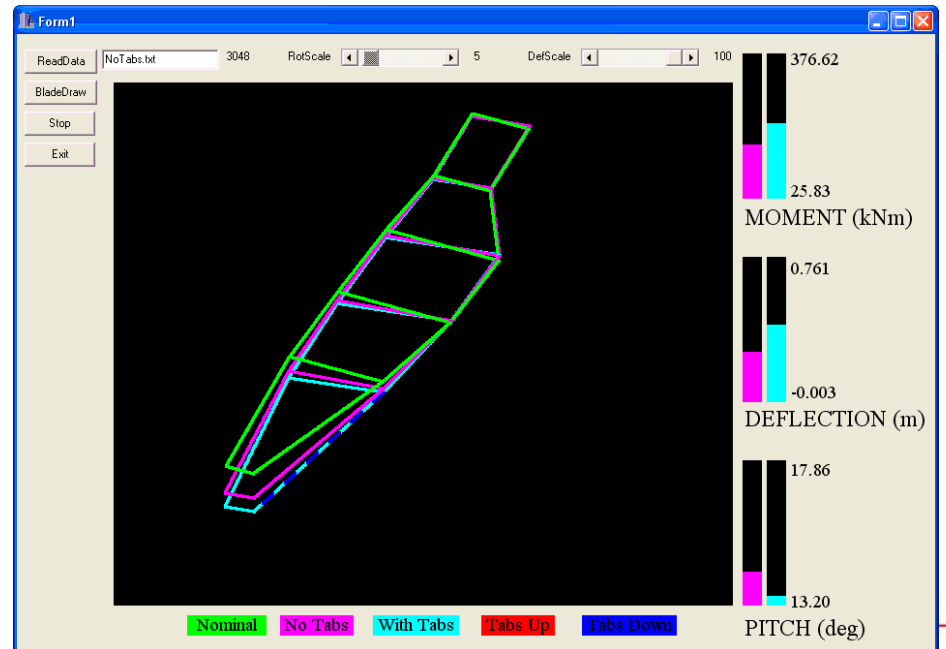
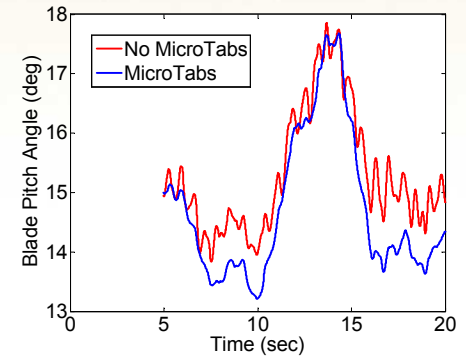
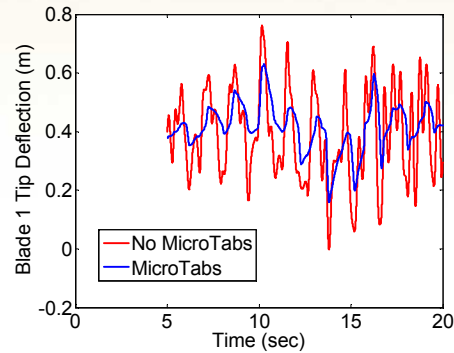
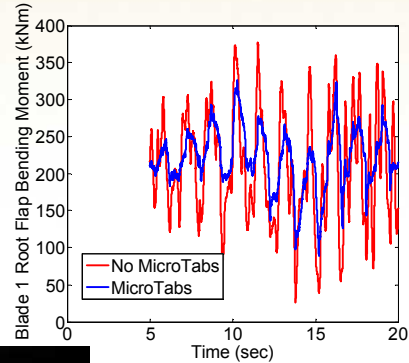
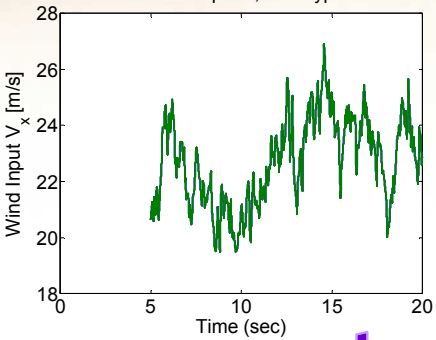


Microtab Profiles
AeroDyn Inputs



Microtab Active Aero Blade Control Performance Visualization

23.2 m/s Mean Wind Speed, IEC Type A Turbulence



Region III

Sandia is also Working with Other Organizations

- **Memorandum of Understanding with TU Delft**
 - active aero device
 - material development
 - reliability
 - controls
- **CRADA with FlexSys**
 - evaluation of morphing trailing edge



Summary

- **IEA Expert Meeting**
 - lots of activity in past 17 months
 - still very much a research effort
 - need considerable work in sensor area
 - continue to hold Expert Meetings for now
- **Sandia Effort**
 - goal is to decrease fatigue loads and increase energy capture
 - focusing on microtabs, but also looking at morphing TE
 - full system modeling, including control system
 - cooperative efforts with TUDelft and FlexSys



Thank You!

Questions?