

PANTHER DA Uncertainty

Approximate Pattern Matching under Uncertainty in Geospatial Semantic Graphs

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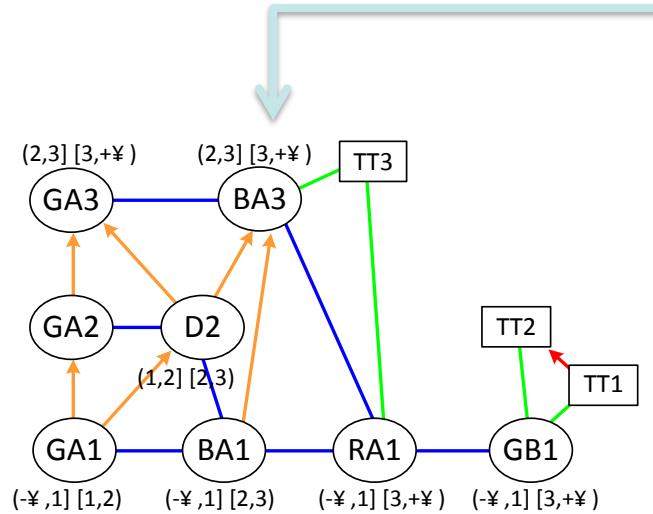
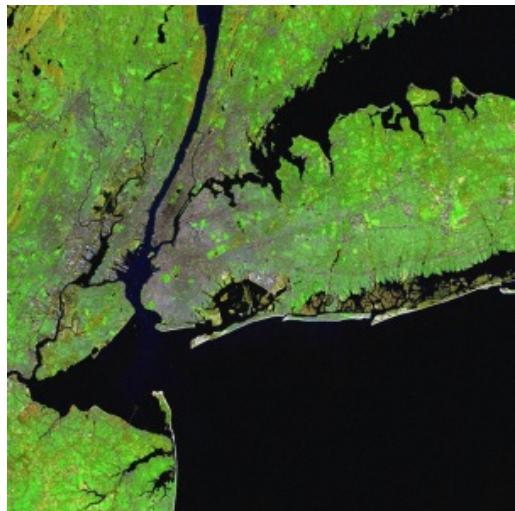


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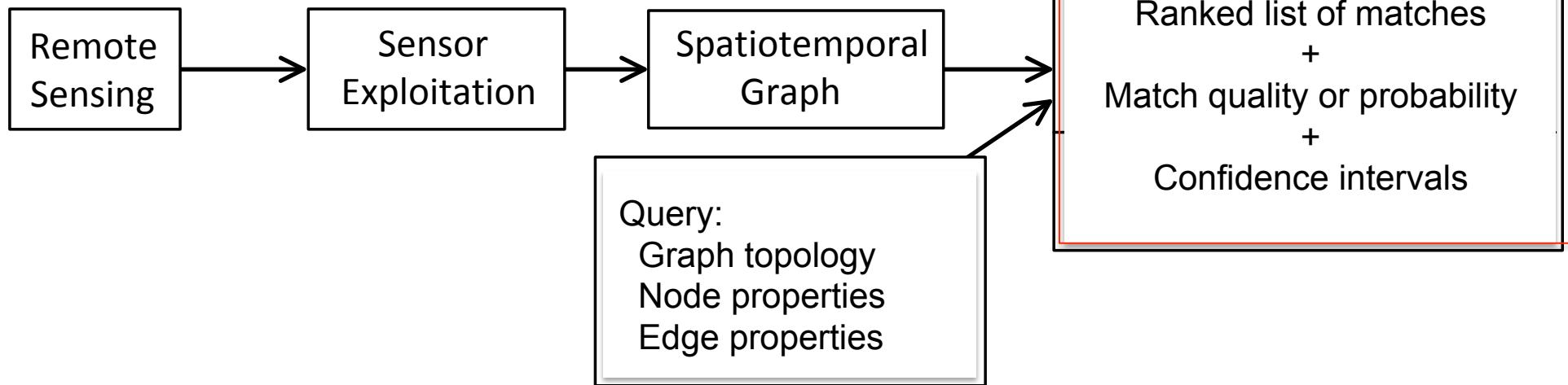


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High-Level View, Overall Problem

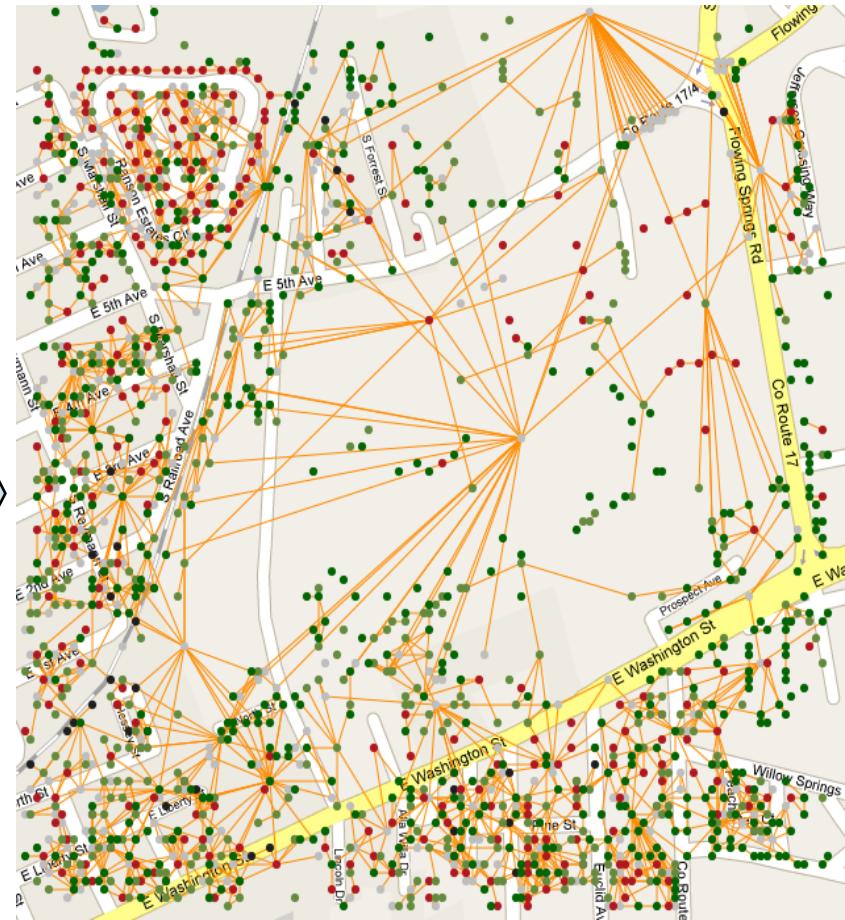
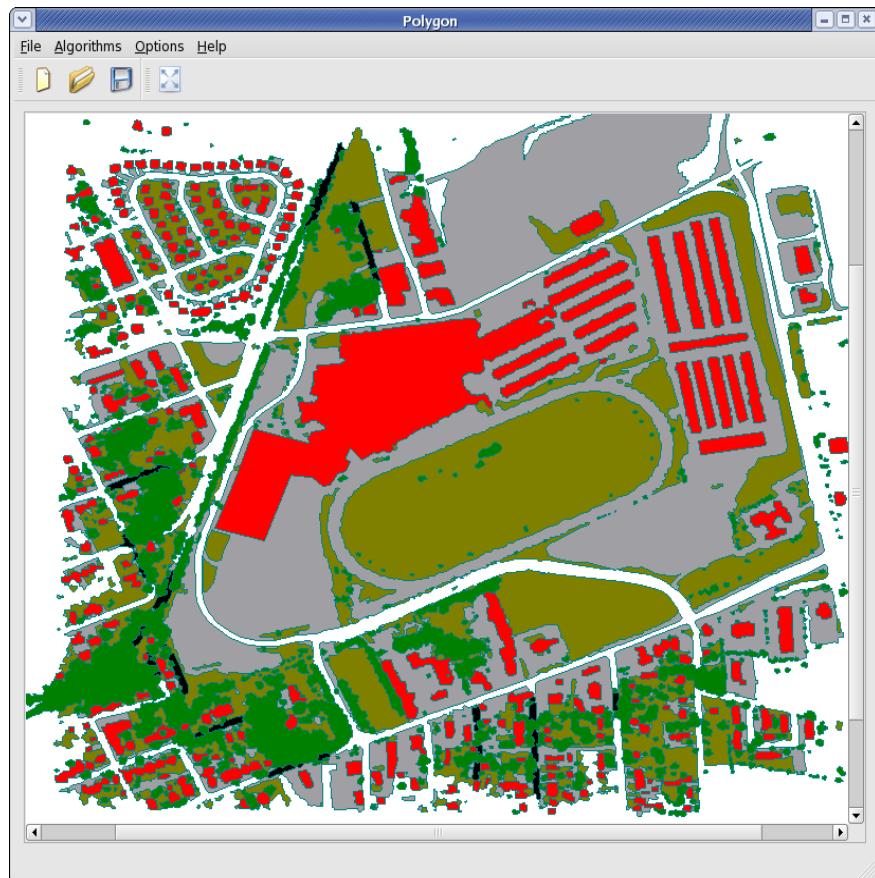


Human Analytics





Geospatial Semantic Graphs

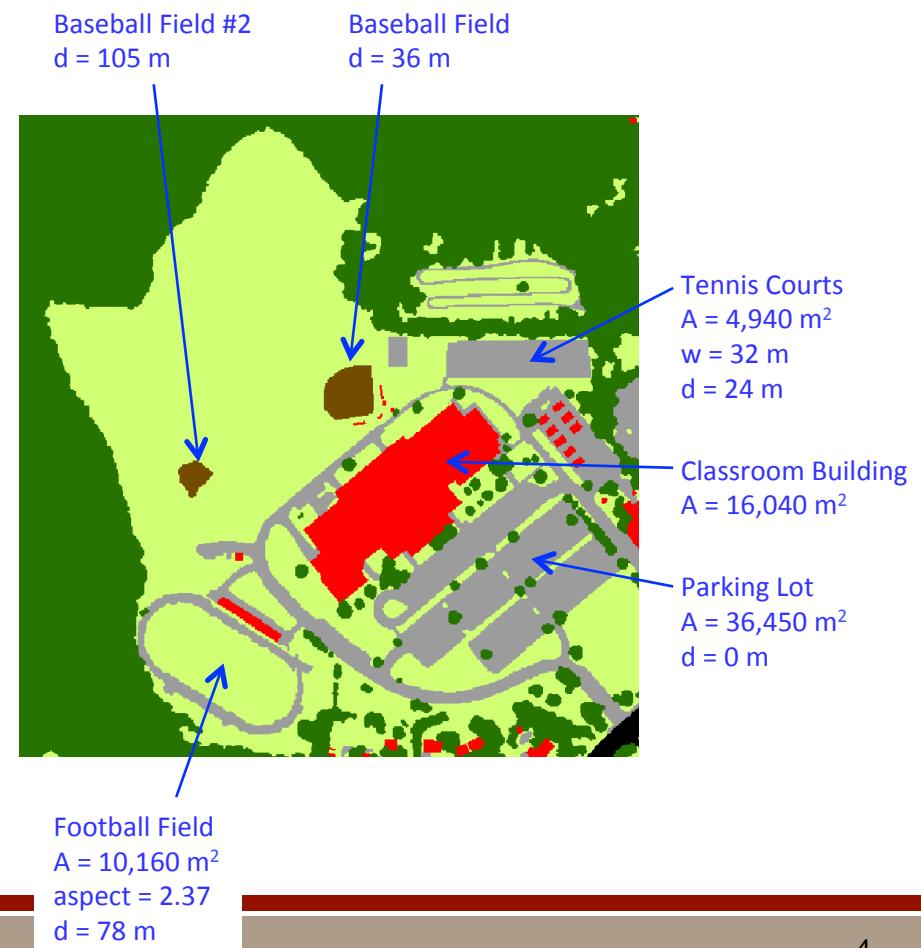


- Left: ground cover representation from an image
- Right: derived graph

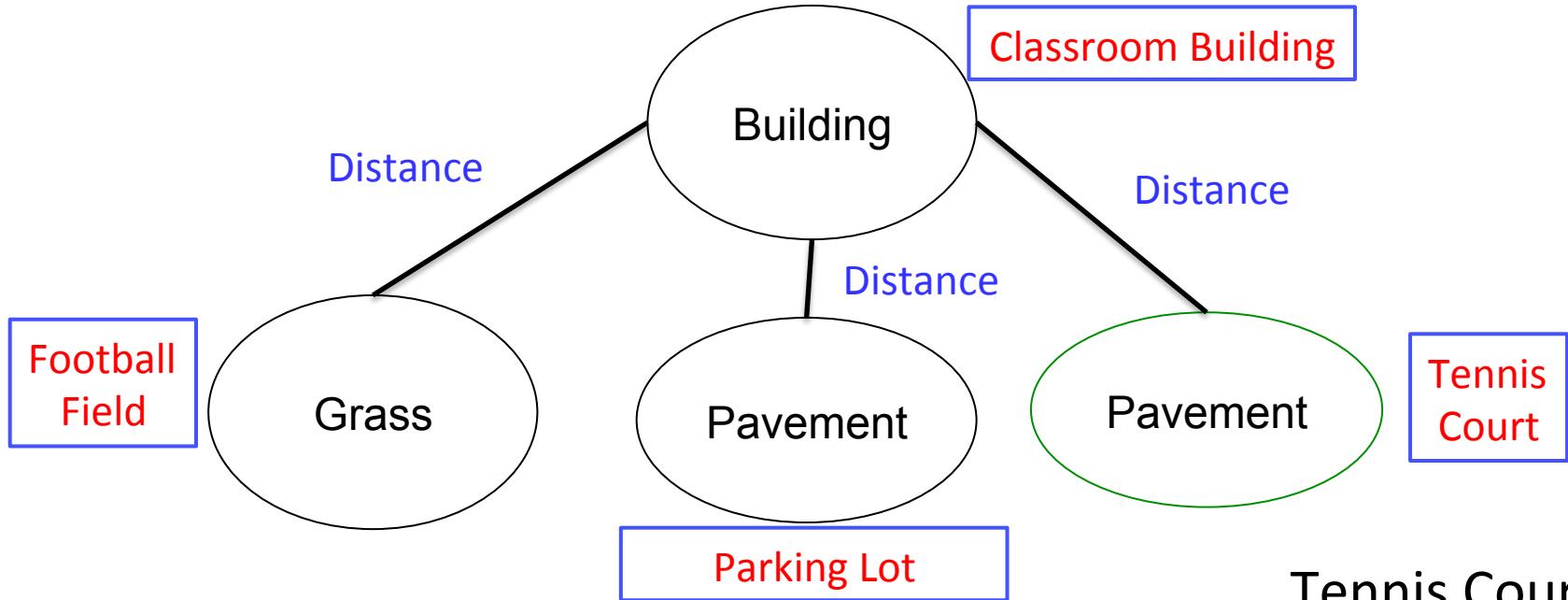


Example: Find US High School

- Ann Arundel County, MD



Example Template: High School



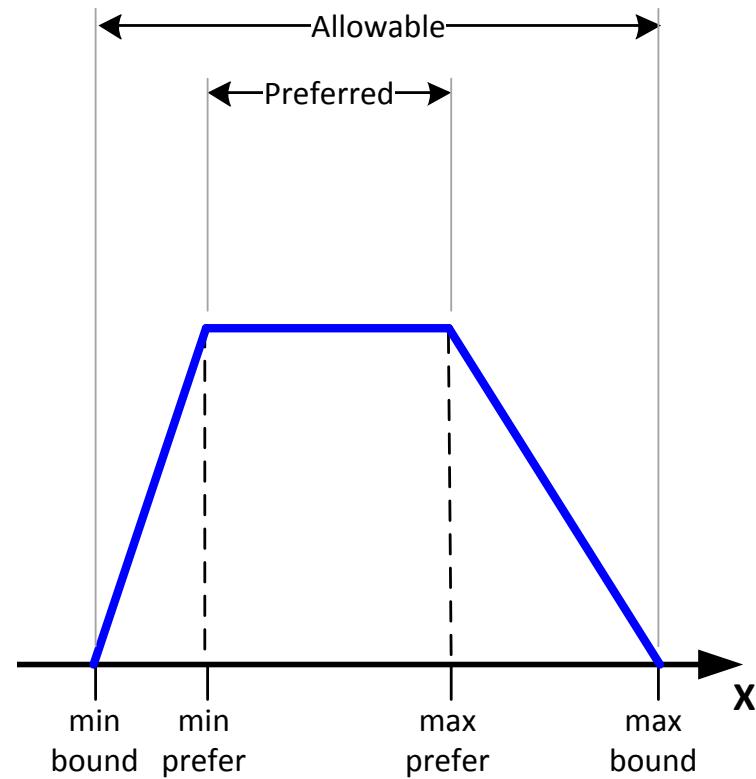
- All nodes have: **Land Cover**, **size**.
- Football field has **aspect ratio**.
- Tennis court has **width** (assume one line of courts).

Tennis Court
optional



Numerical Tolerances

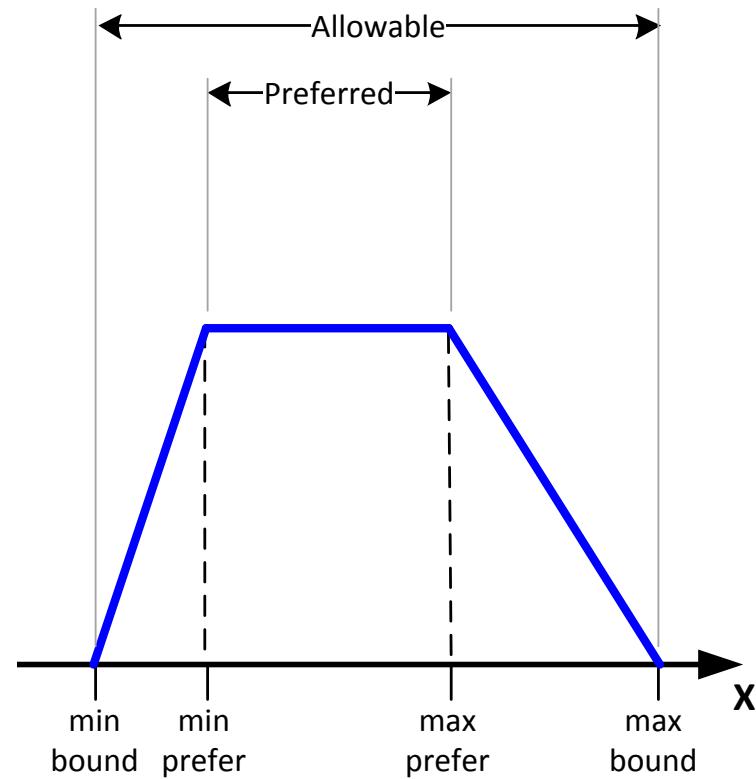
- Classroom Building
 - Size : [5000, 6000, 25000, 30000]
- Parking Lot
 - Size: [9000, 10000, 1000000000, 1000001000]
 - Distance to Classroom building : [0, 0.1, 100, 101]
- Football Field
 - Size: [8000, 8200, 10500, 10700]
 - Aspect Ratio: [1.7, 1.8, 3.2, 3.3]
 - Distance : [0, 1, 370, 600]
- Tennis Court
 - Size: [3700, 3800, 5500, 5600]
 - Width: [20, 30, 40, 50]
 - Distance : [0, 0.1, 200, 201]





Numerical Tolerances

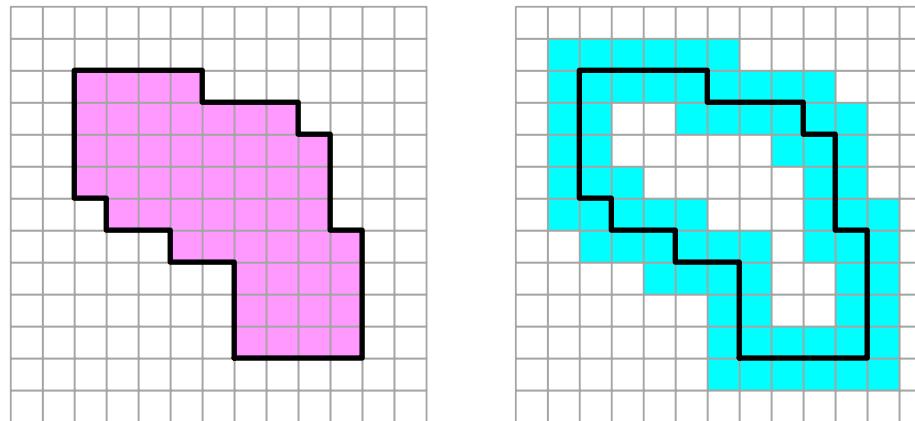
- Allows for variation among high schools
- Appropriate for any numerical value
- Discretization





Sources of Uncertainty

- (Physics) limitations of sensors
- Algorithms
- Example: Boundary uncertainty
 - Leads to uncertainty in area, aspect ratio, distances between objects





Landcover Uncertainty

Error matrix for a similar Philadelphia data set:

Algorithm output

Classified data	Reference data (ground truth)								User's
	Tree canopy	Grass/ shrub	Bare soil	Water	Buildings	Roads/ railroads	Other Paved		
Tree canopy	647	7	0	2	5	6	3	97%	
Grass/shrub	8	641	15	0	2	8	25	92%	
Bare soil	0	3	28	4	0	1	4	70%	
Water	3	1	0	158	0	0	0	98%	
Buildings	8	5	0	0	505	0	9	96%	
Roads/railroads	2	3	0	0	0	289	4	97%	
Other paved	8	21	6	1	12	5	487	90%	
Producer's	96%	94%	57%	96%	96%	94%	92%	2755	

From O'Neil-Dunne, et al, "An Object-Based System for LiDAR Data Fusion and Feature Extraction," Geocarto International, 2012.

* See R. Congalton and K. Green. *Assessing the Accuracy of Remotely Sensed Data: Principles and Practices, 2nd Edition.* CRC Press/Taylor and Francis, 2009.



Evaluating Candidates

- Goal: Given set of candidates, approximately evaluate, rank
- Methods that give probability of a match (e.g. high school)
 1. Elicitation, regression to a beta distribution
 2. Bayes Network
 3. Hierarchical Naïve Bayes
- Methods that score match/distance to the template
 4. Our quality score metric
 5. Earth Mover's Distance
- Score does not comment on semantic meaning, only the quality of match to what the analyst asked for.



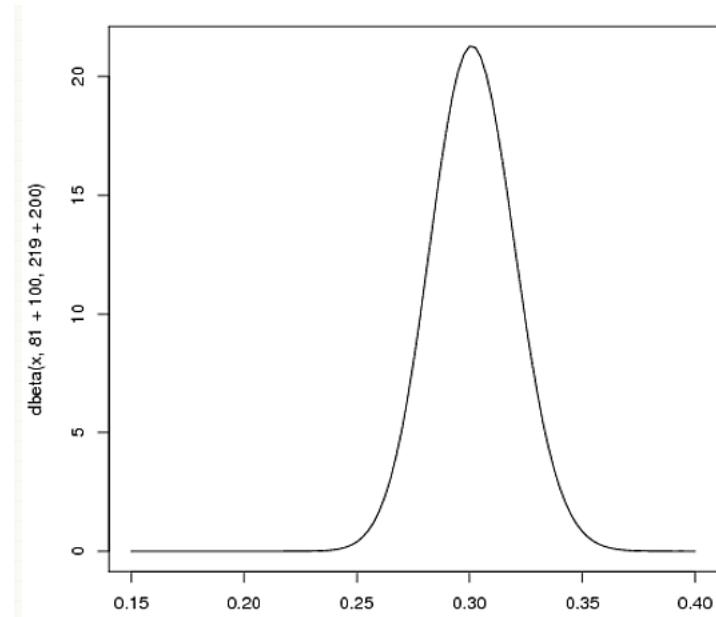
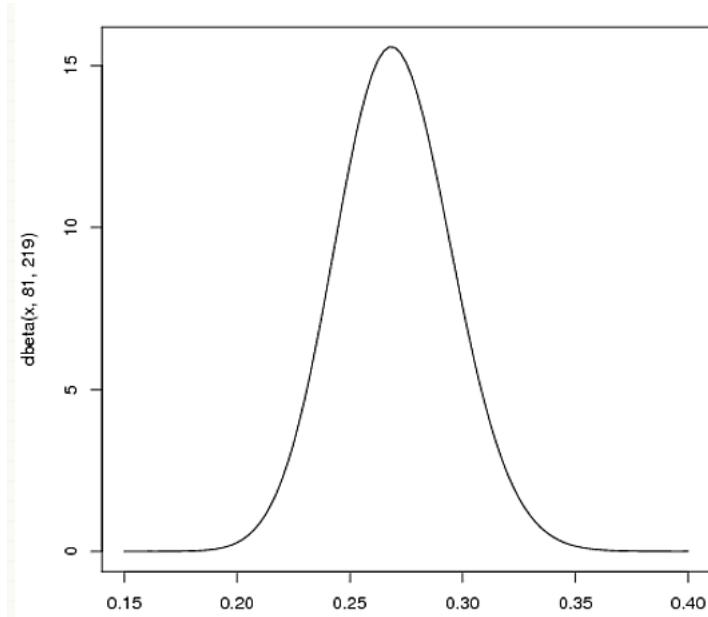
1. Elicitation-based method

- Assume training data is rare: “unicorn farm.”
- Elicit information from experts one attribute at a time.
 - Order attributes by importance.
 - Elicit trapezoid values: preferred and allowable ranges.
 - Estimate p_1 , probability of HS if attribute one is in preferred range.
 - Estimate p_i , **additional** probability of a HS if **all** of the first $i-1$ attributes in **preferred range**.
 - If $\sum_{i=1}^n p_i < 1$, remaining probability represents other hypotheses
- This elicitation is **difficult** for the “unicorn farm” expert



Beta Distribution

- Beta(α, β) has mean $\alpha/(\alpha+\beta)$. Larger values of α, β tighter.



- Distribution of probabilities
- Represent prior knowledge. Posterior knowledge still beta.

David Robinson, from stats.stackexchange.com



Compute a beta distribution

- Assume the mean at each step is linear function of attributes:

$$\sum_{j=1}^i (\gamma_{j,0} + \gamma_{j,1}z_j)$$

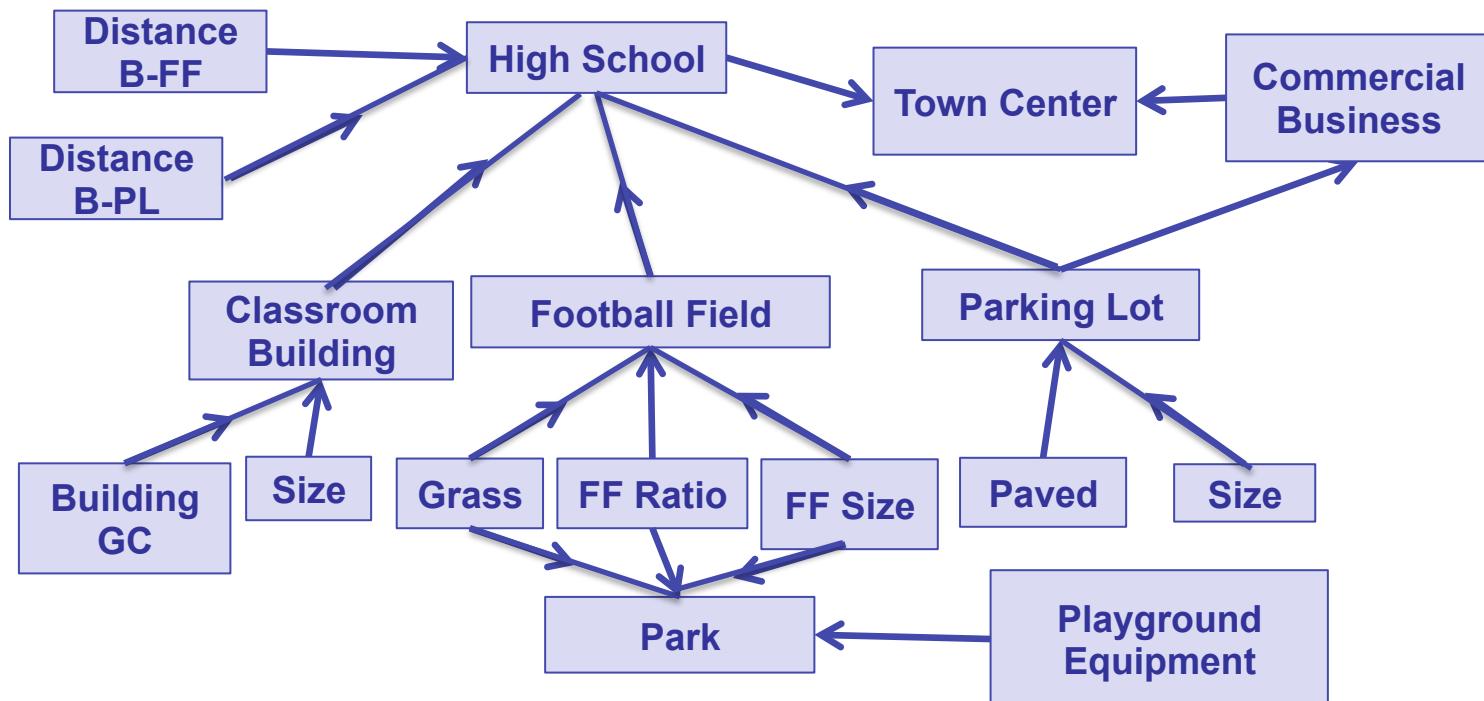
where γ are regression values, z_j represent deviation from preferred value range for the candidate match.

- Infer $\gamma_{j,0}$ from preferred values where $z_j = 0$.
- Infer $\gamma_{j,1}$ from the instances.
- For confidence intervals: confidence from experts gives a measure of variance. Can compute weight around mean.
- **Order matters:** Don't get full credit if the earlier values upon which p_i is conditioned are not perfect.

2. Bayes Nets



- Directed Acyclic Graph
 - Nodes are variables.
 - Edges represent conditional dependence.
 - Non-edges represent conditional independence.



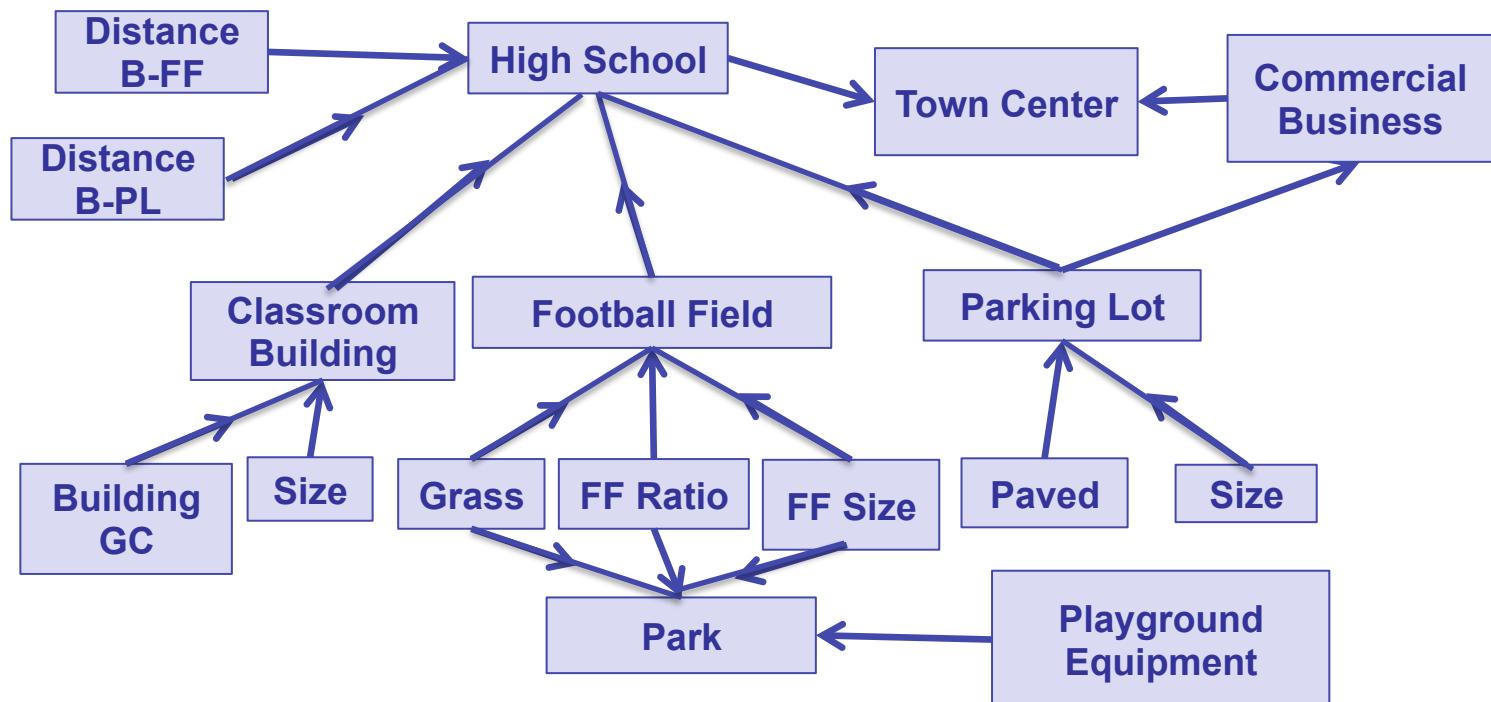


Bayes Nets

- Requires more data than we are ever likely to have.

Conditional Prob of HS	Football Field	Classroom Building	Parking Lot	Distance (BP)	Distance (BF)
.95	1	1	1	1	1
.20	1	0	1	0	0
.30	0	1	1	1	0
.70	1	1	0	0	1

Etc...

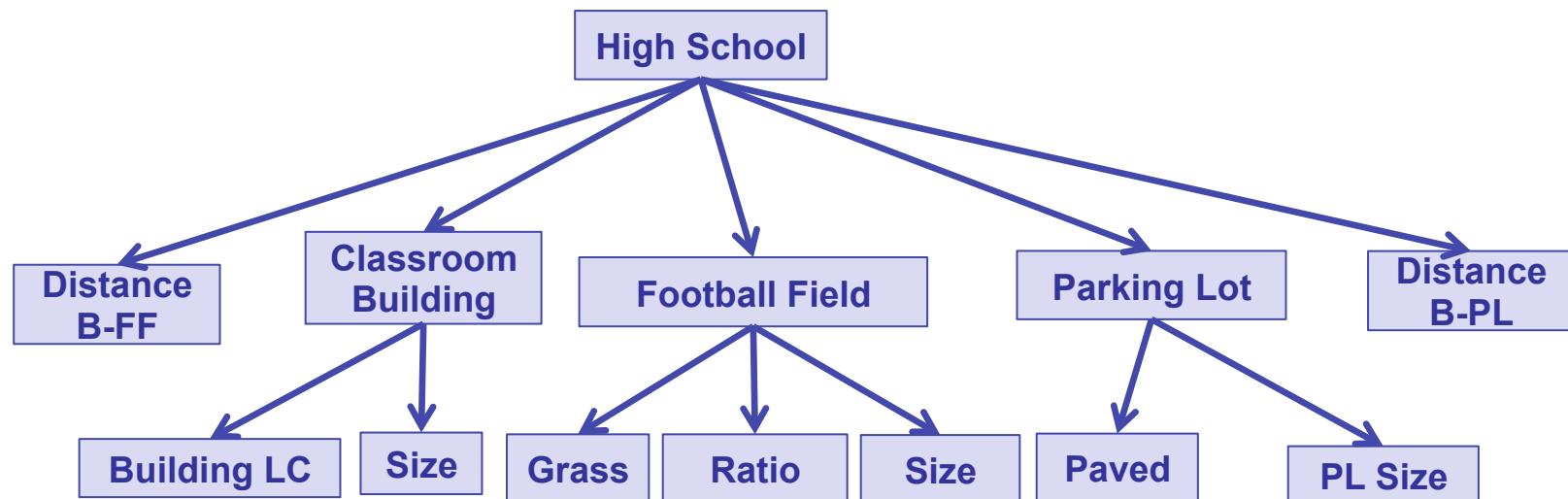




3. Hierarchical Naïve Bayes

- We create ensembles from features and other ensembles
- Assume attribute values are conditionally independent given the object class.

$$P(H|F, B, L, d_1, d_2) = \frac{P(H)P(F|HS)P(B|HS)P(L|HS)P(d_1|HS)P(d_2|HS)}{P(F, B, L, d_1, d_2)}$$

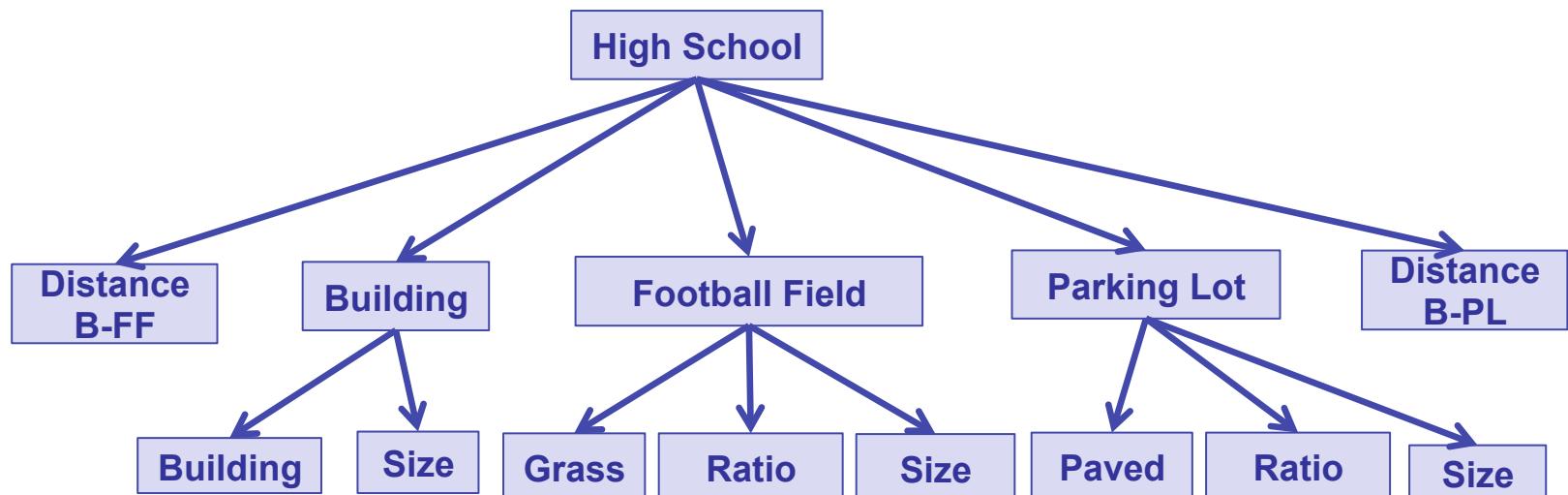




Hierarchical Naïve Bayes

- Requires training data.
- Challenge defining what to count/how to estimate conditional probabilities.

$$P(H|F, B, L, d_1, d_2) = \frac{P(H)P(F|HS)P(B|HS)P(L|HS)P(d_1|HS)P(d_2|HS)}{P(F, B, L, d_1, d_2)}$$





4. Scoring Match Quality

- Scoring individual pieces q_i
 - Ground cover: score using confusion matrix
 - Area, distance, aspect ratio:
 - Compute a range of values based on sensor limitations
 - Score is percentage of the range within preferred/acceptable range
 - Other options for more complex attributes
- How to combine the individual scores?



Desired Score Properties

1. Intuitive magnitude \Rightarrow range (0,1]; good scores e.g. ≈ 0.9 .
2. Increasing number of attributes, components \Rightarrow stable score.
3. Low-probability required components \Rightarrow very low score.
4. Low-probability optional components \Rightarrow stable score.
5. Optional components present \Rightarrow increase score.
6. Smooth:
 - Smooth degradation with noise, uncertainty.
 - Avoid binary decisions causing discontinuous behavior.
7. Monotonic response to component scores.
8. Not sensitive to order of attributes or components.
9. Differentiate required vs. optional components.
10. Adjustable contribution of required vs. optional components.
11. Adjustable weights of individual components.
12. Understand relationship between attribute and component contributions.
 - Avoid instabilities.



Geometric Mean Approach

Normalizing joint probability product:

where:

$$q = \sqrt[n_a]{\prod_i \prod_j q_{ij}}$$

q Overall quality score.
 n_c Number of template components.
 n_a Number of attributes per component.
 i Component index.
 j Attribute index.
 q_{ij} Quality of attribute j for component i .

- Intuitive: Good scores remain near 1.0. → Supports goal #1.
- Provides stable aggregate score, regardless of n . → Supports goal #2.
- Low-probability components drive a small score. → Supports goal #3.
- Smooth, monotonic. → Supports goals #6 and #7.
- Insensitive to order. → Supports goal #8.
- Understandable attribute/component relationship. → Supports goal #12.



Extending to Include Weighting

Attribute equation:

$$q_i = \sqrt[n_{ia}]{\prod_j q_{ij}}$$

where:

- q_i Quality score for component i .
- n_{ia} Number of attributes for component i .
- j Attribute index.
- q_{ij} Quality of attribute j for component i .
- $q_{ij} \in (0, 1]$; note that $q_{ij} \neq 0$.

Component equation:

$$q = \sqrt{\prod_i q_i^{k_i}}$$

where:

- q Overall quality score.
- k_i Weighting exponent for component i .
- i Component index.
- q_i Quality score for component i .
- $q_i \in (0, 1]$ follows from constraint on q_{ij} .

The vector of weights $[k_1 \ k_2 \ k_3 \ \dots \ k_{nk}]$ can be arbitrary.



What If All k Values are Equal?

If all $k_i = 1$:

$$q = \left[\prod_i q_i \right]^{\frac{1}{n}}$$

Quality q reduces to simply the geometric mean.

Compare to arithmetic mean:

$$q_{\text{arith}} = \left[\frac{\sum_i q_i}{n} \right]$$



Partitioning Required and Optional

General equation:

$$Q = \left[\prod_i q_i^{k_i} \right]^{\frac{1}{\sum k_i}}$$

- k_i values are an arbitrary vector.

Reducing free parameters:

- Partition components into “required” and “optional” subsets.
- For each required component, select $k_i = k$.
- For each optional component, select $k_i = 1$.
- Resulting quality score:

$$Q = \left\{ \left[\prod_{\text{req}} q_i^k \right] \left[\prod_{\text{opt}} q_i \right] \right\}^{\frac{1}{n_{\text{req}} k + n_{\text{opt}}}}$$

- This allows quality score to have a different response to required vs. optional components, controlled by a single adjustment parameter k .



Calculating k

Method:

- Choose small “zero” quality score q_{zero} corresponding to clear absence of a required feature (for example, select $q_{\text{zero}} = 0.0001$).* Assure all $q_i \geq q_{\text{zero}}$.
- Choose desired quality score q_{pr} desired when all required components have perfect quality (for example, select $q_{\text{pr}} = 0.75$). q_{pr} = 0.75 Free adjustment parameter.
- Compute k:

$$k = \left(\frac{n_{\text{opt}}}{n_{\text{req}}} \right) \left[\left(\frac{\log(q_{\text{zero}})}{\log(q_{\text{pr}})} \right) - 1 \right]$$

where:

n_{req} Number of required components.
 n_{opt} Number of optional components.

* The special value $q_{\text{zero}} > 0$ is required:

- (a) to prevent a missing optional component from driving the overall score to zero, and
- (b) to prevent $\log(q_{\text{zero}})$ from blowing up when computing k.

If the same q_{zero} value is used when computing k and setting minimum quality scores, then the overall q value is not sensitive to the choice of q_{zero} , when all required components are present.



Advantages

Advantages of partitioned geometric mean:

- Intuitive: Good scores remain near 1.0. → Supports goal #1.
- Provides stable aggregate score, regardless of n. → Supports goal #2.
- Low-probability required components drive a small score. → Supports goal #3.
- Low-probability optional components leave score stable. → Supports goal #4.
- High-probability optional components increase score. → Supports goal #5.
- Smooth, monotonic. → Supports goals #6 and #7.
- Insensitive to order. → Supports goal #8.
- Adjustable required/optional differentiation. → Supports goals #9 and #10.
- Individual component weights possible. → Supports goal #11.
- Understandable attribute/component relationship. → Supports goal #12.



Confidence intervals for Scores

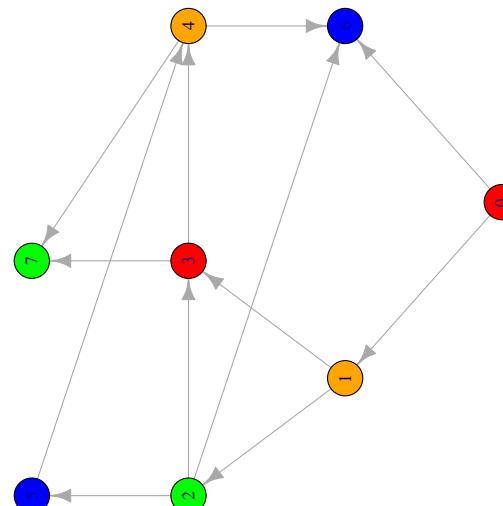
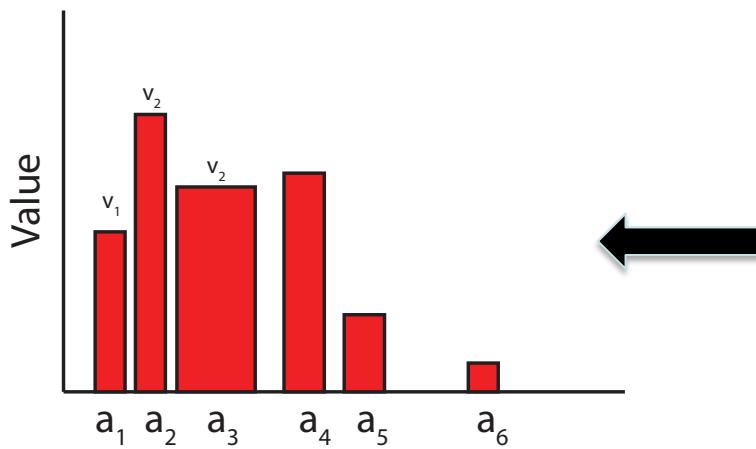
Bootstrapping:

- Generate many random tuples of values from the initial data based on uncertainty
 - Draw from the confusion matrix for ground cover
 - Draw from intervals for numerical values
- Compute score for each instance
- Compute desired percentile (e.g. 5% to 95%)



5. Bertillonage

- Compute a distance/similarity between attributed graphs
 - In general does not require knowledge of a matching between nodes
 - In general does not require graphs to be the same size
- Create a signature (distribution)
 - Depends on the application
 - For large graphs (10,000 nodes), local topological measures from each node does very well





Ground Cover Revisited

- Consider ground cover as a distribution
 - Ground cover program finds a boundary and counts pixel/patch types



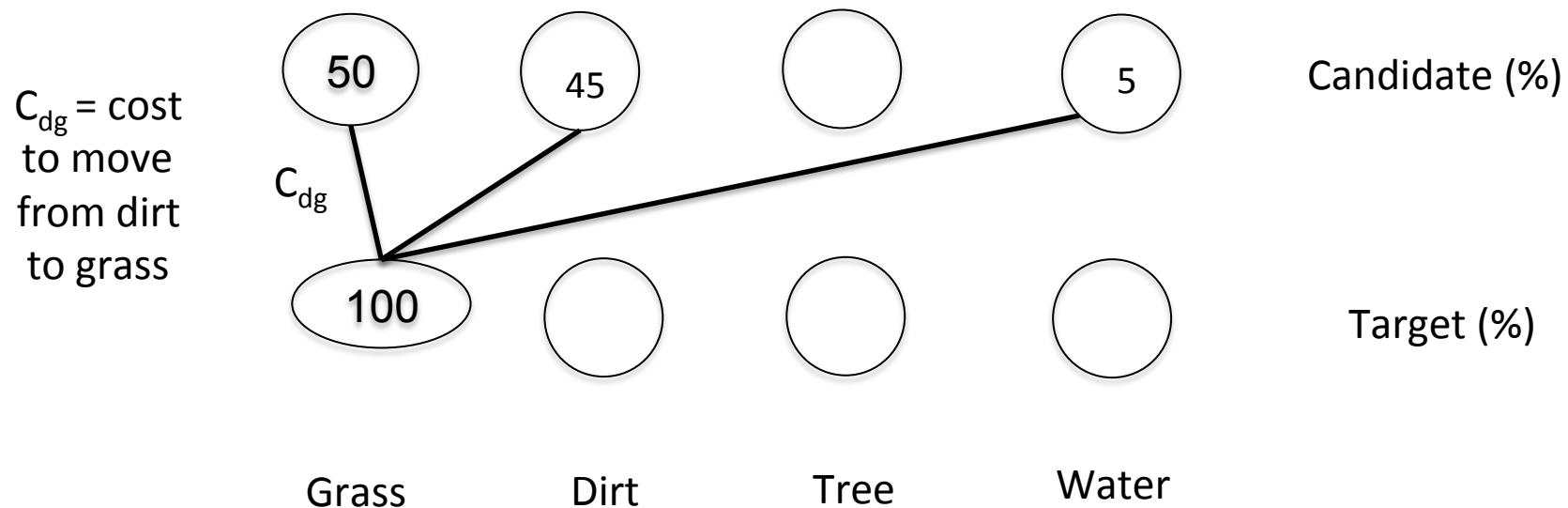
A football field near Capulin, Colorado.

Image from Google Earth.



Earth Mover's Distance

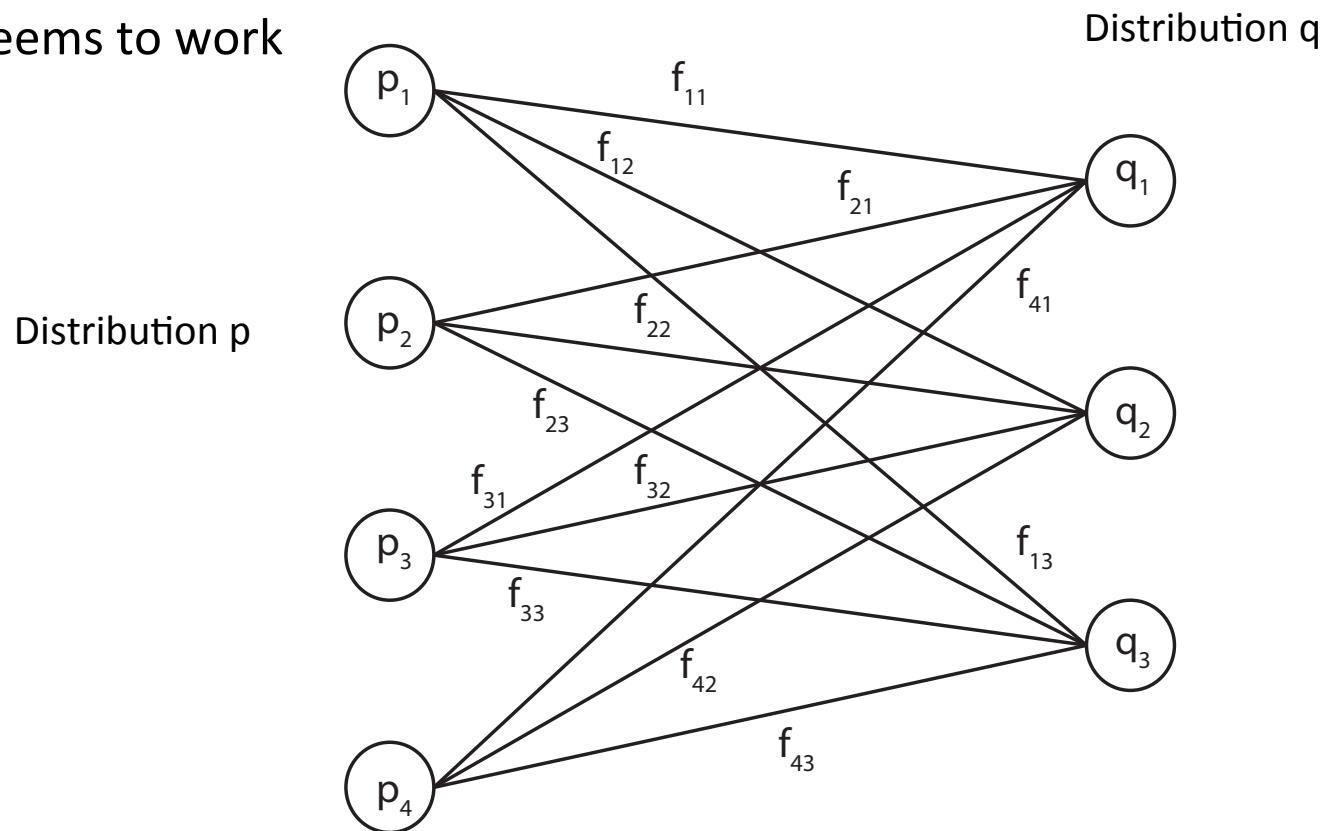
- For computing distances between distributions.
 - Also has meaning for unnormalized distributions (e.g. compare size).
 - A true metric if the ground distance is a metric. (Mallow's)
 - Any node can move weight to any other node.





EMD-based signatures

- Combine ground cover with area, distances, etc
- Challenge to normalize and combine
 - Simple seems to work





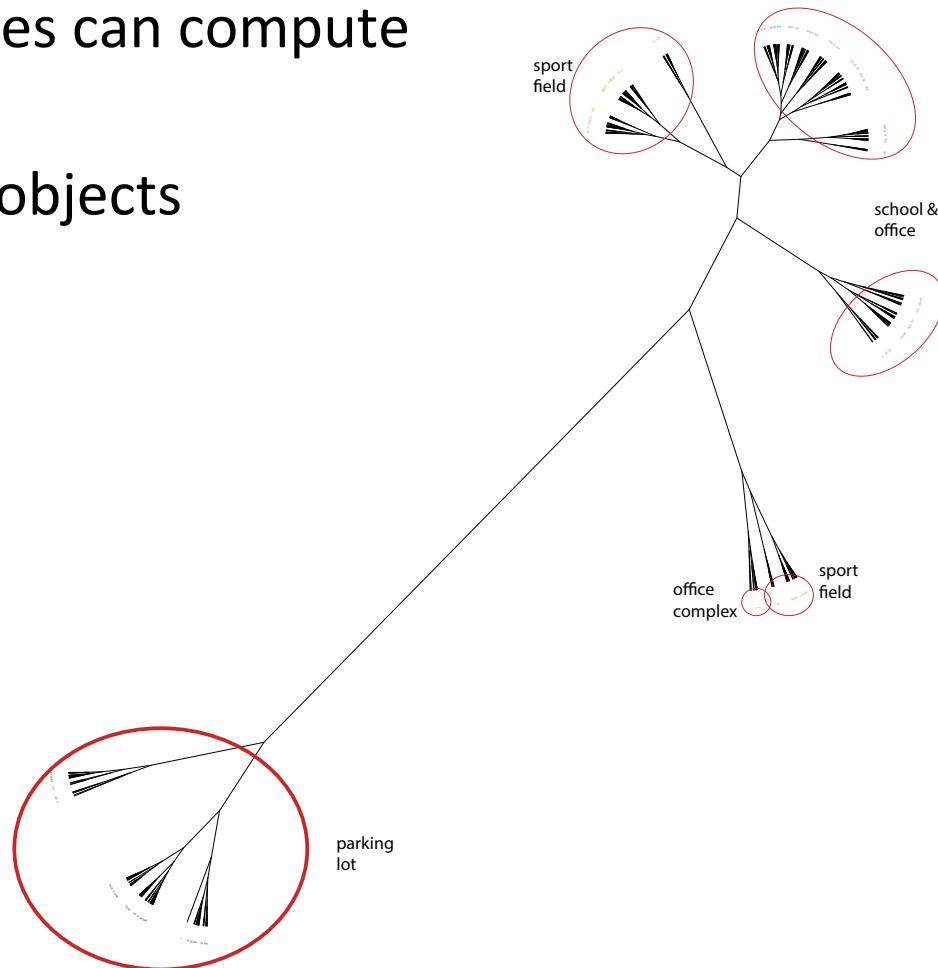
What To Do with Distances

- Libraries of instances
 - Random instances based on uncertainty or tolerances
 - Confusion matrix, sensor measurement errors, etc
 - Instances we've seen before (e.g. interesting instances)
- Compare to library
 - What is this example most closely related to?
 - Are examples changing over time?
 - Have we seen something like this before?
- In high school example, comparison to template ranks candidates



Dendograms

- Given distances can compute dendograms
- Clustering of objects



Preliminary Experiments



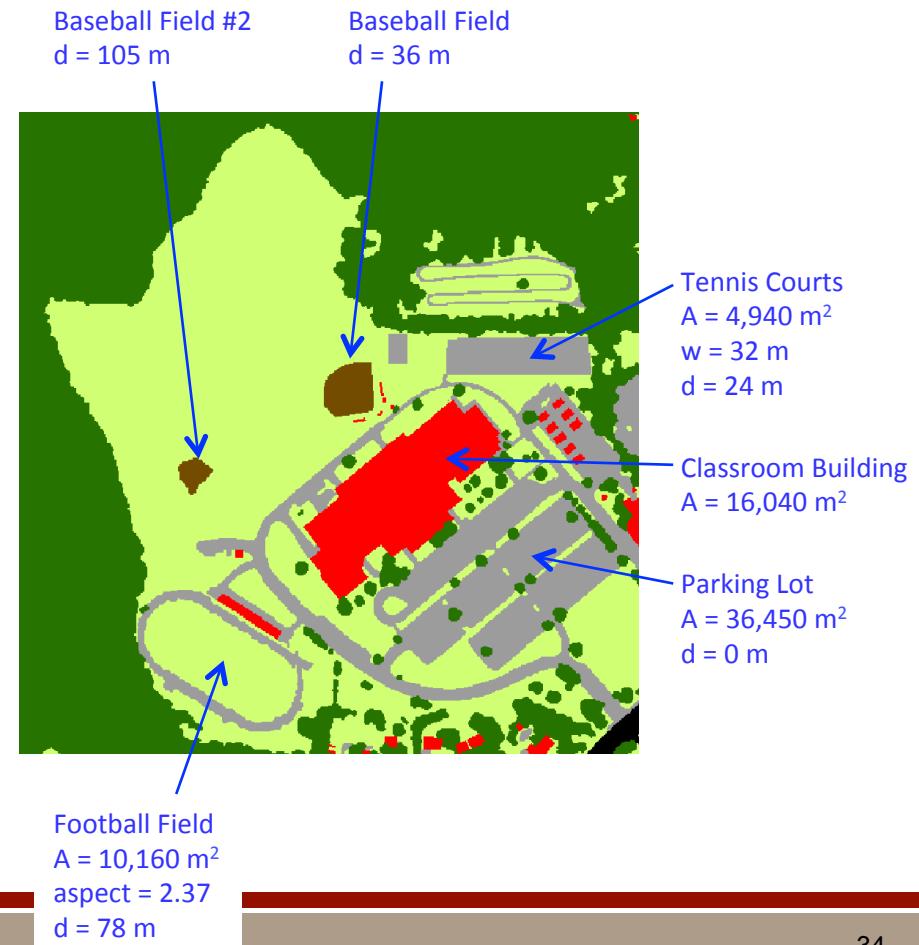
- Consider 5 high-school-(like) objects from Ann Arundel County
- Apply all but full Bayes Nets
- Many details still evolving



Annapolis High School

Characteristics:

- Location $(38.9746^\circ, -76.5655^\circ)$
- Original NA-22 match: **true**
- Perfect – all components are present.

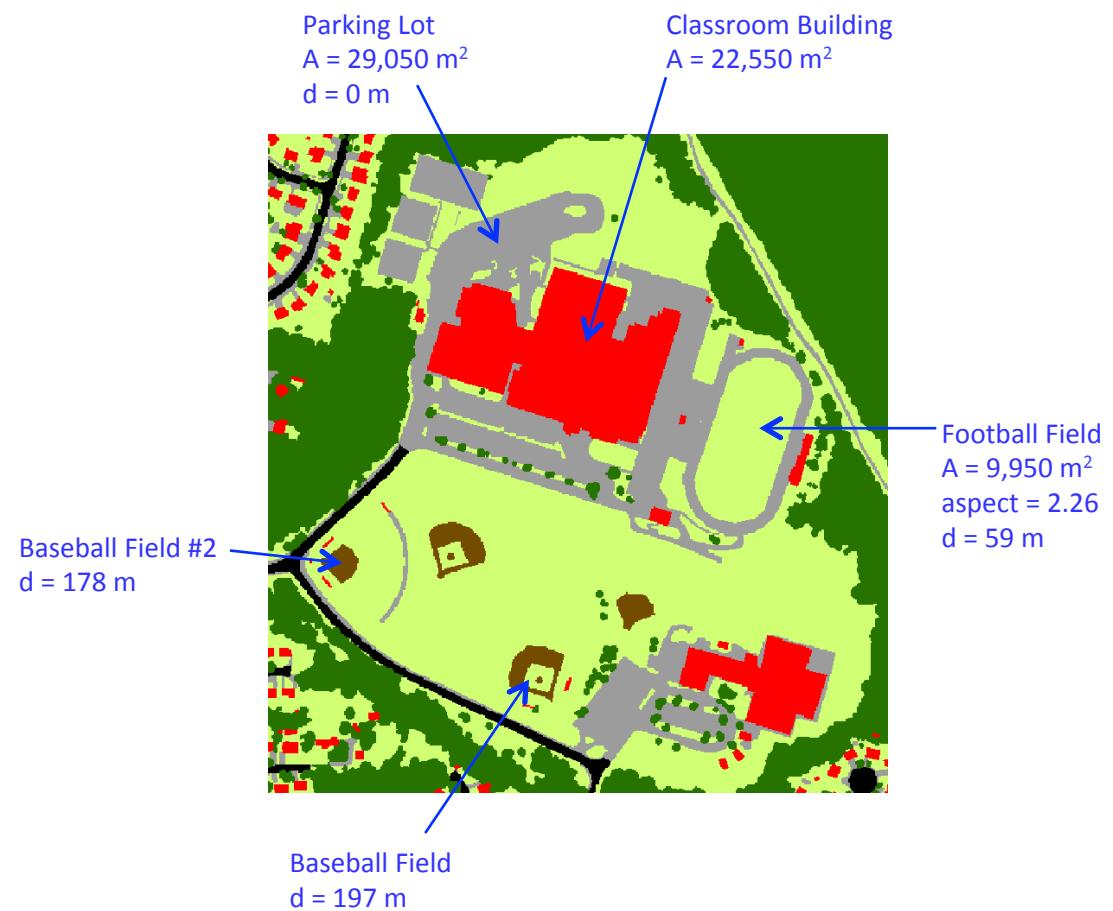


North County High School



Characteristics:

- Location (39.1930 °, -76.6370°)
- Original NA-22 match: **true**
- No tennis courts.
(Broken into too-small segments)



Lindale Middle School

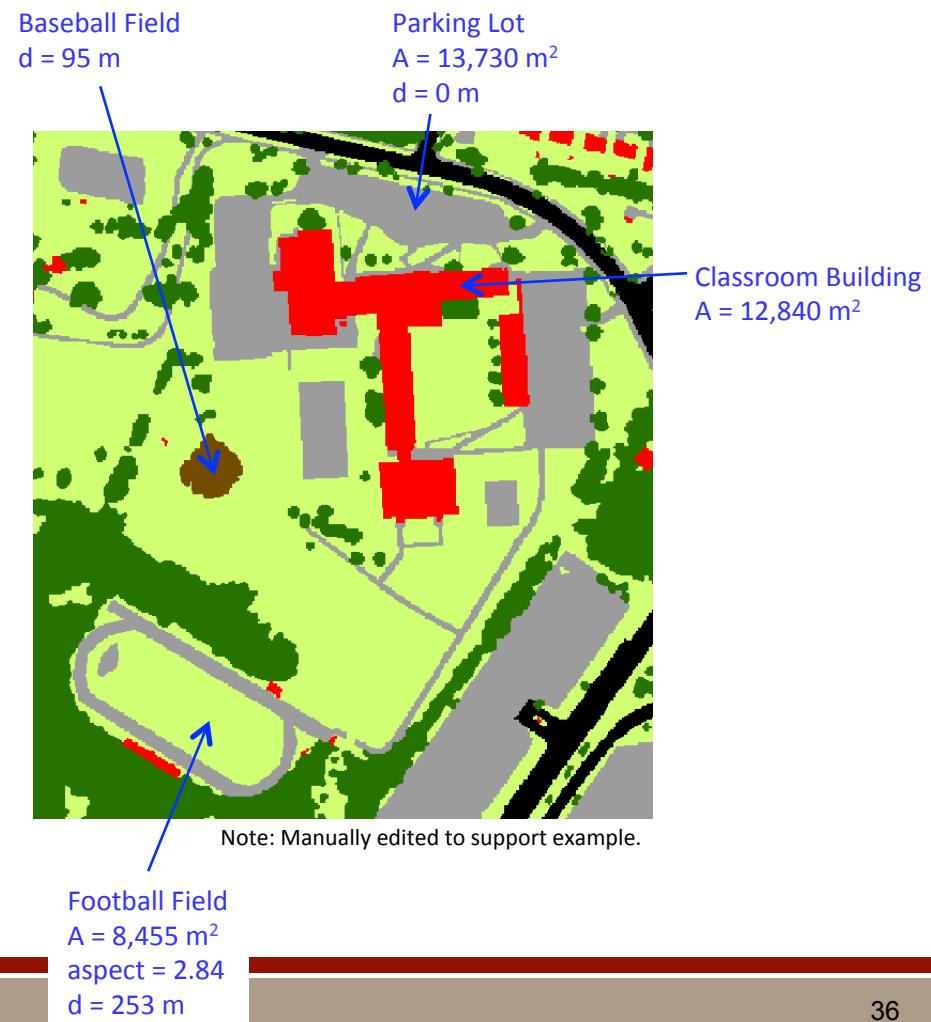


Characteristics:

- Location (39.1965°, -76.6620°)
- Original NA-22 match: **true**
- No tennis courts.
- No baseball field #2.



Note: Manually edited to support example.

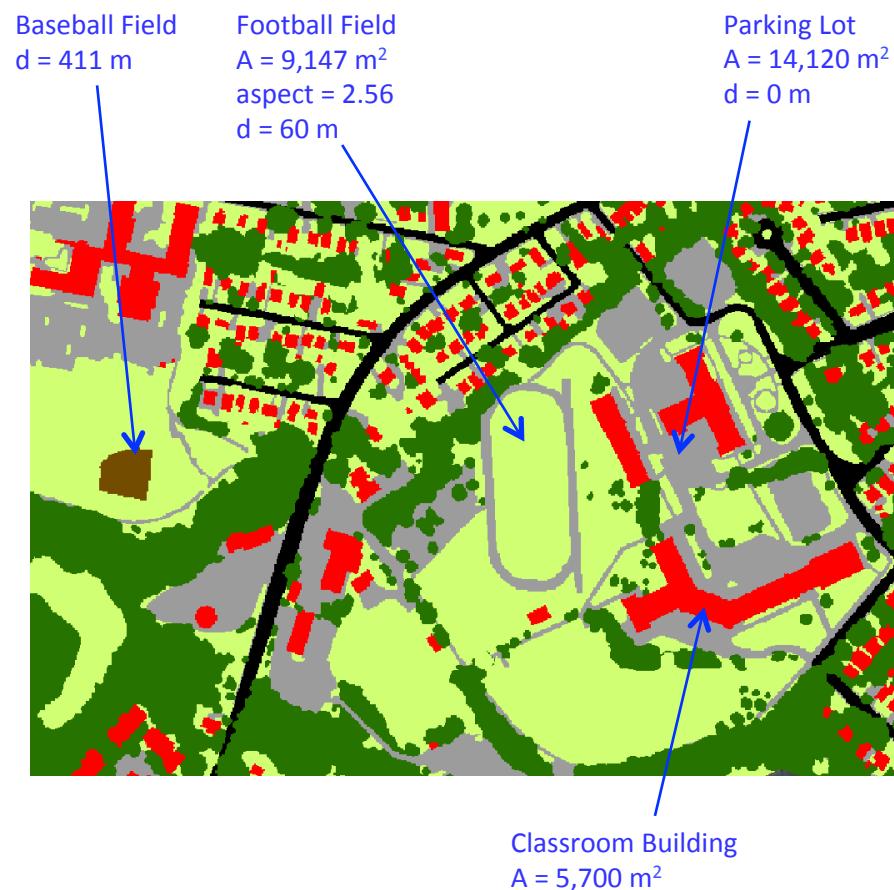


Wiley Bates Middle School



Characteristics:

- Location $(38.9723^\circ, -76.5053^\circ)$
- Original NA-22 match: **MARGINAL**
- No tennis courts.
- No baseball field #2.
- Building area marginal.
- Baseball field distance marginal.





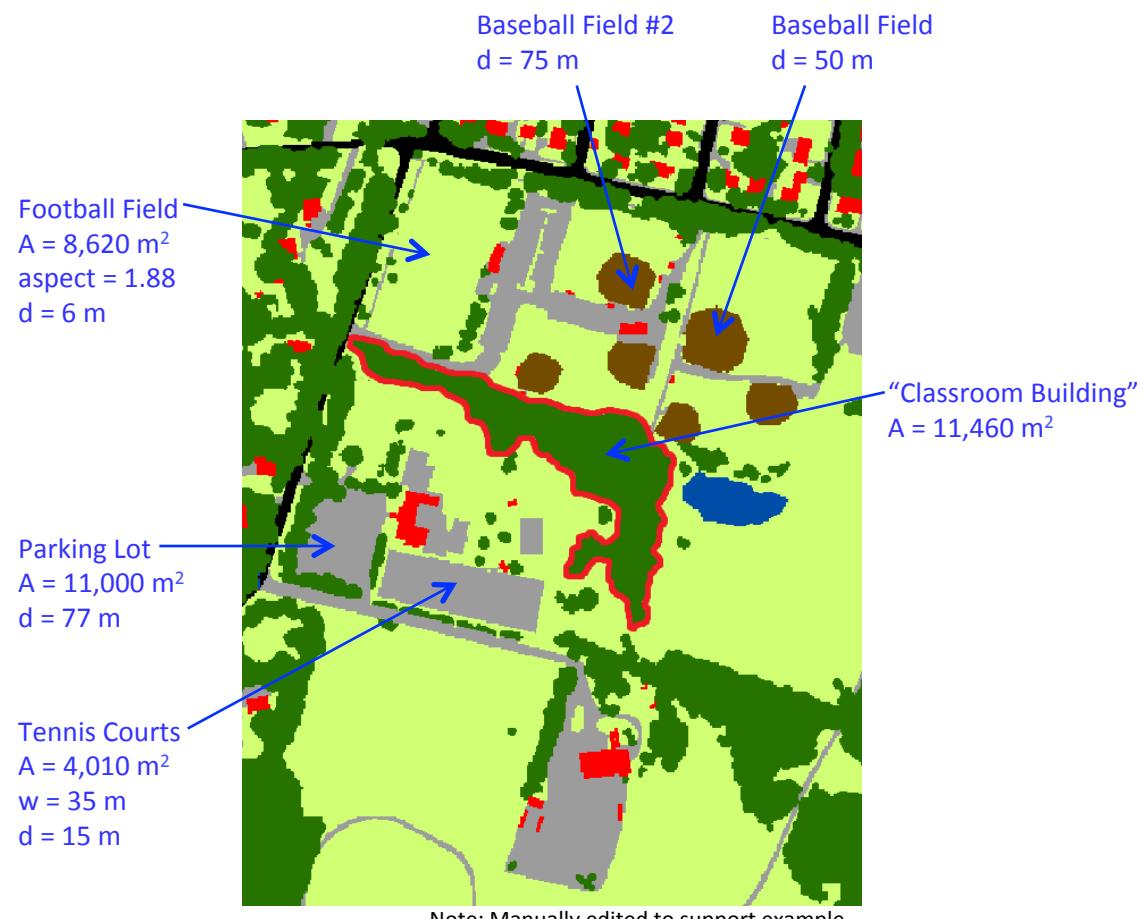
Andover Park

Characteristics:

- Location (39.1968°, -76.6680°)
- Original NA-22 match: **false**
- No building (tree misclassification).
- All other components present, including optional.



Note: Manually edited to support example.



ISU Method



	Annapolis High School	North County High School	Lindale Middle School	Wiley Bates Middle School	Andover Park (Trees as Building)	Andover Park (No Building)
ISU Method (phi = 0.005)	0.9500000 [0.9157908, 0.9756950]	0.8726458 [0.8230521, 0.9151563]	0.8726458 [0.8230521, 0.9151563]	0.10941637 [0.07002800, 0.1562255]	0.9500000 [0.9157908, 0.9756950]	0.07212672 [0.04053871, 0.11182950]



Graphical Bertillonage

- Rank
 - 1. North County High
 - 2. Wiley Bates Middle
 - 3. Annapolis High
 - 4. Lindale Middle
 - 5. Andover Park No Building
 - 6. Andover Park Tree as Building



Naïve Bayes

- With Normalization

	Annapolis High School	North County High School	Lindale Middle School	Wiley Bates Middle School	Andover Park (Trees as Building)	Andover Park (No Building)
Naïve Bayes	1.00E+00	1.00E+00	1.00E+00	1.00E+00	1.00E+00 (Actual Eccentricity was outside of boundary)	0.00E+00

- Without Normalization

	Annapolis High School	North County High School	Lindale Middle School	Wiley Bates Middle School	Andover Park (Trees as Building)	Andover Park (No Building)
Naïve Bayes	2.89E-07	1.05E-16	1.05E-16	2.92E-35	8.05E-26 Actual Eccentricity was outside of boundary)	0.00E+00



Match Quality

- Landcover Exponent = 1

	Annapolis High School	North County High School	Lindale Middle School	Wiley Bates Middle School	Andover Park (Trees as Building)	Andover Park (No Building)
Match Quality (q_zero= 0. 0001, q_pr = 0.85)	0.9745259	0.8287246	0.828394	0.7813322	0.4934152	0.04799298

- Landcover Exponent = 100

	Annapolis High School	North County High School	Lindale Middle School	Wiley Bates Middle School	Andover Park (Trees as Building)	Andover Park (No Building)
Match Quality (q_zero= 0. 0001, q_pr = 0.85)	0.926541	0.7889549	0.7889427	0.7880354	0.2416516	0.04602881



Summary Table

Quality score summary:



Ideal match.

Missing one optional.

Missing two optional.

Missing two optional,
marginal parameters.

Missing one required,
other items perfect.

$q_{pr} = 0.85$	Annapolis High School	North County High School	Lindale Middle School	Wiley Bates Middle School	Andover Park (Trees as Building)	Andover Park (No Building)
Classroom Building	0.98	0.98	0.98	0.82	0.12	0.00
Parking Lot	0.97	0.97	0.97	0.97	0.97	0.97
Football Field	0.98	0.98	0.96	0.98	0.95	0.95
Baseball Field	0.86	0.88	0.86	0.73	0.85	0.85
Baseball Field #2	0.83	0.84	0.00	0.00	0.83	0.83
Tennis Courts	0.97	0.00	0.00	0.00	0.97	0.97
OVERALL QUALITY	0.94	0.88	0.80	0.74	0.56 ?	0.10



Our Current Method Choices

- Hierarchical Naïve Bayes when we have data
 - Primitive ensembles
- Match quality score when we do not



More Challenges

- Dynamic/ephemeral components
- Human behavior
- Both
 - E.g, Tents on a mountainside. Cars in a parking lot.
 - Discontinuous snapshots may miss
- Elements whose existence reduces match likelihood
- Learning from negative examples