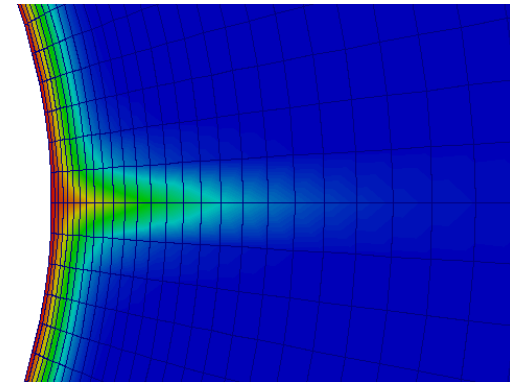
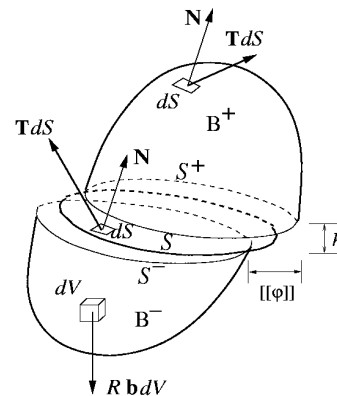
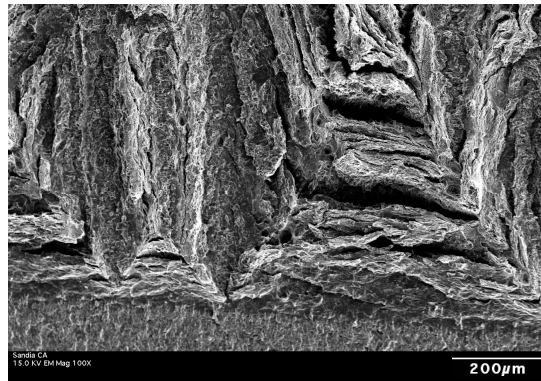


Exceptional service in the national interest



Simulating hydrogen embrittlement and fast pathways for diffusion through localization elements

J. Foulk III, W. Sun, J. Ostien, A. Mota, C. San Marchi, B. Somerday

ME Seminar 395 Seminar Series, Stanford University

February 27, 2014

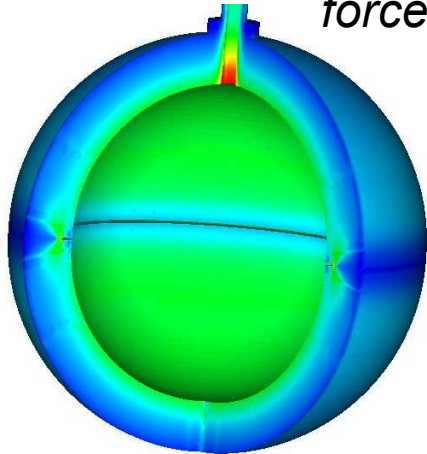
The driving force and the resistance

Π – potential energy of body
 R – resistance of the body
 a – crack length

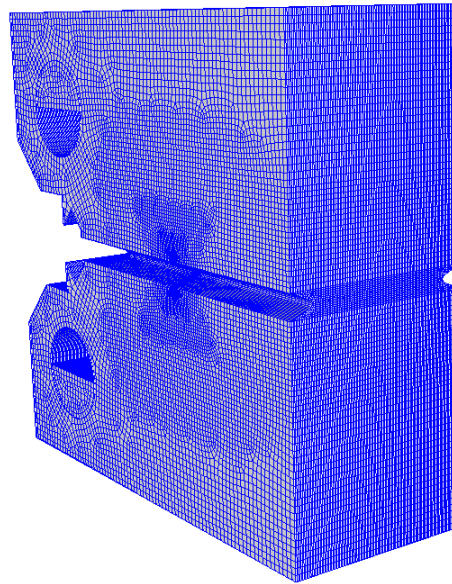
$$\frac{\partial \Pi}{\partial a} + R(a) = 0$$

energetics of crack propagation

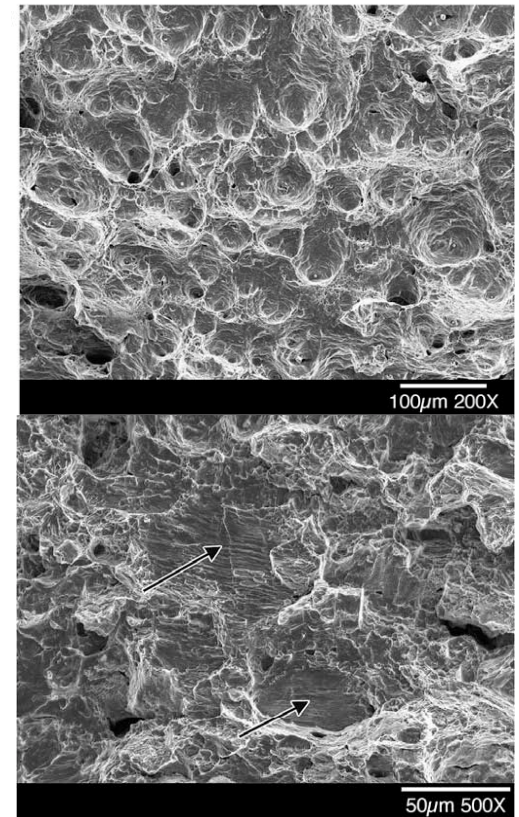
*calculate driving
forces*



*measure fracture
toughness*



*quantify fracture
mechanisms*



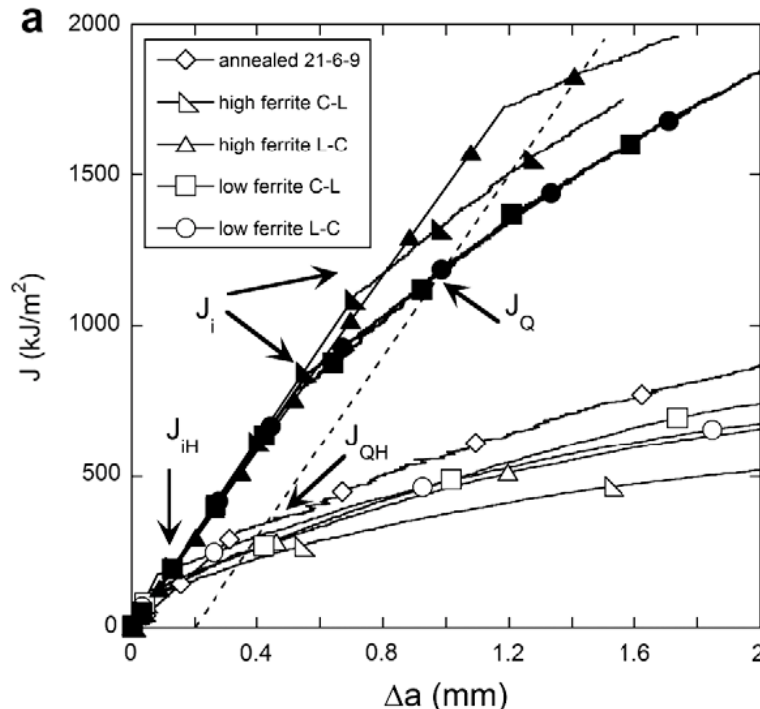
$$J = \int_{\Gamma_0} \mathbf{L} \cdot \boldsymbol{\Sigma} \mathbf{N} dA$$

\mathbf{L} – crack trajectory
 $\boldsymbol{\Sigma}$ – Energy-momentum tensor
 \mathbf{N} – surface normal

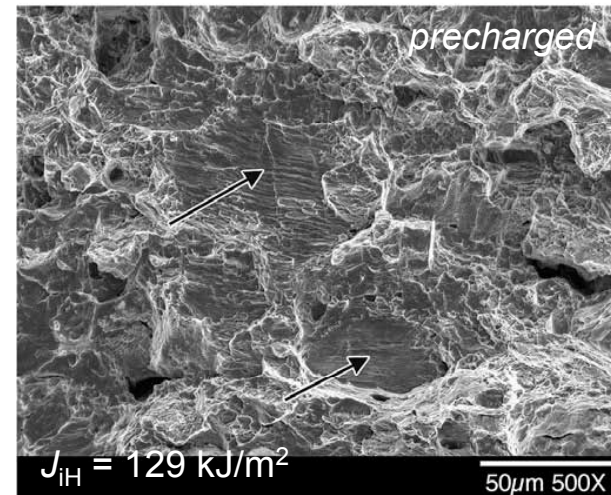
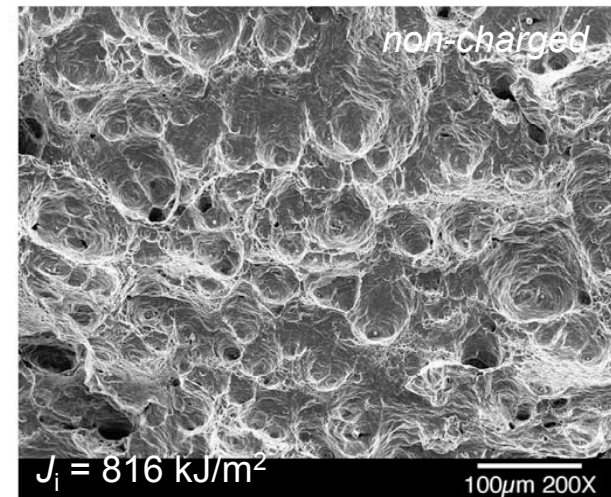
Our goal is to model the resistance and predict crack initiation and propagation

Hydrogen localizes deformation

The role of localized deformation in hydrogen-assisted crack propagation in 21Cr-6Ni-9Mn stainless steel, Nibur, Somerday, Balch, and San Marchi, Acta Materialia, 2009.



- Hydrogen enhanced localized deformation (HELP)
 - Increases dislocation mobility
 - Stabilized edge component
 - Deformation bands (slip localization) evolve
- Voids nucleate at intersection of boundaries
- Planar nucleation and growth – elongated dimples

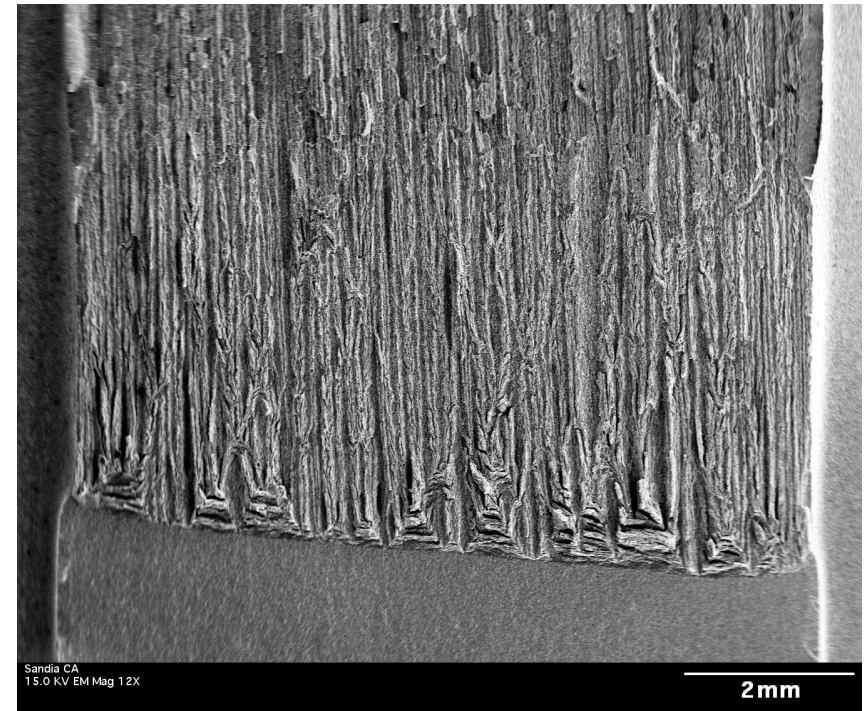
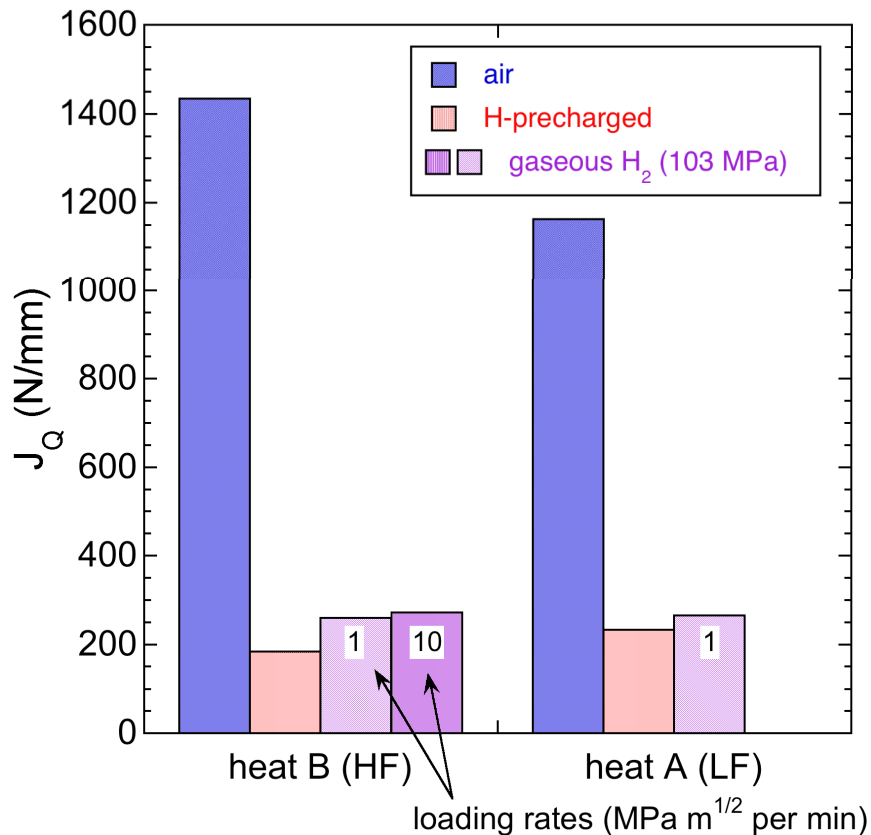
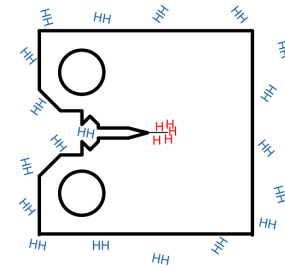


forged, low ferrite, 21-6-9 (L-C)

Embrittlement stems from hydrogen enhanced localized deformation – Coupling needed!

Initial studies in 21Cr-6Ni-9Mn SS

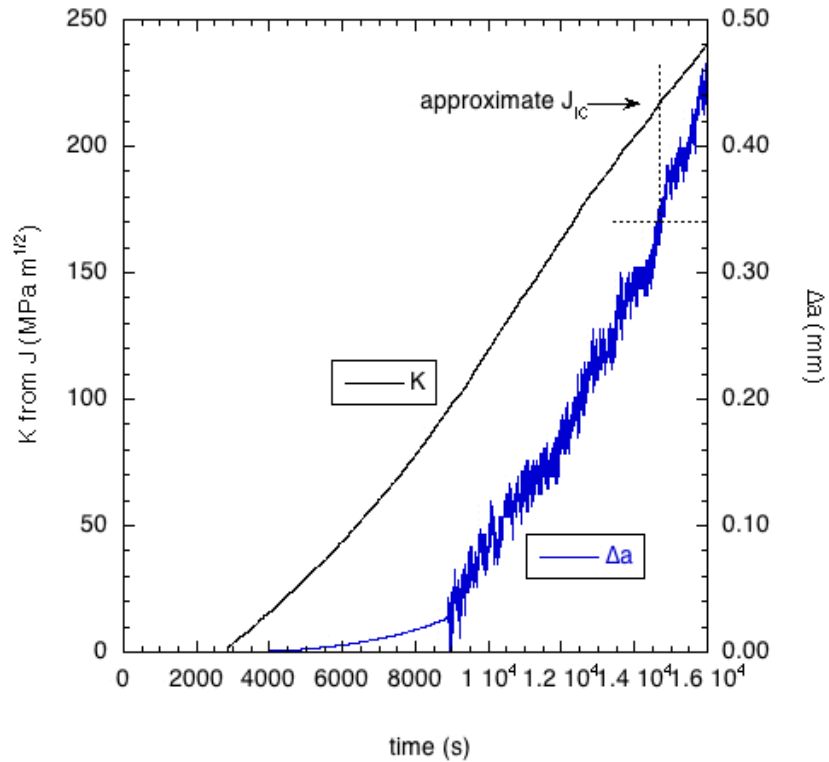
- Compact tension specimens, B ~ 13 mm; W ~ 26 mm
- Constant pressure of gaseous hydrogen: 103 MPa
- “Loading rates” ~ 0.6 - 10 MPa m^{1/2} per minute



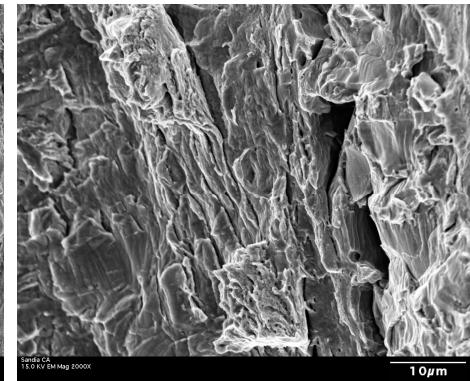
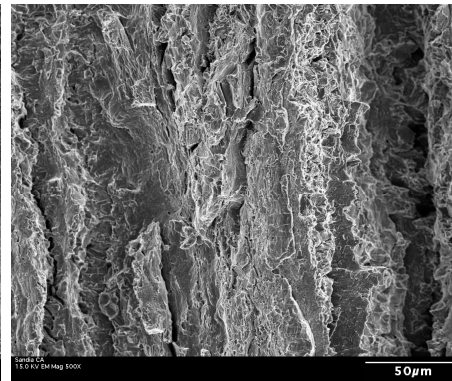
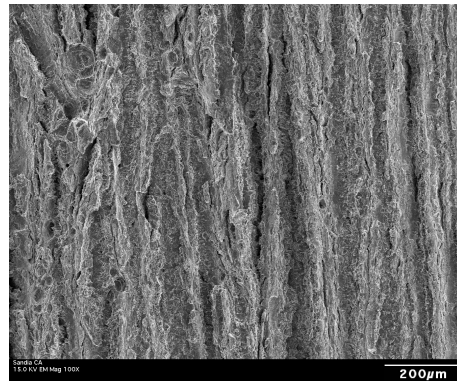
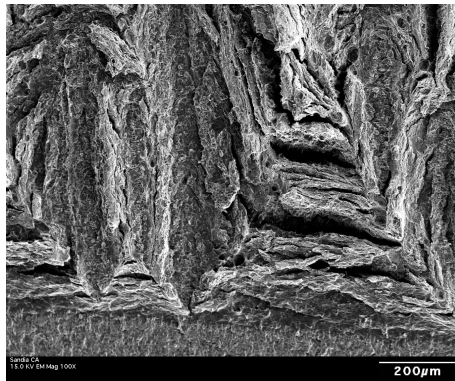
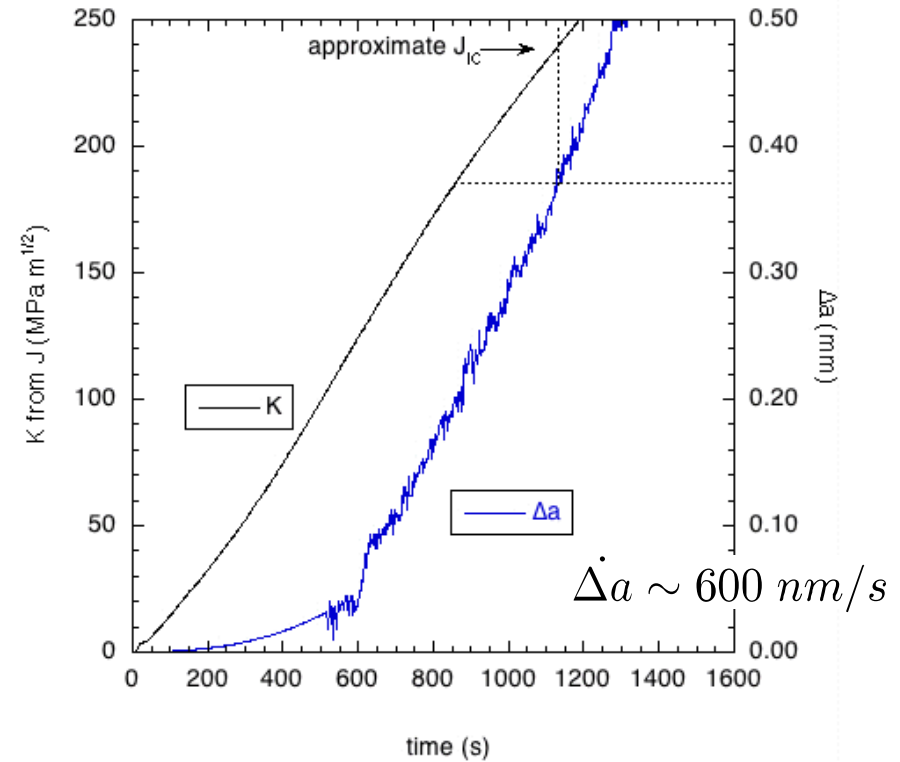
Note: 220 MPa m^{1/2} = 224 kJ/m² (N/mm)

Rapid crack growth in 21Cr-6Ni-9Mn

21-6-9, high-ferrite alloy (specimen HF12)



21-6-9, high-ferrite alloy (specimen HF18)

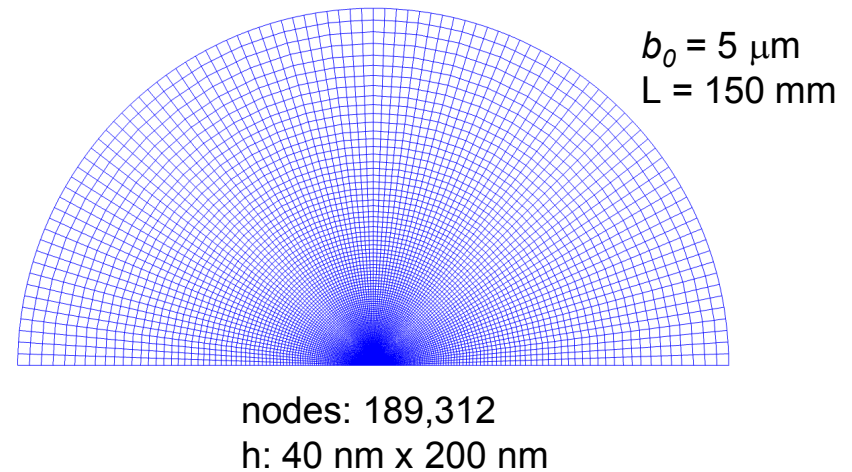
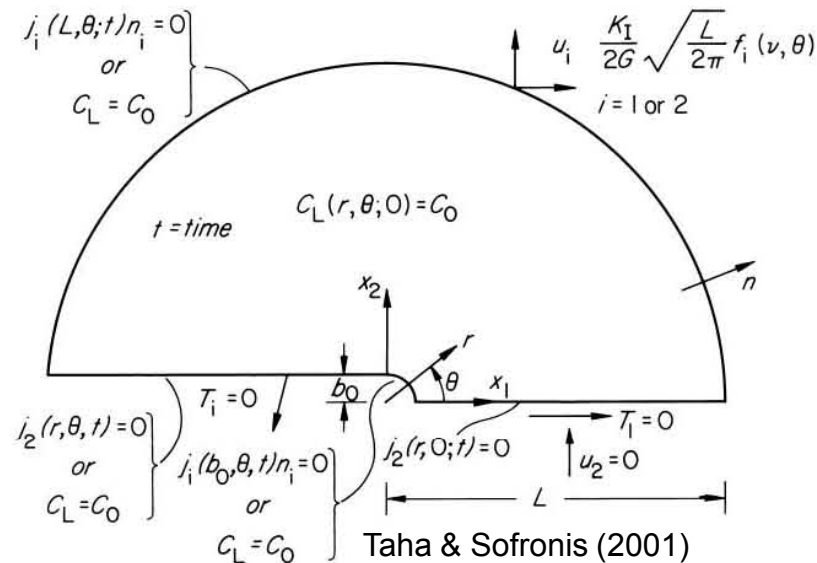
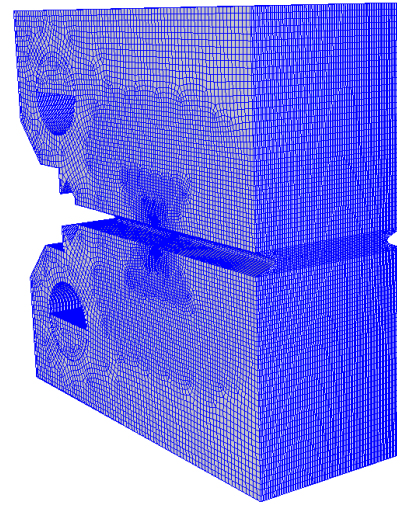


(HF18)

Modeling 21Cr-6Ni-9Mn in H₂ gas

Before moving to complex and computationally challenging fracture geometries, we need to understand phenomena in plane strain

Mechanical analysis should be performed to help experimentalists reduce driving forces from non-standard fracture geometry. Iteration required.



NOTE: Not pre-charged, constant concentration $C_{L,applied}$ applied to crack faces

Coupled hydrogen transport

This path heavily leverages Sofronis/McMeeking (1989)* and Krom (1998).
Recent work by Leo and Anand (2013).

*chemical
potential*

$$\mu_l = \mu_0 + RT \ln(\theta_l) - v_h \sigma_h$$

*model
for flux*

$$\dot{j}_l = -m_l c_l \nabla_x \mu_l$$

*conservation
of hydrogen*

$$\frac{d}{dt} \int_B c dv = - \int_{\partial B} \mathbf{j} \cdot \mathbf{n} da \quad \dot{c} = \dot{c}_l + \frac{\partial c_t}{\partial c_l} \dot{c}_l + \frac{\partial c_t}{\partial n_t} \frac{\partial n_t}{\partial \epsilon_p} \dot{\epsilon}_p + \frac{\partial c_t}{\partial n_t} \frac{\partial n_t}{\partial J} \dot{J}$$

*equilibrium of
lattice/trap sites*

$$\theta_t = \frac{1}{1 + \frac{1}{k_t \theta_l}}$$

$$\mathbf{F} = \frac{\partial \mathbf{x}}{\partial \mathbf{X}}$$

$$J = \det[\mathbf{F}]$$

$$\theta_l = c_l / n_l$$

$$\theta_t = c_t / n_t$$

$$n_l = N_L / J$$

$$n_t = N_T(\epsilon_p) / J$$

$$v_h = V_H J$$

$$\tau_h = J \sigma_h$$

$$d_l = RT m_l$$

$$c_t = c_t(c_l, \epsilon_p, J)$$

$$C^* = c_l + \frac{n_t}{1 + \frac{n_l}{k_t c_l}} \quad D^* = 1 + \frac{\partial c_t}{\partial c_l}$$

$$D^* \dot{c}_l + C^* \operatorname{div} \mathbf{v} - \nabla_x \cdot \mathbf{d}_l \nabla_x c_l - \nabla_x \cdot \frac{c_l}{J} \mathbf{d}_l \nabla_x J + \nabla_x \cdot \frac{c_l V_H}{RT} \mathbf{d}_l \nabla_x \tau_h +$$

$$\frac{\theta_l}{J} \frac{\partial N_T}{\partial \epsilon_p} \dot{\epsilon}_p - \frac{\theta_t N_T}{J^2} \dot{J} = 0$$

*P. Sofronis and R.M. McMeeking, J. Mech. Phys. Solids 37 (1989) 317

Simplification in reference

Transport of hydrogen in the current configuration

$$D^* \dot{c}_l + C^* \operatorname{div} \mathbf{v} - \nabla_{\mathbf{x}} \cdot \mathbf{d}_l \nabla_{\mathbf{x}} c_l - \nabla_{\mathbf{x}} \cdot \frac{c_l}{J} \mathbf{d}_l \nabla_{\mathbf{x}} J + \nabla_{\mathbf{x}} \cdot \frac{c_l V_H}{RT} \mathbf{d}_l \nabla_{\mathbf{x}} \tau_h + \frac{\theta_l}{J} \frac{\partial N_T}{\partial \epsilon_p} \dot{\epsilon}_p - \frac{\theta_t N_T}{J^2} \dot{J} = 0$$

Transport of hydrogen in the reference configuration (push back)

$$D^* \dot{C}_L - \nabla_{\mathbf{X}} \cdot \mathbf{d}_l \mathbf{C}^{-1} \nabla_{\mathbf{X}} C_L + \nabla_{\mathbf{X}} \cdot \frac{\mathbf{d}_l V_H}{RT} \mathbf{C}^{-1} \nabla_{\mathbf{X}} \tau_h C_L + \theta_T \frac{dN_T}{d\epsilon_p} \dot{\epsilon}_p$$

*transient
term*

*diffusion
term*

*advection term
from pressure*

*source term
from trapping*

Deformation-dependent diffusivity $D_L = \mathbf{F}^{-1} \mathbf{d}_l \mathbf{F}^{-T} = \mathbf{d}_l \mathbf{C}^{-1}$

Baseline properties for 21Cr-6Ni-9Mn

Transport*

$$D_0 = 5.4E-7 \text{ m}^2/\text{s}$$

$$Q = 53.9E3 \text{ J/mol}$$

$$R = 8.314 \text{ J/(mol K)}$$

$$T = 300 \text{ K}$$

$$D_L = 2.2E-16 \text{ m}^2/\text{s}$$

$$N_A = 6.0232 \text{ atoms/mol}$$

$$V_M = 7.116E-6 \text{ m}^3/\text{mol} - \text{molar volume of Fe}$$

$$V_H = 2.0E-6 \text{ m}^3/\text{mol} - \text{partial molar volume of H}$$

$$N_L = 8.46E28 \text{ atoms/m}^3 = 1.40E5 \text{ solvent lattice mol/m}^3$$

$$C_{L,0} = 38.7 \text{ mol/m}^3 \text{ (from 316 alloys, assumes 5 wppm)}$$

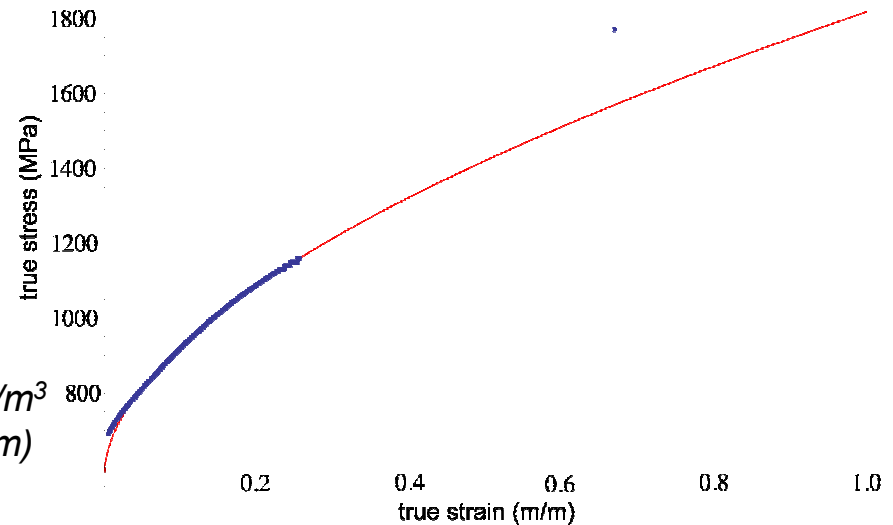
$$C_{L,\text{applied}} = 560 \text{ mol H/m}^3 \text{ (280 moles } H_2/\text{m}^3)$$

$$N_{T,\text{total}} = \alpha N_T = 10 N_T = 10^{(26.6 - 1.5 \exp(-6.96 \epsilon_p))} \text{ mole/m}^3$$

$$C_{T,0} = 3.94E24 \text{ atoms/m}^3 = 6.542 \text{ mol/m}^3$$

$$W_B = 9.65E3 \text{ J/mol}$$

$$K_T = 47.9$$



$$C_{L,\text{applied}} = K f^{\frac{1}{2}} \quad \text{San Marchi, et al., IJHE, 2007}$$

Mechanics – non-charged, forged, transverse, LF

$$\rho = 7806 \text{ kg/m}^3$$

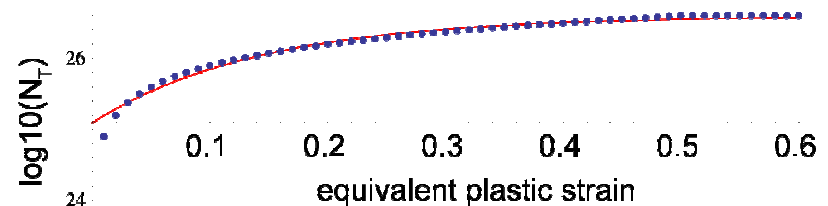
$$E = 196.6 \text{ GPa}$$

$$\nu = 0.3$$

$$\sigma_0 = 590 \text{ MPa}$$

$$H = 1227 \text{ MPa}$$

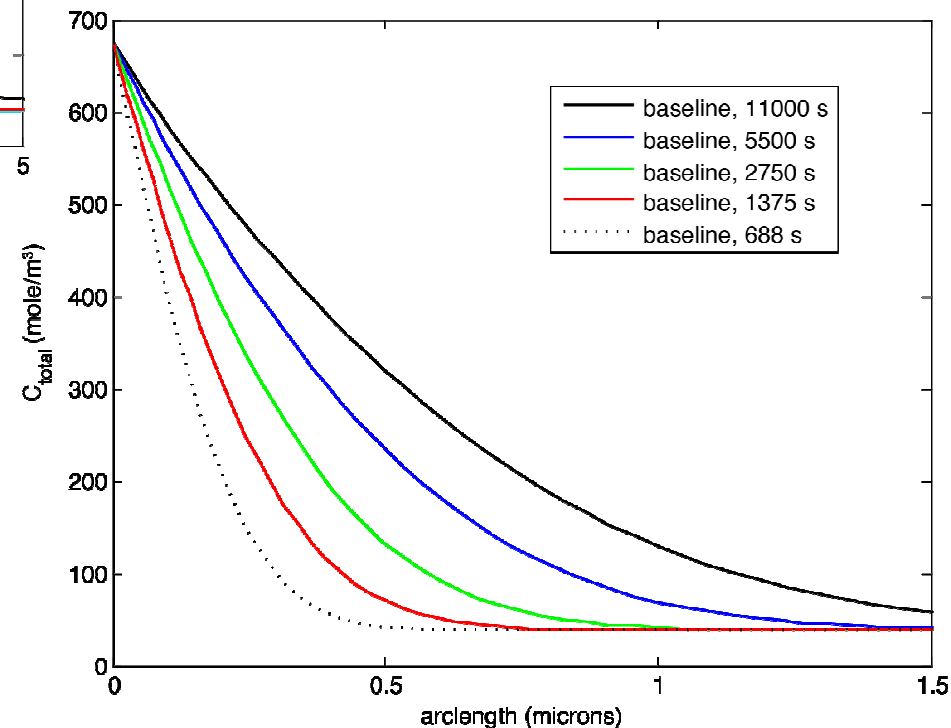
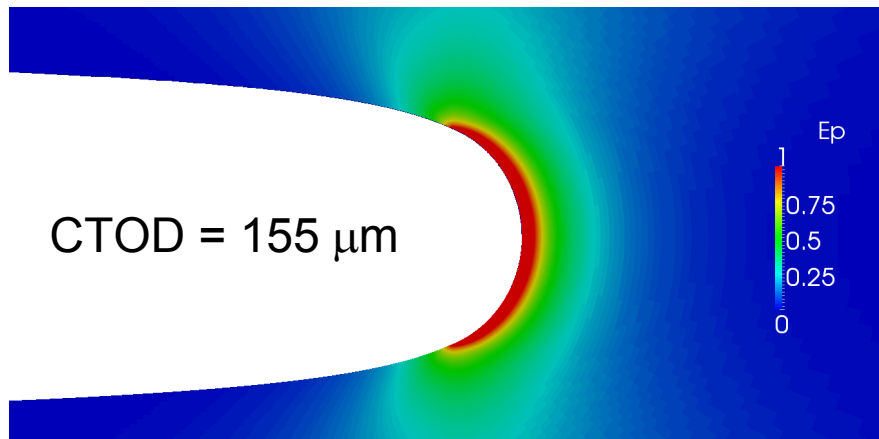
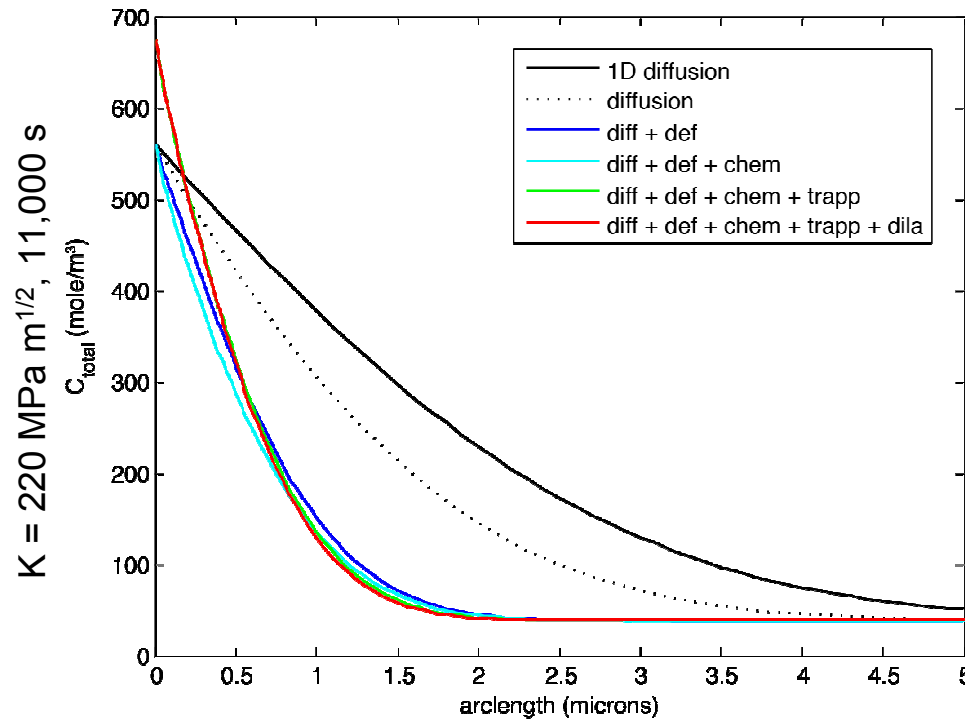
$$m = 0.563$$



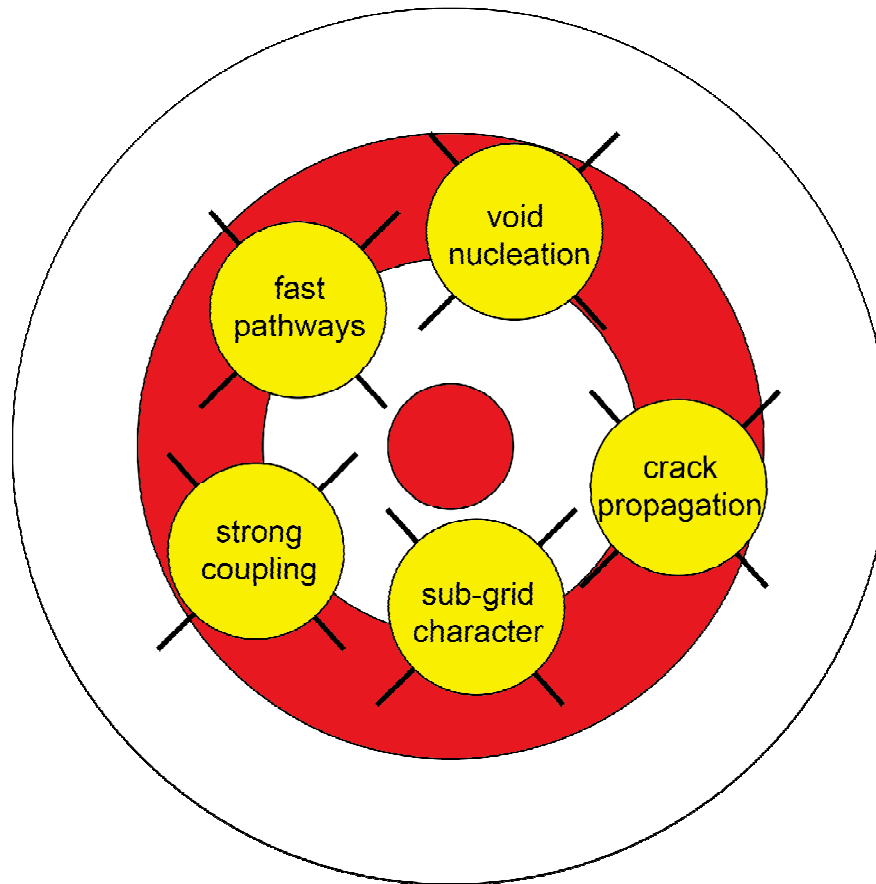
*Transport properties aligned with Somerday, et al., Met Trans, 2009

NOTE: Constant concentration, not chemical potential, is applied. Will fix.

Initial computations in 21Cr-6Ni-9Mn SS



Tools useful for discovery



- We may need strong coupling to capture auto-catalytic processes
- Capture sub-grid processes through a smooth idealization
- Test hypotheses regarding fast pathways for diffusion
- Flexibility to easily include models for void nucleation and growth
- Model both crack initiation and propagation

Analysis Tools (black-box)

Optimization
UQ (sampling)
Parameter Studies
V&V, Calibration
OUU, Reliability

Analysis Tools (embedded)

Nonlinear Solver
Time Integration
Continuation
Sensitivity Analysis
Stability Analysis
Constrained Solves
Optimization
UQ Solver

Linear Algebra

Data Structures
Iterative Solvers
Direct Solvers
Eigen Solver
Preconditioners
Matrix Partitioning

Architecture-Dependent Kernels

Multi-Core
Accelerators

Reusable Software Tool Components



Composite Physics

MultiPhysics Coupling
System Models
System UQ

Mesh Tools

Mesh I/O
Inline Meshing
Partitioning
Load Balancing
Adaptivity
Remeshing
Grid Transfers
Quality Improvement
DOF map

Utilities

Input File Parser
Parameter List
Memory Management
I/O Management
Communicators

PostProcessing

Visualization
Verification
Model Reduction

Mesh Database

Mesh Database
Geometry Database
Solution Database

Local Fill

Discretizations

Discretization Library
Field Manager

Derivative Tools

Sensitivities
Derivatives
Adjoint
UQ / PCE Propagation

Physics Fill

Element Level Fill
Material Models
Objective Function
Constraints
Error Estimates
MMS Source Terms

(Andy Salinger)

Data-Centric Algs

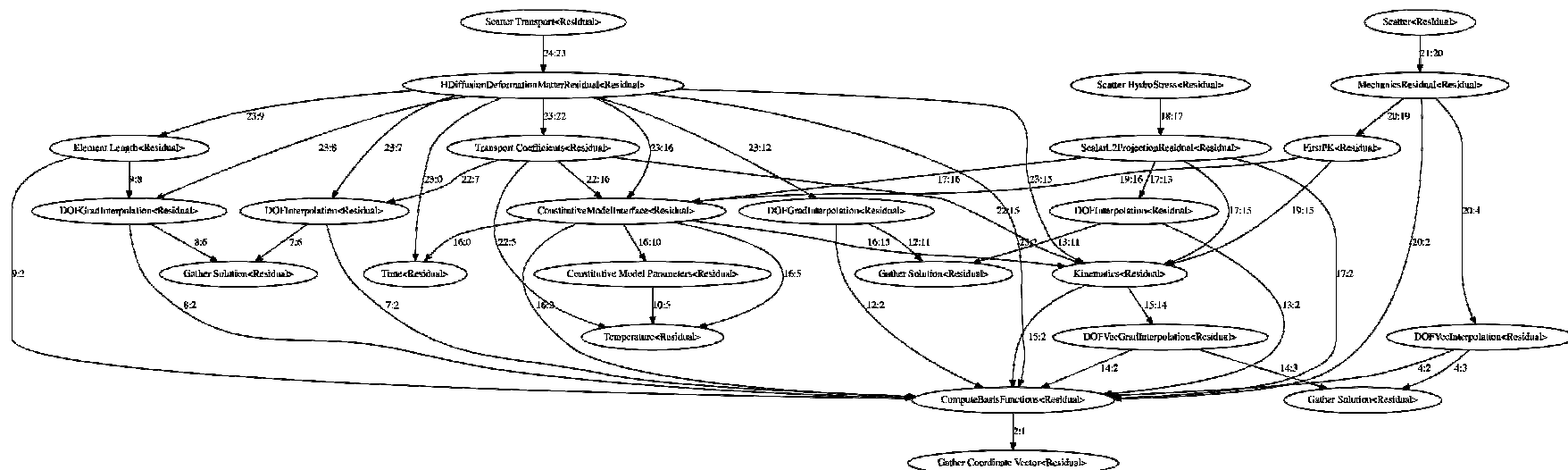
Graph Algorithms
SVDs
Map-Reduce
Linear Programming
Network Models

Software Quality

Version Control
Regression Testing
Build System
Backups
Verification Tests
Mailing Lists
Unit Testing
Bug Tracking
Performance Testing
Code Coverage
Porting
Web Pages
Release Process

LCM research environment

The Laboratory for Computational Mechanics (LCM) is a research environment that leverages Albany which employs a host reusable components in Trilinos

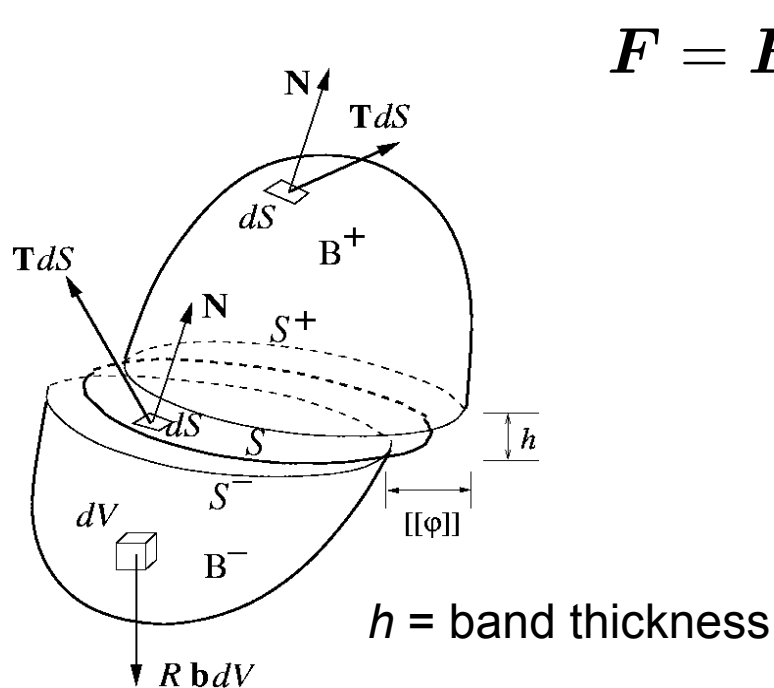


- *Phalanx* helps manage multiphysics dependencies
- *Intrepid* provides an extensive element library
- *Sacado* yields an exact Jacobian via automatic differentiation
- *NOX* provides nonlinear solution methods



Capture sub-grid processes

Goal: Capture sub-grid processes through methods that regularize the jump

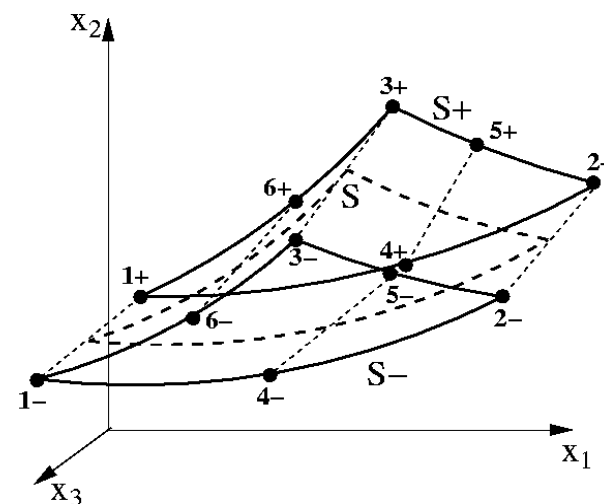


$$\mathbf{F} = \mathbf{F}^{\parallel} \mathbf{F}^{\perp}$$

$$\mathbf{F}^{\parallel} = \mathbf{g}_i \otimes \mathbf{G}^i$$

$$\mathbf{F}^{\perp} = \mathbf{I} + \frac{[[\Phi]]}{h} \otimes \mathbf{N}$$

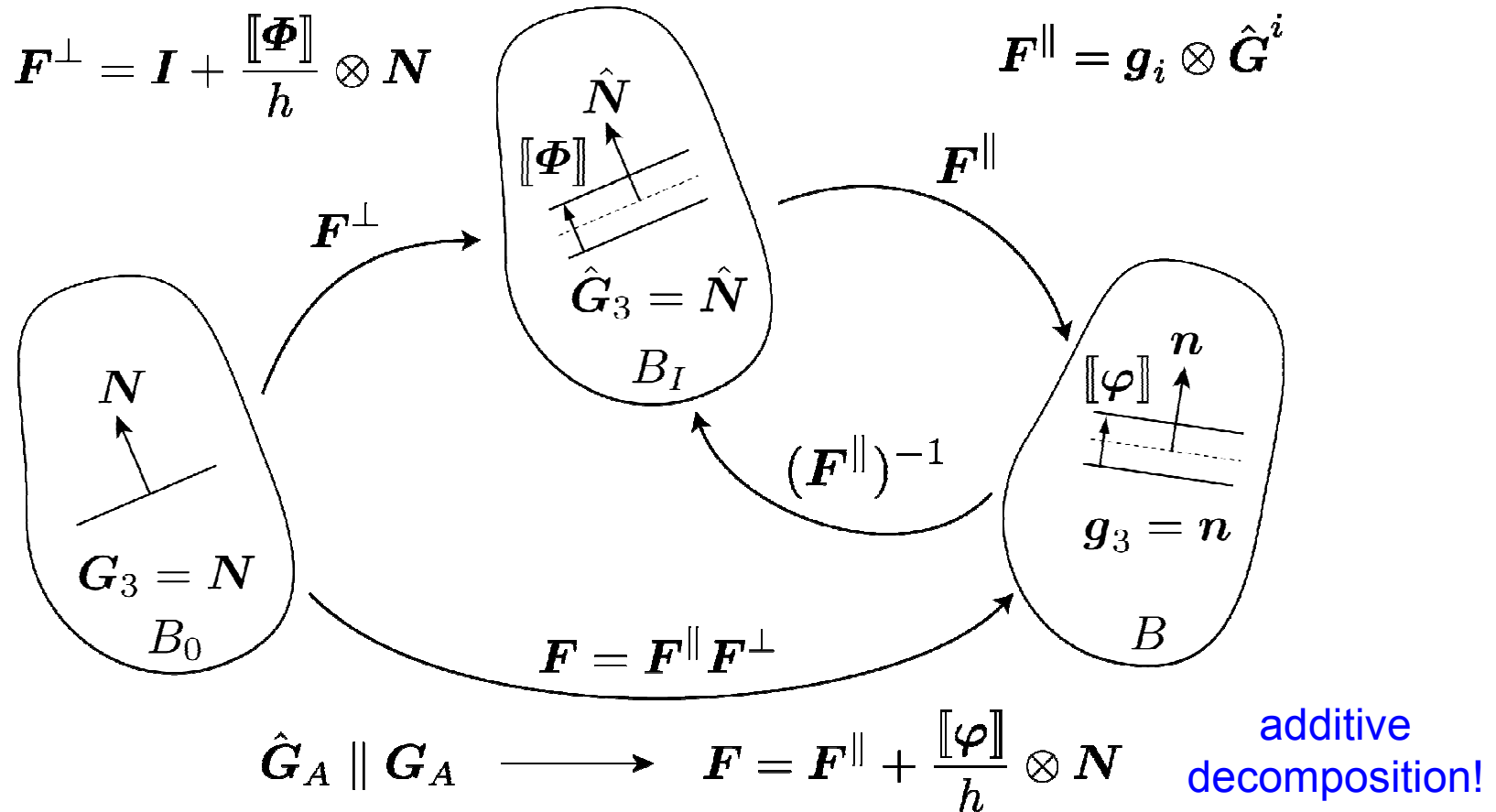
$$\mathbf{F} = \mathbf{F}^{\parallel} + \frac{[[\varphi]]}{h} \otimes \mathbf{N}$$



- Finite-deformation kinematics
- Simulation of strain localization
- No additional constitutive assumptions

Akin to "cohesive" element

An intermediate configuration



The jump is pushed backwards

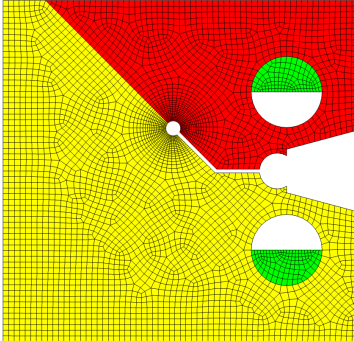
$$[[\Phi]] = (F^\parallel)^{-1} [[\varphi]]$$

Retain definition of membrane def. grad.

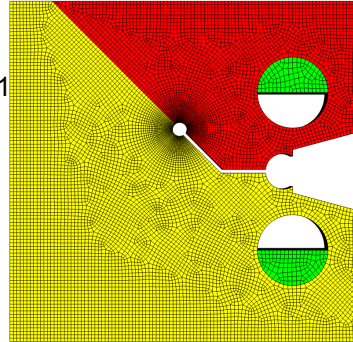
$$F^\parallel = g_i \otimes G^i$$

Damage is convergent with refinement

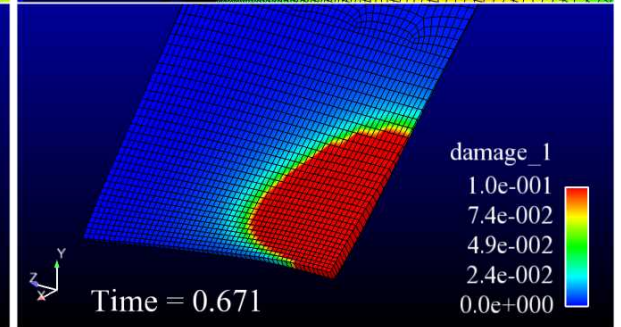
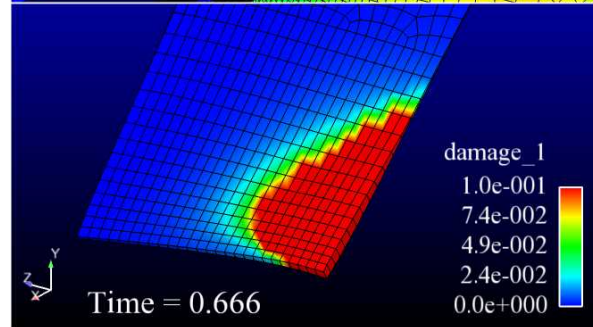
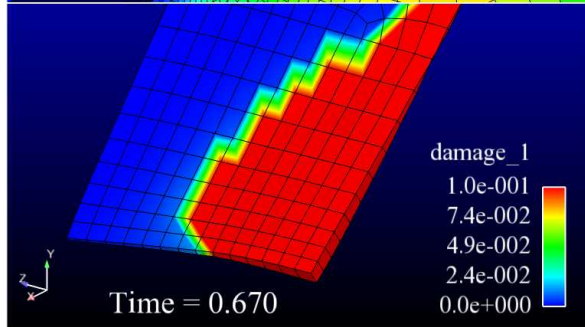
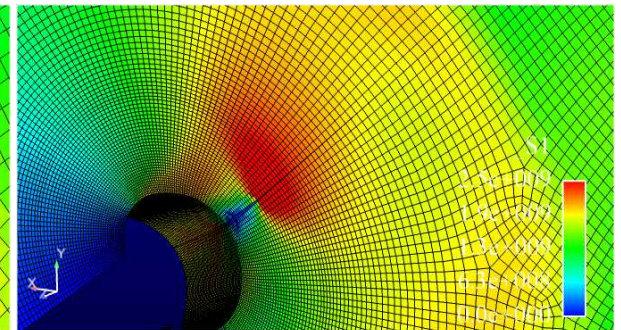
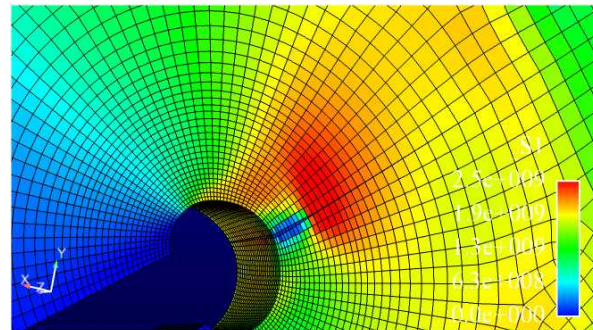
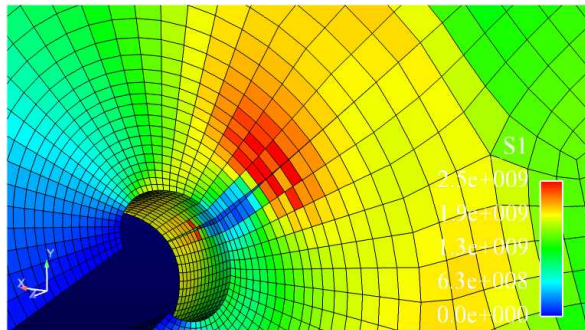
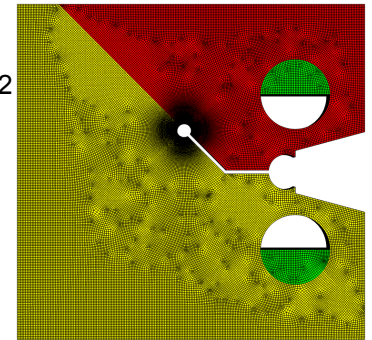
Mesh: 02
Label: Medium
Nodes: 29,535
Elem: 23,673
 $s \sim 120 \mu\text{m}$



Mesh: 03
Label: Fine
Nodes: 141,831
Elem: 125,865
 $s \sim 60 \mu\text{m}$



Mesh: 04
Label: Finest
Nodes: 1,079,622
Elem: 1,015,812
 $s \sim 30 \mu\text{m}$



Although at slightly different times, the evolution of damage is comparable for 03 & 04.

NOTE: Smooth notch – the specimen was not pre-cracked.

Extend sub-grid model for multiphysics

Fox and Simo (1980), Callari, Armero, Abati (2010)

redefine space $\mathbf{X} = \Phi(\xi^1, \xi^2, \xi^3) = \bar{\Phi}(\xi^1, \xi^2) + \mathbf{N}(\xi^1, \xi^2)\xi^3$ $G_i = \Phi_{,i} = \frac{\partial \mathbf{X}}{\partial \xi^i}$

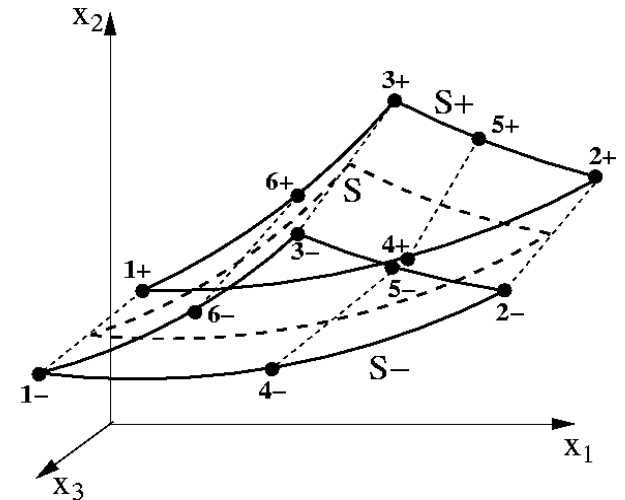
include jump in C $C(\mathbf{X}) = \bar{C}(\phi[\xi^1, \xi^2]) + \frac{[[C]](\phi[\xi^1, \xi^2])}{h}\xi^3$ $\nabla_{\mathbf{X}} C = (\nabla \Phi)^{-T} \frac{\partial C}{\partial \xi^i}$

Finite element implementation is straightforward

$$\nabla_{\mathbf{X}} C|_{\xi^3=0} = [B] \begin{bmatrix} \{C\}^+ \\ \{C\}^- \end{bmatrix} = [[B]^+ \quad [B]^-] \begin{bmatrix} \{C\}^+ \\ \{C\}^- \end{bmatrix}$$

$$B_{ia}^{\pm} = [G_i^1 \quad G_i^2 \quad G_i^3] \cdot \left[\frac{1}{2} \frac{\partial N_a}{\partial \xi^1} \quad \frac{1}{2} \frac{\partial N_a}{\partial \xi^2} \quad \pm \frac{1}{h} N_a \right]$$

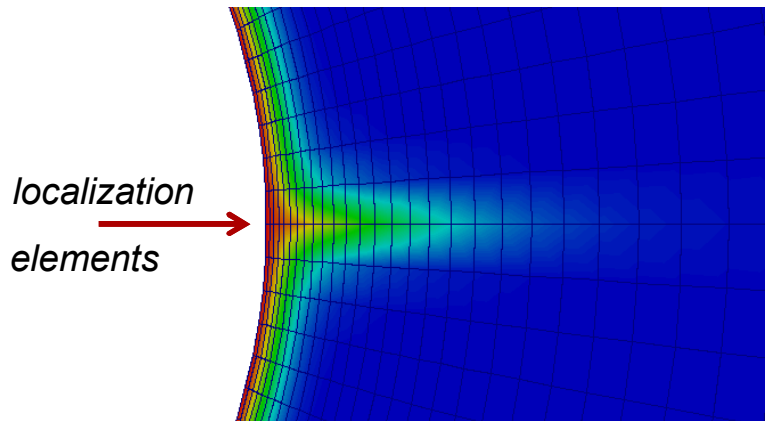
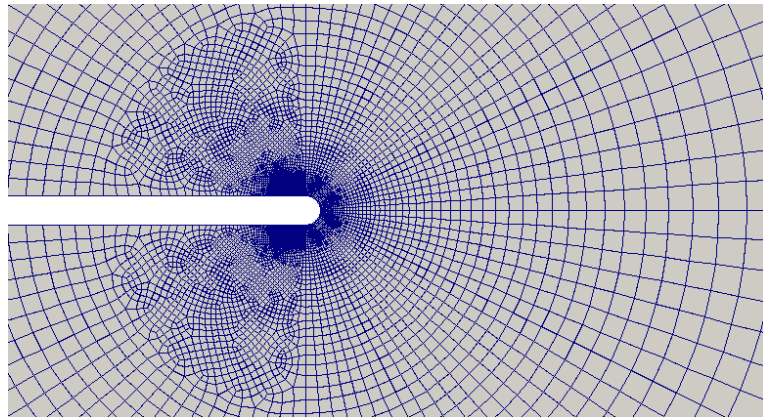
$i = \# \text{ dimensions, } a = \# \text{ nodes}$



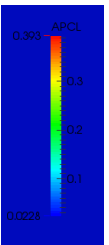
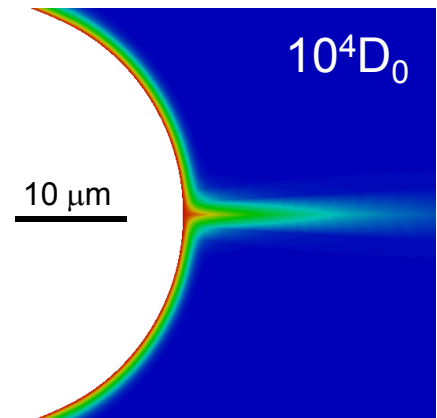
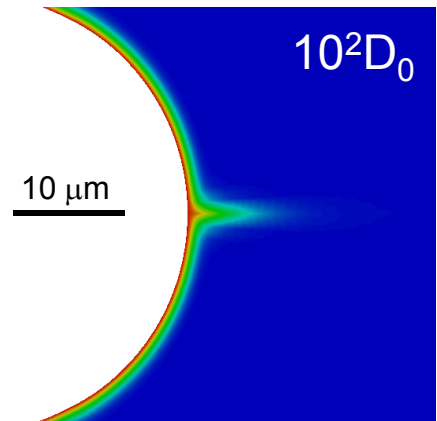
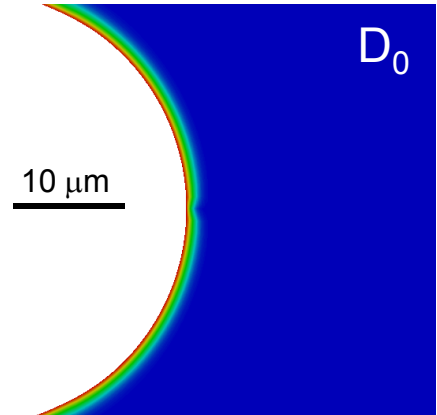
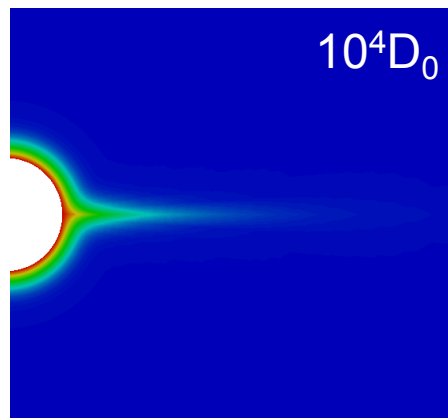
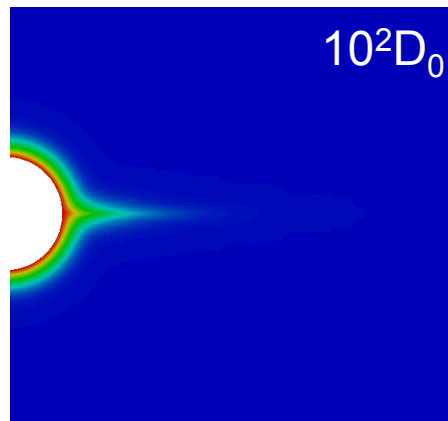
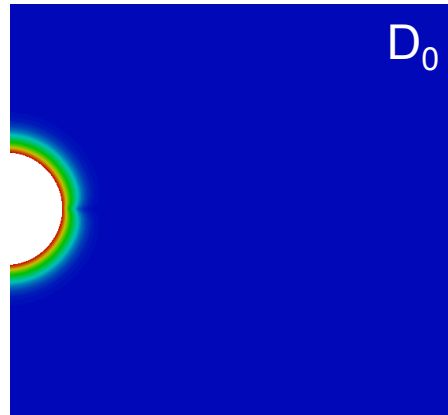
Given this gradient operator, we can use the same PDE for finite-deformation diffusion

$$D^* \dot{C}_L - \nabla_{\mathbf{X}} \cdot d_l \mathbf{C}^{-1} \nabla_{\mathbf{X}} C_L + \nabla_{\mathbf{X}} \cdot \frac{d_l V_H}{RT} \mathbf{C}^{-1} \nabla_{\mathbf{X}} \tau_h C_L + \theta_T \frac{dN_T}{d\epsilon_p} \dot{\epsilon}_p$$

Examining a fast pathway



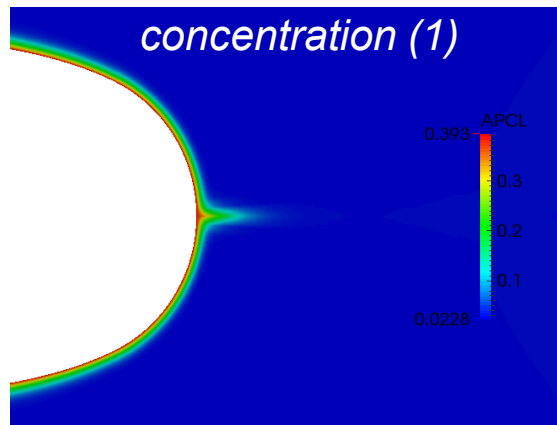
- Baseline properties, 21-6-9
- Study: D_0 , $10^2 D_0$, $10^4 D_0$
- No deformation, 100 MPa $m^{1/2}$
- Rate: 100 MPa $m^{1/2}$ / hour
- Tip element size ~ 330 nm
- Length scale, $h = 2$ nm
- Plotting atomic %, (lattice H)/Fe



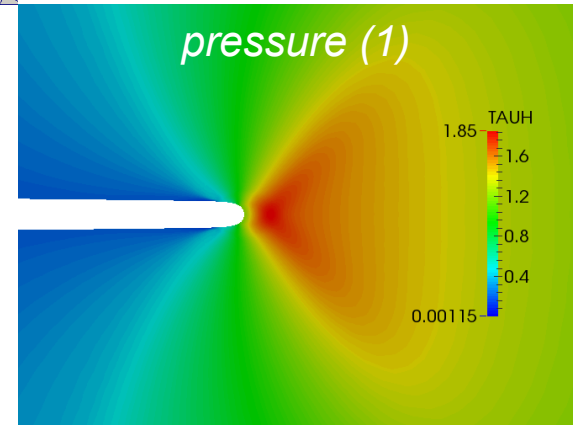
Solving 5 fields simultaneously

Units are scaled in the balance of linear momentum, conservation of concentration, and L_2 projection to improve condition number of the system

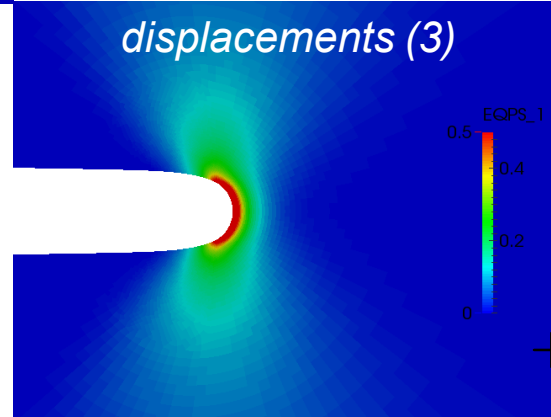
$$D^* \dot{C}_L$$



- Path: $10^2 D_0$
- K_{app} : 100 MPa $m^{1/2}$
- Time: 3600 s



$$\nabla_{\mathbf{X}} \cdot d_l \mathbf{C}^{-1} \nabla_{\mathbf{X}} C_L$$



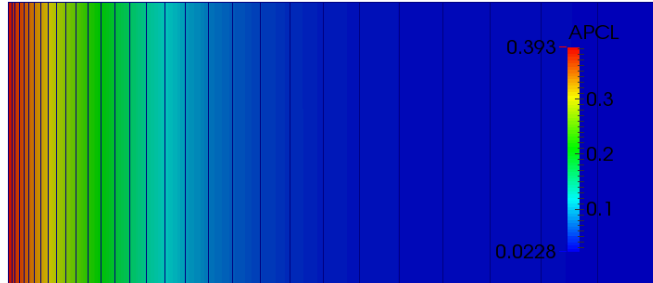
$$\nabla_{\mathbf{X}} \cdot \frac{d_l V_H}{RT} \mathbf{C}^{-1} \nabla_{\mathbf{X}} \tau_h C_L$$

$$+ \theta_T \frac{dN_T}{d\epsilon_p} \dot{\epsilon}_p$$

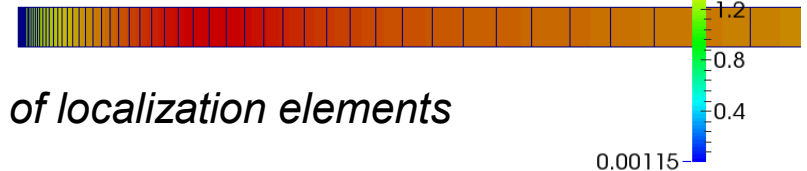
NOTE: 100 MPa $m^{1/2}$ is well below J_Q for 21Cr-6Ni-9Mn (220 MPa $m^{1/2}$)

Because we have an analytical Jacobian, we employ Newton's method.

Natural sub-grid representation



solution variables, C_L and τ_H



top view of localization elements

path: $10^2 D_0$, K_{app} : 100 MPa $m^{1/2}$, time: 3600 s

NOTE: Width of localization elements is 10 μm

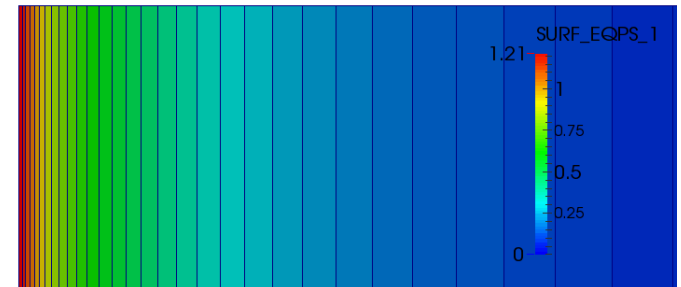
Localization elements leverage bulk models

- Employing bulk, J_2 plasticity model
- Finite deformation kinematics
- Evolve stresses and internal state variables
- Employing bulk models for trapping
- Damage nucleation, growth straightforward

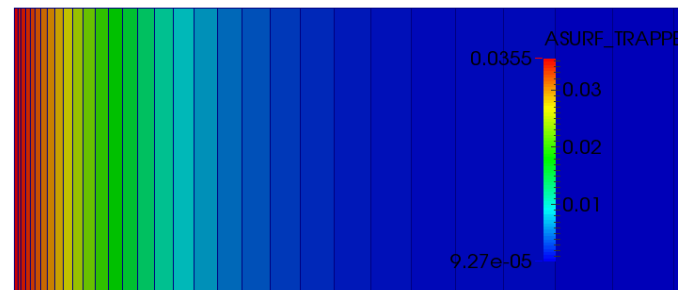


stress triaxiality

eqps



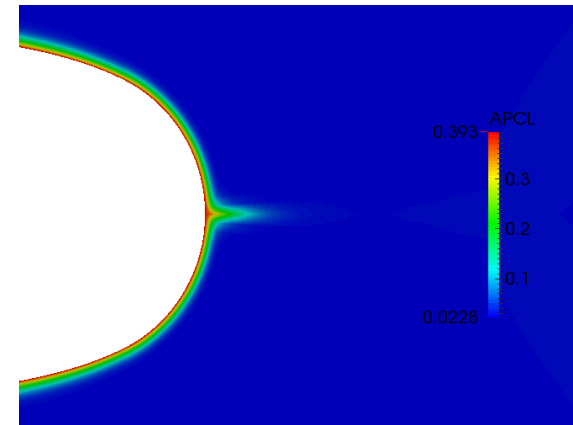
atomic % trapped hydrogen



Future goal: Adaptive insertion along element boundaries (simplicial elements)

Summary and path forward

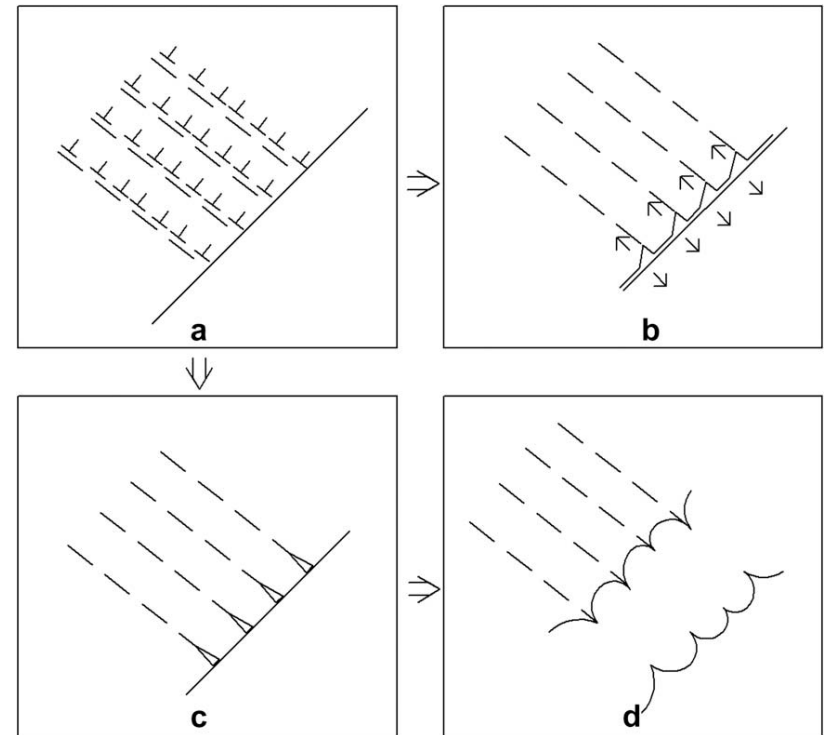
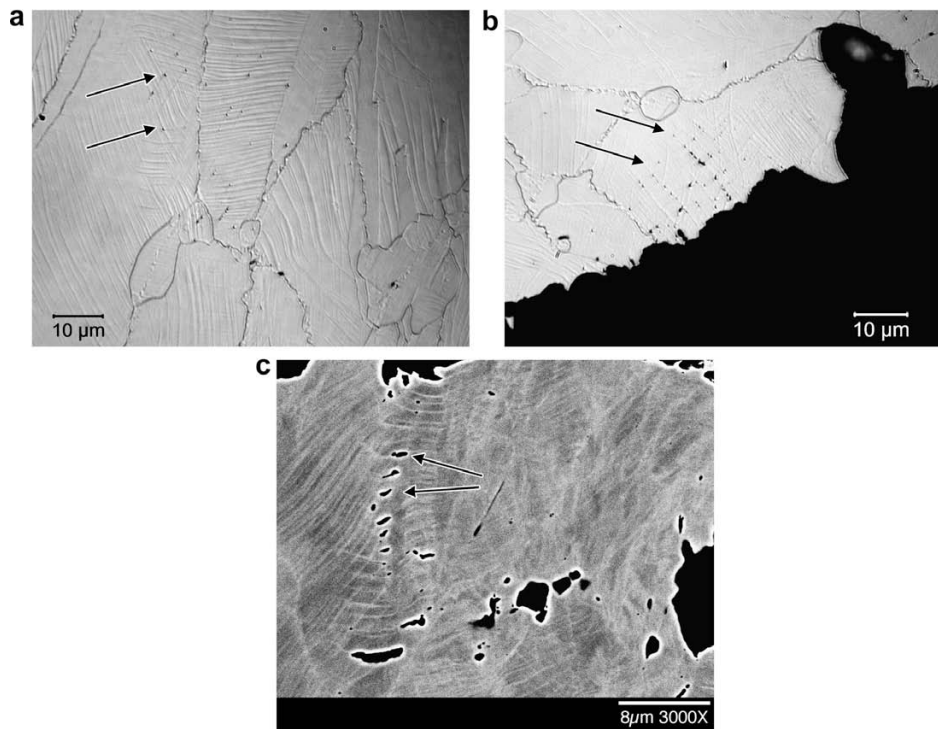
- Strong research environment
- Coupling is maturing
- Incorporated sub-grid multiphysics
- Enabled fast pathways
- Nucleation model maturing
- Propagation on horizon



Our ability to form and test hypothesis through modeling and simulation can aid the discovery process and provide a pull for more fundamental measurements and computational methods.

BACKUP SLIDES

Damage nucleation model w/H

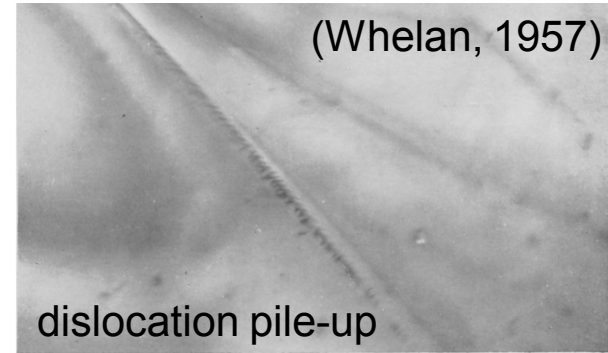
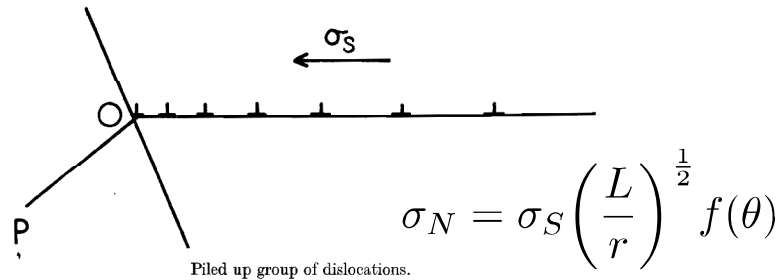


IDEA: Hydrogen enables the premature formation of planar deformation bands that impinge on boundaries of grains, annealing twins, and/or other deformation bands. The stress concentration induced by the intersection may nucleate a void of large aspect ratio (cylinder) that will evolve, coalesce and create the observed “fluted” fracture surface.

The fracture process is still ductile! Need to capture the premature nucleation of voids in the presence of hydrogen. Can we first construct a simple model to aid our intuition?

Analytical basis for nucleation

Stroh, A Theory of the Fracture of Metals, 1957



Using a work argument, the normal stress σ_N for nucleation can be derived from the shear stress σ_S given the fracture energy γ and the number of dislocations n in a pile-up (band) along a boundary.

$$\sigma_{S,crit} = \frac{3\pi^2\gamma}{8n(\rho_{ss}, \theta_T)b} \quad n = A(\theta_T)\rho_{ss} = hs(\theta_T)\rho_{ss} \quad \begin{aligned} \kappa &= \mu\epsilon_{ss} \\ \epsilon_{ss} &= b\sqrt{\rho_{ss}} \end{aligned}$$

Given b is burgers vector and A is an effective area characterized by the grain size h and the pile-up spacing s . We relate the pile-up spacing to the occupancy of hydrogen in the traps θ_T . If we approximate σ_S through the yield stress σ_y and the isotropic hardening variable κ , we can express nucleation in terms of a scalar strain metric ϵ_{ss} that is reflective of the dislocation density ρ_{ss} .

$$\epsilon_{ss,crit}^3 + \frac{\sigma_y}{\mu}\epsilon_{ss,crit} - \frac{3\pi b\gamma}{4hs(\theta_T)\mu} \quad \text{permits analytical solution (1 real root)}$$

If we assume heavily worked materials, $\rho_{ss} \sim 10^{15}$, the specification of $s(\theta_T)$ becomes problematic. We need to construct a simplified model for nucleation in the correct state variable ϵ_{ss} that can capture a statistical sampling of boundary orientations having dislocation pile-ups (bands) which are stabilized and extended through hydrogen transport.

$$\theta_T = \frac{C_T}{N_T} \quad \text{Occupancy of hydrogen in the traps } \theta_T \text{ derives from trapped concentration } C_T \text{ and the number of traps } N_T.$$

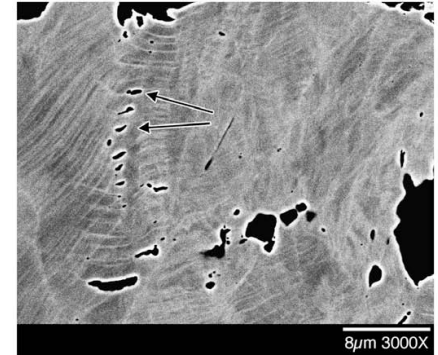
Phenomenological extension

The deformation bands that evolve under large deformations cannot be easily idealized

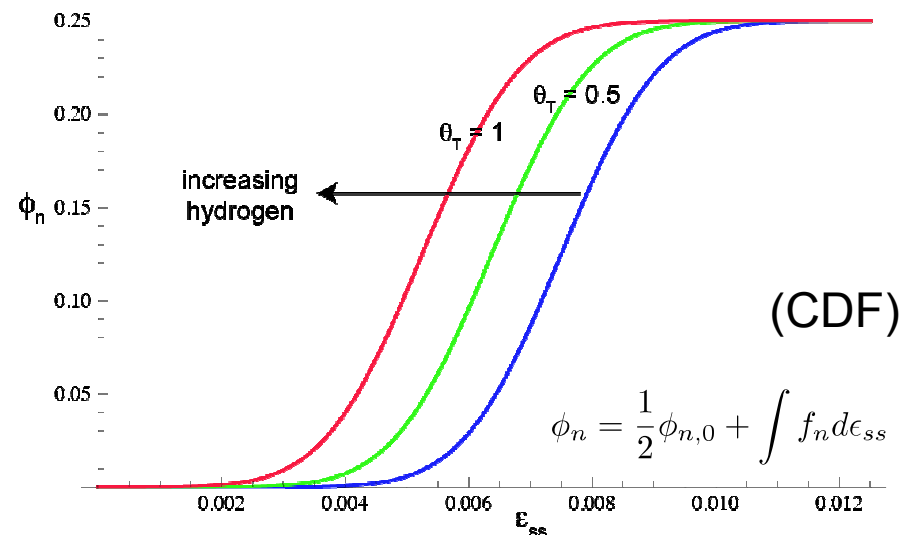
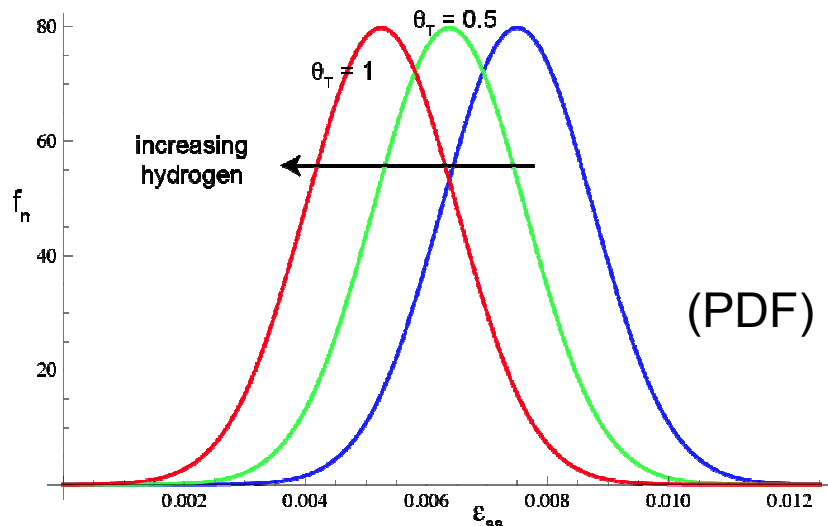
$$f_n = \frac{\phi_{n,0}}{\epsilon_{ss,std}\sqrt{2\pi}} \exp \left[-\frac{1}{2} \left(\frac{\epsilon_{ss} - \epsilon_{ss,mean}}{\epsilon_{ss,std}} \right)^2 \right]$$

In spirit of Chu and Needleman (1980) we choose an appropriate state variable to capture void nucleation through elevated stresses at pile-ups. We assume the probability of void nucleation f_n follows a normal distribution.

We assume that hydrogen affects the mean $\epsilon_{ss,mean}$ and not the standard deviation $\epsilon_{ss,std}$ through the occupancy of hydrogen in the traps θ_T . The nucleated void volume fraction ϕ_n can be found through integration and is limited by $\phi_{n,0}$.



(Nibur, 2009)

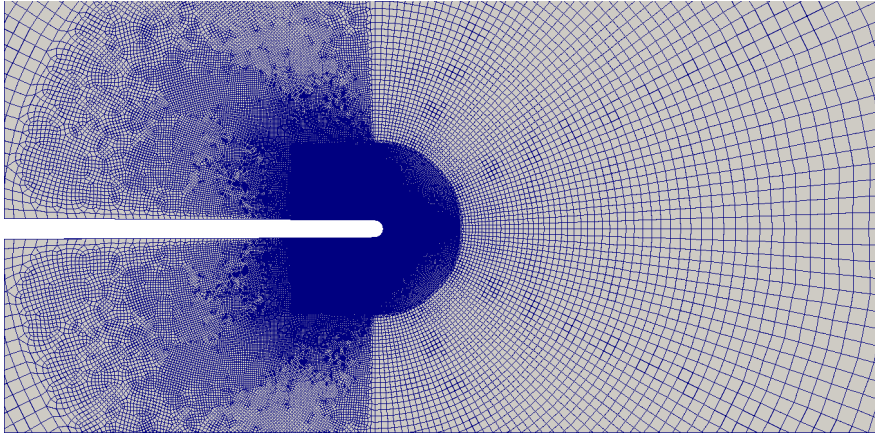


NOTE: In this case, we assume that $\phi_{n,0}$ is 0.25. Nucleation will account for 25% of porosity

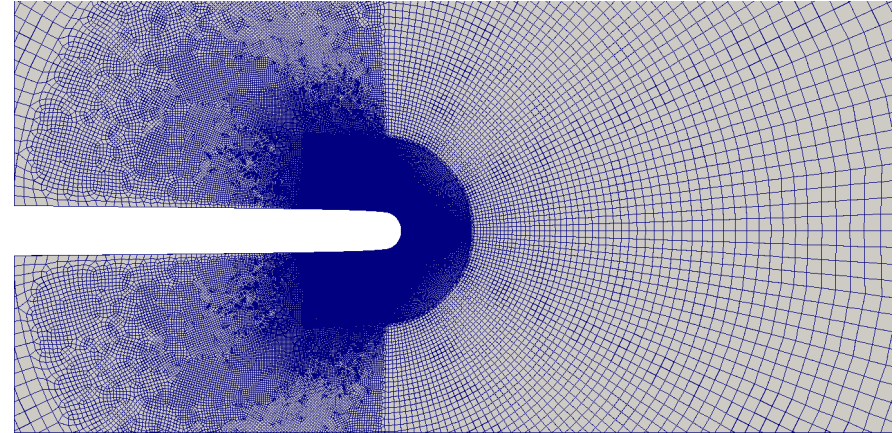
Resolution required

$$r_p \ll L \text{ (150 mm)} \quad 2b_0 \text{ (10 } \mu\text{m)} \ll \text{CTOD (155 } \mu\text{m)}$$

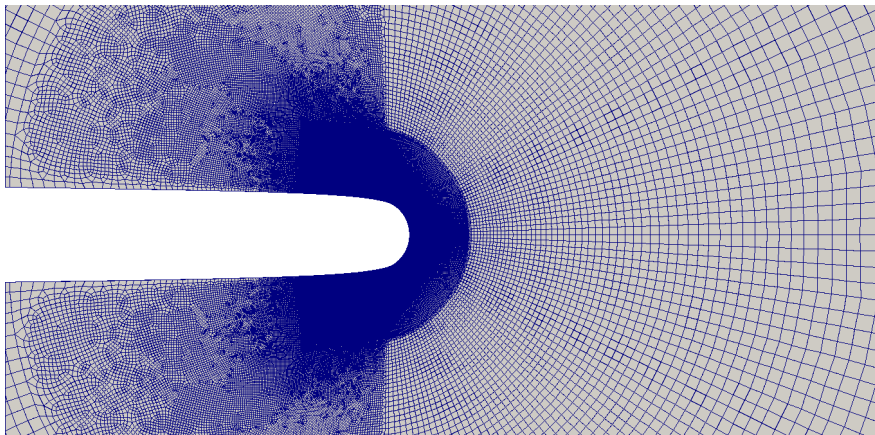
undeformed, $2b_0 = 10 \mu\text{m}$



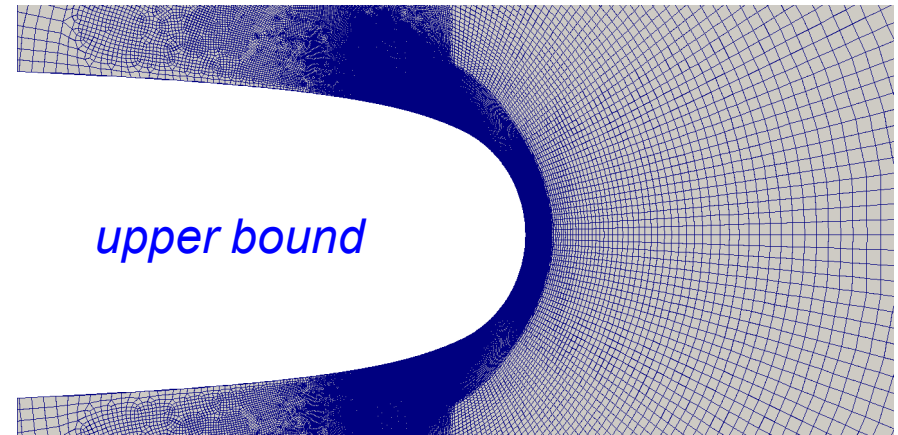
$K = 50 \text{ MPa m}^{1/2}$, CTOD = $23.4 \mu\text{m}$



$K = 110 \text{ MPa m}^{1/2}$, CTOD = $43.9 \mu\text{m}$

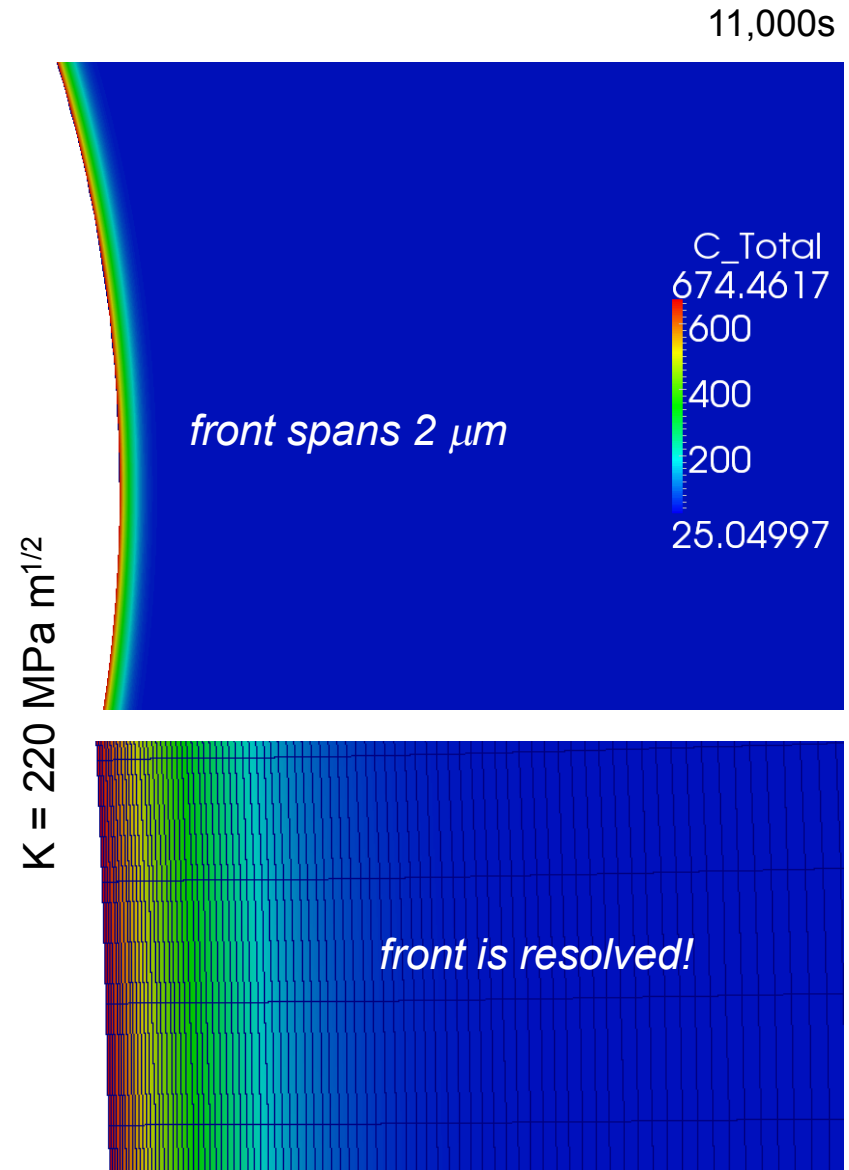
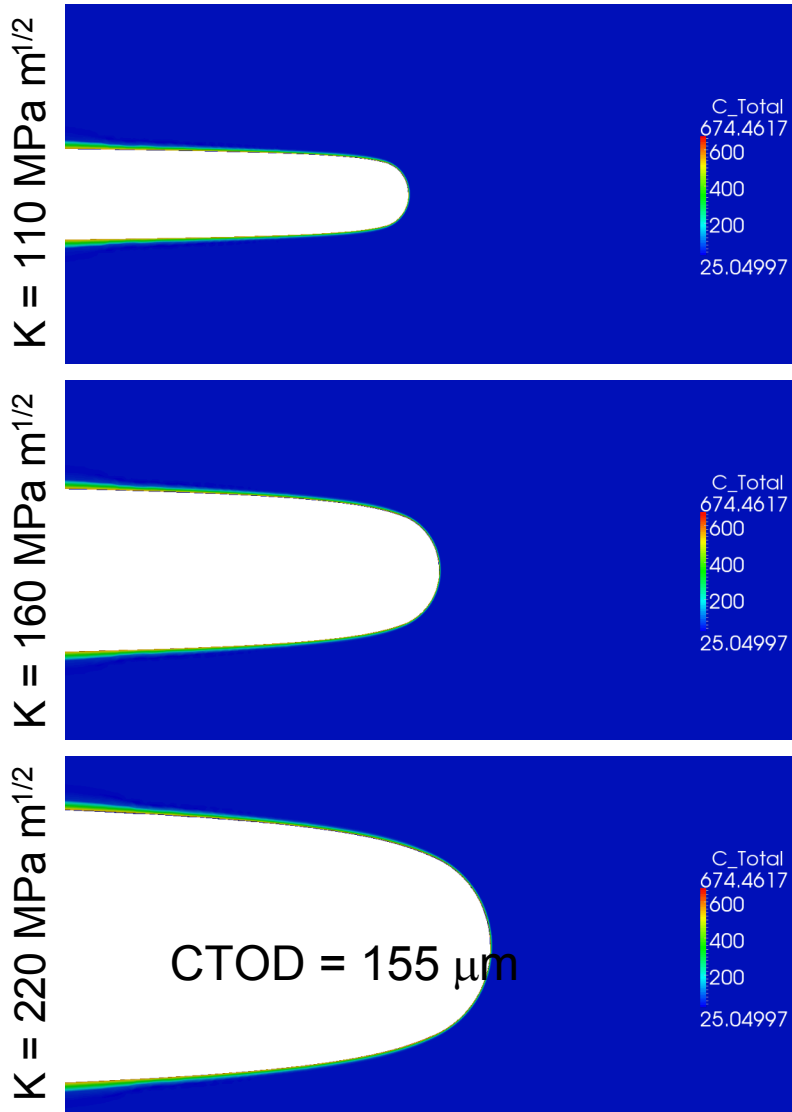


$K = 220 \text{ MPa m}^{1/2}$, CTOD = $155 \mu\text{m}$



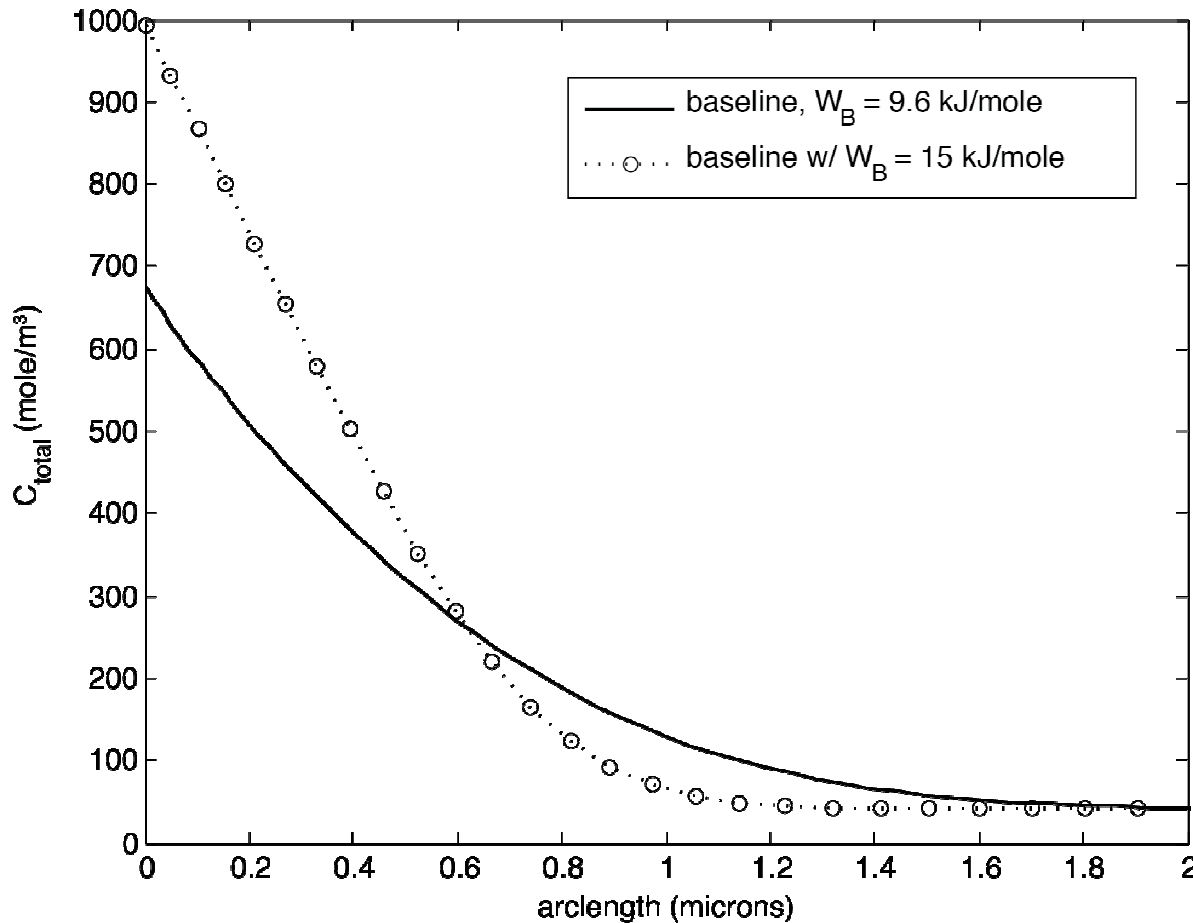
We are required to resolve a diffusion front l_{front} that is $\sim 0.5 \mu\text{m}$, $\text{CTOD}_{\text{max}}/l_{\text{front}} \sim 310$

Diffusion remains local and is resolved



Increasing W_B compacts front

Increased binding energy W_B compacts front and substantially raises the total concentration



$K = 220 \text{ MPa m}^{1/2}$
 $\text{CTOD} = 155 \text{ }\mu\text{m}$
 time: 11,000 s

$$\theta_t = \frac{1}{1 + \frac{1}{k_t \theta_i}}$$

$$N_T = N_T(\epsilon_p)$$

$$k_t = e^{\frac{W_B}{RT}}$$

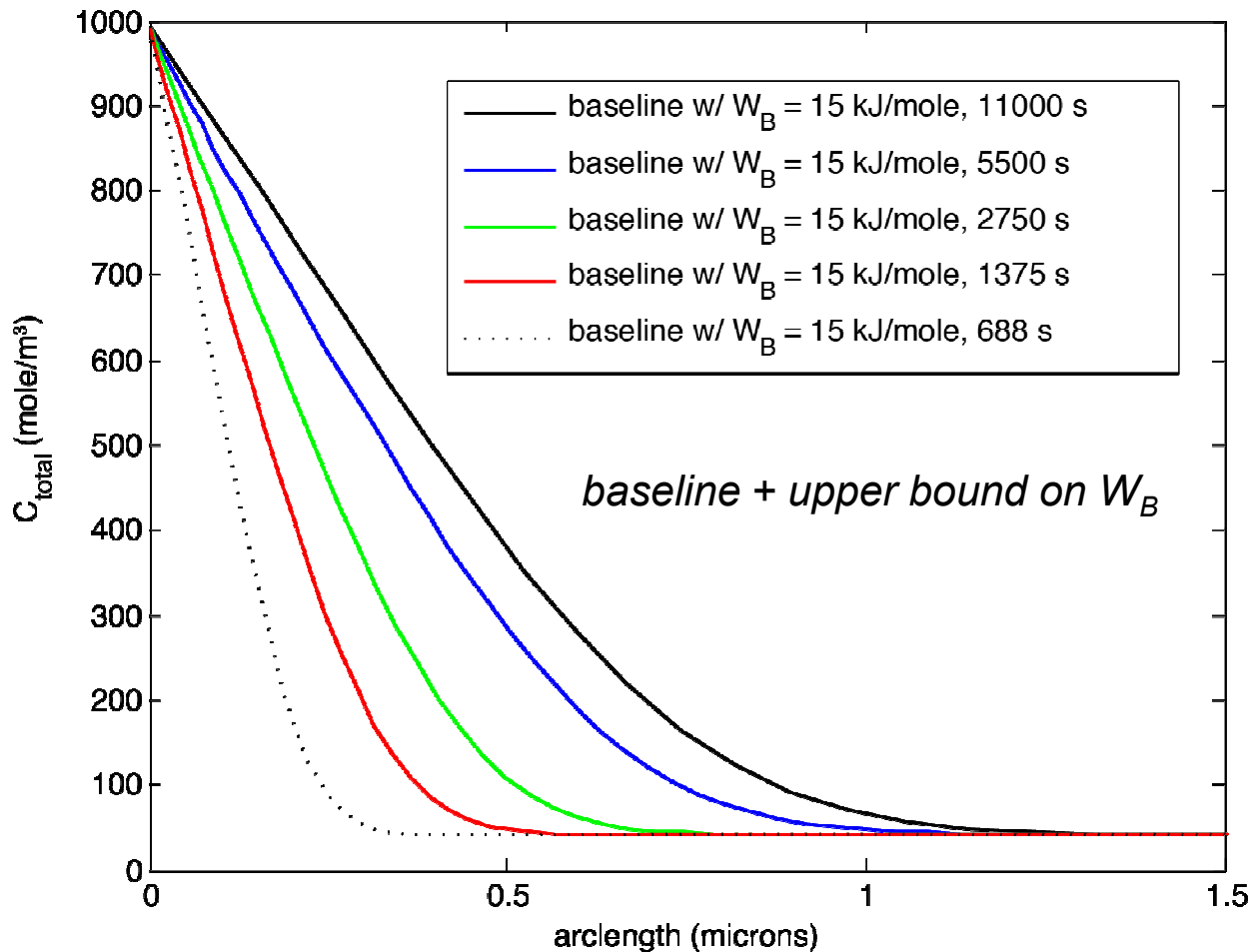
trapping

Diffusion front decreased by a factor of 2 – $2 \text{ }\mu\text{m}$ to $1 \text{ }\mu\text{m}$

Total hydrogen concentration raised from 687 mol/m^3 to 991 mol/m^3

Faster loading rates compact front

- Test conditions: 1320 s and 13200 s to 220 MPa m^{1/2}
- Model cases: 688 s, 1375 s, 2750 s, 5500 s, and 11000 s to 220 MPa m^{1/2}
- Employing increased binding energy to investigate steeper gradients



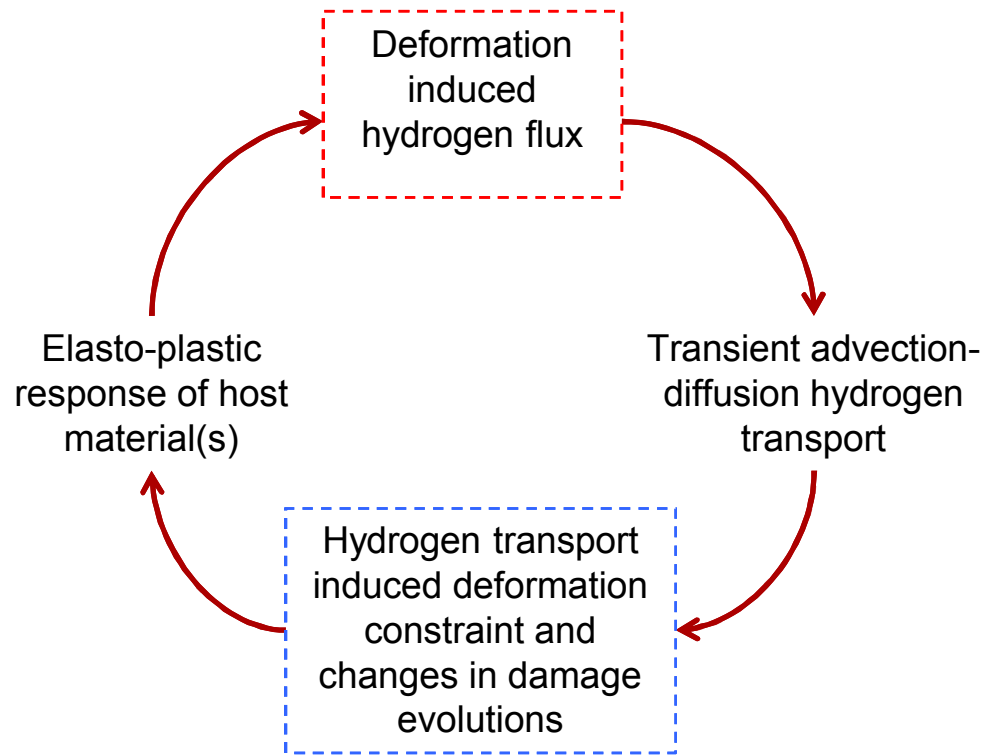
$K = 220 \text{ MPa m}^{1/2}$

CTOD = 155 μm

*More rapid loadings
result in a diffusion front
than spans only a few
hundred nanometers.*

*Fast pathways or is this
a surface effect?*

Monolithic system for strong coupling



- When coupling terms (red and blue boxes) are **both** non-trivial, the coupling mechanism is two-way.
- There are two possible ways to solve two-way coupling problems are:
 - Iterative split-operator approach (Simo-Miehe 1992, Kim, Tchelepi and Juanes, 2013). In this case, solid mechanics and convection-diffusion solvers exchange information by allowing inconsistent linearization (i.e., freezing some nonlinear parameter, for instance, freezing displacement when solving for hydrogen concentration and vice versa) in each iteration.
 - Monolithic mixed finite element method, which guarantees consistency of the linearization, but may lead to an ill-conditioned linearized system of equations (Sun, Ostien, Salinger 2013).

$$\begin{bmatrix} \mathbf{0} & \mathbf{0} \\ \mathbf{M}_{c_L u} & \mathbf{K}_{c_L c_L}^{tran} \end{bmatrix} \begin{bmatrix} \dot{\mathbf{u}} \\ \dot{\mathbf{c}}_L \end{bmatrix} + \begin{bmatrix} \mathbf{K}_{uu} & \mathbf{B}_{uc_L} \\ \mathbf{0} & \mathbf{K}_{c_L c_L}^{st} \end{bmatrix} \begin{bmatrix} \mathbf{u} \\ \mathbf{c}_L \end{bmatrix} = \begin{bmatrix} \mathbf{F}_u^{ext} \\ \mathbf{F}_{c_L}^{ext} \end{bmatrix}$$

Physical interpretation of the matrix form