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CSYS 300 – COMPLEX SYSTEMS FUNDAMENTALS, METHODS & APPLICATIONS

Optimization: Heuristic Methods and Applications

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CSYS 300 – COMPLEX SYSTEMS FUNDAMENTALS, METHODS & APPLICATIONS

Optimization: Heuristic Methods and Applications



Outline of Presentation

- Brief Biographical Note
- Where this Section Fits in the Structure of the Complex Systems Course
- Overview of heuristic optimization techniques (Tabu Search and GA)
- Small case study: MILP versus GA for Optimal Terrorist Attack
- Real-world case study: Mitigating Bridges in NMSZ
- Summary
- Question & Answer Session

CSYS 300 – COMPLEX SYSTEMS FUNDAMENTALS, METHODS & APPLICATIONS



Optimization: Heuristic Methods and Applications

Brief Biographical Note on Nathanael Brown

- Education: BSEE (UNM), MSEE (Purdue) focused on DSP/algorithms
- Non-SNL Work Experience
 - Intel Corp (2001 – 2003): Performance tuning expert system (patent 7,043,719)
 - Tera Research (1997 – 2000): Data analysis software
 - Amtech Systems Corp (1996-1997): RF tag reader embedded software
 - American Laser Games (1993 – 1996): Video game design
 - Compaq Computer Corporation (1991 – 1992): Handwriting recognition
- SNL Work Experience
 - Investment Planning LDRD (2010 – 2013): Development of a Modeling Framework for Infrastructures in Multi-Hazard Environments
 - Resilience LDRD (2010): Measurement and Optimization of Infrastructure Resilience
 - Systems tester development (2003 – 2010): Helped design/develop a suite of testers which utilizes multiple networked subsystems to capture and analyze real-time data from a unit under test

CSYS 300 – COMPLEX SYSTEMS FUNDAMENTALS, METHODS & APPLICATIONS

Structure of the Course

- | | <i>Focus of this session</i> |
|---|-------------------------------------|
| ■ Fundamentals of Complex Systems | <input checked="" type="checkbox"/> |
| ■ Methods | <input checked="" type="checkbox"/> |
| ■ Modeling Techniques | <input checked="" type="checkbox"/> |
| ■ Approaches to Examining Complex Systems | <input checked="" type="checkbox"/> |
| ■ Applications | |
| ■ Examples of the use of complex systems fundamentals to solve problems | <input checked="" type="checkbox"/> |
| ■ Learning how to use complex systems modeling tools | <input type="checkbox"/> |

*Note: These approaches represent a simplified set of complex systems concepts chosen for the CSYS 300 systems lectures. Please see the initial two lectures for additional detail and expanded references.

Heuristic Methods for Optimization – Overview

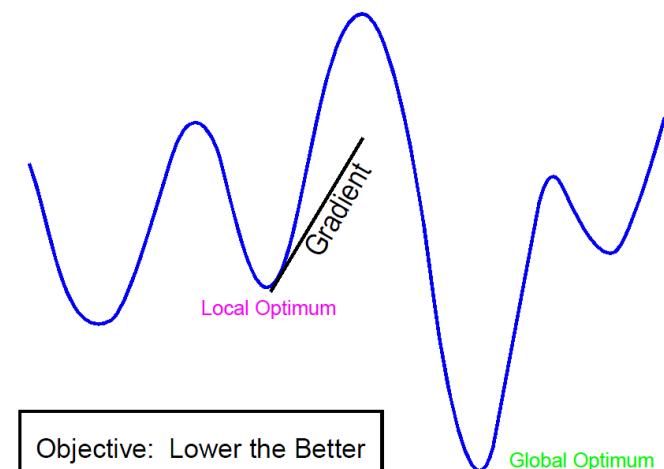
- What is a Heuristic Method (in the context of optimization)?
 - Approximate algorithms that do *not* guarantee global optimality
 - An iterative, non-deterministic algorithm used for solving combinatorial optimization problems (finding an optimal arrangement or ordering of a finite set of discrete objects)
 - Useful when solution space is non-convex and/or is dependent on multiple, possibly competing, objectives
- When should a Heuristic Method be used?
 - When standard techniques (e.g., MILP) are insufficient
 - Solution space is too large and can't be searched exhaustively
 - Objective calculation is very expensive (e.g., solution evaluation involves a complex simulation)
- Popular Heuristic Methods
 - **Simulated Annealing, Tabu Search, Genetic Algorithm**
 - Sait, S. M. and H. Youssef. 1999. "Iterative Computer Algorithms with Applications in Engineering: Solving Combinatorial Optimization Problems." Los Alamitos, CA: IEEE Computer Society.

Simulated Annealing – Overview

- General adaptive heuristic for solving combinatorial optimization problems, designed to escape local optima
- Algorithm is analogous to the physical annealing process: heating a solid to a high enough temperature to melt, then slowly cooling the liquid until it crystallizes
 - By cooling at a proper rate, proper crystal structure with perfect lattices will be created
 - The algorithm simulates the heating/cooling cycle of annealing
- Has been used to solve a variety of optimization problems
 - Traveling salesman problem (TSP)
 - Image Processing
 - Scheduling
 - Facilities layout
 - VLSI design
- Fairly easy to implement

Simulated Annealing – Algorithm Details

- From a random initial state, iteratively searches the local neighborhood for better solutions
- Starts with a heating cycle which allows for poor solutions to be accepted with a certain probability
 - Allows the escape from local optima by “hill climbing”
- The cooling cycle slowly decreases the probability of accepting “worse” solutions until only “better” solutions are accepted
- Utilized in an LRD to determine the best recovery strategy for a damaged railway system based on: cost of repairs, duration of repairs, priority of commodity delivery
- Found to be within 1% – 2% of “true” optimal based on full enumeration

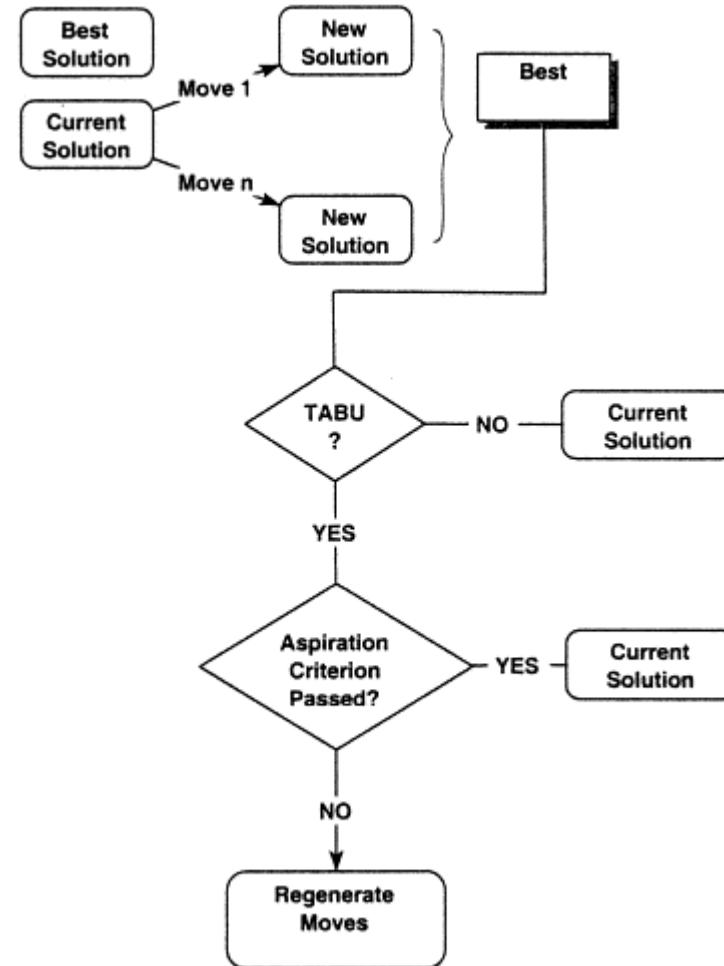


Tabu Search – Overview

- Generalization of local search used to explore very large solution spaces
- Algorithm samples different “neighborhoods” within the solution space via a sequence of “moves”
- Composed of three different memory components:
 - Short-term component prevents cycling (Tabu List)
 - Intermediate-term component is used for regional search **intensification**
 - Long-term component promotes global solution **diversification**
- Designed to escape local optima

Tabu Search – Algorithm Details

- Find “best” solution in current neighborhood by doing a local search
- Accept *best* solution as *current* if:
 - Not on the Tabu List
 - Better than current *best* solution
- If solution *is* accepted, continue searching in current neighborhood (intensification)
- If solution *is not* accepted, move to a new neighborhood (diversification)
- Repeat process a fixed number of times

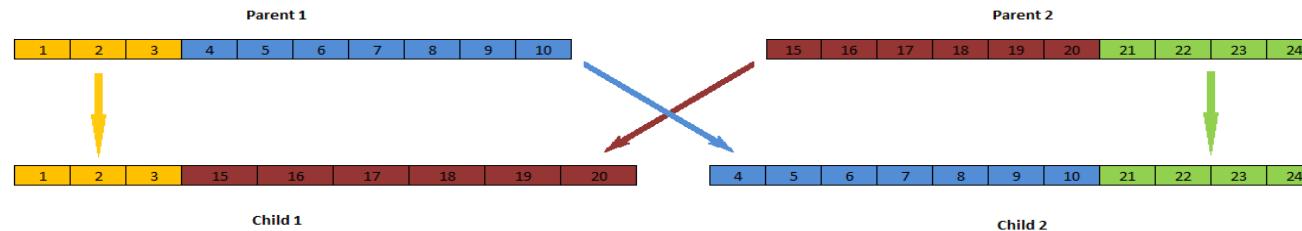


Genetic Algorithm (GA) – Overview

- Simulates the process of evolution based on the Darwinian theory of natural selection
- Individuals are represented by encoded strings (chromosomes) which mate to produce offspring with (mostly) the best characteristics of both parents
- Computationally straightforward and easy to implement
 - Requires no assumptions about the search space (e.g., continuity, existence of derivatives)
 - Only need objective function values to evaluate solution fitness
- Composed of the following steps:
 - Initialization
 - Selection
 - Crossover
 - Mutation
 - Termination

Genetic Algorithm (GA) – Algorithmic Details

- **Initialization** – Create a population of randomly generated individuals (hundreds to thousands depending on search space)
- **Selection** – Choose a portion of the existing population to breed a new generation
 - Bias the selection such that fitter individuals are more likely to be selected
- **Crossover** – Each new individual is created from a pair of “parent” solutions by splitting and recombining the parent chromosomes



- **Mutation** – Randomly change a few genes in the child chromosome to promote diversity (on the order of 5%)
- **Termination** – Terminate after a fixed number of iterations or when there is no significant improvement

Implementing a Biased Selection

- Heuristic Algorithms often require making probabilistically-biased selections
- One technique is to assign contiguous, integer intervals to each item based on a bias factor and use a random number generator to select
- Example: 10 numbers to select from where probability of selection is proportional to the square of the number

Number	Square	Interval Start	Interval End	Probability
1	1	0	0	0.002597403
2	4	1	4	0.01038961
3	9	5	13	0.023376623
4	16	14	29	0.041558442
5	25	30	54	0.064935065
6	36	55	90	0.093506494
7	49	91	139	0.127272727
8	64	140	203	0.166233766
9	81	204	284	0.21038961
10	100	285	384	0.25974026
Total	385	0	384	1

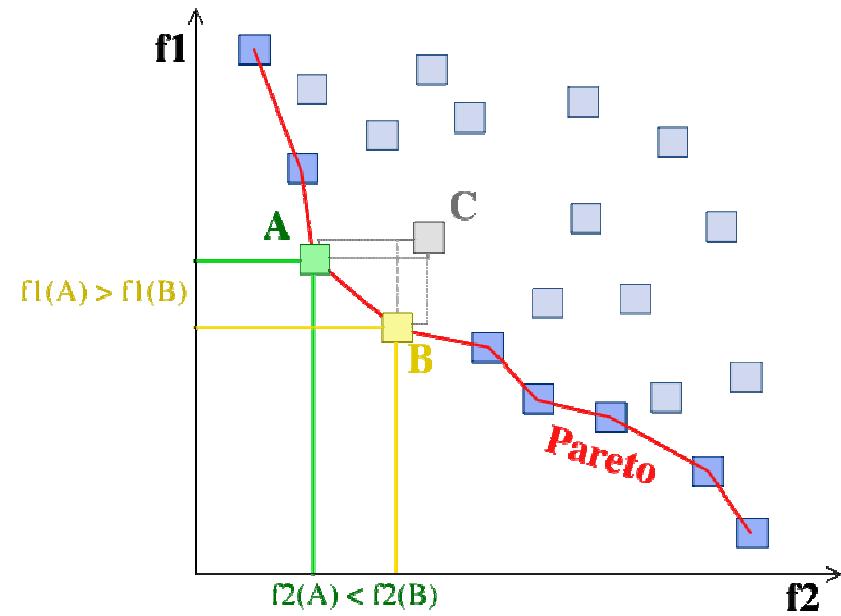
- Randomly select an integer value between 0 and 384; interval that value falls into indicates the target number

- Network consists of 20 hospitals within the Memphis area
- Terrorist has a maximum “budget” of 7 hospitals to disrupt service to the maximum number of people: 77,520 different permutations
 - 20 choose 7 binomial coefficient: $\binom{n}{k} = \frac{n!}{k!(n-k)!}$; $\binom{20}{7} = \frac{20!}{7!13!} = 77,520$
- Full enumeration requires 9.25 minutes for an exhaustive search
- CPLEX (MILP solver) finds optimal solution in 42 seconds
- GA solution searching 30% of solution space (102 seconds)
 - Initial population of 7752 (10% of total) with 20 crossover steps (776 per step)
 - 100 runs: 45% at optimal, 100% within 5.2% of optimal
- GA solution searching 10% of solution space (37 seconds)
 - Initial population of 775 (1% of total) with 90 crossover steps (78 per step)
 - 100 runs: 22% at optimal, 93% within 5.8% of optimal, outliers up to 17.7%
- Neither GA solution is *guaranteed* to be optimal

- Use a “leader-follower” model to find the optimal reinforcement strategy for minimizing the worst terrorist attack.
- Assumptions
 - Same network and terrorist budget
 - Terrorist will not attack reinforced hospitals
 - Cost to reinforce a single hospital is 1 and protector can reinforce up to N-1 (19) hospitals
- Approach
 - Use CPLEX to find optimal attack given a reinforcement
 - Use a GA to determine the optimal investment strategy within solution space of size $2^{20} - 1 = 1,048,575$ different permutations
 - Dual objective: hospital service impact and mitigation cost
- What is the “best” solution?
 - Could equally weight 2 objectives and get a single solution (adequate)
 - Use a Pareto Frontier to give a range of good solutions (better)

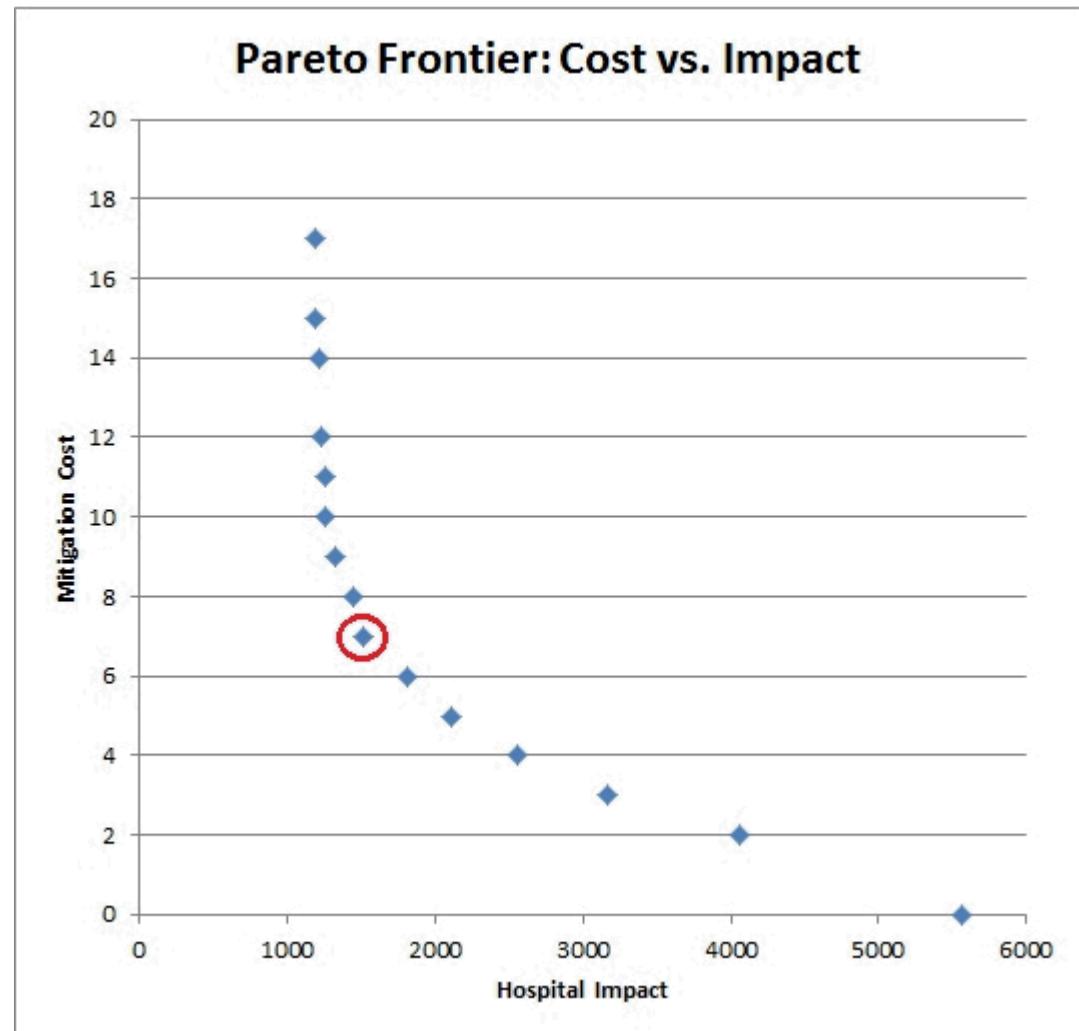
Fitness Evaluation – Pareto Frontier

- A Pareto Frontier consists of only those solutions which are *not* dominated by any other solutions
- Solution A dominates B if both conditions are true:
 - Solution A is no worse than B in all objectives
 - Solution A is strictly better than B in at least one objective
- Example: Solutions A, B and C with dual objectives f_1 and f_2 which must be minimized
 - Solution A does *not* dominate B because $f_1(A) > f_1(B)$
 - Solution A *dominates* C because $f_1(A) < f_1(C)$ and $f_2(A) < f_2(C)$



Terrorist Attack on a Hospital Network – Pareto Frontier

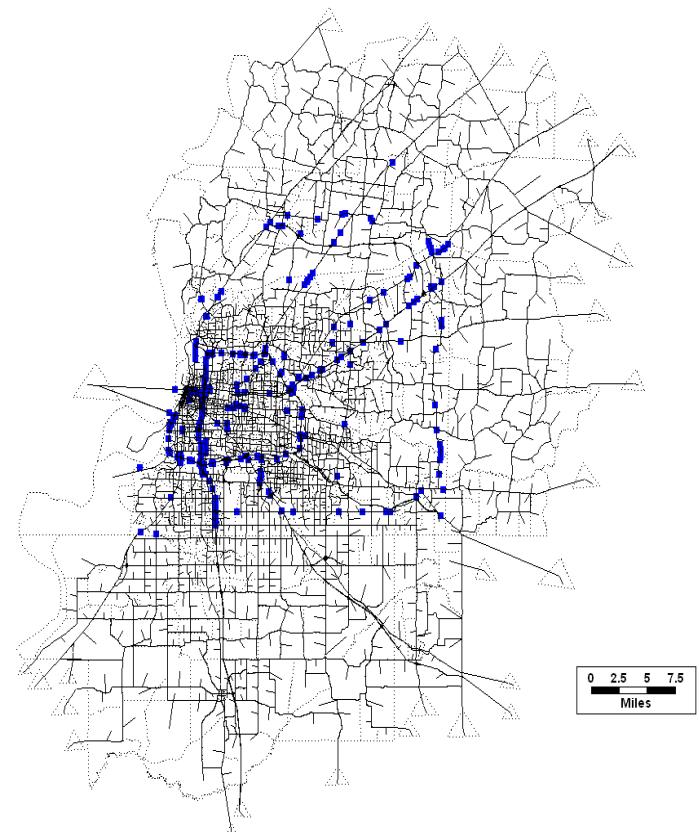
- Frontier is composed of 15 data points
- Equally weighted objectives approach would have selected mitigation cost of 7 (circled in plot)
- Chose 1000 mitigation strategies for initial population (roughly 0.1% of total solution space)
- 90 crossover steps using 100 “parent” solutions per iteration
- Solutions with cost 18 and 19 are non-Pareto



Earthquake Mitigation of a Highway Network – Problem Overview

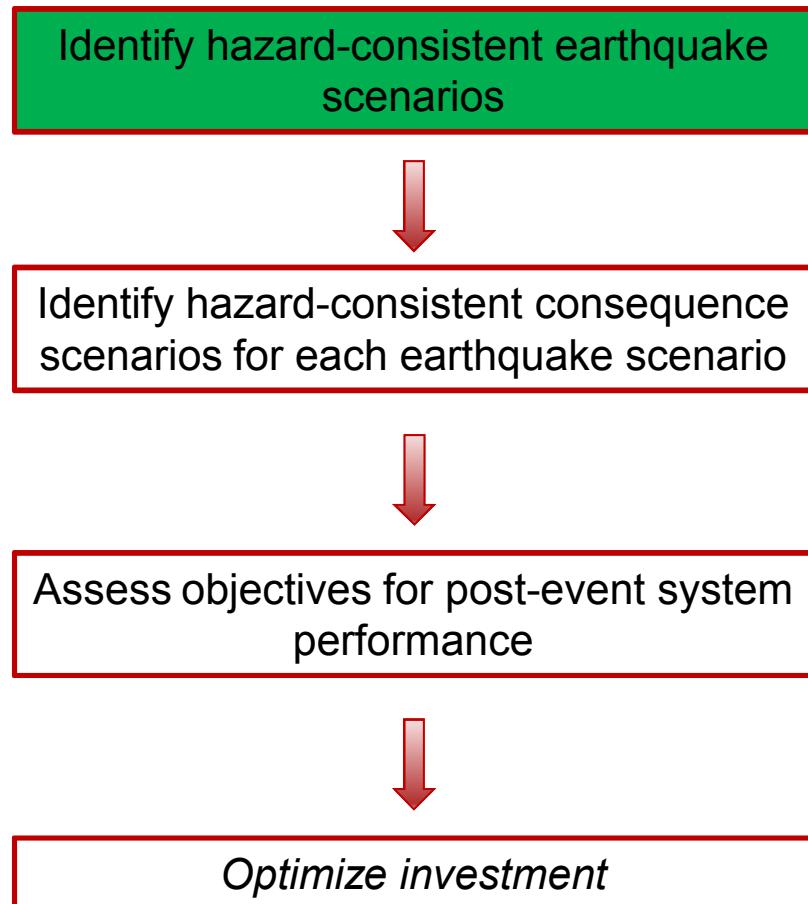
Memphis Highway Network

- Examine earthquake hazard in New Madrid Seismic Zone (NMSZ)
- Highway network overlaid with hospital locations
- Bridges are the most vulnerable components of the network
 - Damage affects both travel times and network connectivity
 - Investments can be made to reinforce bridges to reduce level of damage



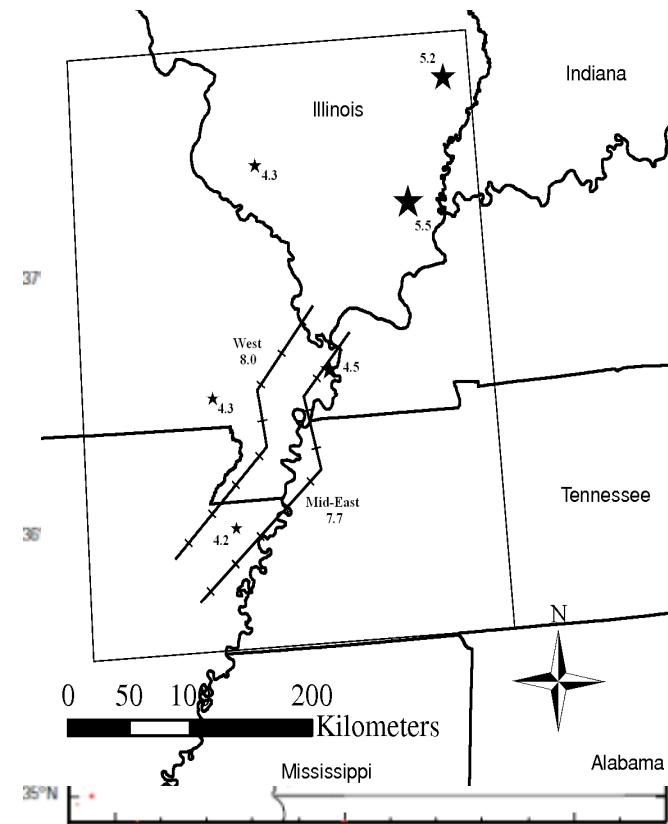
Blue dots represent highway bridges (335 total)

Modeling Process

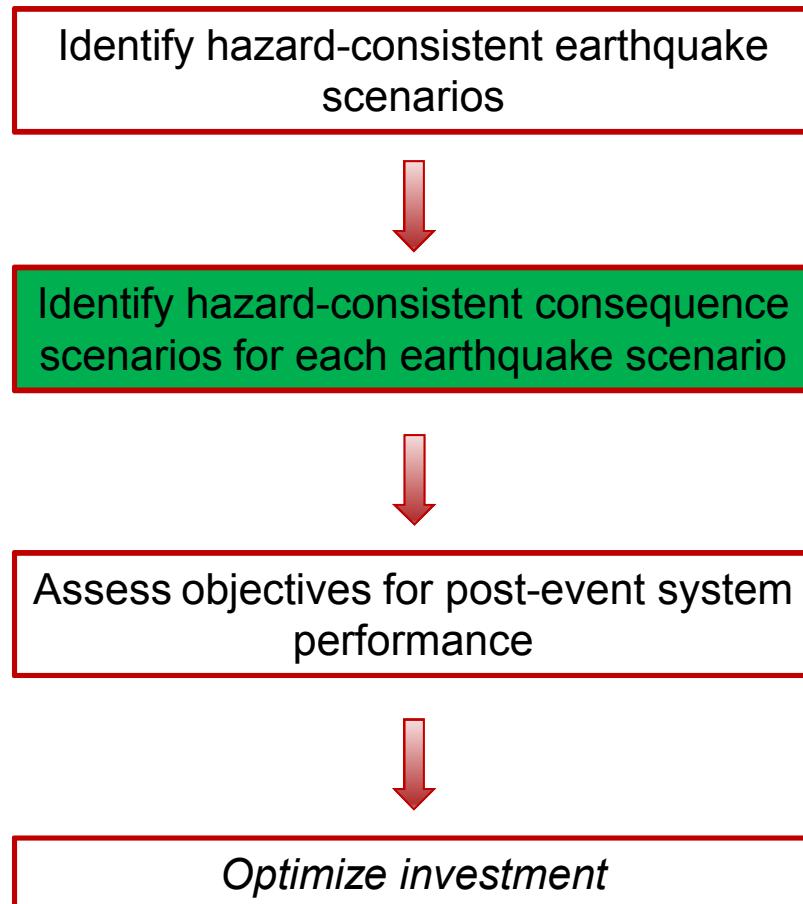


Representing the Hazard

- Analysis requires a collection of earthquake scenarios
- Two sources of candidate earthquake scenarios
 - USGS has cataloged 433 historic events
 - USGS has developed 5 synthetic faults
 - We consider 4 possible magnitudes from each fault (20 total events)
- Computations preclude considering all 453 events
- Use optimization to select a representative subset of 8 events of which only 2 are significant

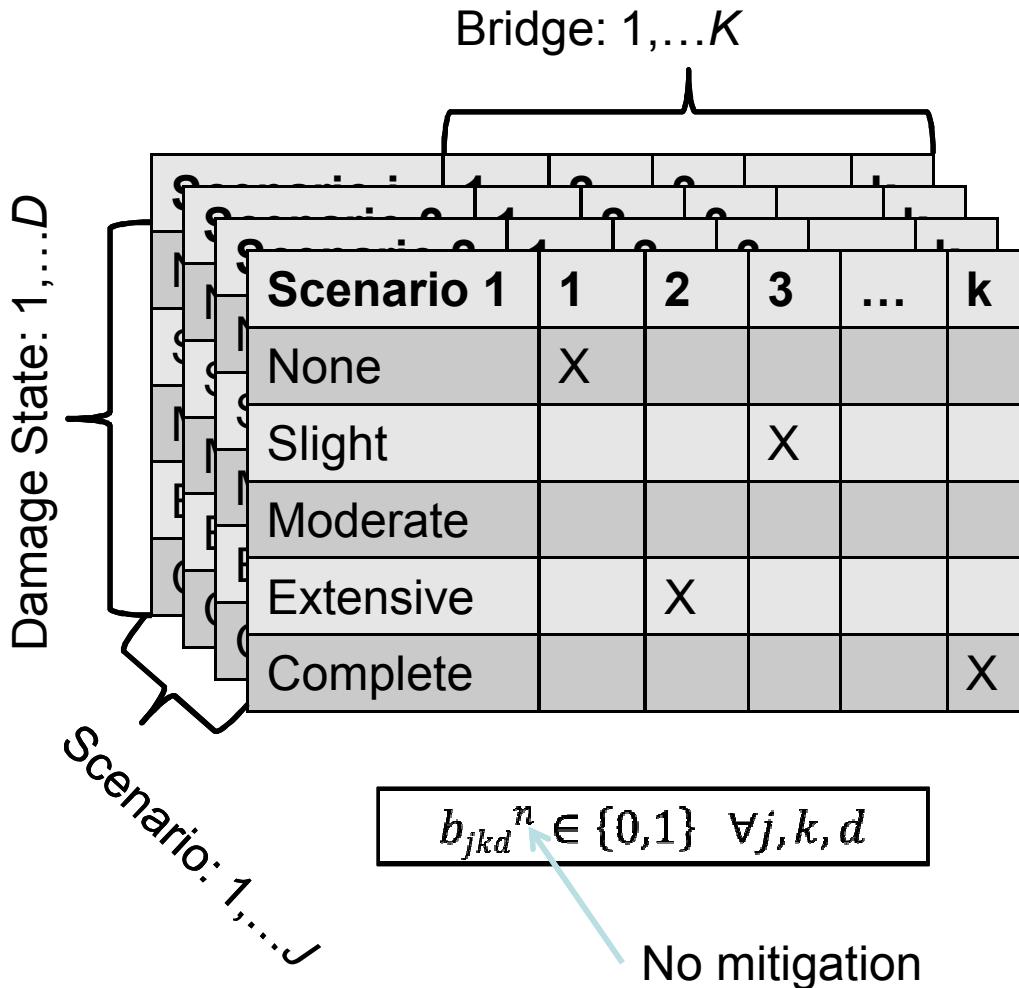


Modeling Process



Consequence Scenarios: Before Mitigation

Scenario Outcome



Scenario Probability

Scenario	Probability
1	0.3
2	0.2
3	0.15
...	
J	0.1
Total	1.0

$$0 \leq s_j \leq 1$$

Consequence Scenarios: After Mitigation

Scenario Outcome

Bridge: 1,...,K

		Scenario 1					
		1	2	3	...	k	
Damage State: 1,...,D	None	X					
	Slight			X			
	Moderate						
	Extensive		X				
	Complete						X

With Mitigation

$b_{jkd}^w \in \{0,1\} \quad \forall j, k, d$

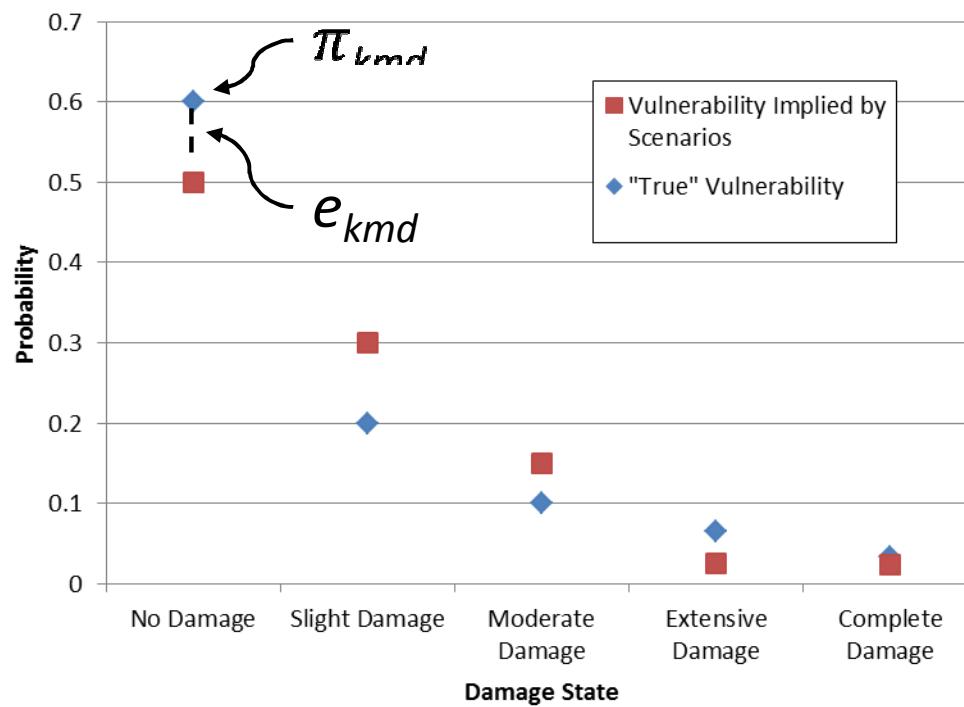
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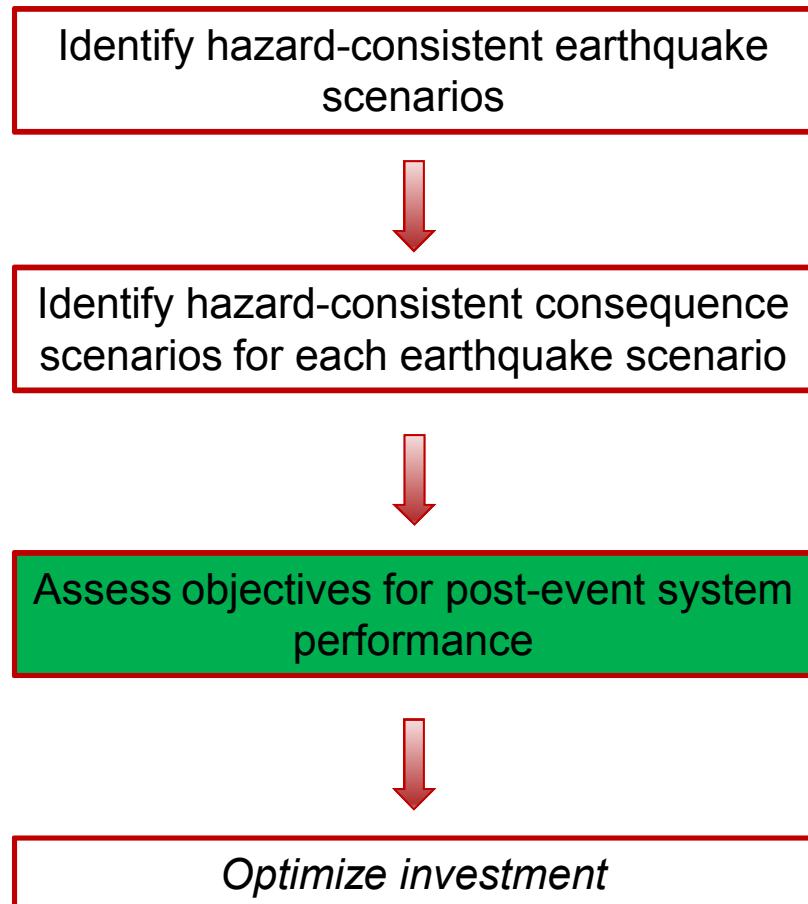
$$0 \leq s_j \leq 1$$

Approach

- Use optimization to identify a set of consequence scenarios and the probability of occurrence for each that “match” marginal distribution of damage for each component and the correlation between components



Modeling Process



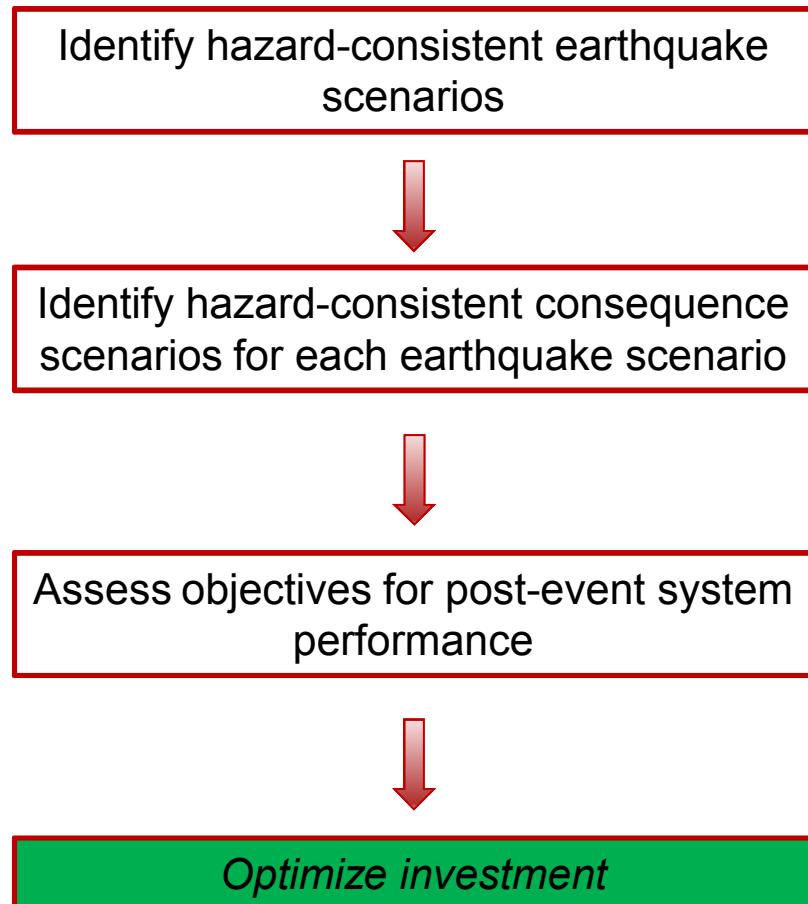
Objective Functions

- Determine optimal investment strategy which minimizes:
 - Travel Time Objective - travel time across the network
 - Hospital Connectivity Objective - travel time and disconnections from major population centers to nearby hospitals
 - Investment Cost Objective – bridge mitigation costs
- Investment cost objective is simply the sum of the mitigation costs
- The other two objectives require an assessment of the post-event network performance

Dynamic Traffic Assignment (DTA)

- Models the dynamic movement of vehicles over a network
 - An extension of Static User Equilibrium
 - Requires a collection of origin-destination tables over a defined time interval (time-varying demand)
 - Li, A., Nozick, L., Davidson, R., Brown, N., Jones, D., and Wolshon, B., "An Approximate Solution Procedure for Dynamic Traffic Assignment", *Journal of Transportation Engineering*, in press.
- Comparable to industry standard but much faster
 - Validated against DynusT and measured link counts during Katrina evacuation
 - Two day Katrina evacuation runs in about 10 seconds on 8 cores versus 110 minutes for DynusT
- "Essentially, all models are wrong, but some are useful."
 - George E. P. Box (statistician, 1919 - 2013)

Modeling Process



Investment Planning Optimization: Multi-Objective 2-Stage Stochastic Program

- Use Pareto Efficiency to evaluate each solution composed of 3 objectives
 - Avoids use of arbitrary weighting method
 - Goal is to minimize the Euclidean distance to the Pareto Frontier
- Overall objective is a weighted aggregate across 40 earthquake scenarios
 - Two earthquake events (remaining 6 do not create a sufficient level of damage to highway bridges in Memphis)
 - Each earthquake has 20 scenarios where each scenario has damage states for each bridge with/without reinforcement
 - The objective for a scenario is weighted by the scenario's probability of occurrence
- Decisions variables: the set of bridges to reinforce

Computational Challenges

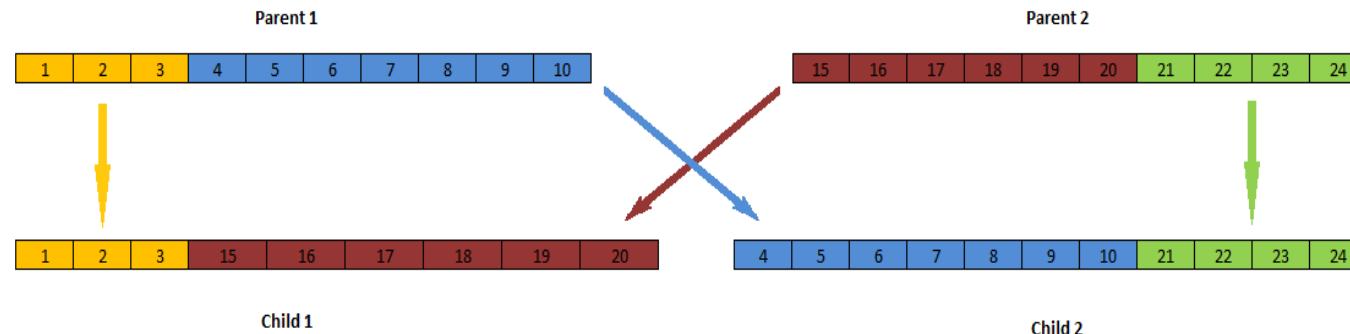
- DTA requires 11 minutes for each consequence scenario at 15 minute time intervals
- A single run requires 40 scenario evaluations at 11 minutes each = 440 minutes (7 hrs 20 min)
- There are 286 bridges that can be reinforced
 - 2^{286} different permutations $\approx 10^{86}$ \approx number of particles in the universe!
- Impossible to examine all permutations

Tabu Search Implementation

- Heuristic method for finding a near optimal solution within a large search space which may contain local optima
- Each iteration examines a single mitigation strategy and the surrounding neighborhood
- Use threading to take advantage of multiple cores
- Scenario differencing
 - Recompute values only for those scenarios that change due to a bridge reinforcement
- Subsample the evaluation space
 - Sample top 10 (25%) of earthquake scenarios based on greatest number of bridges impacted
 - Bias bridge selection towards those that impact the most scenarios
 - Run DTA at 1 hour time intervals
- Use parallel processing to cover more of the solution space

Parallel Processing

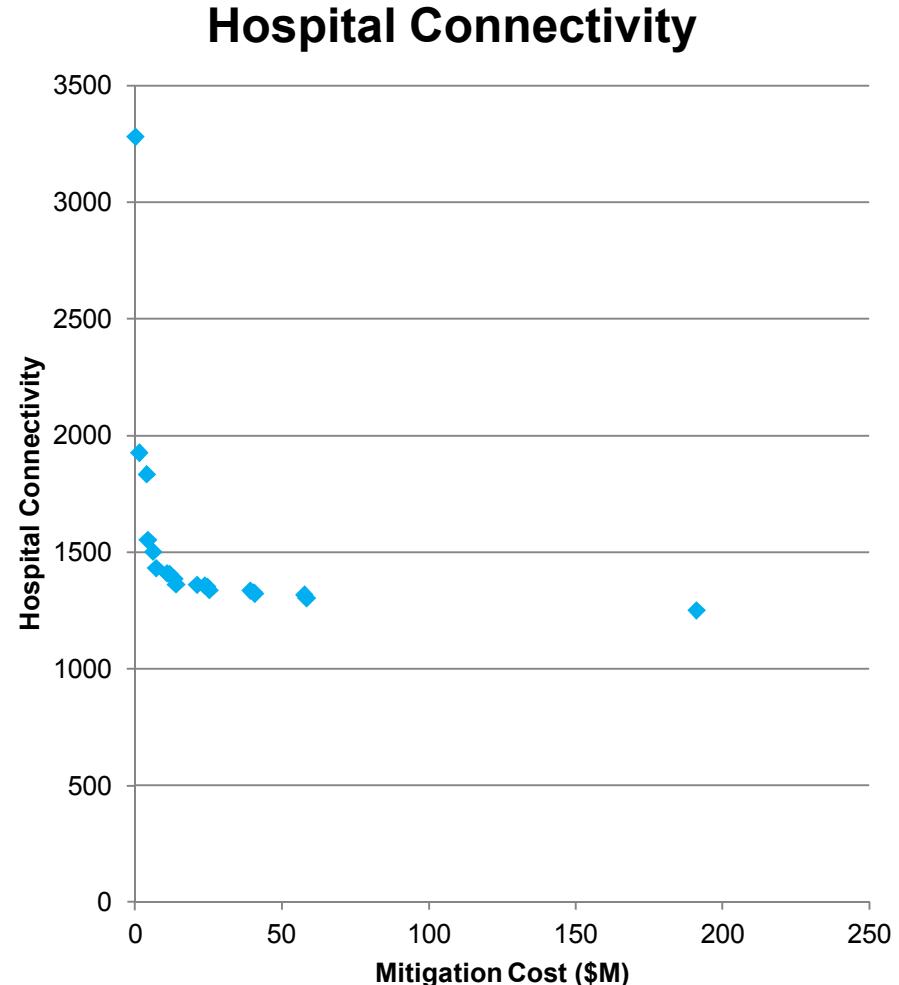
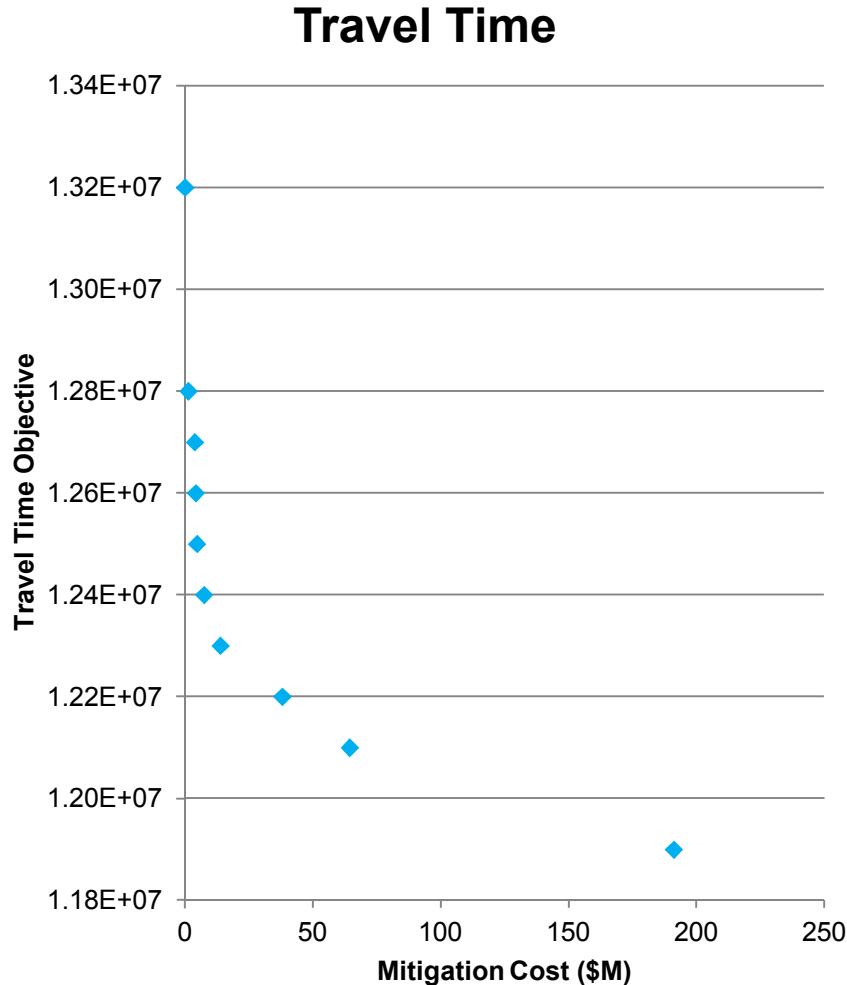
- Spawned 100 processes across a collection of compute nodes using RMI (Remote Method Invocation) and MPI (Message Passing Interface)
- Each instance starts with a random bridge mitigation strategy
- Best solution from each instance sent back to master which generates a new set of starting points via genetic crossover



- Add diversification by performing variable-rate genetic mutation
 - Used a *similarity ratio* to determine the rate of mutation
 - Ratio of bridges that are *usually* reinforced/unreinforced to total number of bridges across current collection of solutions

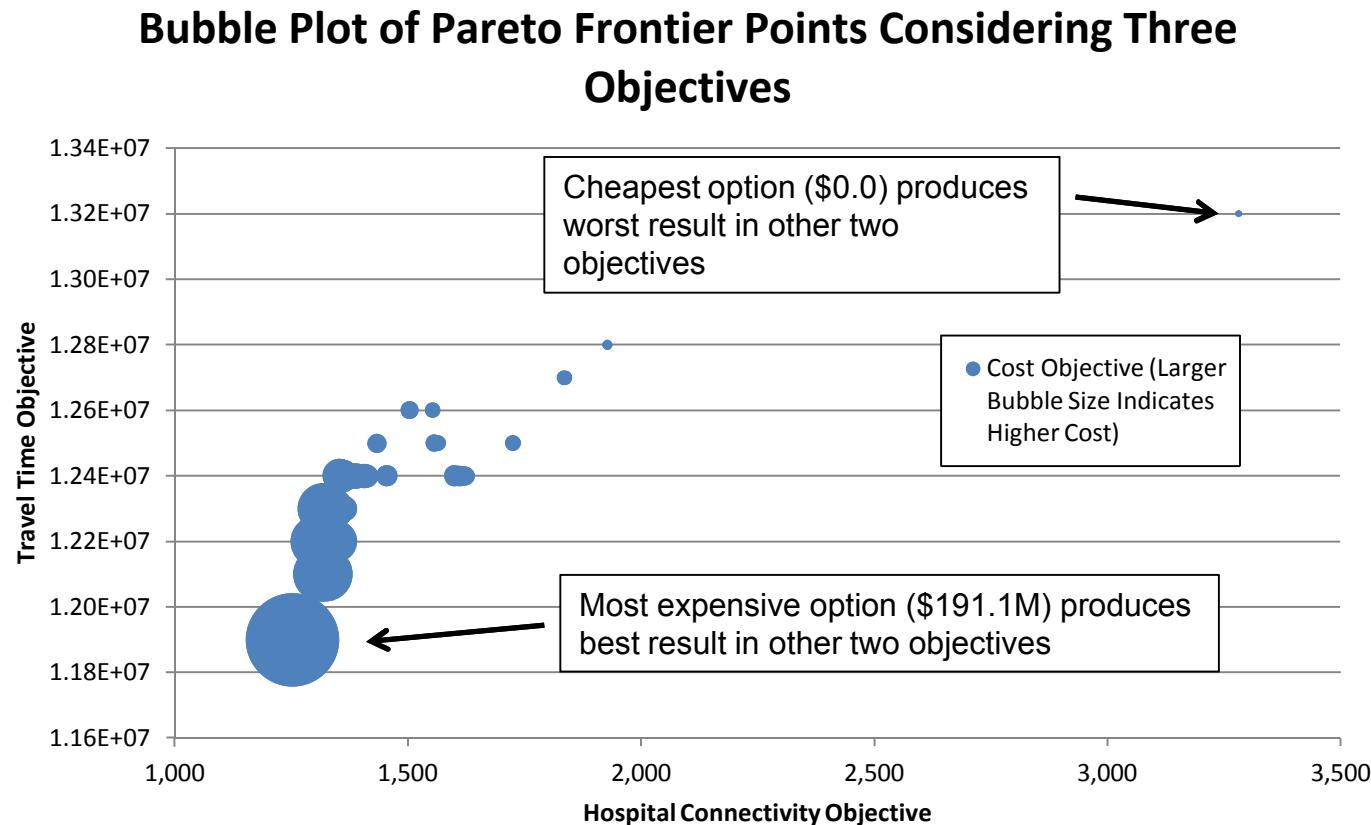
Pareto Frontier (2D)

- Pareto frontier when only 2 of the 3 objectives are examined



Pareto Frontier (3D)

- Tradeoffs across all three objectives can be explored
- Relatively small tradeoffs between travel time and hospital connectivity compared to mitigation cost



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QUESTIONS & ANSWERS



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