

A Comparison of Mortar and Tied Contact Approaches for Acoustic and Structural Acoustic Meshes

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Motivation

- Acoustic and structural meshes typically generated independently
- Acoustic and structural meshes almost always have different mesh density requirements
- Mesh tying methods have been researched extensively in solid mechanics – but not in acoustics or structural acoustics
- Fully coupled simulations are needed
 - Coupled modes, coupled frequency response

Mesh tying methods are needed for
nonconforming wet interface



Acoustic-Structure Interaction

Equations of motion of solid

$$\rho u_{tt} - \nabla \bullet \sigma = f(x, t) \quad \Omega_e x[0, T]$$

Acoustic wave equation for fluid

$$\frac{1}{c^2} \phi_{tt} - \Delta \phi = 0 \quad \Omega_f x[0, T]$$

Boundary conditions

$$\frac{\partial \phi}{\partial n} = \dot{u}_n \quad \text{Continuity of Displacement}$$

$$\sigma_n = -\hat{n} \dot{\psi} \quad \text{Continuity of Stress}$$

Weak Formulation for Time Domain

Find (u, ϕ) $[0, T] \rightarrow H_1(\Omega_f) \times (H_1(\Omega_e))^3$

$$\rho(u_{tt}, v)_{\Omega_e} - (\sigma, \nabla v)_{\Omega_e} + (\rho \dot{\phi}, v)_{\partial\Omega} = (f, v)_{\Omega_e} \quad \forall v \in (H^1(\Omega_f))^3$$

$$\frac{1}{c^2}(\phi_{tt}, \psi)_{\Omega_f} + (\nabla \phi, \nabla \psi)_{\Omega_f} + \frac{1}{c^2}(2 \nabla \phi \bullet \nabla \dot{\phi}, \psi) + \frac{1}{c^2}(\frac{B/A}{c^2} \phi \dot{\phi}, \psi) +$$

$$b(\nabla \dot{\phi}, \nabla \psi) - (\dot{u}_n, \psi)_{\partial\Omega} = 0 \quad \forall \psi \in H^1(\Omega_f) g$$

Discretized form:

$$\begin{bmatrix} M_s & 0 \\ 0 & -M_a \end{bmatrix} \begin{bmatrix} \ddot{u} \\ \ddot{\phi} \end{bmatrix} + \begin{bmatrix} C_s & L^T \\ L & -C_a \end{bmatrix} \begin{bmatrix} \dot{u} \\ \dot{\phi} \end{bmatrix} + \begin{bmatrix} K_s & 0 \\ 0 & -K_a \end{bmatrix} \begin{bmatrix} u \\ \phi \end{bmatrix} = \begin{bmatrix} f_s \\ f_a \end{bmatrix}$$



Coupling Terms

- **The surface integral is the key to the coupling methods**

$$L_{ij} = \int_{\Gamma} N_{M_i} N_{S_j} d\Gamma$$

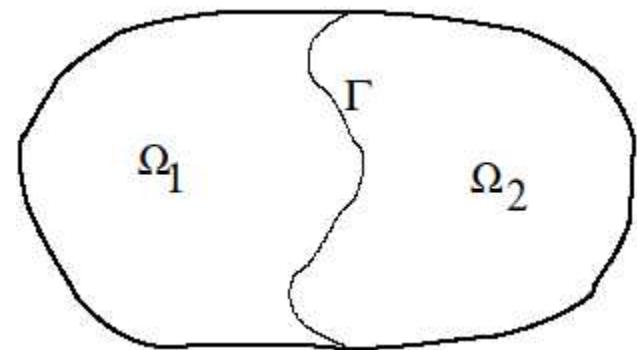
N_{M_i} Surface shape function on master side

N_{S_j} Surface shape function on slave side

- For conforming meshes, this is the classical structural-acoustic coupling matrix since N_M and N_S are the same functions and are on the same surface
- For mortar methods, N_M and N_S are different functions and are defined on different surfaces, but the integral is still the same
 - Since N_M and N_S are defined on different surfaces, a surface projection method is needed – we use approach of Laursen et al.



Mesh Tying Methods for Acoustics



Weak formulations

$$\int_{\Omega_1} \left[\frac{1}{c^2} \ddot{\psi} \phi + \nabla \psi \bullet \nabla \phi \right] d\Omega_1 = 0 \quad \int_{\Omega_2} \left[\frac{1}{c^2} \ddot{\psi} \phi + \nabla \psi \bullet \nabla \phi \right] d\Omega_2 = 0$$

Constraint equations on interface

- Classical MPC equations
- Mortar method

$$\psi_s = \sum c_i \psi_m$$

$$\int_{\Gamma} (\psi_1 - \psi_2) \eta d\Gamma = 0$$



Discretization of Boundary Constraint

Boundary Constraint Equation:

$$\int_{\Gamma} (\psi_1 - \psi_2) \eta d\Gamma = 0$$

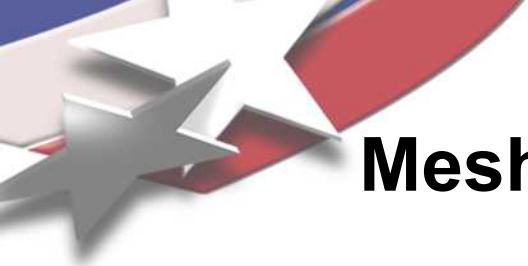
Discretization:

$$\psi_M = \sum N_{M_i}(x) \psi_{M_i} \quad \psi_S = \sum N_{S_i}(x) \psi_{S_i}$$

$$\eta = N_{S_j}$$

$$\int_{\Gamma} (\psi_1 - \psi_2) \eta d\Gamma = \sum_i \int_{\Gamma} N_{M_i} N_{S_j} d\Gamma - \sum_i \int_{\Gamma} N_{S_i} N_{S_j} d\Gamma$$

Mortar method for acoustics involves same surface integrals as for conforming structural acoustics



Mesh Tying Methods for Structural Acoustics

1. **Conforming finite element approach**
 - **Requires matching meshes**
2. **Classical multipoint constraint equations with ghost nodes**
3. **Mortar method with ghost nodes**
4. **Classical mortar method**
 - **Flemisch et al, 2006**

In all cases we need to evaluate integrals of the type: $\int_{\Gamma} N_M N_S d\Gamma$

N_M Surface shape function on master side

N_S Surface shape function on slave side



Mesh Tying Methods for Structural Acoustics

Ghost nodes approach:

- Add “ghost” acoustic degrees of freedom to solid nodes on wet interface
- Use conforming coupling operators to couple solid nodes on wet interface to appended acoustic dof
- Couple acoustic dof on both sides of wet interface with mortar or standard MPC equations

For conforming meshes, this method reduces to a conforming structural acoustics

Same constraint equations for acoustic-acoustic coupling and structural-acoustic coupling

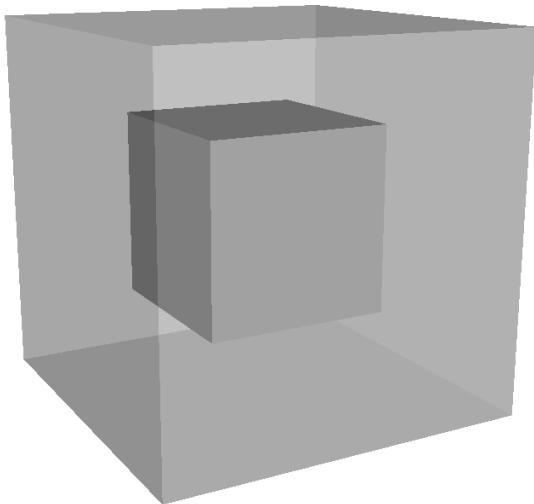


Mesh Tying for Structural Acoustics – Ghost Node Approach

(solid dof + ghost acoustic dof)



Cube-In-Cube Structural Acoustic Example

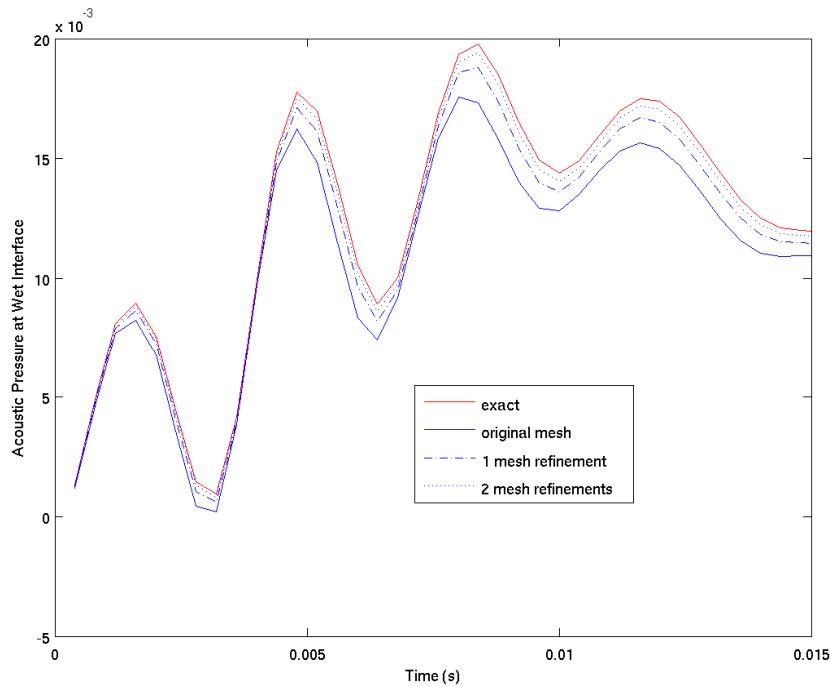


- Aluminum tank filled with water
- time-dependent pressure load (sinusoid) applied to end of tank
- far-end of tank fixed to rigid wall

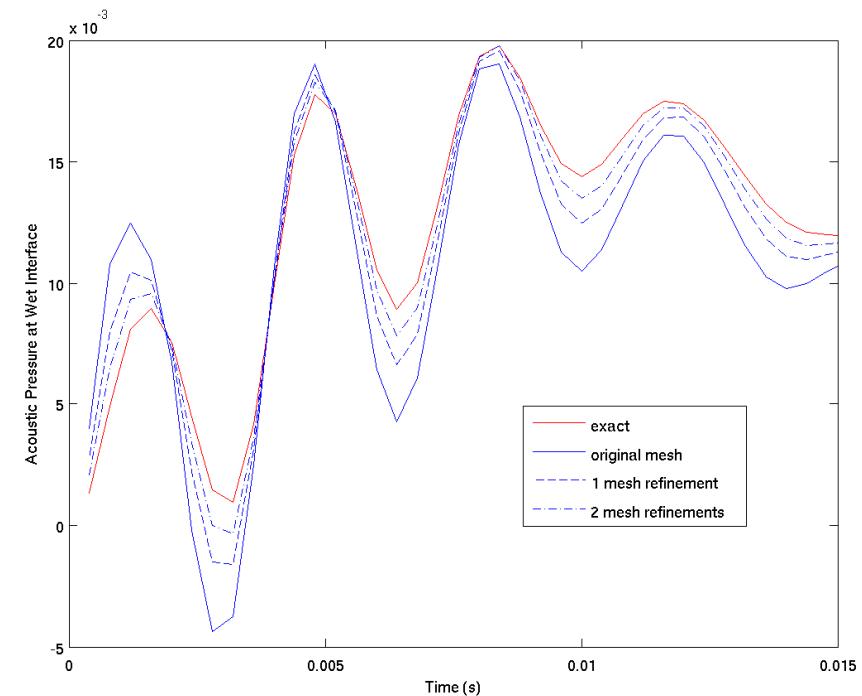
We compare the results using 3 methods:

- **Conforming meshes**
- **Nonconforming meshes with ghost nodes and classical MPCs**
- **Nonconforming meshes with ghost nodes and mortar constraints**

Convergence Results for Cube-in-Cube

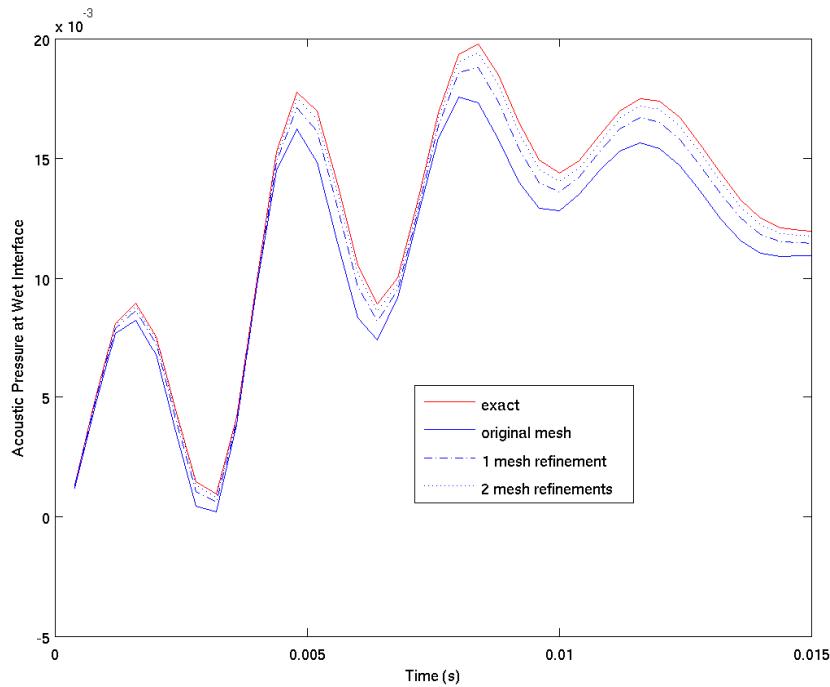


Conforming meshes

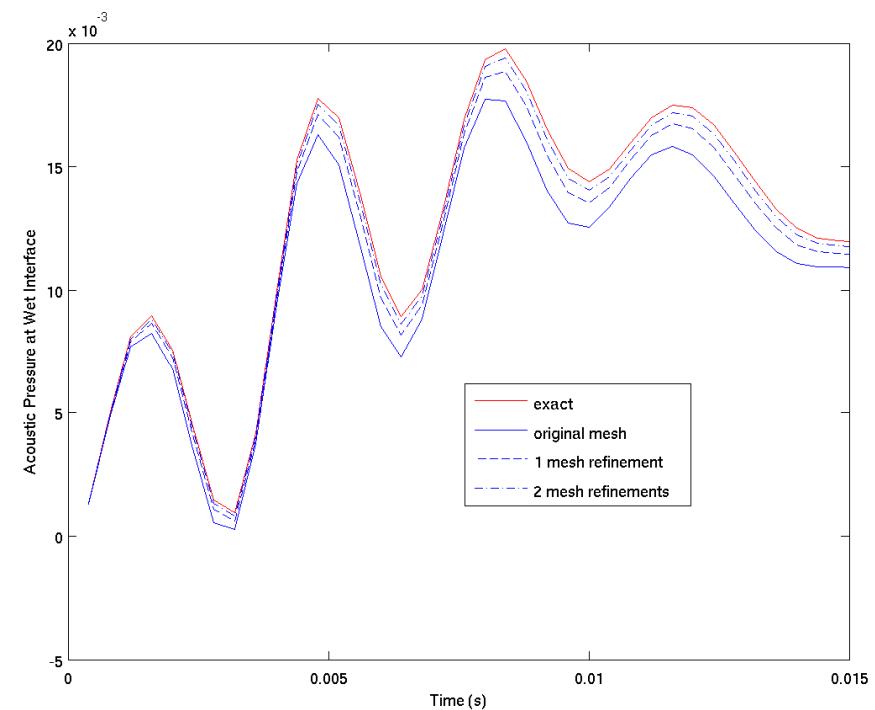


Ghost nodes approach
with classical MPC's

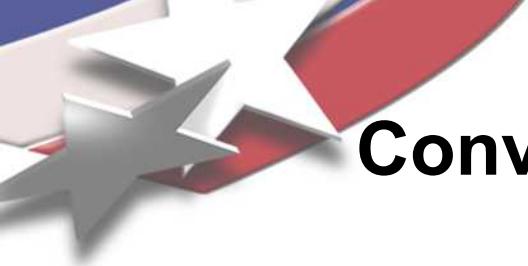
Convergence Results for Cube-in-Cube



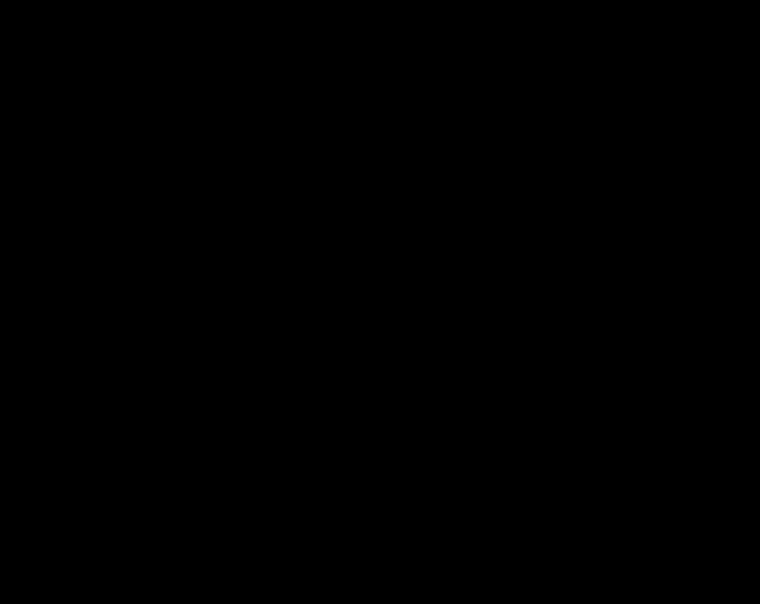
Conforming meshes



Ghost nodes approach
with mortar method



Convergence Results for Water-Castor Oil System



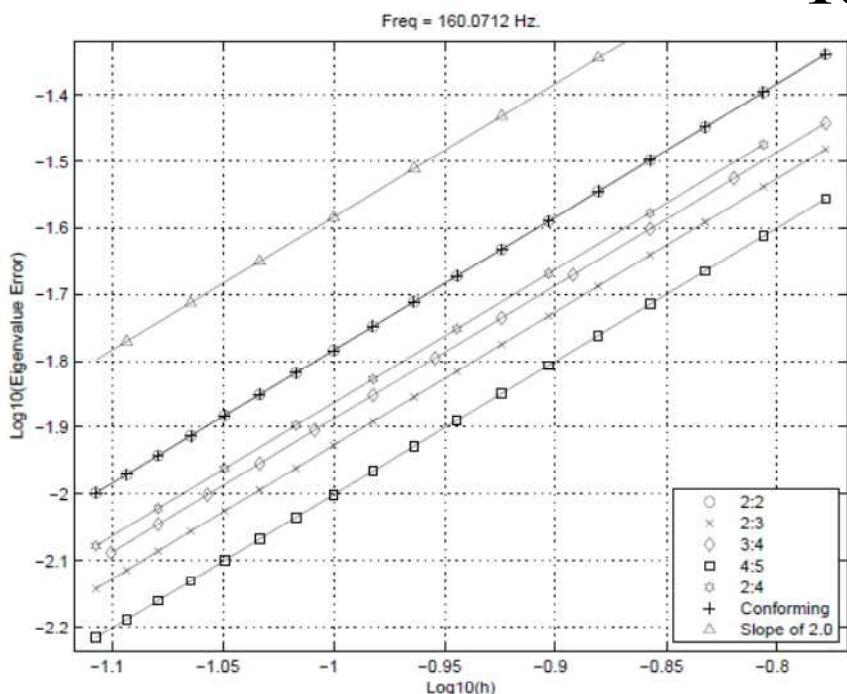
- Two-fluid tank filled with water and castor oil
- Assumed that no mixing occurs

We compare the results using 3 methods:

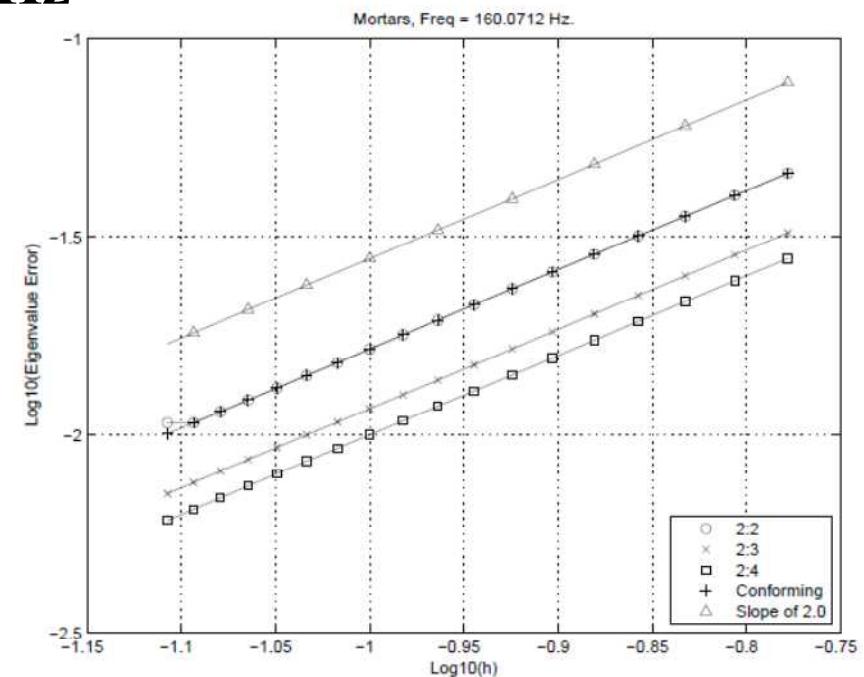
- Conforming meshes
- Nonconforming meshes with ghost nodes and classical MPCs
- Nonconforming meshes with ghost nodes and mortar constraints

Convergence Results Two-Fluid System

160 Hz



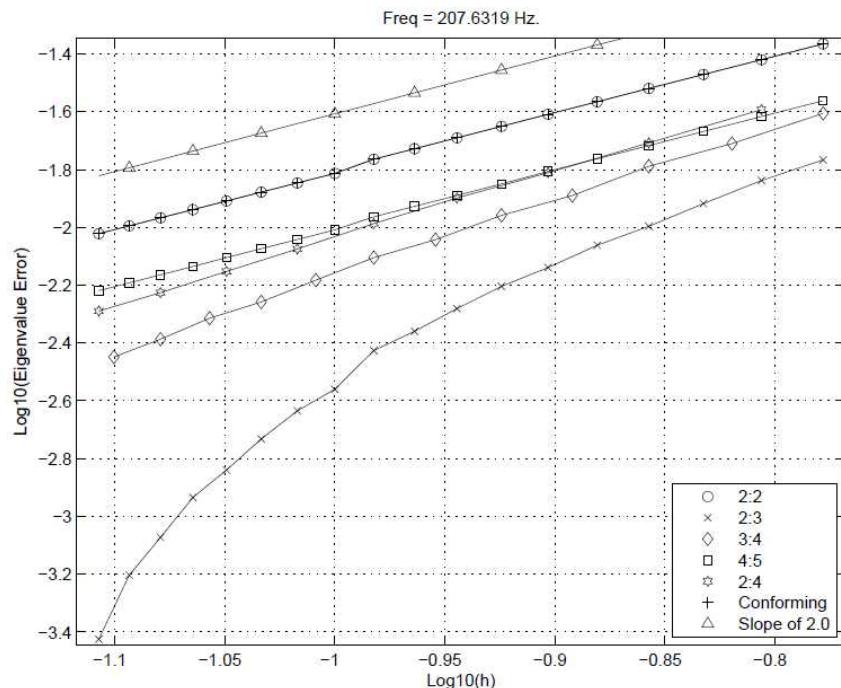
Classical MPCs



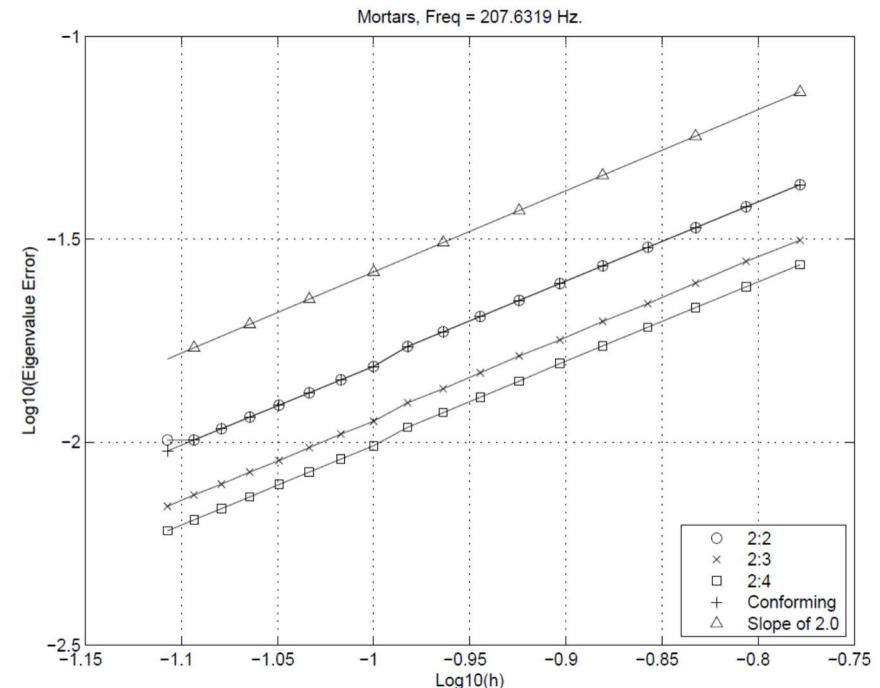
Mortar method

Convergence Results Two-Fluid System

207 Hz



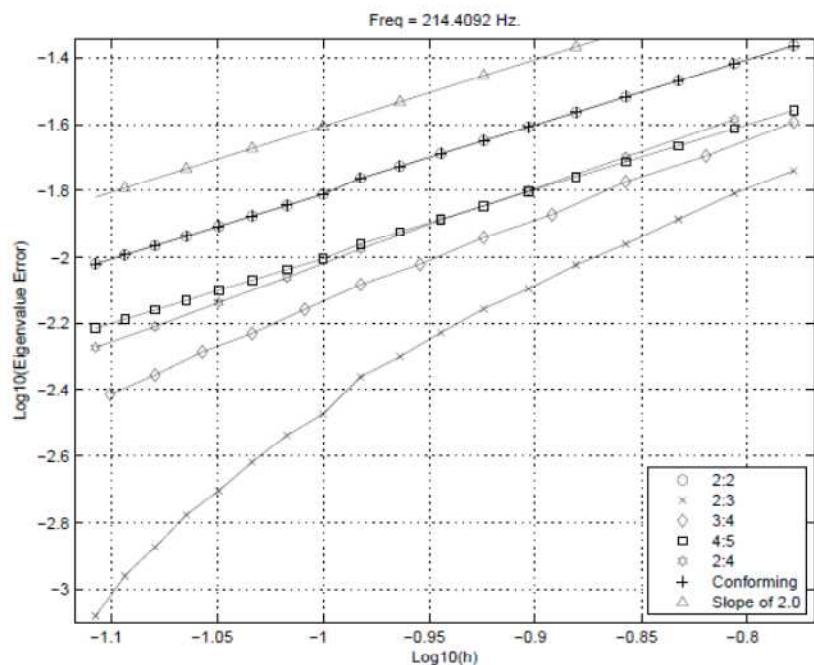
Classical MPCs



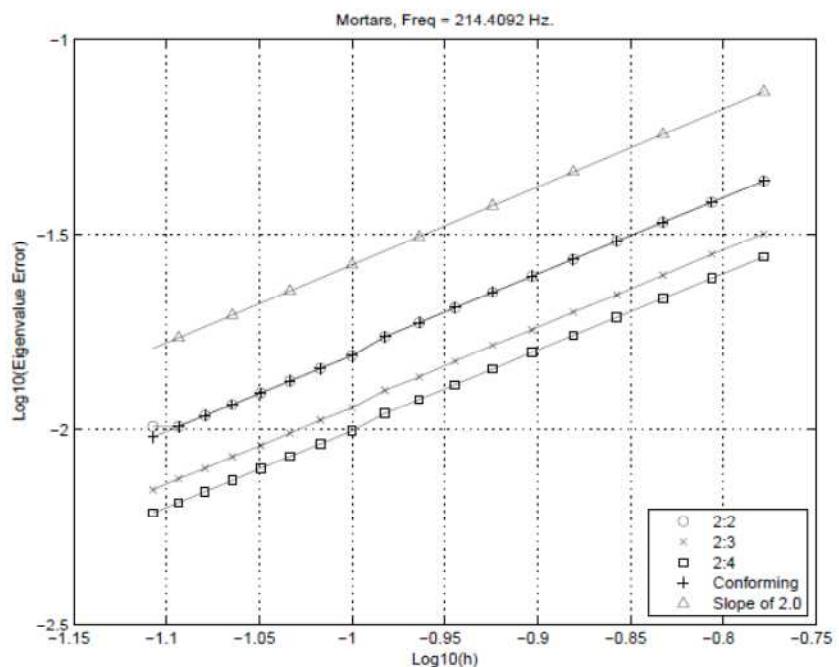
Mortar method

Convergence Results for Two-Fluid System

214 Hz



Classical MPCs



Mortar method



Observations and Conclusions

- Both Classical MPCs and mortar method demonstrate convergence for both acoustic and structural acoustic mesh tying
- Mortar method appears to converge faster on cube-in-cube transient structural acoustic problem
- For two-fluid system, mortar method appears to give convergence rates that are consistent with theory
- For two-fluid system, classical MPCs show consistent convergent rates for some modes, and inconsistent rates for other modes