

# Use of a Manufactured Solution for Verifying CFD Flux Schemes and BCs

Tuesday, 20 February, 2007

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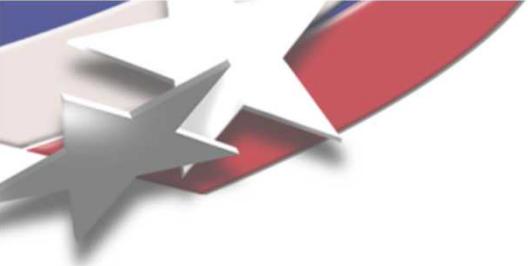
SIAM Conference on Computational Science and Engineering

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# Verification

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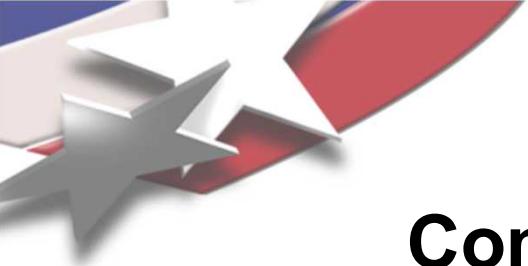
- **Code verification** deals with identifying:
  - Programming mistakes that cause the governing equations to be solved incorrectly, or
  - Shortcomings of formulations or algorithms that cause undesirable behavior in certain situations.
- Code verification involves comparing code output with known solutions.
- **Solution verification** deals with quantifying numerical errors in a given solution.



# Order Verification

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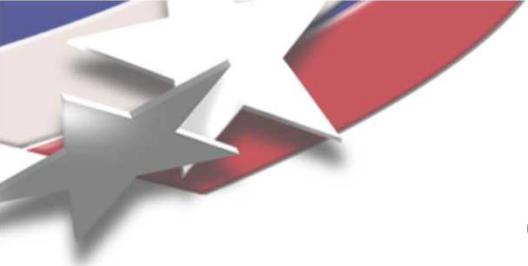
- One thing to verify is **consistency**: does the discrete solution converge to the continuum solution as the mesh is systematically refined?
- A more thorough analysis includes **order verification**: does the observed order of accuracy match the expected order of accuracy?
- Order verification can be performed via
  - the method of exact solutions, for equation sets having classical exact solutions or
  - the method of manufactured solutions (MMS), also known as order verification via the manufactured solution procedure (OVMSp).



# Comparison to Exact Solutions

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1. An exact solution to the governing equations is obtained for a given domain and set of initial/boundary conditions.
2. Numerical solutions are produced using a series of systematically refined spatial and/or time discretizations.
3. The error norms of these numerical solutions are compared to determine the spatial and/or temporal order of accuracy.



# Shortcomings of Using Classical Exact Solutions

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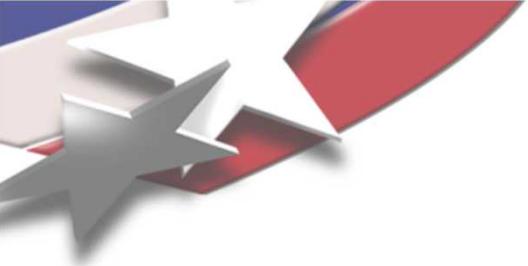
- A classical exact solution may not exist for a given equation set.
- Classical exact solutions which do exist may lack generality and therefore fail to test all of the terms in the governing equations.
- Testing the full suite of boundary conditions may not be possible using classical exact solutions.
- Classical exact solutions which do exist may be difficult to accurately implement (e.g., solutions obtained by Laplace transforms).



# The Method of Manufactured Solutions

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1. Generate (*i.e.*, manufacture) a solution on the domain of interest: it need not satisfy the governing equations, but it needs to satisfy certain constraints (Knupp & Salari, 2003).
2. Operate on this manufactured solution with the differential operator found in the governing equation set.
3. Add the resulting expression to the governing equation set as a source term.
4. Provide this source term to the code, and then proceed with order verification.



## Example

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1) Consider Laplace's Equation :

$$\nabla^2 u = 0.$$

2) Manufacture a solution  $u^*$ .

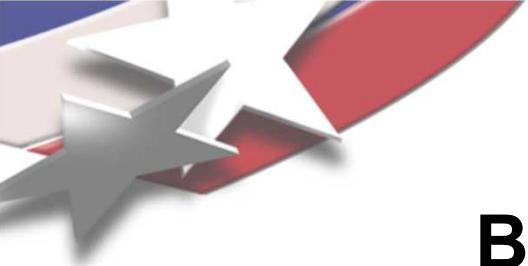
3) Operate (analytically) on  $u^*$  with  $\nabla^2$  :

$$\nabla^2 u^* = f^*.$$

4) Provide the source term  $f^*$  to the code.

5) Run the code with the additional source term to obtain numerical solutions on a series of systematically refined grids.

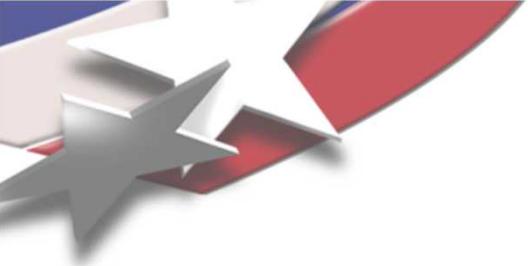
6) Compare the numerical solutions with  $u^*$  to determine the spatial order of accuracy for the code.



# Boundary Condition Issues

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- For general boundary conditions (Dirichlet, Neumann, etc.), code input can be derived from the conditions satisfied by  $u^*$  on the boundary.
- For specialized boundary conditions (a.k.a. hardwired boundary conditions) one way to perform a test is to have  $u^*$  satisfy the boundary conditions in order to test their implementation.
- For hyperbolic and parabolic equation sets, only constraints corresponding to incoming characteristics need to be satisfied.



# Premo

*premo* (Latin) – to squeeze (compress)

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**Develop simulation capabilities to perform compressible flow calculations.**

- Compressible subsonic through hypersonic
- Laminar through turbulent regimes
- Inviscid and viscous flows
- Steady state and transient
  
- Finite Volume
- Node centered
- Edge Based
- Unstructured Mesh



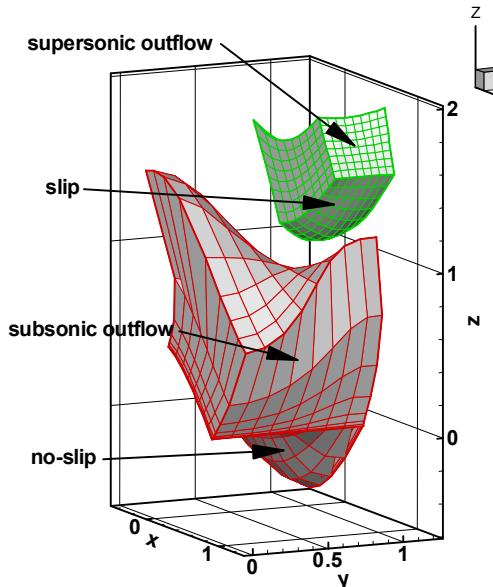
# Meshes Used with Manufactured Solution

## Original

$$F = \frac{1}{2} \cos(A_f x) \cos(B_f y) - z$$

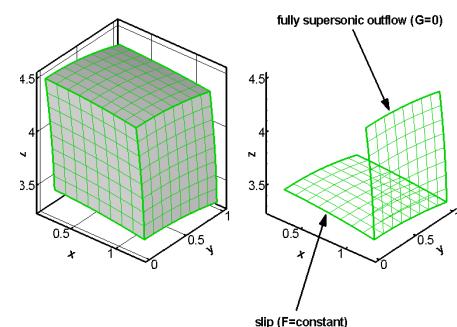
$$G = x - \frac{1}{2} \cos(A_g y) \sin(B_g y) - \frac{\pi}{4}$$

$$H = -y$$



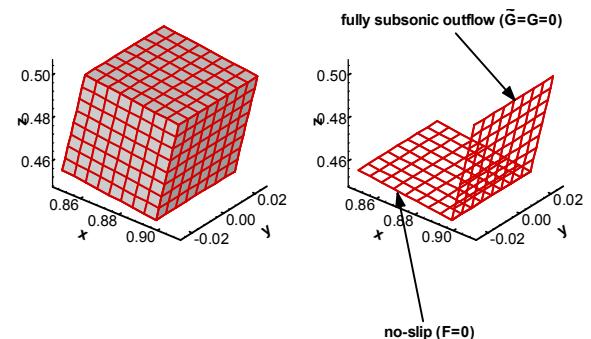
## First Modification

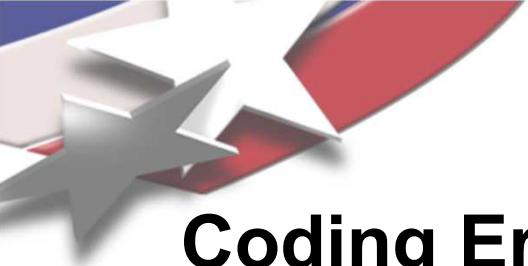
Reduced the wave numbers by 4x  
( $A_f, B_f, A_g$  and  $B_g$ )



## Current

- \* Reduced computational domain by  $\sim 25x$
- \* Created  $\tilde{G}$  to handle  $p \neq \text{constant}$  on outflow BC





# Coding Errors and Algorithmic Weaknesses

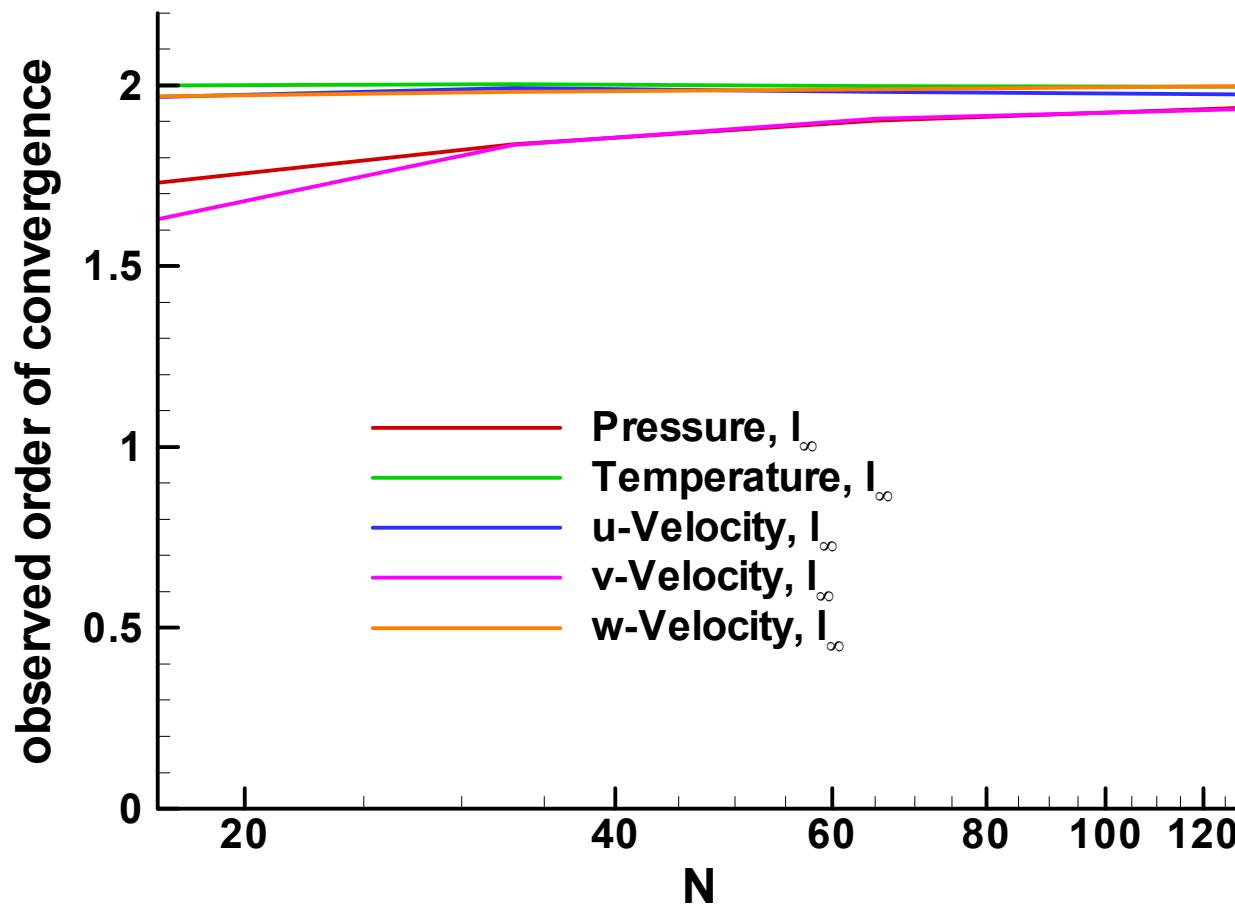
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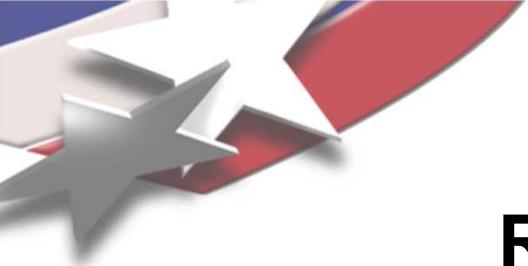
- Coding Errors
  - several parallel issues
  - indexing error for least squares gradient
  - CHAD gradient correction
  - several ‘kinks’ in fast-turnaround tests
  - other ‘bonus’ finds (bugs found while looking for others)
- Algorithmic Weaknesses
  - weak slip and outflow BC formulations
  - numerous gradient issues

# Euler Equations

Inverse Distance Weighted Least Squares

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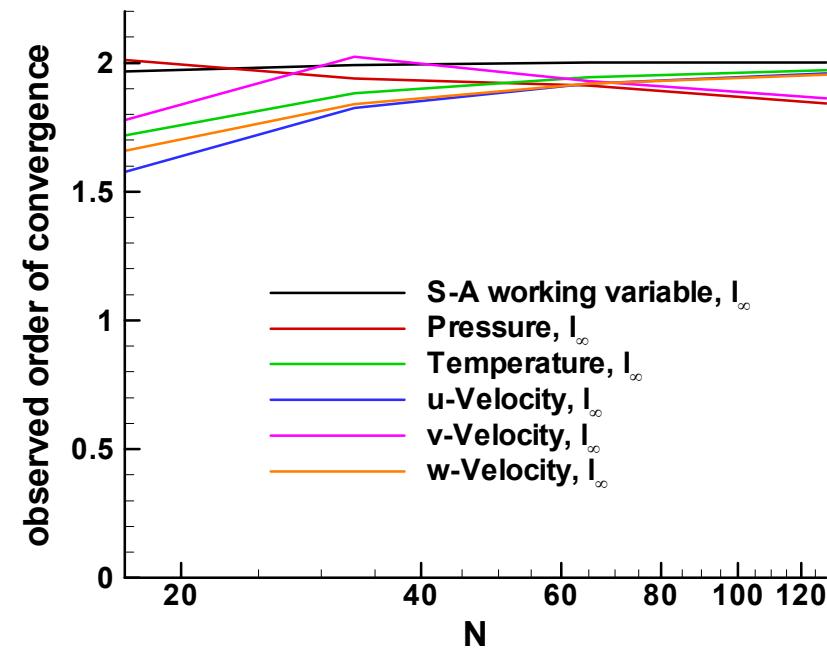




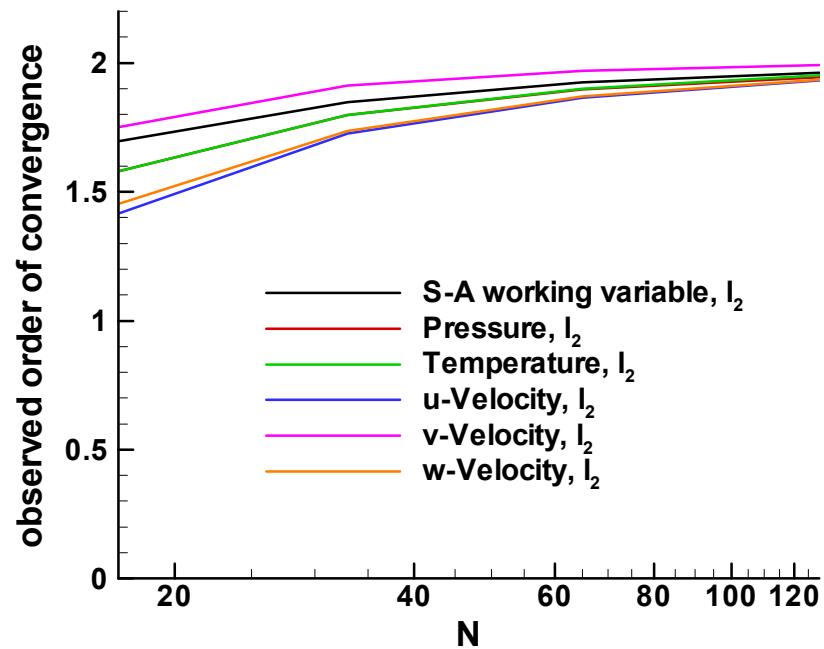
# RANS w/ Spalart-Allmaras

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$l_\infty$  norms

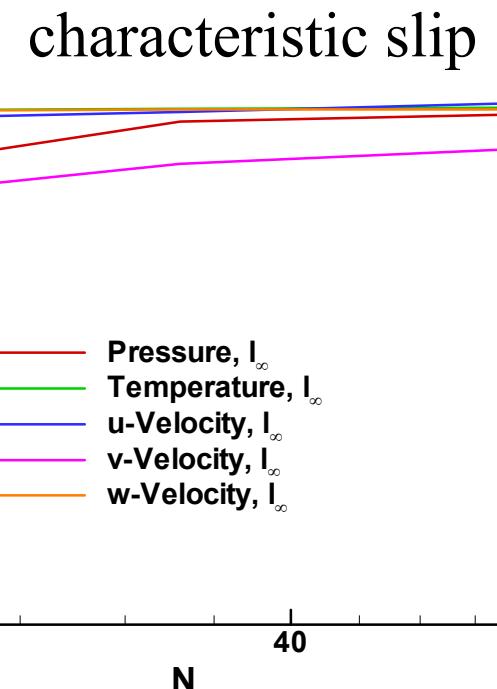
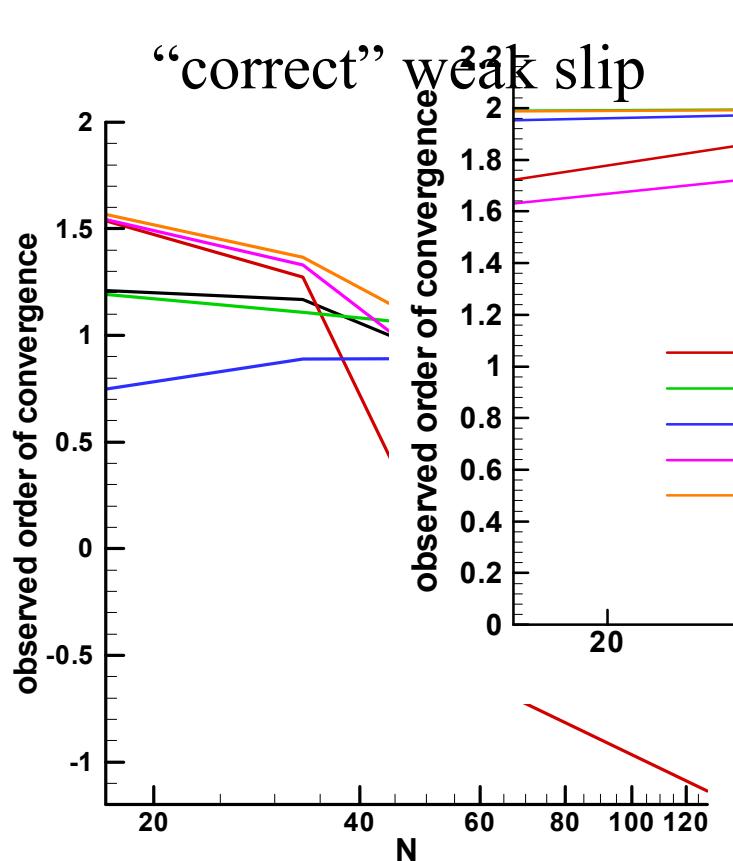
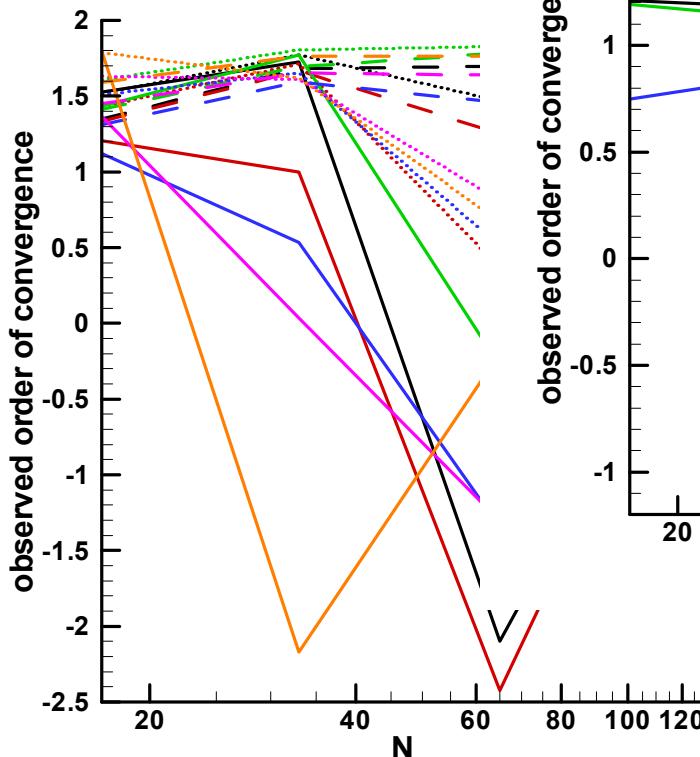


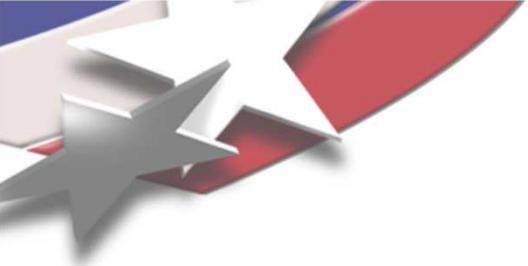
$l_2$  norms



# Slip Condition

weak slip with parallel bug in surface normal

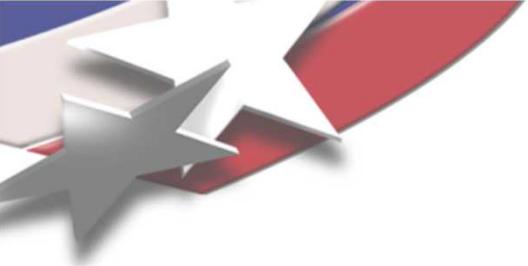




## Fast-Turnaround MMS

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- Formal order verification is often viewed as a certification that takes place very late in the development cycle.
- Once the initial overhead of deriving and implementing manufactured solutions is done, new tests can be run very quickly.
- This fast-turnaround time allows order verification to be used early in the development cycle of new capabilities, especially when only one thing differs from a previous order verification exercise.



## STVD Schemes

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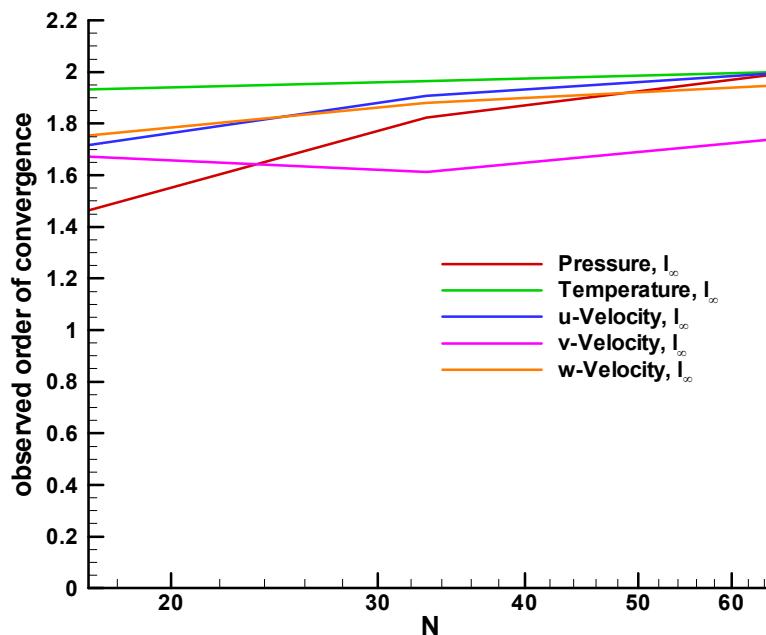
- Robustness issues were observed with MUSCL-based schemes in the edge-based discretization, suspected to be the result of limiter issues.
- These issues were improved with the introduction of a symmetric, total variation diminishing (STVD) scheme, since the limiter is “built-in”.
- Even better robustness was gained from the introduction of a collinear-edge-based STVD.
- 24 candidate formulations of these STVD schemes were tested in a week.
  - verification of correctness complimented other testing
  - head-to-head error comparison on manufactured solution



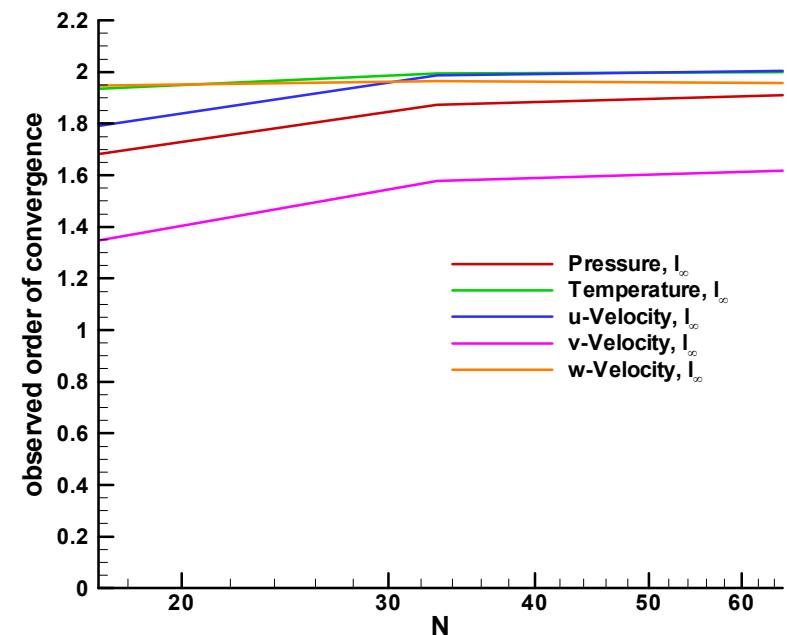
# Order of Accuracy for STVD Schemes

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extrapolation-based

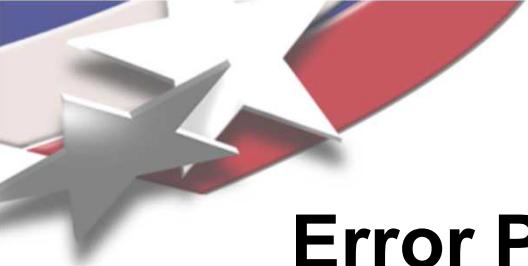


collinear-edge-based



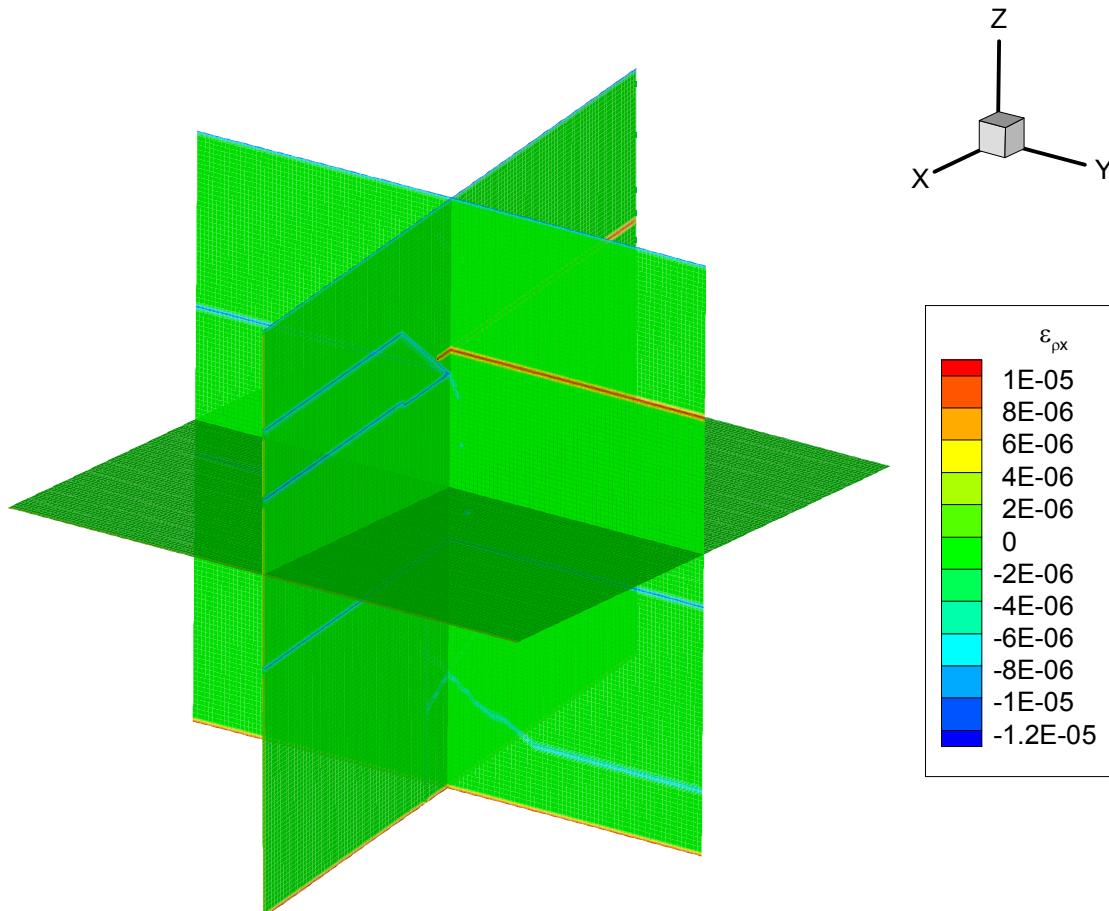
# Gradient Reconstruction Options in Premo

- Nodal gradients are used for
  - extrapolation of variables in MUSCL based schemes,
  - calculation of viscous fluxes, and
  - calculation of turbulence model source terms
- legacy options
  - Green-Gauss (GG) accuracy suffers for high mesh curvature/skewness
  - least squares (LS)
    - equally weighted accuracy suffers for high mesh aspect ratio
    - inverse-distance weighted robustness issues
- new options
  - control volume finite element (CVFEM)
    - three quadrature options
  - finite element least squares (FELS)
    - two options for boundary treatment

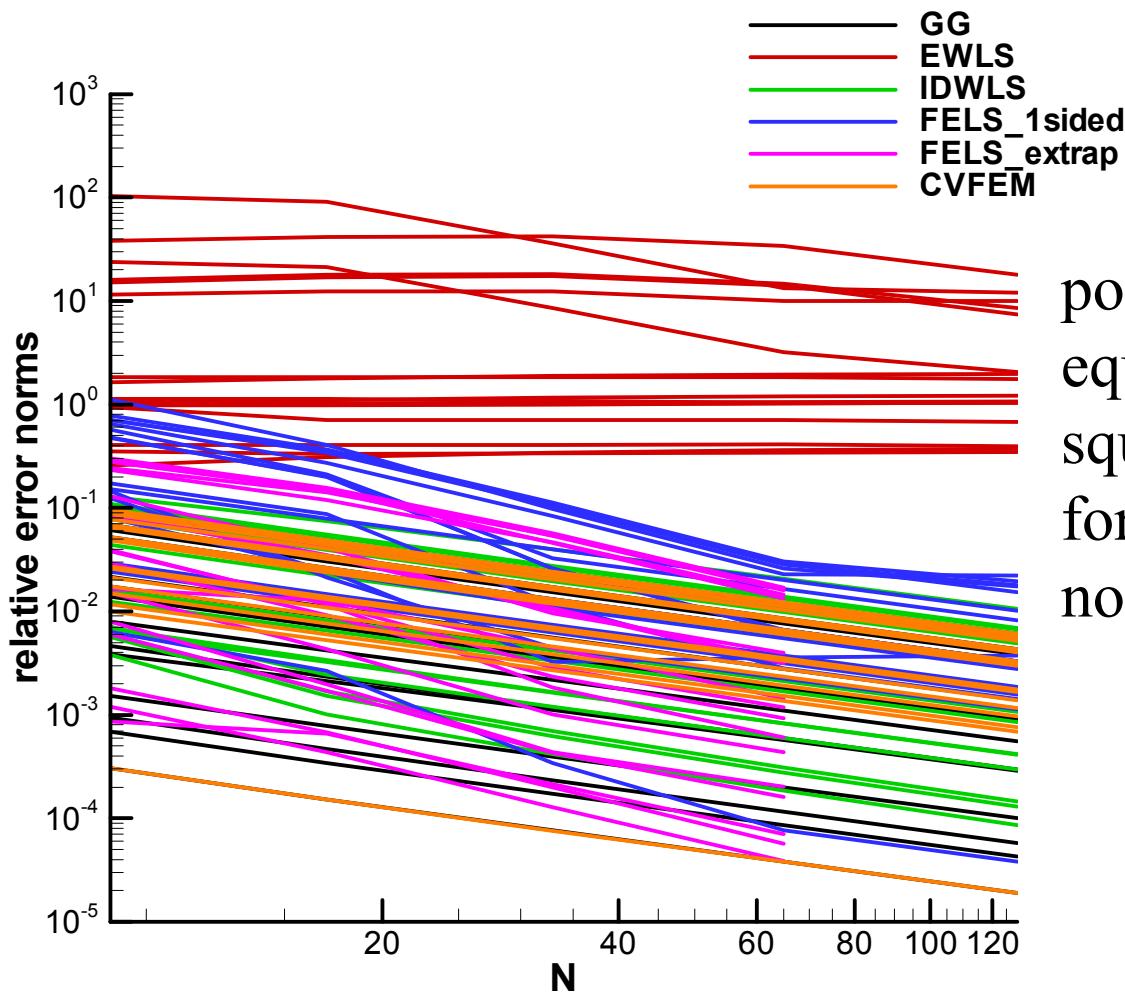


# Error Plot Representing Parallel Issue

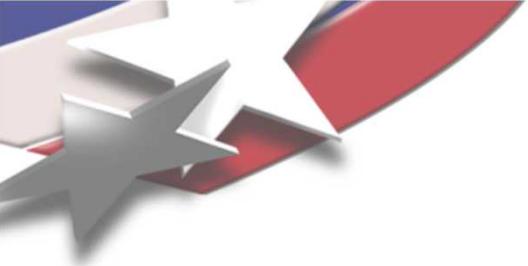
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# Error Norms for High Aspect Ratio Mesh



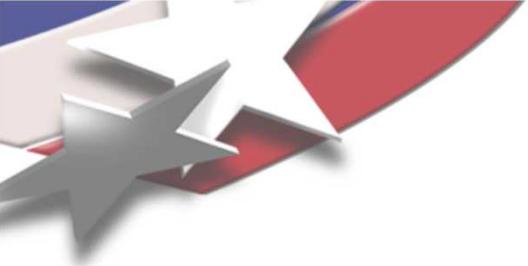
poor accuracy of  
equally weighted least  
squares is a  
formulation weakness,  
not a coding mistake



# Summary

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- Formal order verification via the method of manufactured solutions has been instrumental in the development of Premo.
- Coding mistakes and formulation weaknesses have been detected and addressed.
- Order verification has been integrated into the development process so that new capabilities can be verified as soon as they are implemented.
- Order verification has become instrumental in advancing the state of the art in flux schemes and gradient reconstruction within Premo.



## Selected References

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- “A Manufactured Solution for Verifying CFD Boundary Conditions,” AIAA Paper 2004–2629.
  - Parts II and III, AIAA 2005–0088, 2006–3722.
  - Upcoming AIAA Journal article.
- “Aspects of Reconstruction Schemes on Unstructured Mesh Flow Solvers,” 9:45–10:10 on Wednesday in session MS63, Bristol 3 L.
- *Verification of Computer Codes in Computational Science and Engineering*, Knupp & Salari