

Saddle-Point Preconditioners Based on Commutators

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Outline

- Incompressible Navier-Stokes
- Differential Commuting
 - Pressure Convection Diffusion (PCD) Preconditioning
 - BFBT method
- Some Computational Results
- Discrete Issues
 - Mass Matrices
 - BFBT $\Rightarrow$ Least Squares Commutator (LSC)
 - Stabilization
 - Boundary Conditions
- Modified PCD & LSC Methods
- Computational Results

Incompressible Navier-Stokes

$$\alpha u_t - \nu \nabla^2 u + (u \cdot \text{grad})u + \text{grad } p = f$$
$$\text{div } u = 0$$

Continuous

$$\begin{pmatrix} F & B^T \\ B & 0 \end{pmatrix} \begin{pmatrix} u \\ p \end{pmatrix} = \begin{pmatrix} f \\ 0 \end{pmatrix}$$

Discrete

$$\begin{pmatrix} F & B^T \\ B & -C \end{pmatrix} \bar{u} = rhs$$

$C \neq 0$: stabilized

Use preconditioner of form

$$\begin{pmatrix} Q_F & B \\ 0 & -Q_S \end{pmatrix}$$

with Krylov subspace method (GMRES)

Schur Complement & Commuting

How to precondition the Schur complement, $S = -\mathcal{B} F^{-1} \mathcal{B}^\top$?

Suppose

$$\mathcal{B}^\top F_p = F \mathcal{B}^\top \quad \& \quad \mathcal{M}^{-1} = -F_p (\mathcal{B} \mathcal{B}^\top)^{-1}$$

$\Rightarrow$

$$S \mathcal{M}^{-1} = I$$

Also

$$F_p \mathcal{B} = \mathcal{B} F \quad \& \quad \mathcal{M}^{-1} = -(\mathcal{B} \mathcal{B}^\top)^{-1} F_p$$

$\Rightarrow$

$$\mathcal{M}^{-1} S = I$$

Is there hope for $\mathcal{F}_p \mathcal{B} = \mathcal{B} \mathcal{F}$?

Consider

$$\mathcal{F} = \begin{bmatrix} \mathcal{F}_p & 0 \\ 0 & \mathcal{F}_p \end{bmatrix} \quad \mathcal{B}^T = \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \end{pmatrix}$$

and

$$\mathcal{F}_p = \frac{\partial}{\partial t} + v \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) + c_1 \frac{\partial}{\partial x} + c_2 \frac{\partial}{\partial y}$$

$\Rightarrow$

$$\mathcal{F}_p \mathcal{B} = \mathcal{B} \mathcal{F}$$

Preconditioners

PCD

$$\mathcal{M}^{-1} = -F_p (\mathcal{B} \mathcal{B}^T)^{-1} \quad \Rightarrow \quad \mathbf{M}^{-1} = (\mathbf{M}_p)^{-1} F_p (\mathbf{A}_p)^{-1}$$

where

$\mathbf{M}_p$: pressure mass matrix

$\mathbf{A}_p$: Laplace Operator

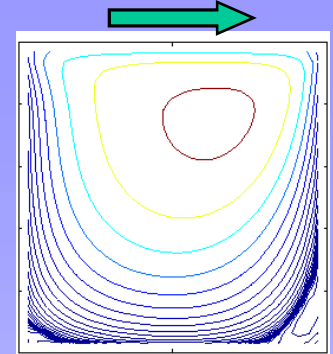
F_p : convection-diffusion operator

BFBT

$$\mathbf{M}^{-1} = (\mathbf{B} \mathbf{B}^T)^{-1} \mathbf{B} \mathbf{F} \mathbf{B}^T (\mathbf{B} \mathbf{B}^T)^{-1}$$

$$\mathbf{M}^{-1} = (\mathbf{A}_p)^{-1} \mathbf{B} \mathbf{F} \mathbf{B}^T (\mathbf{A}_p)^{-1}$$

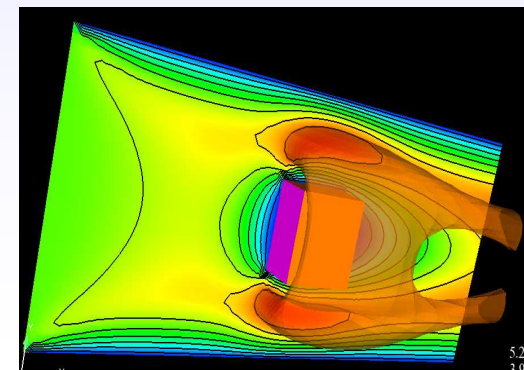
Re	Mesh	DD	PC-D	Proc
10	32x32x32	67.0 (634.6)	28.0 (803.2)	1
	64x64x64	159.8 (1507.5)	28.4 (865.2)	8
	128x128x128	356.2 (4529.3)	29.1 (1103.2)	64
100	32x32x32	61.7 (730.7)	56.0 (1232.7)	1
	64x64x64	168.5 (2131.6)	62.1 (1697.8)	8
	128x128x128	404.6 (6953.9)	67.9 (2487.3)	64



- GMRES
- Inexact F^{-1} & A_p^{-1} via AMG
- DD uses ILUT
- Newton's Method

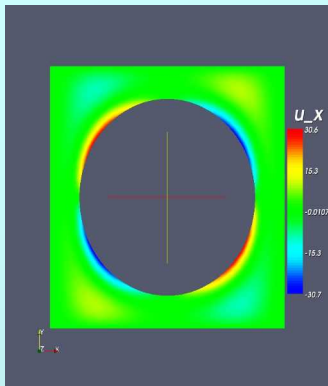
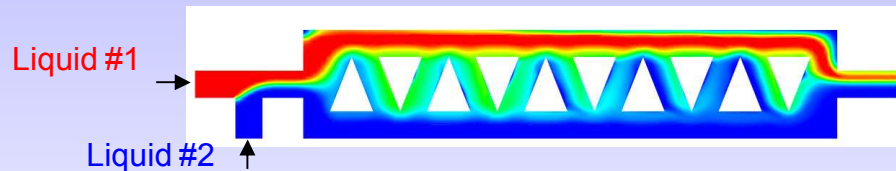
Average outer iterations per Newton step. (*) is the total CPU time for the experiment

Re	Mesh	DD	PC-D	Nprocs
10	270K	67.2 (859.8)	20.7 (997.7)	1
	2.1 M	151.2 (2004.1)	21.7 (1507.5)	8
	16.8 M	667.2 (20908.0)	24.7 (1997.7)	64
50	270K	69.4 (889.2)	35.9 (1209.1)	1
	2.1 M	132.4 (2676.1)	38.7 (1797.2)	8
	16.8 M	637.2 (18646.0)	44.7 (2397.7)	64



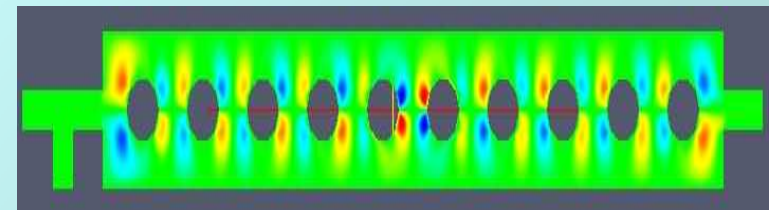
Microfluidic Results

- Bio-briefcase
 - Mix liquids at low Re by induced charge electro osmosis
 - Optimize shape & topology of mixing obstructions



Re	Unknowns	PC-D
1	140K	52.1
	320K	51.2
20	140K	57.2
	320K	56.3

Re	Unknowns	PC-D
1	62K	64.0
	256K	62.1
20	62K	68.0
	256K	67.9
50	62K	77.0
	256K	74.9



Research Topics

➤ Discrete vs. Differential Commuting

- BFBT $\Rightarrow$ Least Squares Commutator (LSC)

===== Book by Elman, Silvester, Wathen=====

➤ Stabilization

- S-LSC

➤ Boundary Conditions

- Weighted LSC & Modified PCD

LSC: Discrete vs. Differential Commuting

$$F_p \mathcal{B} = \mathcal{B} F \quad \not\Rightarrow \quad F_p B = B F \quad \text{as} \quad B \not\approx \mathcal{B}, \quad F \not\approx \mathcal{F}$$

e.g. F.E's mass matrices play a role

Recall $\mathcal{M}^{-1} = -F_p (\mathcal{B}\mathcal{B}^T)^{-1}$

- Approximate $\mathcal{B}\mathcal{B}^T$ via $A_p = B (M_v)^{-1} B^T$
- Approximate F_p via normal equations solution to

$$\Rightarrow \left\| [M_v^{-1} F M_v^{-1} B^T]_j - M_v^{-1} B^T [M_p^{-1} F_p]_j \right\|_{M_v}$$

$$M^{-1} = \underbrace{(A_p)^{-1} B (M_v)^{-1} F (M_v)^{-1} B^T (A_p)^{-1}}_{\begin{matrix} F_p & F_p \end{matrix}}$$

Stabilization

$$\begin{pmatrix} F & B^T \\ B & -C \end{pmatrix}$$

- $(BB^T)^{-1}$ is unstable
 - Amplifies high frequencies
 - C effectively stabilizes $(B F^{-1} B^T)$
- Preconditioner $(A_p)^{-1} B (M_v)^{-1} F (M_v)^{-1} B^T (A_p)^{-1}$ needs stabilization
 - Best to design new stabilization matrix
 - Using C for preconditioner stabilization keeps method algebraic
 - Not really designed for BB^T
 - S-LSC:

$$(A_p)^{-1} B (M_v)^{-1} F (M_v)^{-1} B^T (A_p)^{-1} + \alpha D$$

$$\text{with } A_p = B (M_v)^{-1} B^T + \gamma C$$

$\Rightarrow$ simple formulas for α and γ obtained by constant coefficient analysis

Oseen

Q_2-Q_1

Re	F_p	LSC
10	33	23
100	58	29
200	63	29

Size(n=7)

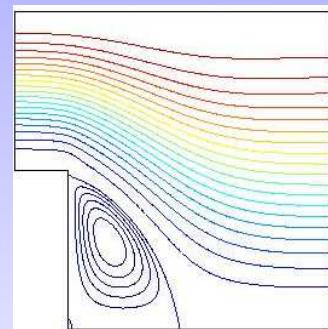
grid $2^n \times 3(2^n)$

Newton

Q_1-P_0

	F_p			S-LSC		
Size (n)	4	5	6	4	5	6
Re 10	29	35	37	12	16	22
Re 100	62	66	79	21	19	25
Re 200	94	92	100	35	26	27
Re 10	27	32	35	13	19	26
Re 100	57	61	76	18	19	28
Re 200	89	84	93	31	22	29

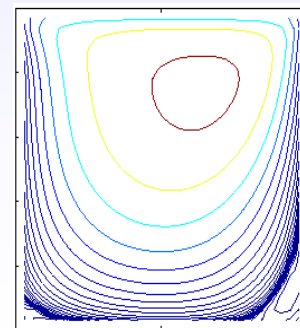
Q_1-Q_1



Oseen

MAC

	F_p		LSC	
	64x64	128x128	64x64	128x128
Re 10	6	6	7	9
Re 100	18	16	18	23
Re 1000	51	52	40	49



Boundary Conditions

PCD (F_p & A_p):

Dirichlet @ inflow

Neumann otherwise

LSC implicitly defines bcs

LSC's $A_p \Rightarrow$ Neumann at inflow

Observation:

$$\mathcal{F} = \begin{bmatrix} \mathcal{F}^{(u_1)} & 0 \\ 0 & \mathcal{F}^{(u_2)} \end{bmatrix}$$

$$\mathcal{E} = \mathcal{B}\mathcal{F} - \mathcal{F}_p\mathcal{B}$$

$$= [\mathcal{B}_x \mathcal{F}^{(u_1)} - \mathcal{F}_p \mathcal{B}_x, \quad \mathcal{B}_y \mathcal{F}^{(u_2)} - \mathcal{F}_p \mathcal{B}_y]$$

$$= [(1) + (2), \quad (3) + (4)]$$

$$(1) \quad \mathcal{B}_x \mathcal{F}_x^{(u_1)} - \mathcal{F}_x^{(p)} \mathcal{B}_x$$

$$(2) \quad \mathcal{B}_x \mathcal{F}_y^{(u_1)} - \mathcal{F}_y^{(p)} \mathcal{B}_x$$

$$(3) \quad \mathcal{B}_y \mathcal{F}_x^{(u_2)} - \mathcal{F}_x^{(p)} \mathcal{B}_y$$

$$(4) \quad \mathcal{B}_y \mathcal{F}_y^{(u_2)} - \mathcal{F}_y^{(p)} \mathcal{B}_y$$

$$(1) \mathcal{B}_x \mathcal{F}_x^{(u_1)} - \mathcal{F}_x^{(p)} \mathcal{B}_x$$

Composite operators $\mathcal{B}_x \mathcal{F}_x^{(u_1)}$

with $\mathcal{F}_x^{(u_1)} \mathbf{u} = -\nu \mathbf{u}_{xx} + c_1 \mathbf{u}$

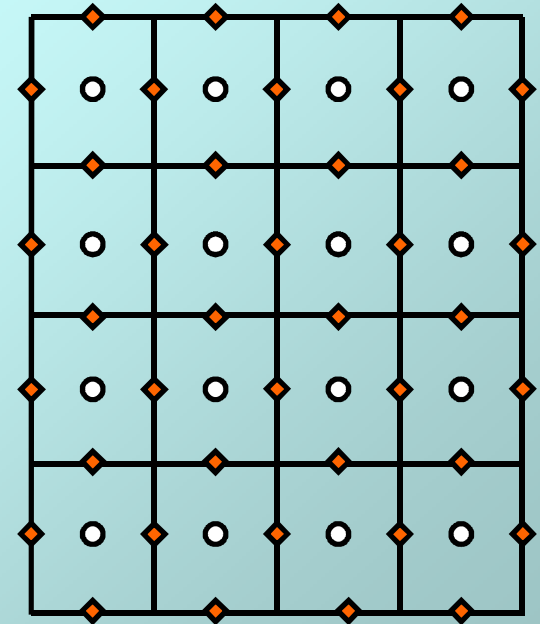
Now assume $\mathcal{F}_x^{(u_1)} \mathbf{u} \Rightarrow \mathbf{u}(0, y) = 0$

Observe that $\hat{\mathbf{u}} = \mathcal{F}_x^{(u_1)} \mathbf{u}$ implies

$$\hat{\mathbf{u}} = \left(-\nu \frac{\partial}{\partial x} + c_1\right) \mathbf{u}_x = \left(-\nu \frac{\partial}{\partial x} + c_1\right) \mathcal{B}_x \mathbf{u}$$

$$\mathcal{B}_x \mathcal{F}_x^{(u_1)} = \mathcal{F}_x^{(p)} \mathcal{B}_x$$

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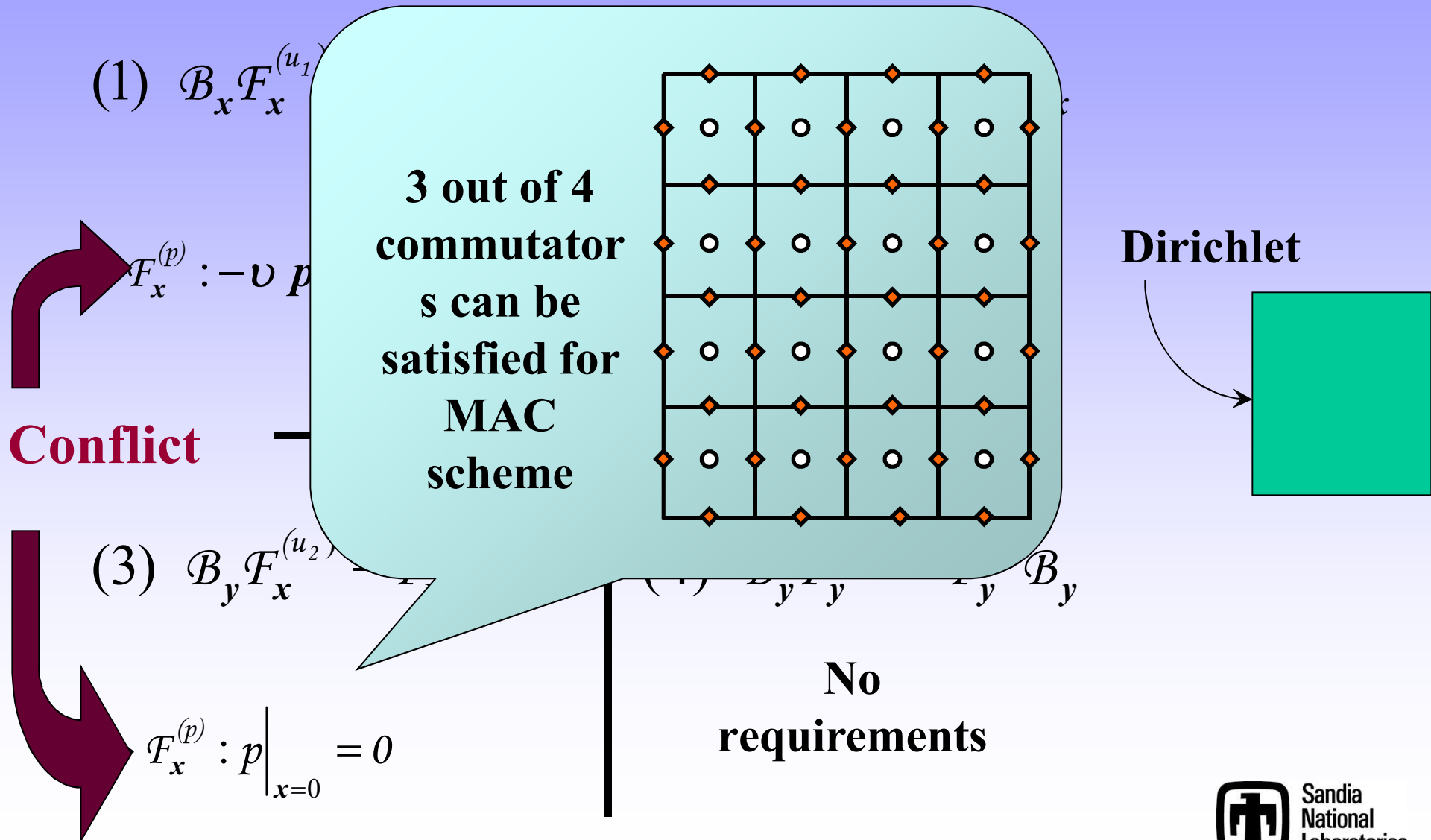


$\Rightarrow \mathcal{F}_x^{(p)}$ should enforce Robin condition $-\nu p_x + c_1 p = 0$

Notice that $\mathbf{u}(0, y) = 0 \not\Rightarrow \mathbf{p}(0, y) = 0$ with $\mathbf{p} = \mathcal{B}_x \mathbf{u}$

High Re $\approx$ Dirichlet, low & characteristic $\approx$ Neumann

Dirichlet bcs & 4 commutators



Which commutators are important?

Perturbation Analysis

- Constant co

Let $Y = F_p S M$

Y

Y

⊥ more important @ Dirichlet!

⇒ inflow bcs

* Robin

⇒ characteristic bcs

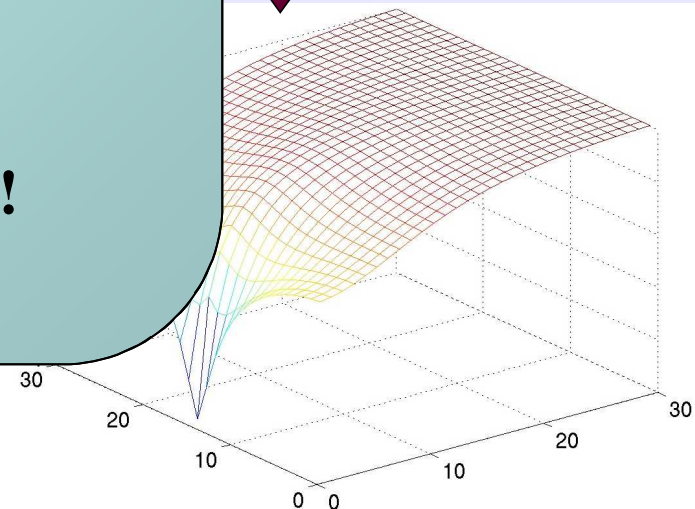
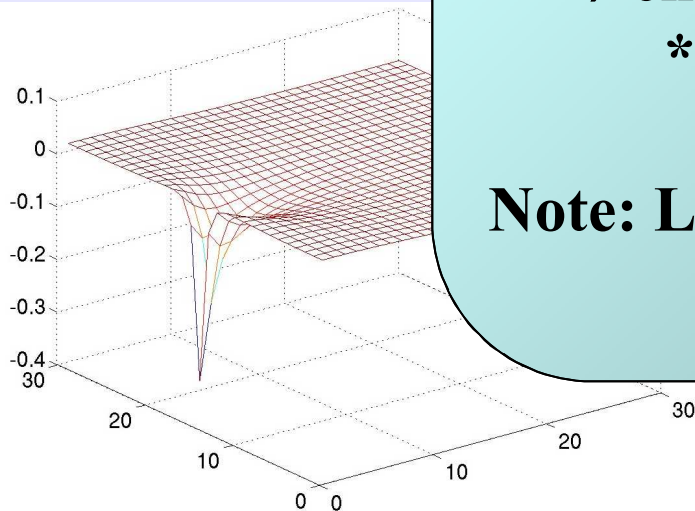
* Neumann

Note: LSC weights equally!

left bc

$$Y = \begin{pmatrix} \text{---} \\ \text{---} \\ \text{---} \\ 0 \\ \text{---} \\ \text{---} \\ \text{---} \end{pmatrix}$$

right bc



What about outflow?

$$F \ \& \ B : \quad v(u_1)_x = p \quad (u_2)_x = 0$$

- Perturbation analysis:
- B_x & B_y make no special assumptions @ bc
- unclear whether $Y^\perp$ or $Y^\parallel$ is more significant
- PDE arguments $\Rightarrow$ satisfy (1) via Dirichlet (3) via Neumann
- Discrete setting must also be considered
- We'll show some experiments

Weighted LSC

$$\min \| B (Q_v)^{-1} F]_j - [X]_j B \|_H$$

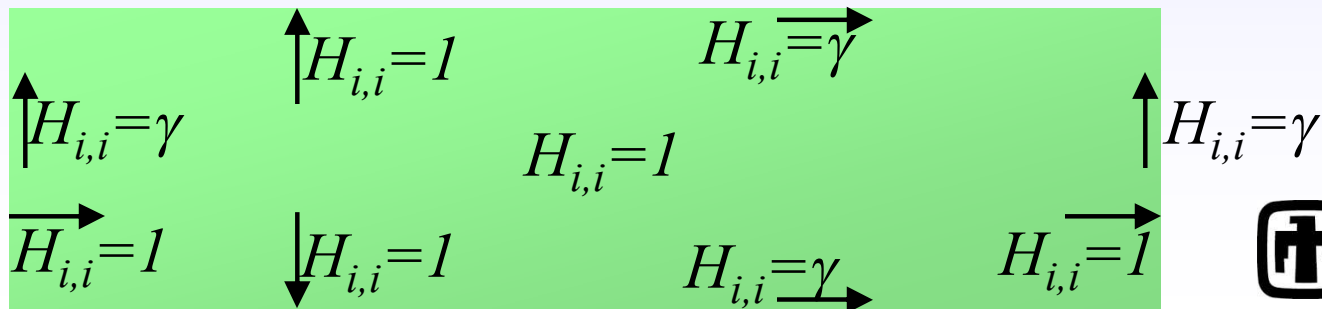
with

$$H = W'^{\frac{1}{2}} (Q_v)^{-1} W'^{\frac{1}{2}}, \quad [X]_j \text{ is } j^{\text{th}} \text{ row of } F_p$$

If $Q_v = I$

$$\Rightarrow M^{-1} = (A_p)^{-1} B H F B^T (B H B^T)^{-1}$$

Consider diagonal matrix for H with entries 1 or γ ($\gamma < 1$)



Results

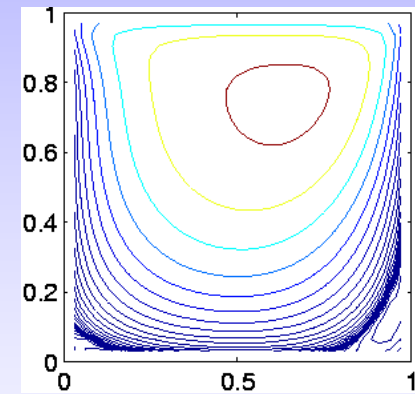
Conclusions

- Preconditioners based on commutators can give mesh independent convergence rates
- But ... getting the details right can be important
 - Discrete commuting (mass matrix)
 - Stability issues
 - Boundary conditions
- Two new/modified methods
 - New bcs for PCD
 - W-LSC

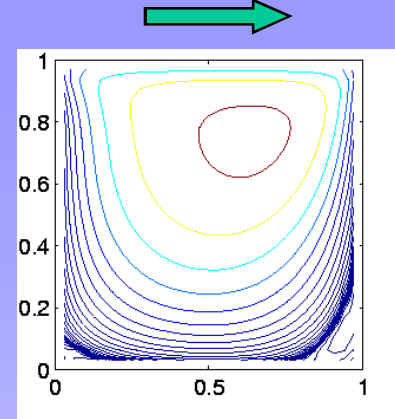
Lid Driven Cavity Results

	Old PCD			New PCD		
Mesh	32x32	64x64	128x128	32x32	64x64	128x128
Re = 10	15	15	15	16	16	16
Re = 100	25	26	26	26	25	25
Re = 400	41	41	39	53	39	37
Re = 1000	76	65	55	82	71	53

	Old LSC			New LSC		
Mesh	32x32	64x64	128x128	32x32	64x64	128x128
Re = 10	11	14	18	9	9	10
Re = 100	16	21	27	14	14	13
Re = 400	31	30	35	31	26	22
Re = 1000	62	55	45	67	58	40



Lid Driven Cavity



Re	Mesh	DD	PC-D	Proc
10	128 x 128	220.6	21.2	4
	256 x 256	467.2	23.0	16
500	128 x 128	334.9	74.5	4
	256 x 256	896.1	76.3	16
1000	128 x 128	352.5	126.4	4
	256 x 256	839.5	126.6	16

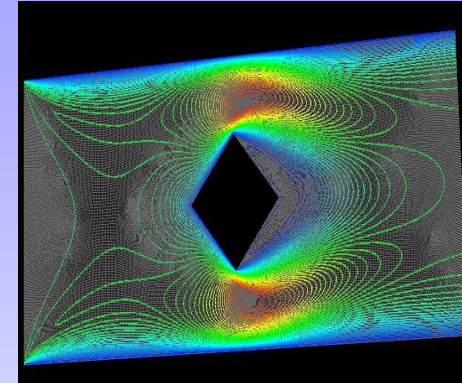
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- Newton's Method
- GMRES
- Inexact F^{-1} & A_p^{-1} via AMG
- DD uses ILUT

Average outer iterations per Newton step. (*) is the total CPU time for the experiment

Flow over Obstruction

Re	DOFs	DD	PC-D	Nprocs
10	256K	282.6 (1054.9)	22.6 (192.7)	4
	1M	890.2 (6187.4)	25.6 (252.3)	16
	4M	NC (NC)	29.7 (397.5)	64
40	256K	203.9 (1269.3)	68.9 (975.2)	4
	1M	770.0 (6933.5)	72.7 (1039.6)	16
	4M	NC (NC)	78.3 (1528.6)	64



Re	Mesh	DD	PC-D	Nprocs
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	2.1 M	151.2 (2004.1)	21.7 (1507.5)	8
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