



Quantifying the Agreement between Microstructural Plasticity Simulations and Experiment

Luke N. Brewer, Corbett C. Battaile, Remi
Dingreville, and Tim J. Bartel

Sandia National Laboratories

Acknowledgements: Thanks for help from Brad Boyce and Tom Buchheit.

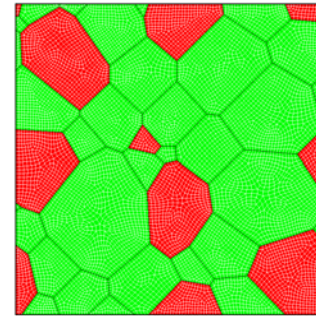
Sandia is a multiprogram laboratory operated by Sandia Corporation, a Lockheed Martin Company, for the United States Department of Energy (DOE) under contract DE-AC0494AL85000.

Modeling Plasticity at the Continuum Scale

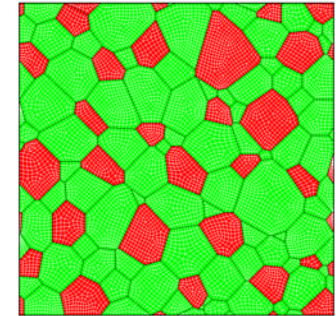


- Structural finite element codes are continuum based—parameterized models
- For local, polycrystalline plasticity (PP) models, predicted σ - ϵ results from two different grain sizes are similar

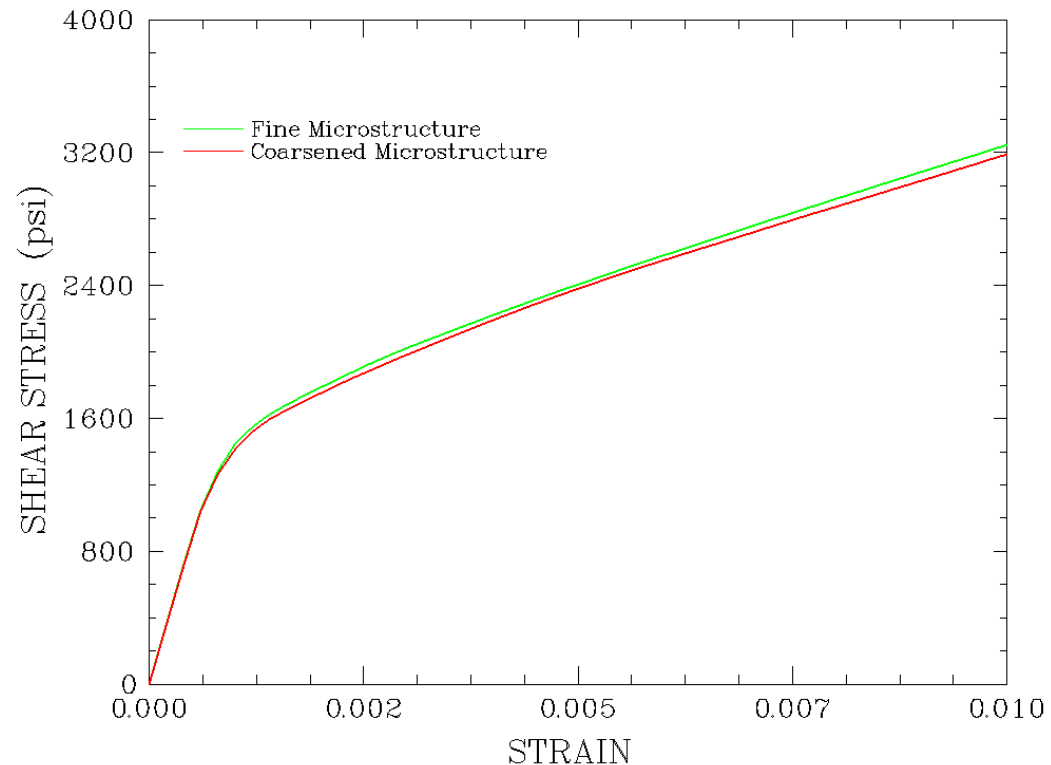
We need models and experiments that possess sensitivity to microstructure!



150 um



3.4 um



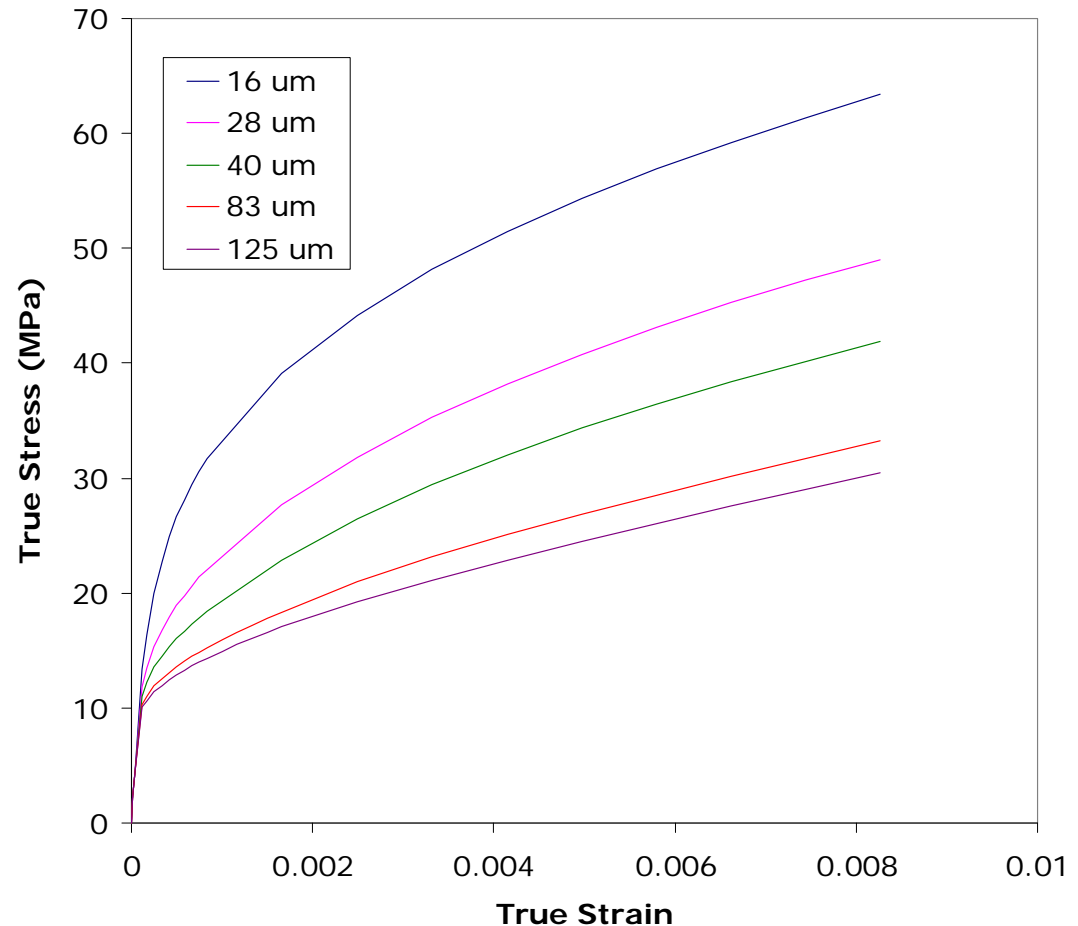
Non-local Plasticity Model

Non-Local Model

- Newly implemented with GND* initialization—misorientation at grain boundaries sets GND densities
- Integral of GND densities provides length scale
- Elastic behavior is independent of grain size.
- Yield strength increases as grain size decreases.
- Predicts Hall-Petch behavior with exponent of -1

Counts, WA, et al. "Intl. J. Solids and Structures; 2007; vol.44, no.17, p.5742-51

*Geometrically Necessary Dislocations

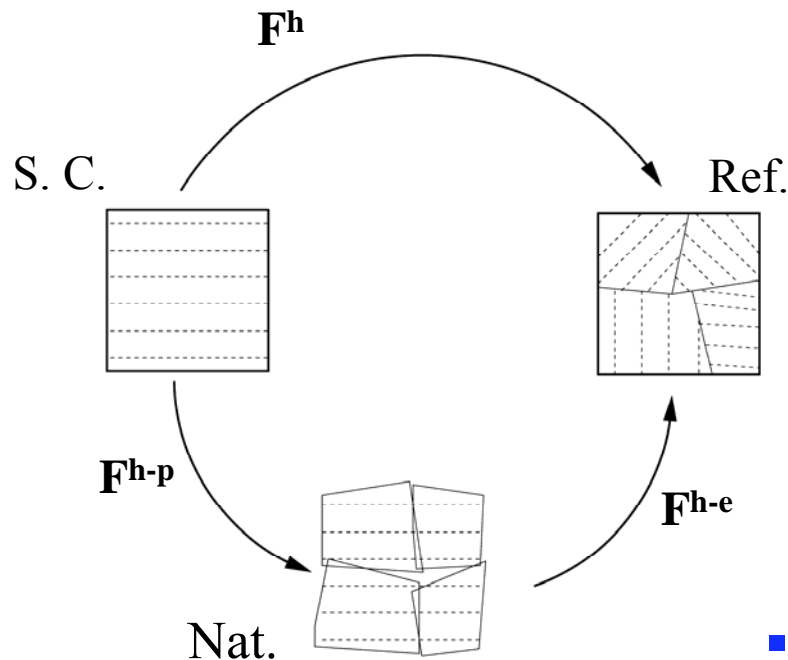


Non-local model produces continuum level results that resemble experiment, but what about the micro-scale??

Polycrystal Kinematics

- Define an Initial Dislocation Tensor

Preliminary Kinematics



$$\tilde{\mathbf{G}}_0 \rightarrow \frac{1}{\text{Det}[\mathbf{F}^{h-e}]} \mathbf{F}^{h-e-1} \text{Curl } \mathbf{F}^{h-e-1}$$

$$\text{Det}[\mathbf{F}^{h-p}] \mathbf{F}^{h-p} \text{Curl } \mathbf{F}^{h-p}$$

$$\tilde{\mathbf{G}}_0 = \frac{1}{\text{Det}[\mathbf{F}^{h-e}]} \mathbf{F}^{h-e-1} \text{Curl } \mathbf{F}^{h-e-1}$$

- $\mathbf{F}^{h-e} = \mathbf{R}^{h-e} \mathbf{U}^{h-e}$

- Assume Ref. is stress free: $\mathbf{U}^{h-e} = \mathbf{I}$

$$\tilde{\mathbf{G}}_0 = \mathbf{R}^{h-e-1} \text{Curl } \mathbf{R}^{h-e-1}$$

\mathbf{R}^{h-e} = orientation of each grain

- Define a Deformation Dislocation Tensor

$$\hat{\mathbf{G}} = \frac{1}{\text{Det}[\mathbf{F}^p]} \mathbf{F}^p \text{Curl } \mathbf{F}^p$$

- Define a Total Dislocation Tensor

$$\hat{\mathbf{G}}^{\text{Tot}} = \mathbf{F}^p \mathbf{R}^{h-e} \tilde{\mathbf{G}}_0 \mathbf{R}^{h-eT} \mathbf{F}^{p-1} + \hat{\mathbf{G}}$$



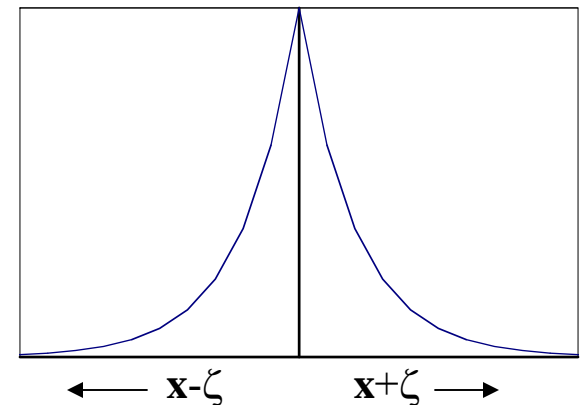
Non-Local Integral Method

Define a non-local curl

$$\{\text{Curl } \mathbf{H}\}_{jk} \equiv \epsilon_{irs} \frac{\int_V \left(H_{js}(\mathbf{x} + \boldsymbol{\zeta}) - H_{js}(\mathbf{x}) \right) \zeta_k \text{Exp} \left[-\frac{1}{\omega} \sqrt{\zeta_1^2 + \zeta_2^2 + \zeta_3^2} \right] dV}{\int_V \zeta_r \zeta_k \text{Exp} \left[-\frac{1}{\omega} \sqrt{\zeta_1^2 + \zeta_2^2 + \zeta_3^2} \right] dV}$$

$\boldsymbol{\zeta}$ = local coordinates centered at \mathbf{x}

- Exponentials ensure $\{\text{Curl } \mathbf{H}\}$ is convergent
- ω represents the distance over which interactions are felt \rightarrow **LENGTH SCALE**



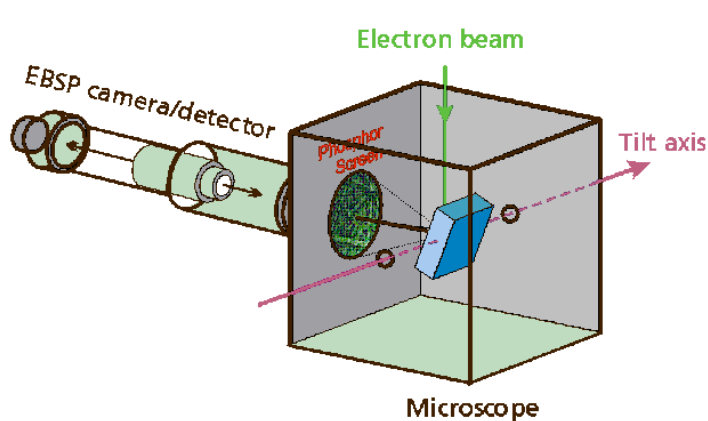
The Non-Local Integral Based Dislocation Tensors

$$\{\hat{\mathbf{G}}\} = \frac{1}{\text{Det}[\mathbf{F}^P]} \mathbf{F}^P \{\text{Curl } \mathbf{F}^P\} \quad \{\tilde{\mathbf{G}}\} = \mathbf{R}^{h-e^{-1}} \{\text{Curl } \mathbf{R}^{h-e^{-1}}\}$$

Combined Study of Microstructural Plasticity Evolution

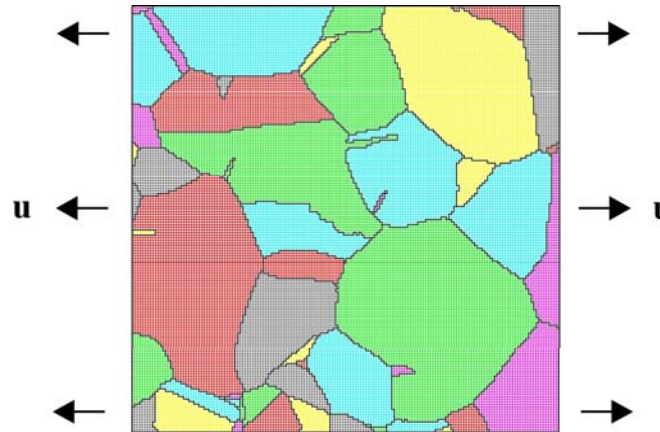
Experimental

- Annealed Ni (99.9%) polycrystal
- Interrupted Tensile Test
 - 0%, 1%, 5%, 10% Strain
- EBSD data @ same location
 - Zeiss Supra 55 VP-FEG SEM
 - 20keV, 0.5 μ m steps, 500x500
 - 3 areas on three tensile samples



Simulation

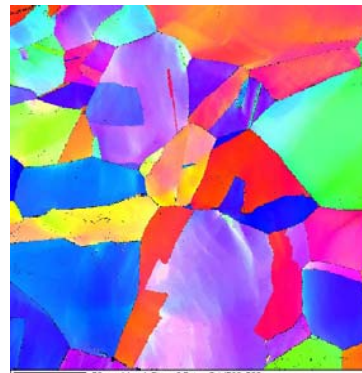
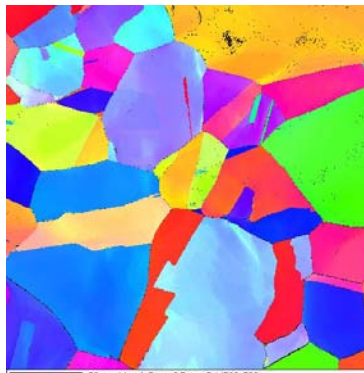
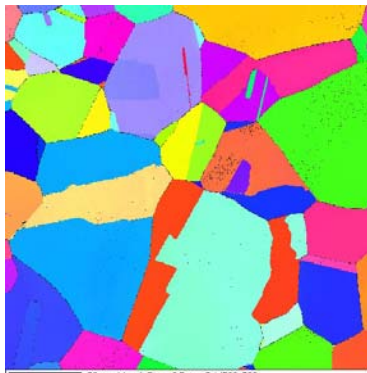
- Meshed the initial microstructure from EBSD*
- Ran both the local and non-local models to 10% strain
- Sandia JAS3D FEM platform, periodic boundary conditions in z.



1% strain

5% strain

10% strain



*Electron backscattered diffraction

EBSD: A technique for crystallography in SEM

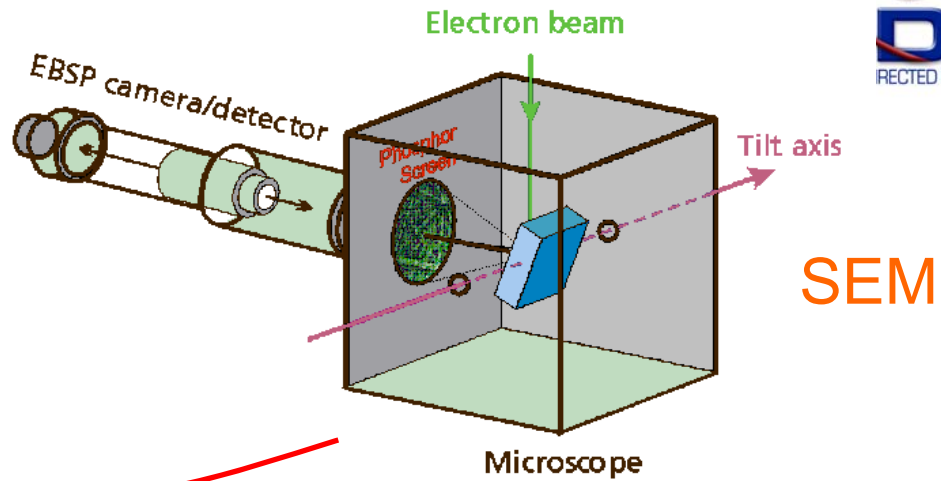
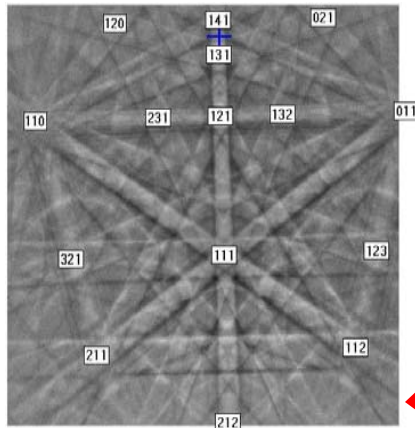
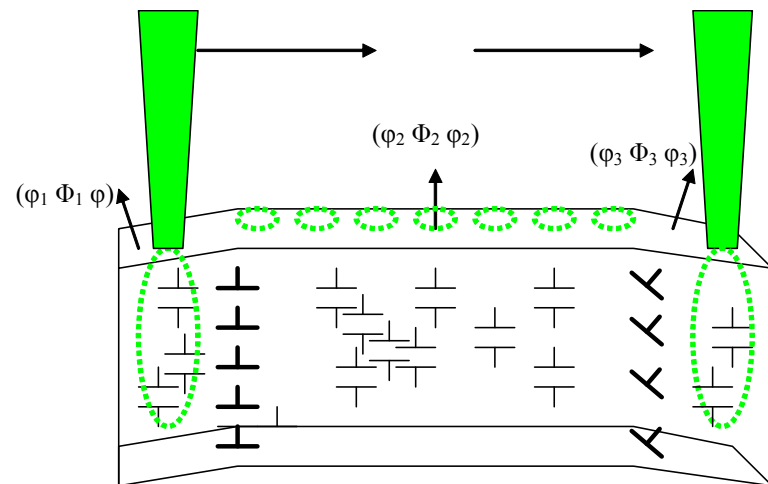


Figure courtesy of J. Sutliff

$$G_i = \begin{pmatrix} \cos(\phi_1) \cdot \cos(\phi_2) - \sin(\phi_1) \cdot \sin(\phi_2) \cdot \cos(\Phi) & \sin(\phi_1) \cdot \cos(\phi_2) + \cos(\phi_1) \cdot \sin(\phi_2) \cdot \cos(\Phi) & \sin(\phi_2) \cdot \sin(\Phi) \\ -\cos(\phi_1) \cdot \sin(\phi_2) - \sin(\phi_1) \cdot \cos(\phi_2) \cdot \cos(\Phi) & -\sin(\phi_1) \cdot \sin(\phi_2) + \cos(\phi_1) \cdot \cos(\phi_2) \cdot \cos(\Phi) & \cos(\phi_2) \cdot \sin(\Phi) \\ \sin(\phi_1) \cdot \sin(\Phi) & -\cos(\phi_1) \cdot \sin(\Phi) & \cos(\Phi) \end{pmatrix}$$



$$M = G_1^{-1} \cdot G_2$$

$$\theta = \cos^{-1} \left(\frac{M_{11} + M_{22} + M_{33} - 1}{2} \right)$$

Some Major Concerns (among many) when comparing experimental and computational microstructural plasticity....

- Fidelity of physical model (usually where all of the effort goes)
 - Dimensions of volumes to be compared (experiments usually plane stress, simulations usually plane strain)
 - Boundary Conditions (are the tractions on the edges of the grain the same as the macro tractions applied on the edges of the bar???)
 - Coordinate Systems (Eulerian vs Lagrangian)
 - What do I compare and how do I compute it???
- Average microstructural metrics
 - Microscale comparisons

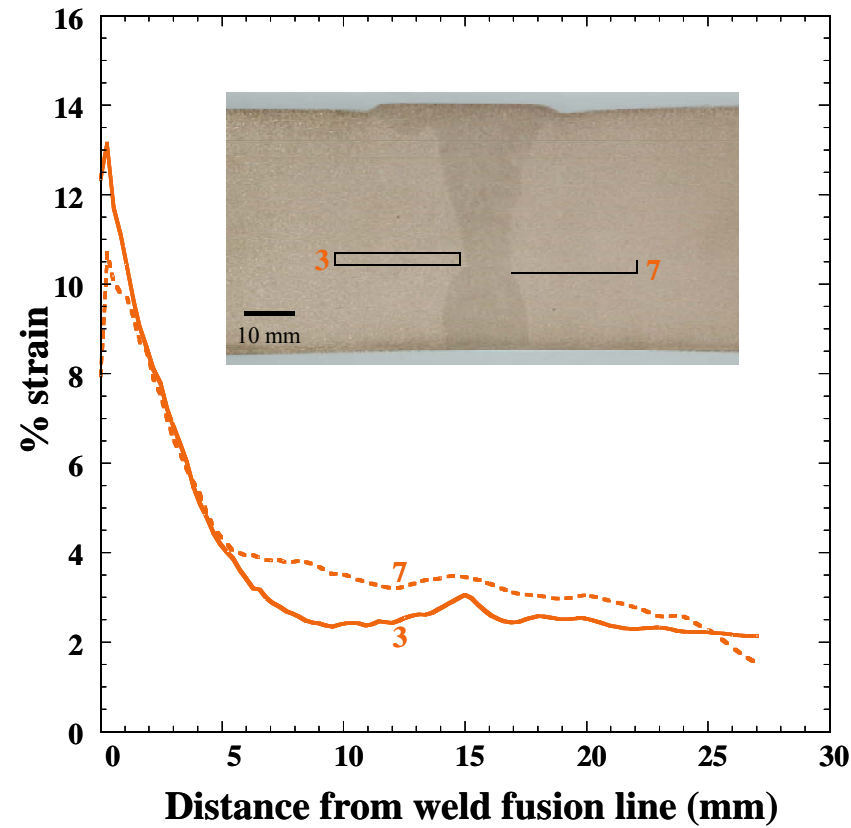
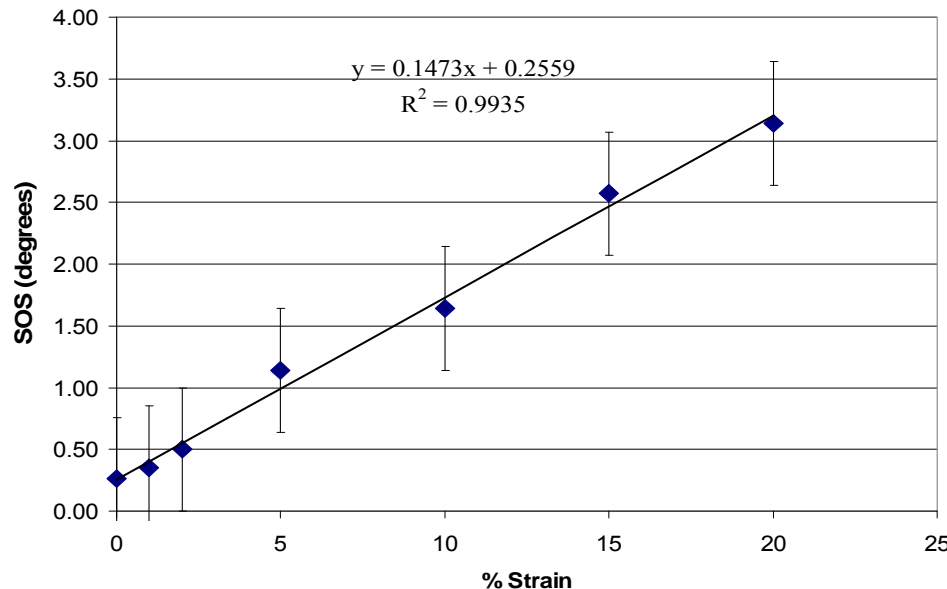
Quantitative
comparison at
microstructural level

Average Microstructural Metric for plastic deformation

Scalar orientation spread (SOS)--or--

Average (Intragrain) Misorientation—AMIS

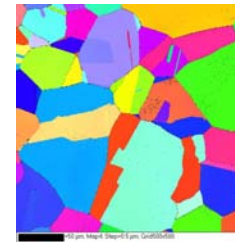
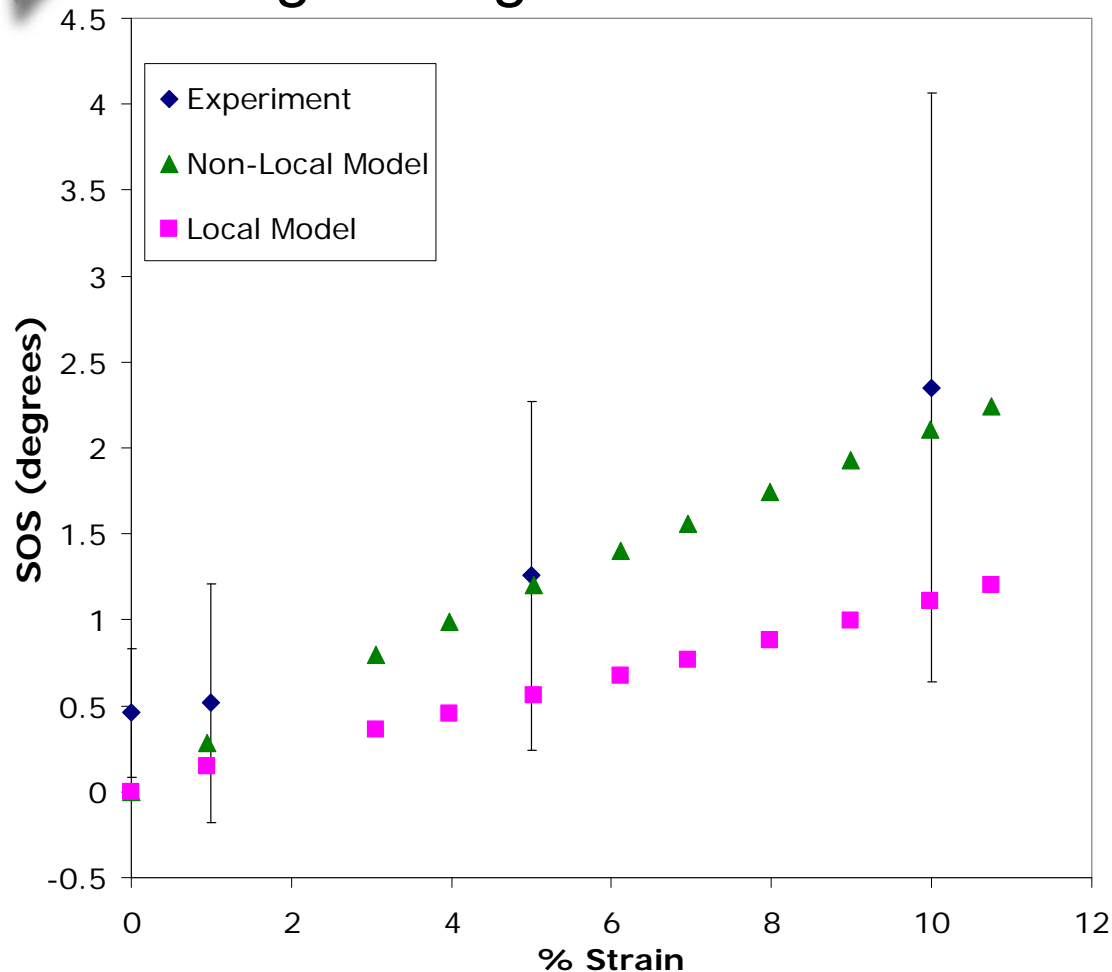
Strain-SOS Calibration for Stainless Steel



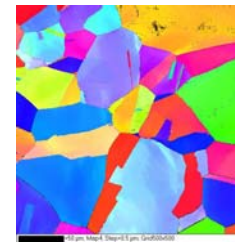
$$SOS_{\text{grain segment}} = \frac{\sum(\text{pixel} - \text{pixel misorientations})}{N \text{ pixel pairs}}$$

$$SOS_{\text{Test Line}} = \frac{\sum(SOS^{\text{Segment}_i})}{N^{\text{Segments}}}$$

Scalar Orientation Spread (aka Average Intragrain Misorientation: AMIS)



1% strain



5% strain

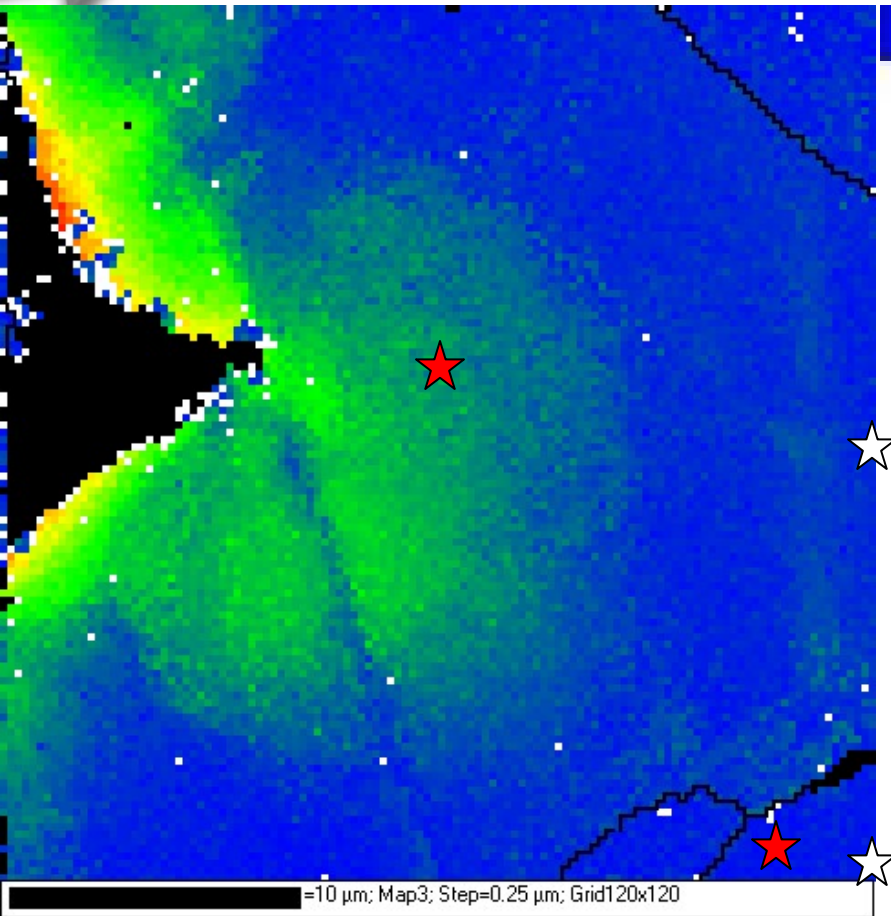


10% strain

- Experimental error bars because of small number (<100) of grains sampled
- Linear trend consistently observed for FCC metals deformed in tension
- SOS values for local model lower than experimental value.

Local Misorientation Mapping

L.N. Brewer et al., Microscopy and Microanalysis, 2006



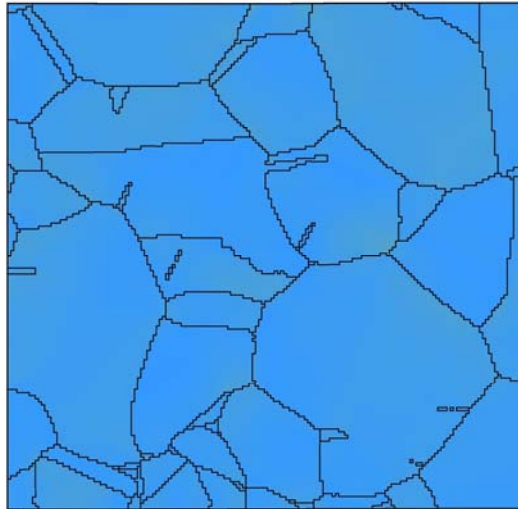
Blue represents small internal misorientation “relaxed”

Red represents large internal misorientation “strained”

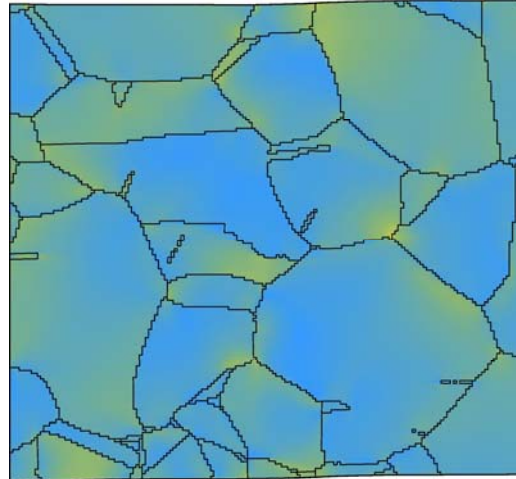
- Locate grain boundaries using standard misorientation calculations
- Assign each pixel in map to a grain
- Locate reference pixel in each grain (minimum distortion)
 - Calculate misorientation for an 8-pixel cluster
 - Choose cluster with least misorientation as reference
- For a given grain, calculate the misorientation between each pixel and the reference pixel.
- Map this misorientation for each pixel using a color table.

Local Misorientation Spread from Simulations

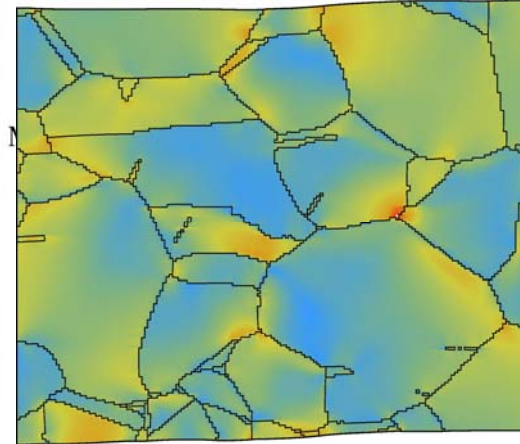
Local Model



1% strain

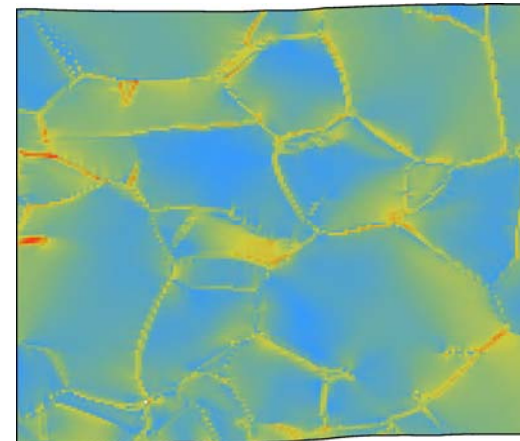
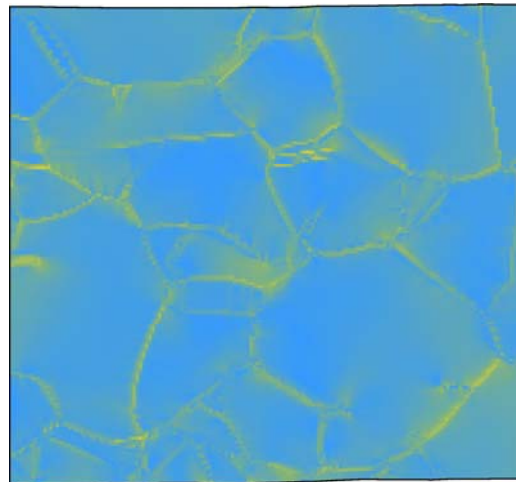
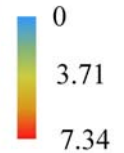


5% strain

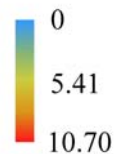


10% strain

Misorientation
(Degrees)

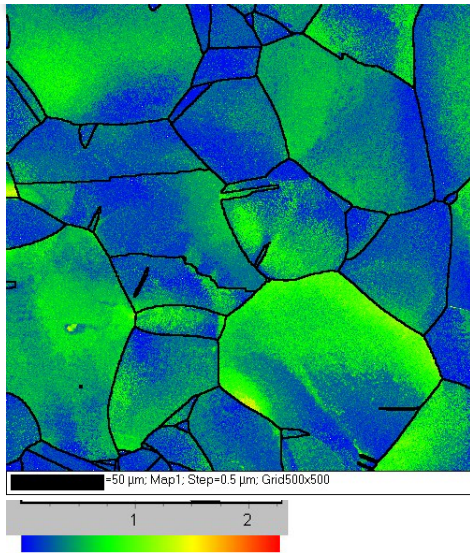


Misorientation
(Degrees)

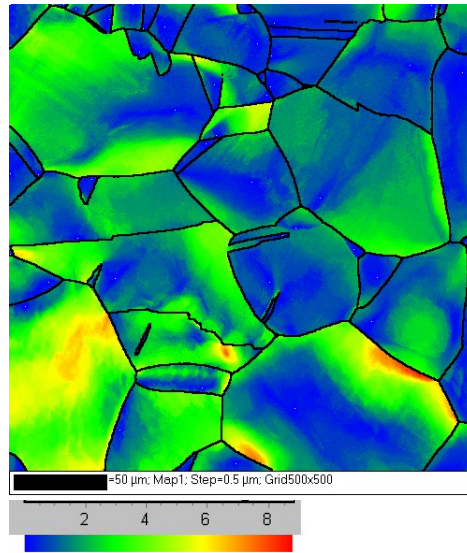


Non-Local Model

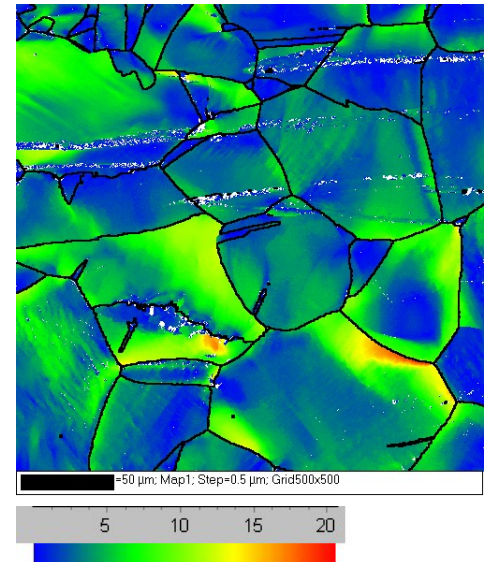
Comparison of Local Model and EBSD: Local Misorientation Distributions



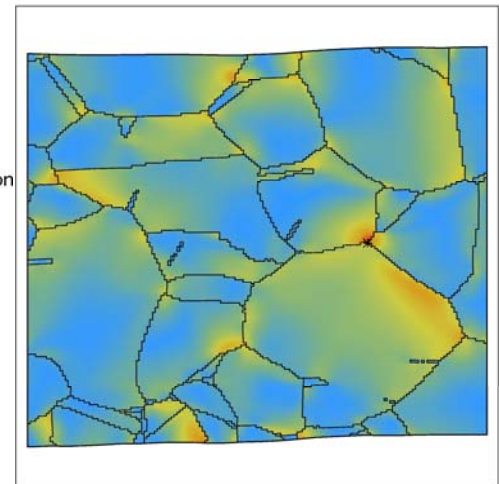
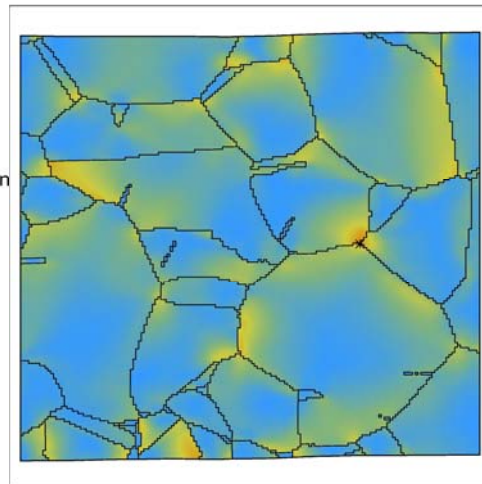
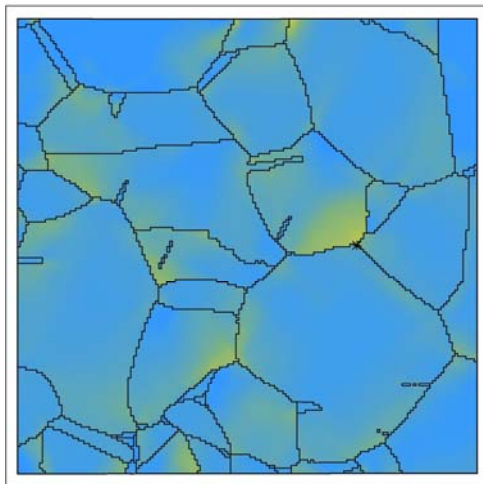
1% Strain



5% Strain



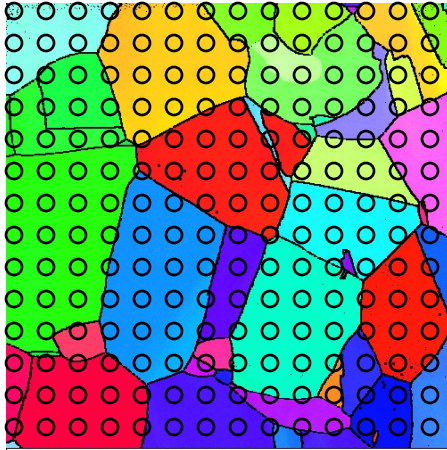
10% Strain



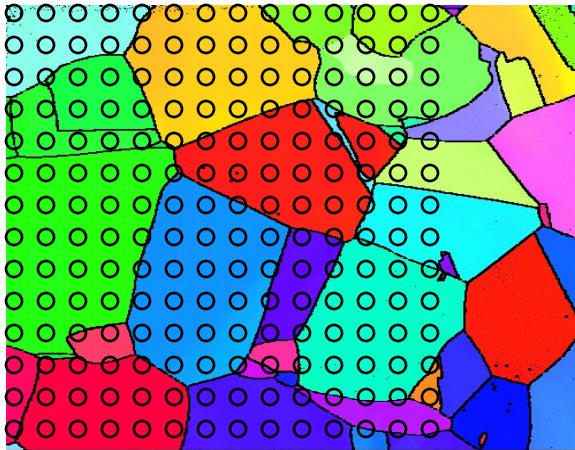
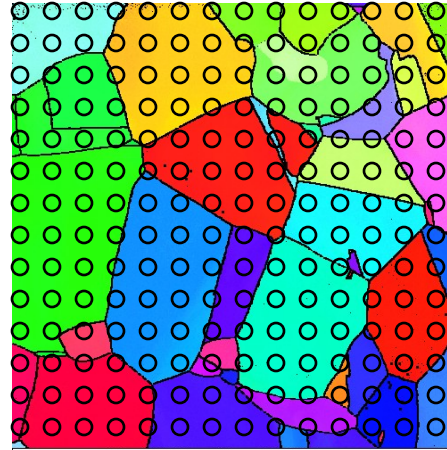
How do we go about comparing these microstructures quantitatively?

Coordinate Systems for Comparing Experiment and Simulation

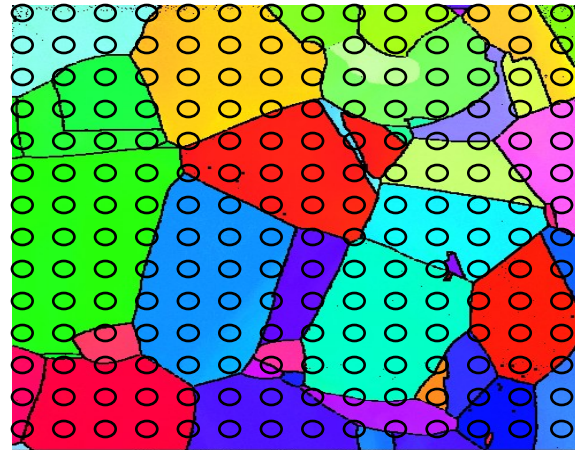
Experiment Initial



Simulation Initial



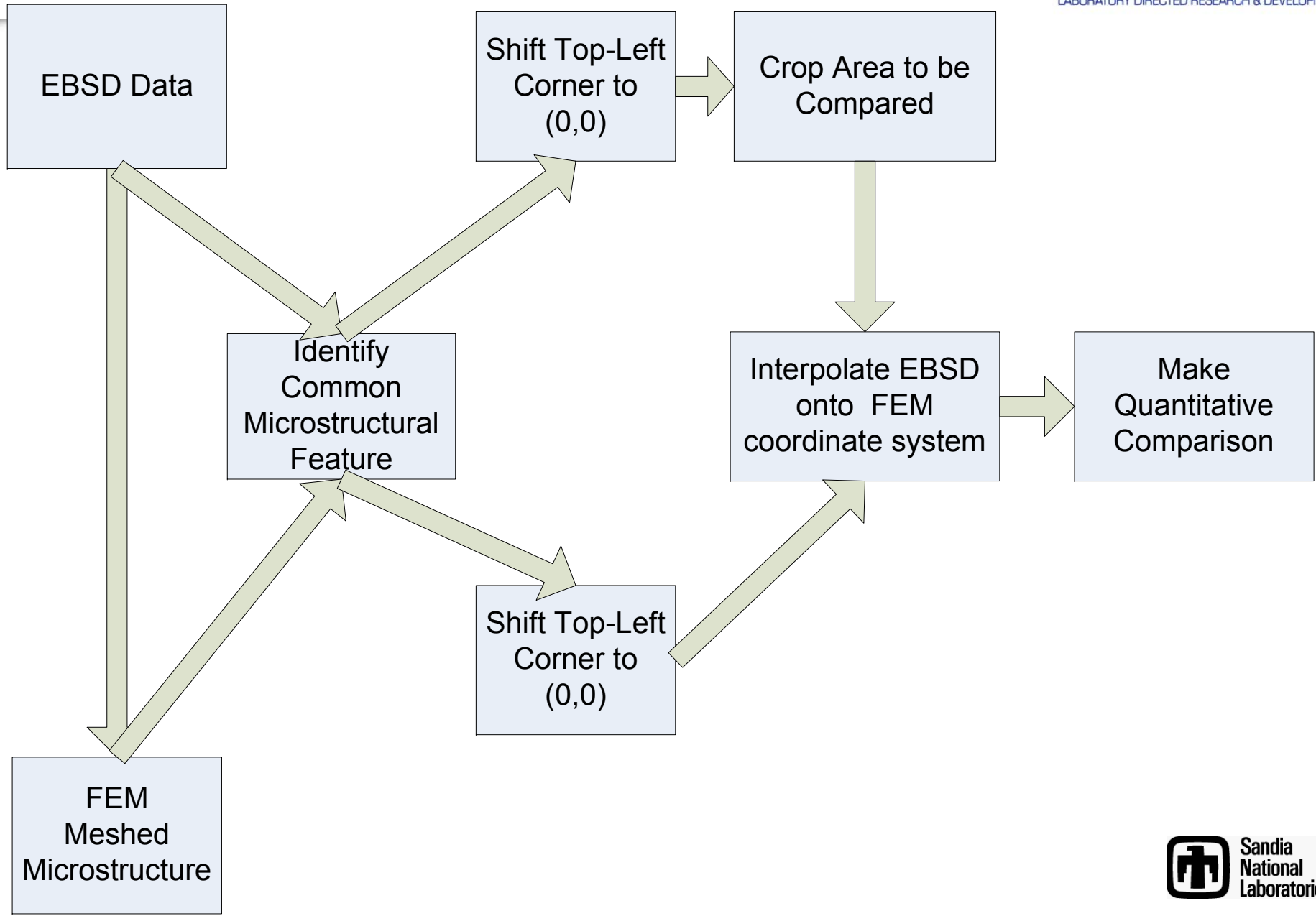
Eulerian---points move
outside of analysis area



Lagrangian---points analysis
area stays with points

Need to match these coordinate systems in order to quantitatively compare the results, point by point...

Remapping the Coordinate Systems

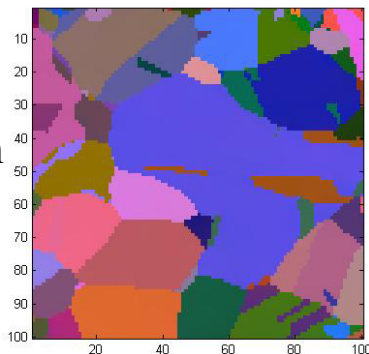


Example: 10 percent strain (Non-local model vs EBSD)

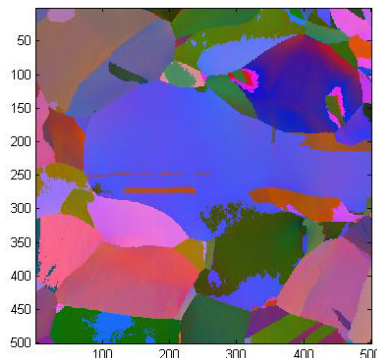
FEM

EBSD

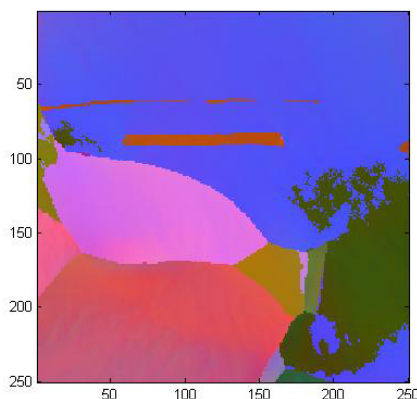
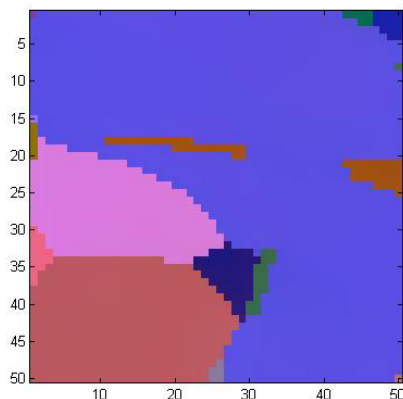
FEM Mesh from
Experimental
data



Experimental
data

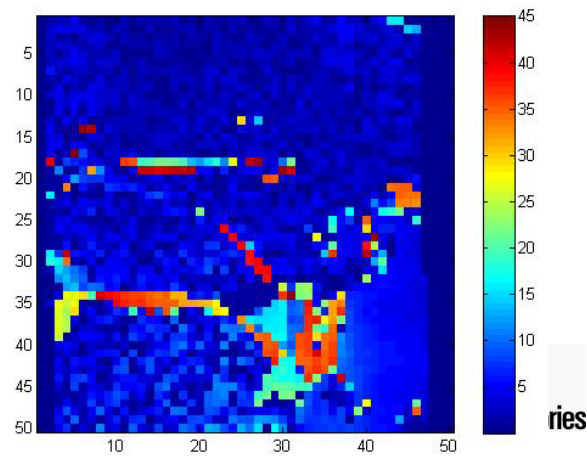
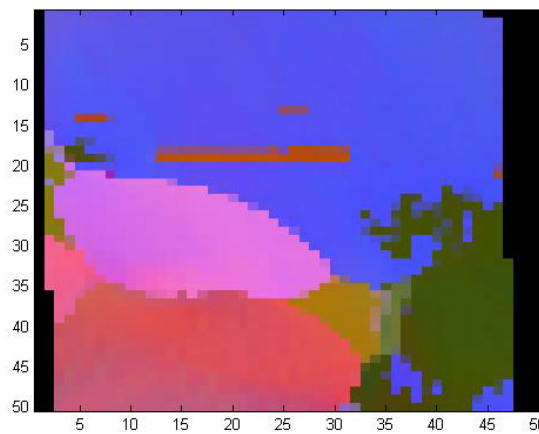


Cropped and
shifted areas



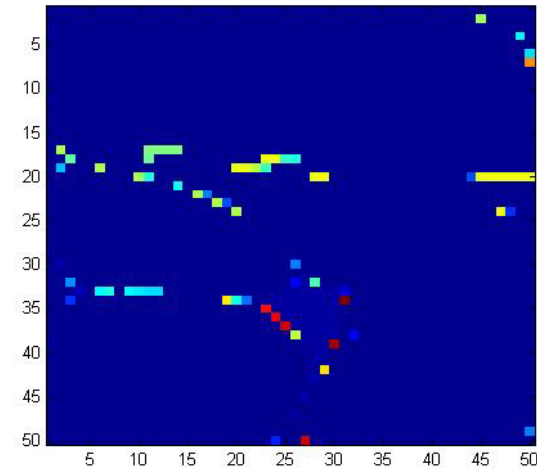
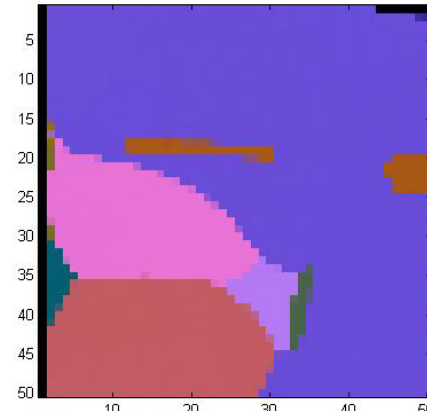
Comparison
(misorientation angle)

Interpolated
EBSD data

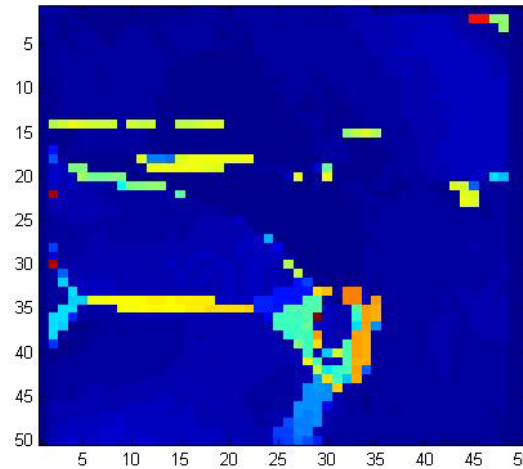


Misorientation maps show local deviation between experiment and model.

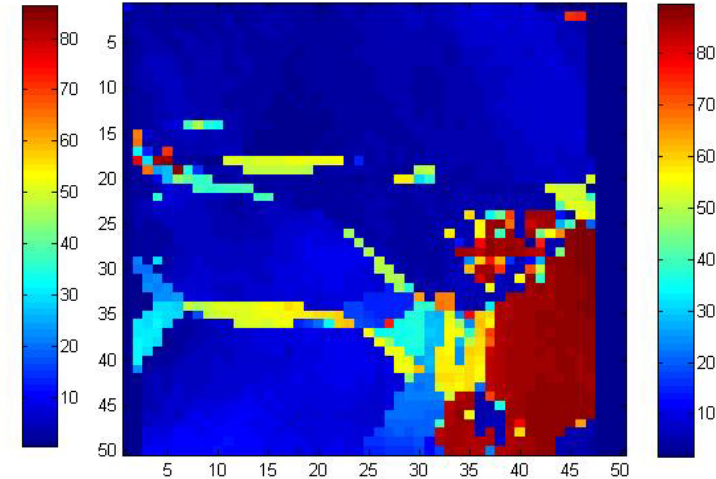
Local model



1%



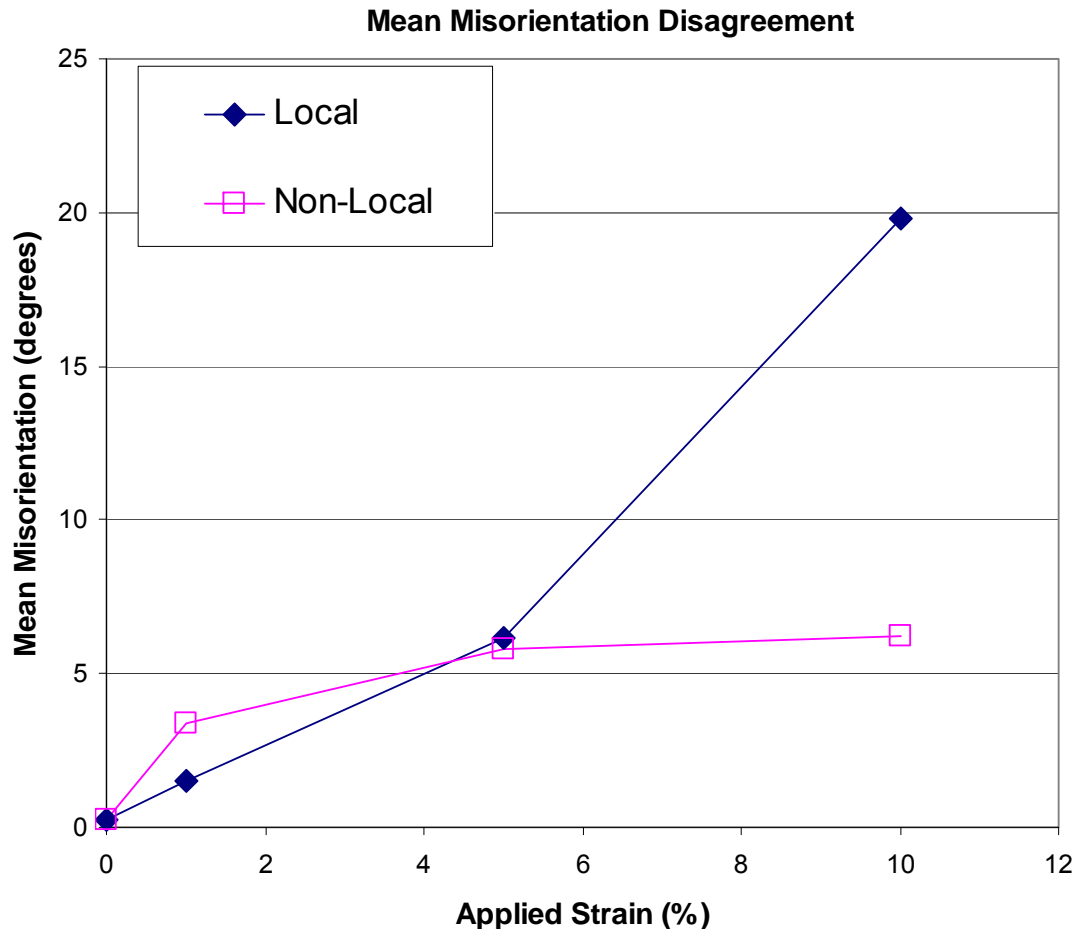
5%



10%

Misorientation (scalar, in degrees)

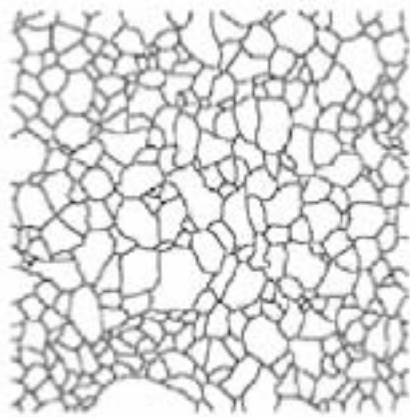
Mean misorientation comparison of Local and Non-Local Models with Experiment



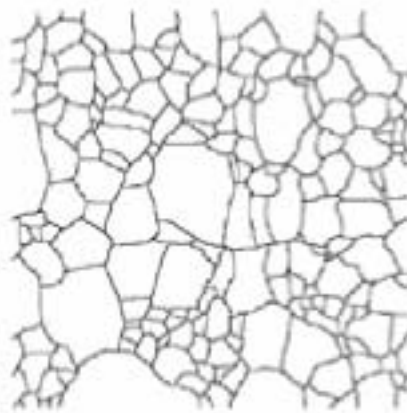
Normalized Area Match Fraction

$$\text{NAMF}_i = \frac{1}{Z} \sum_{x,y} \delta[s_i(x, y) - s_{\text{exp}}(x, y)],$$

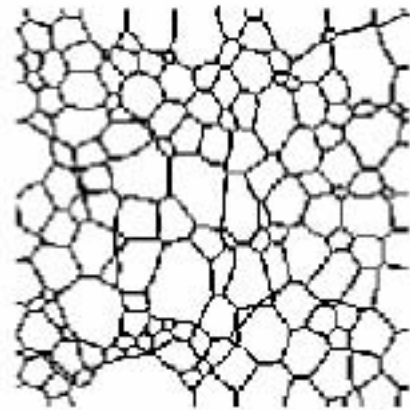
- What percentage of pixels agree?
 - Agreement is binary [0,1]
 - Simple “spin” comparison for grain growth



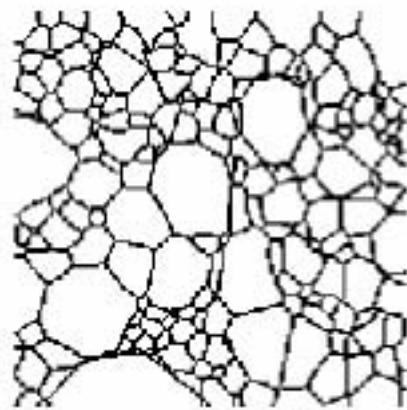
A



B



C



D



E



F

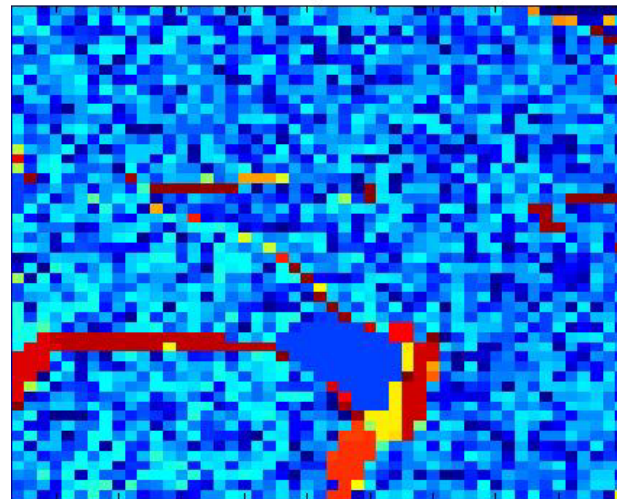
NAMF for Plasticity

$$NAMF = \frac{1}{Z} \sum_{x,y} \begin{cases} 1 & \text{if } \theta < threshold \\ 0 & \text{if } \theta \geq threshold \end{cases}$$

θ is the scalar misorientation between the orientations at a given pixel for the FEM and EBSD data.

Note that the noise floor for θ measured with standard EBSD is 0.3-0.5°. 1-2° may be a better choice

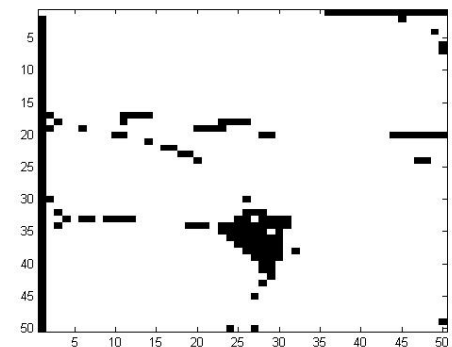
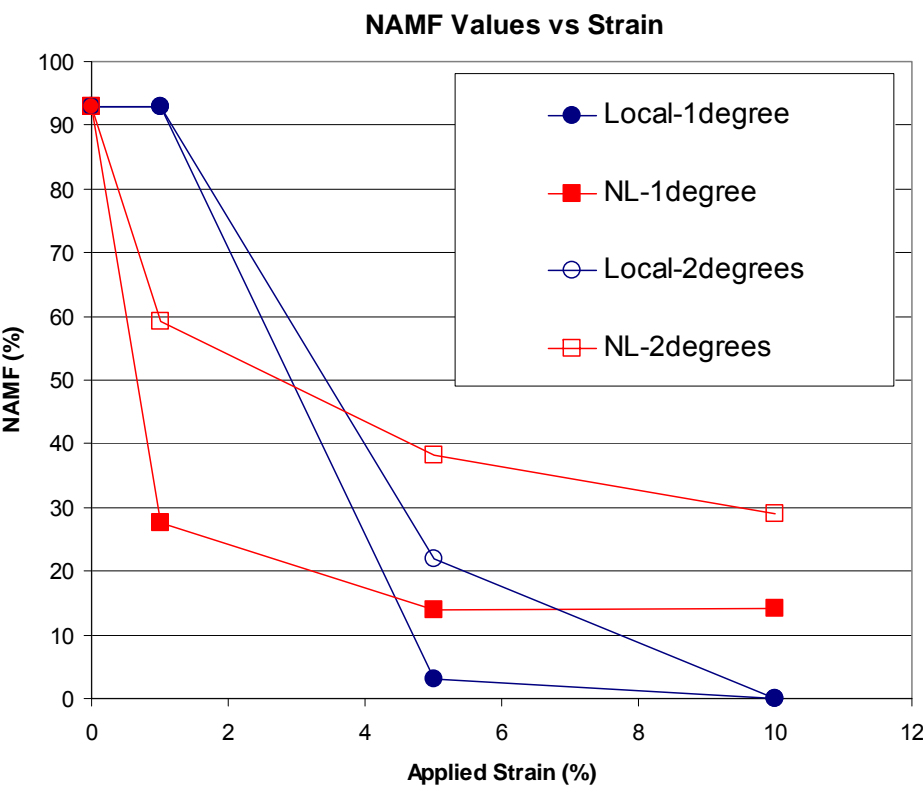
1% Strain Non-Local Log10 Misorientation Map



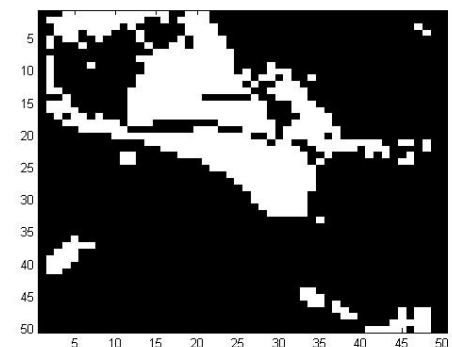
NAMF Map 1degree tolerance 1% Strain, Non-Local



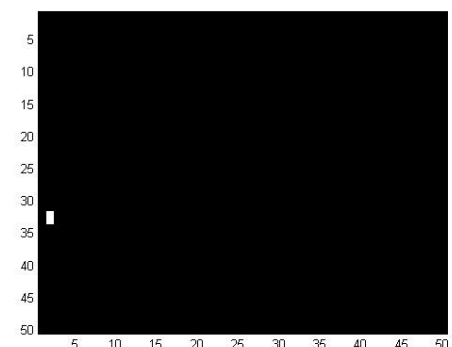
NAMF for Plasticity Comparison



1% strain



5% strain



10% strain

Local model, 2°
threshold

Conclusions

- **Meaningful development of microstructural-level models requires careful comparison with experiment at the microstructural length scale.**
- **Often, the models may give collective stress-strain responses that look acceptably good, but the details microscale of the plasticity are not as stable or as accurate**
- **We are developing methods for quantitatively comparing microstructural simulations and experiment on the same microstructures.**
- **Both average metrics and local plots of simulation-experiment difference are important**



Crystal Plasticity: Theoretical framework

Kinematics of slip systems $\mathbf{L}^p = \dot{\mathbf{F}}^p \mathbf{F}^{p-1} = \sum_{\alpha=1}^{N_{slip}} \dot{\gamma}^{\alpha} (\mathbf{s}^{\alpha} \otimes \mathbf{m}^{\alpha})$

Crystallographic slip

=

Dominant plastic deformation mechanism

Elasticity

$$\sigma^{PK2} = \mathbf{C}^e : \tilde{\mathbf{E}}^e$$

Slip system evolution

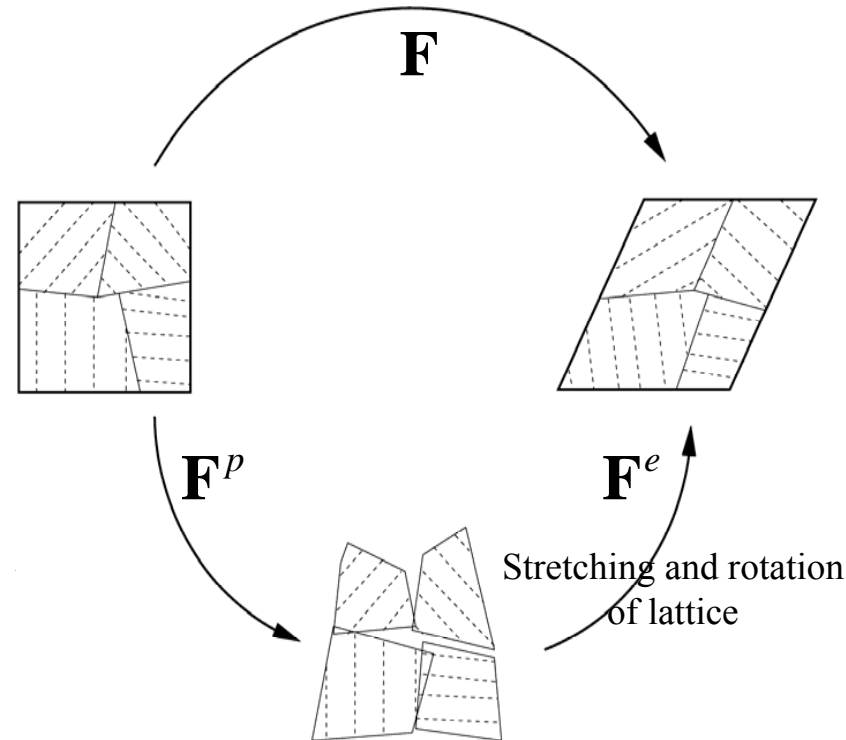
(power law viscoplastic flow rule)

$$\dot{\gamma} = \dot{\gamma}_0 \left| \frac{\tau^a}{\tau_{CRSS}^a} \right|^{1/m} \text{sgn}(\tau^a)$$

Slip system hardening: Taylor dislocation based

$$\begin{cases} \tau_{CRSS}^{\alpha} = C \mu b \sqrt{\rho^{\alpha}} \\ \rho^{\alpha} = \left(c_1 \sqrt{\rho^{\alpha}} - c_2 \rho^{\alpha} \right) \dot{\gamma}^{\alpha} \end{cases}$$

Multiplicative decomposition



Motion of dislocations
on active slip systems.
(undistorted AND unrotated)

What people do elsewhere...

Ecole Polytechnique, FR: J. Crepin

FEM parametric study

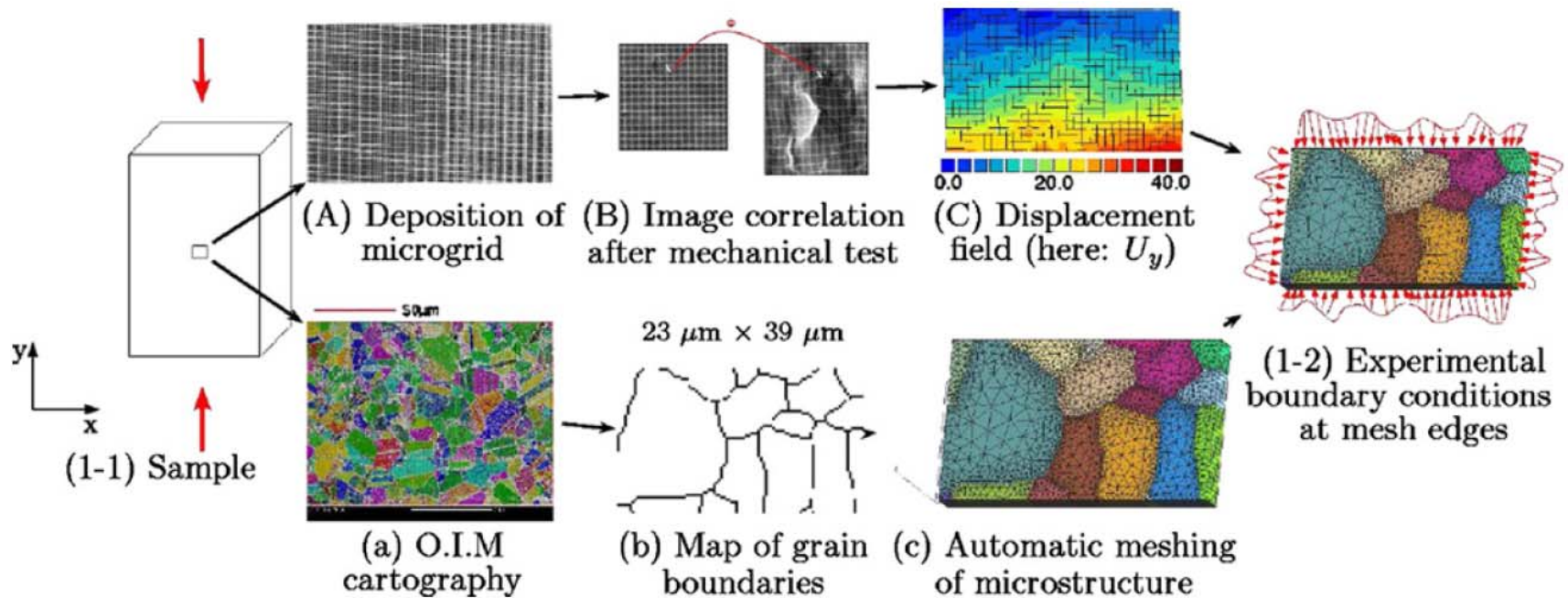
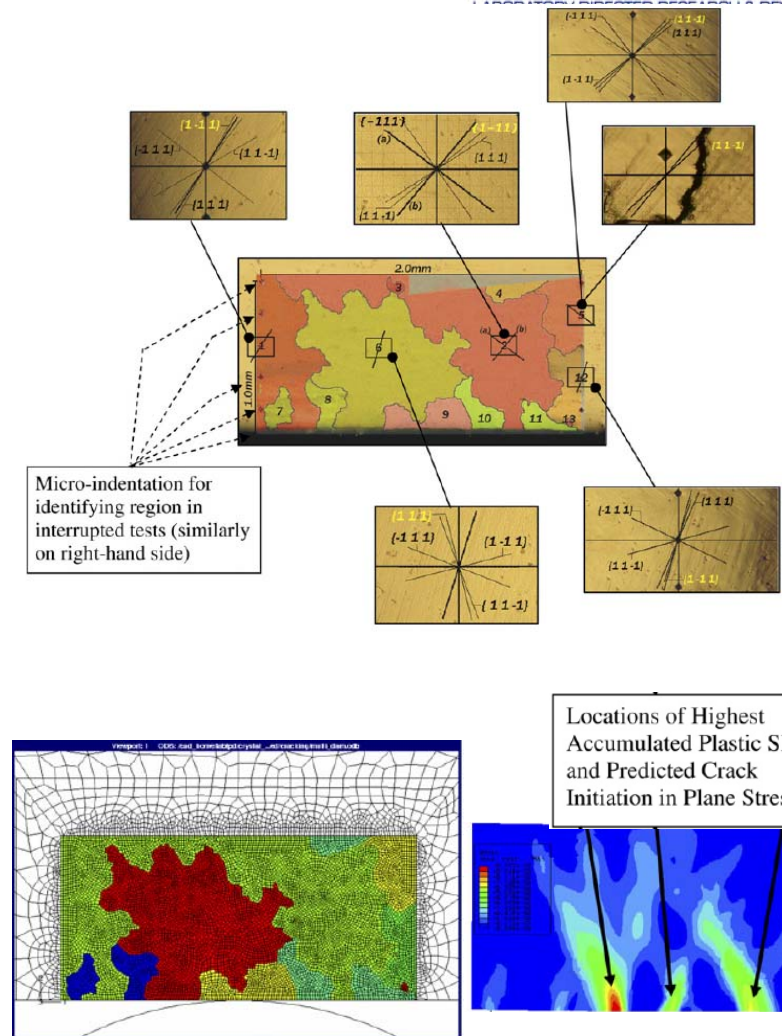
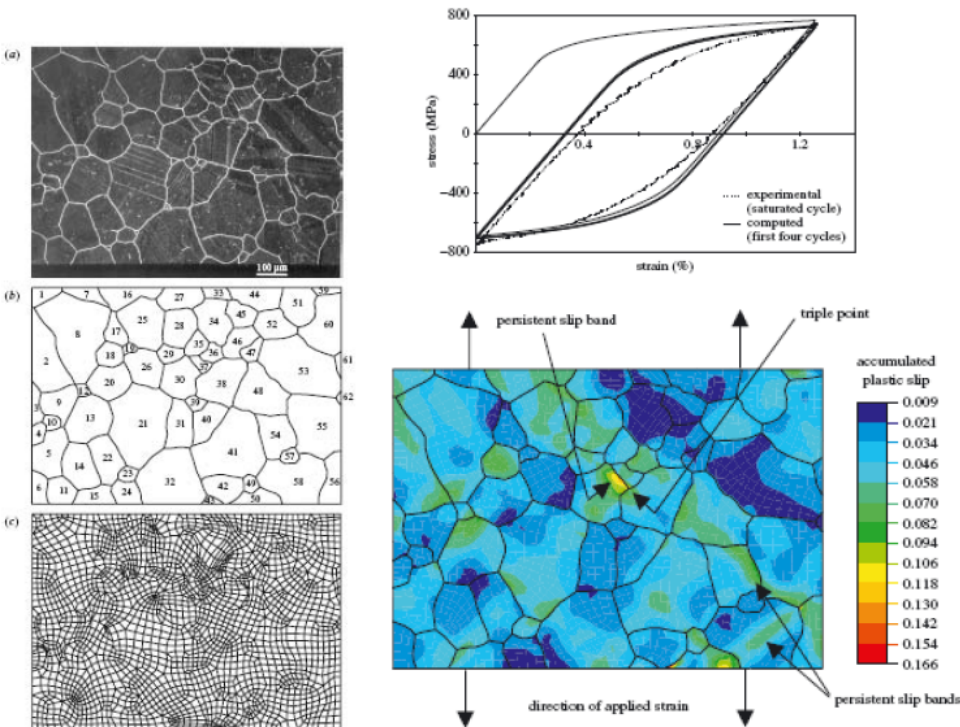


Fig. 1. Coupling between experimental tests and FE simulations.

What people do elsewhere...

Oxford Univ., U.K.: **F.P.E. Dunne**

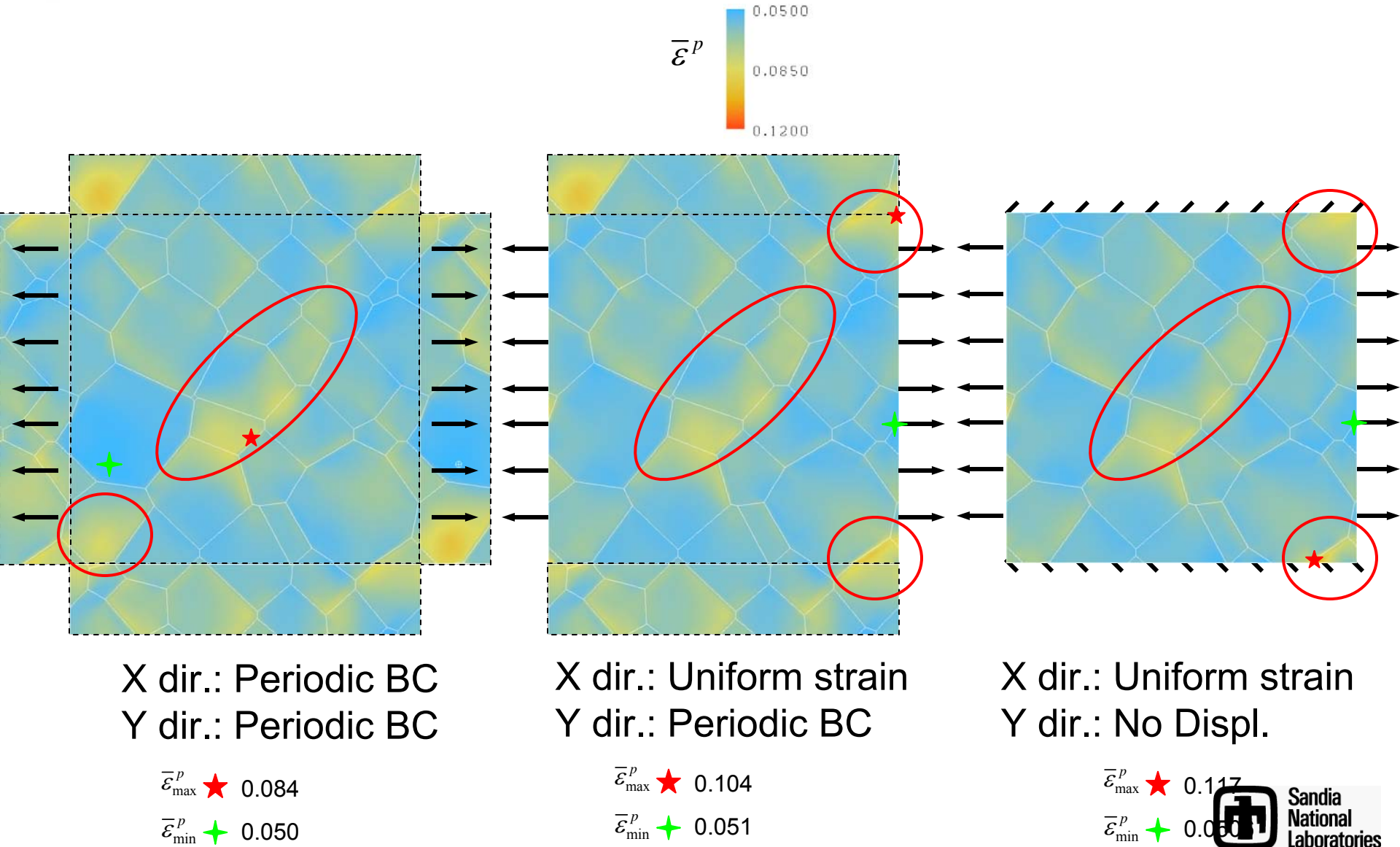


[F. P. E. Dunne et al. (2004) "High- and low-cycle fatigue crack initiation using polycrystal plasticity", *Proc. R. Soc. Lond. A*460, p. 1881–1903]

[F.P.E. Dunne (2007) "Experimental and computational studies of low cycle fatigue crack nucleation in a polycrystal", *IJP* 23 p. 273–295]

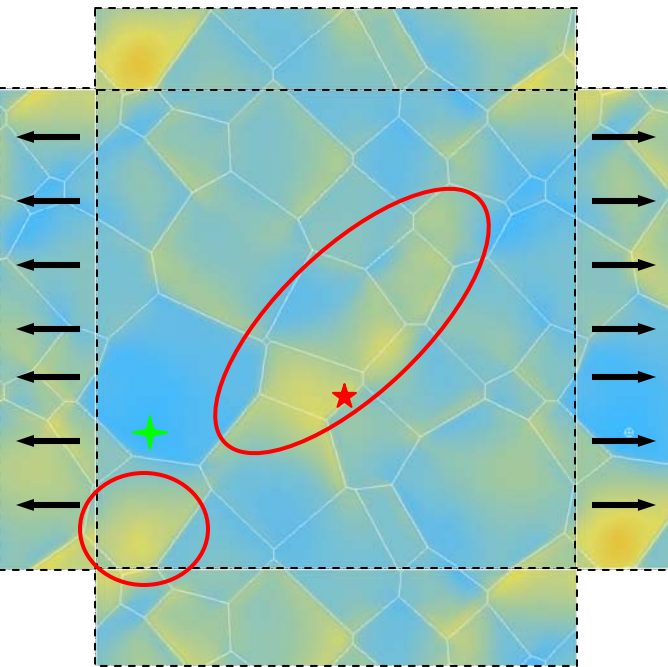
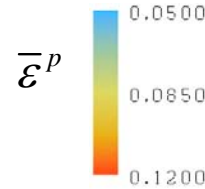
Microstructural level information: Equivalent Plastic Strain

Uniform displacement control



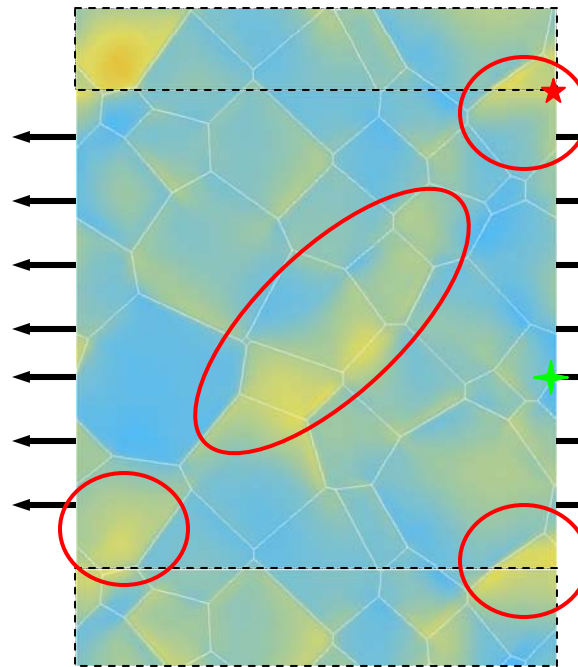
Microstructural level information: Equivalent Plastic Strain

Load control



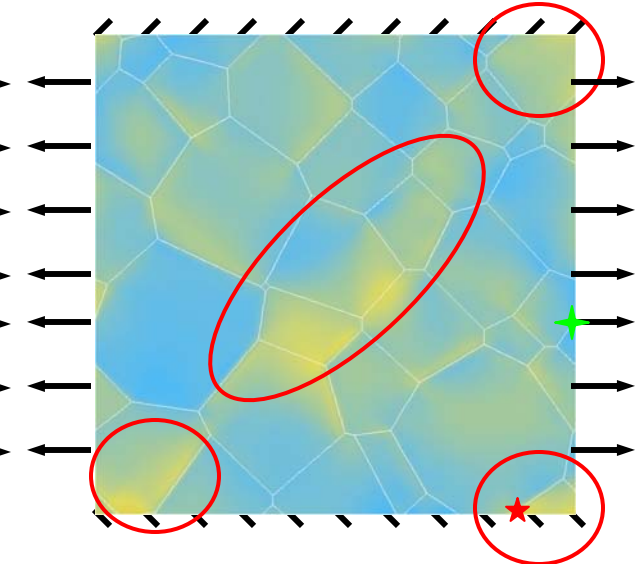
X dir.: Periodic BC
Y dir.: Periodic BC

$\bar{\epsilon}_{\max}^p$ ★ 0.084
 $\bar{\epsilon}_{\min}^p$ + 0.051



X dir.: Uniform strain
Y dir.: Periodic BC

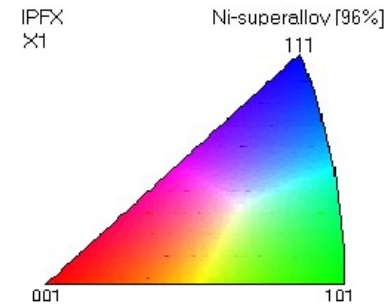
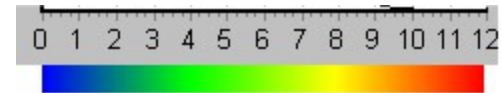
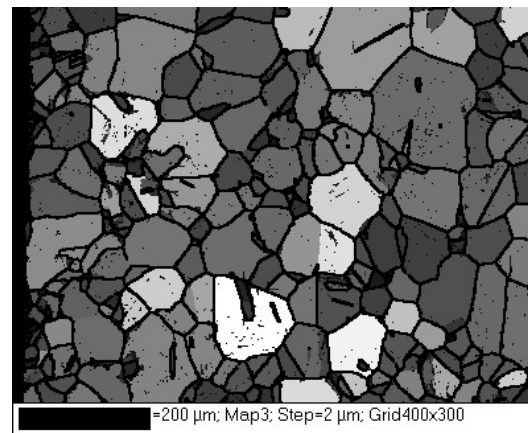
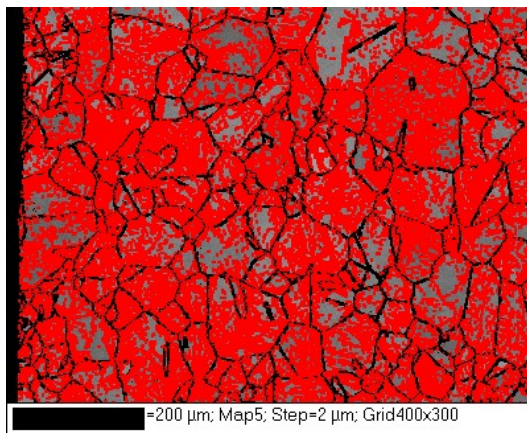
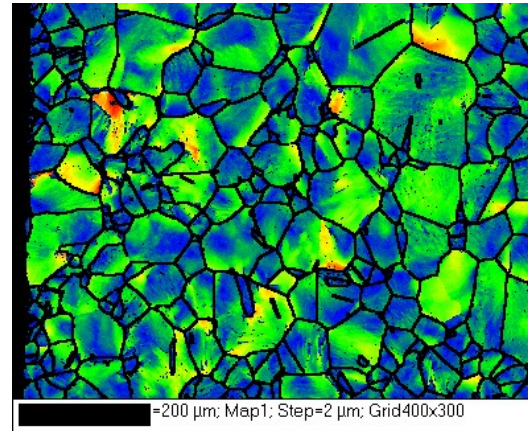
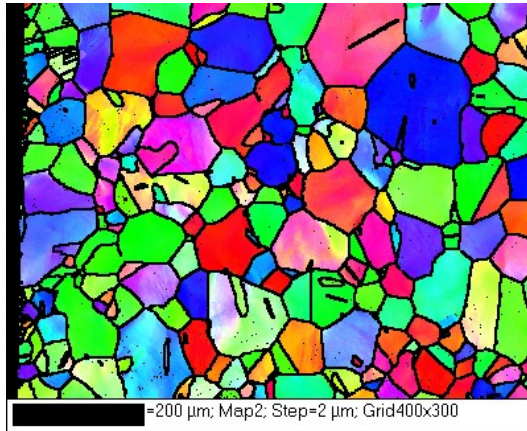
$\bar{\epsilon}_{\max}^p$ ★ 0.089
 $\bar{\epsilon}_{\min}^p$ + 0.052



X dir.: Uniform strain
Y dir.: No Displ.

$\bar{\epsilon}_{\max}^p$ ★ 0.100
 $\bar{\epsilon}_{\min}^p$ + 0.062

EBSD maps from cross section of gage section of tensile bar (10% applied macro strain)



- Really no strong gradient in rotation from surface (on left) to mid-plane of sample