



THETA-DATA: Introduction to rotational seismology and its potential uses

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Rotational Seismic:
measure & analyze
rotational motion at
geophones,
in addition to linear motion.

Potential applications:
spatial sampling, micro-
seismic, elastic wave, . . .

Acknowledgements

- **Geokinetics**
- **Sandia National Laboratories**
- **Schlumberger Cambridge Research**
- **Applied Technology Associates**
- **Eentec**
- **MetTech / MetSensing**

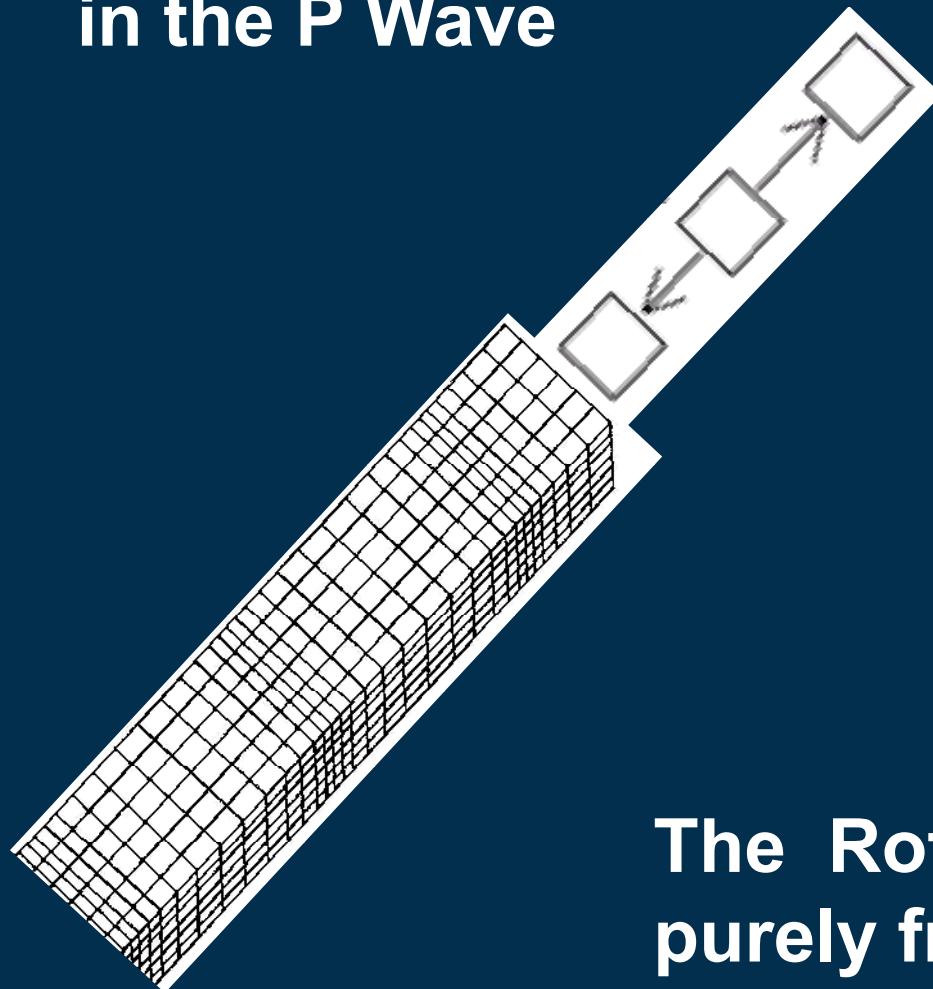
Discussions with many others . . .

Synopsis – Theta-Data Rotational Seismic

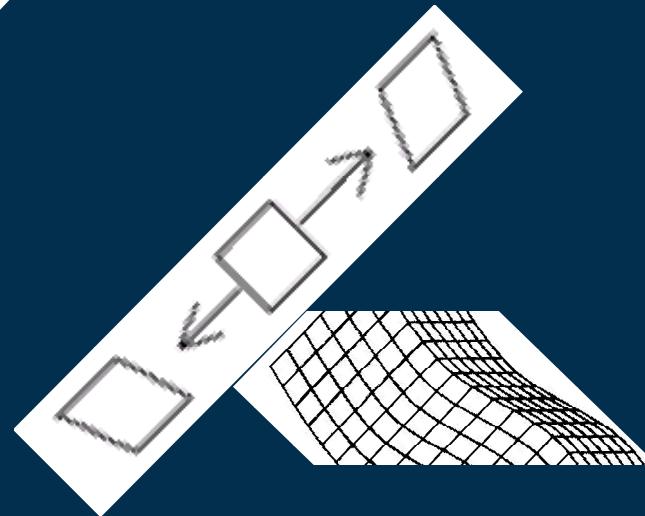
- **What is it and where did it come from?**
- **Sensors - How do we measure it?**
- **What does Theta-Data look like?**
- **What are possible Applications?**
 - **Spatial sampling enhancement**
 - **Shear Wave selectivity – microseismic**
 - **‘other’ uses**
- **Status and ‘Road Ahead’**

Rotational Seismic – Shear Selectivity

There is **NO ROTATION**
in the P Wave



There **IS ROTATION**
in the S wave



The Rotation Signal is
purely from the S wave

3-Theta Data – What is it?

Measure **Rotation**
around 3 axes - 3θ

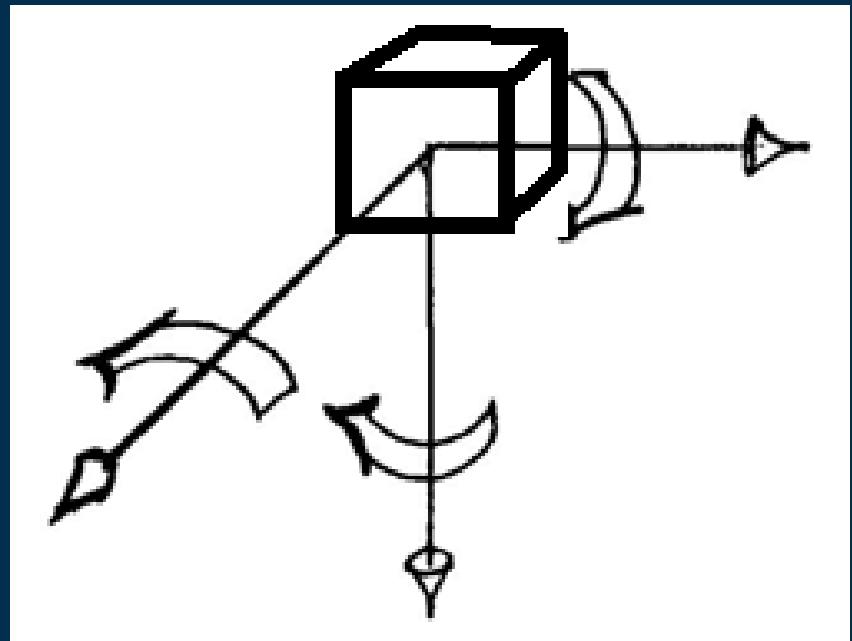
$\theta\text{-}x$

$\theta\text{-}y$

$\theta\text{-}z$

Vector Curl
of displacement

Record **3-θ** Rotation in
addition to 3-C or 4-C



“Theta Data”
is comprised of
“Curl Traces”

Six Degrees-Of-Freedom (6-DOF) Seismic

Classical Mechanics:

Need **Roll, Pitch, Yaw, as well as x, y, z**

To Fully Specify Motion

for a finite body (“elemental cube”)

Y rotation =

Z gradient of X linear

- X gradient of Z linear

$$\underline{\theta} = \begin{bmatrix} \theta_x \\ \theta_y \\ \theta_z \end{bmatrix} \equiv \frac{1}{2} \nabla \times \underline{u}$$

$$\theta_y = \frac{1}{2} \left(\frac{\partial u}{\partial z} - \frac{\partial w}{\partial x} \right)$$

Origins – Where Did Rotational Seismic ‘Come From’?

- **Earthquake Seismology:**
 - **William H. K. Lee (USGS) & others**
 - **Int’l Working Group on Rotational Seismology (IWGRS)**
 - **BSSA (May, 2009)**
- **Sensor technology development - *decades*:**
 - **Defense (US and USSR)**
 - **inertial guidance, etc.**

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Rotational Sensors

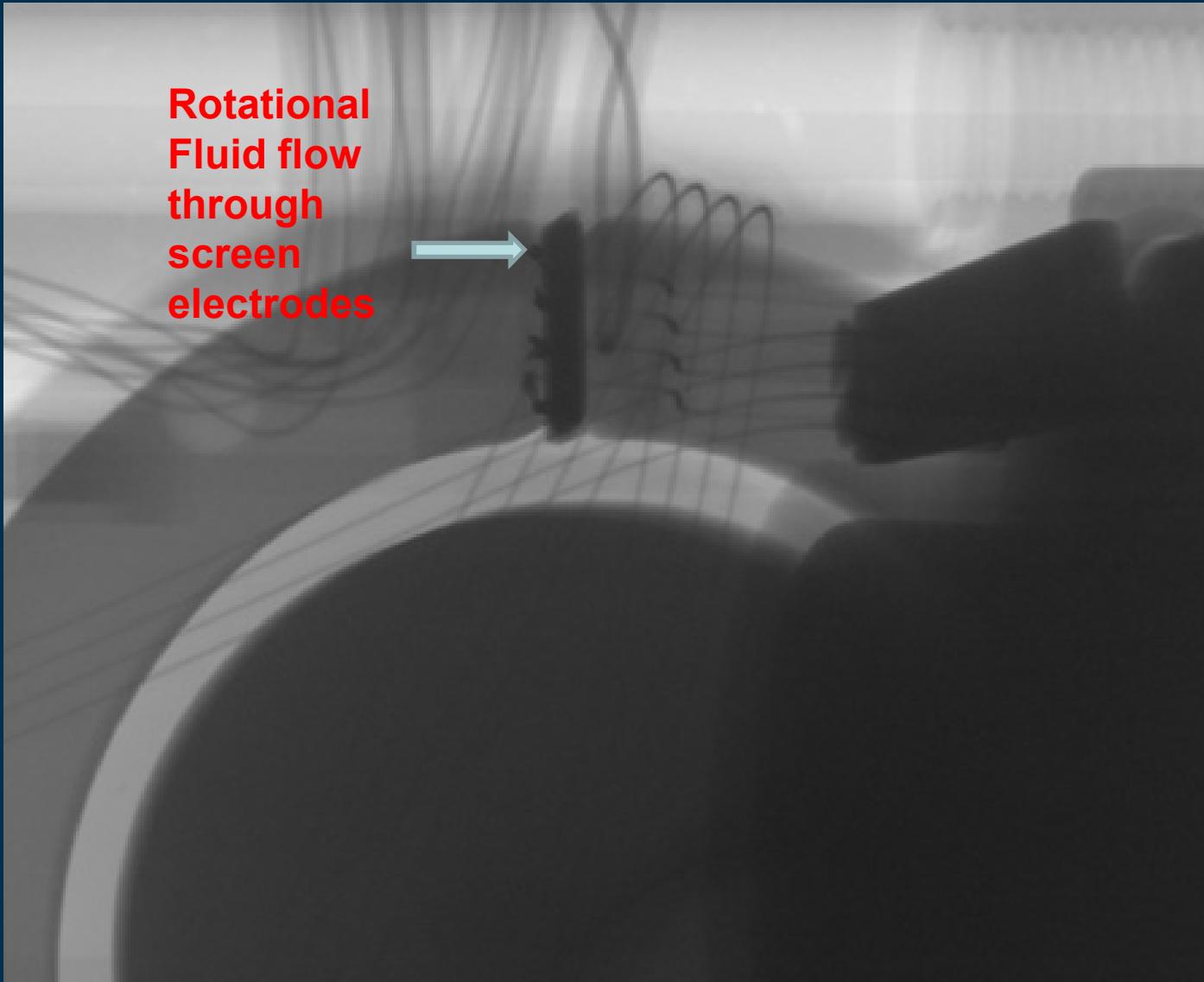


Typically flat spectral response for angular velocity.

Electrokinetic Sensors

- **Simple Concept:**
 - Ionic fluid in container is an inertial mass.
 - The ionic fluid flows through screen electrodes when there is motion.
 - Electrical current due to ionic fluid flow is a measure of **velocity** (linear or angular).
- Fluid in cylinder for **linear** motion
- Fluid in toroidal ‘donut’ for **rotational** motion
- **Electrokinetic Sensor characteristics:**
 - **Low noise** (order of 0.1 micro-radians sec)
 - **Low frequencies** possible

Electrokinetic Rotational Sensor

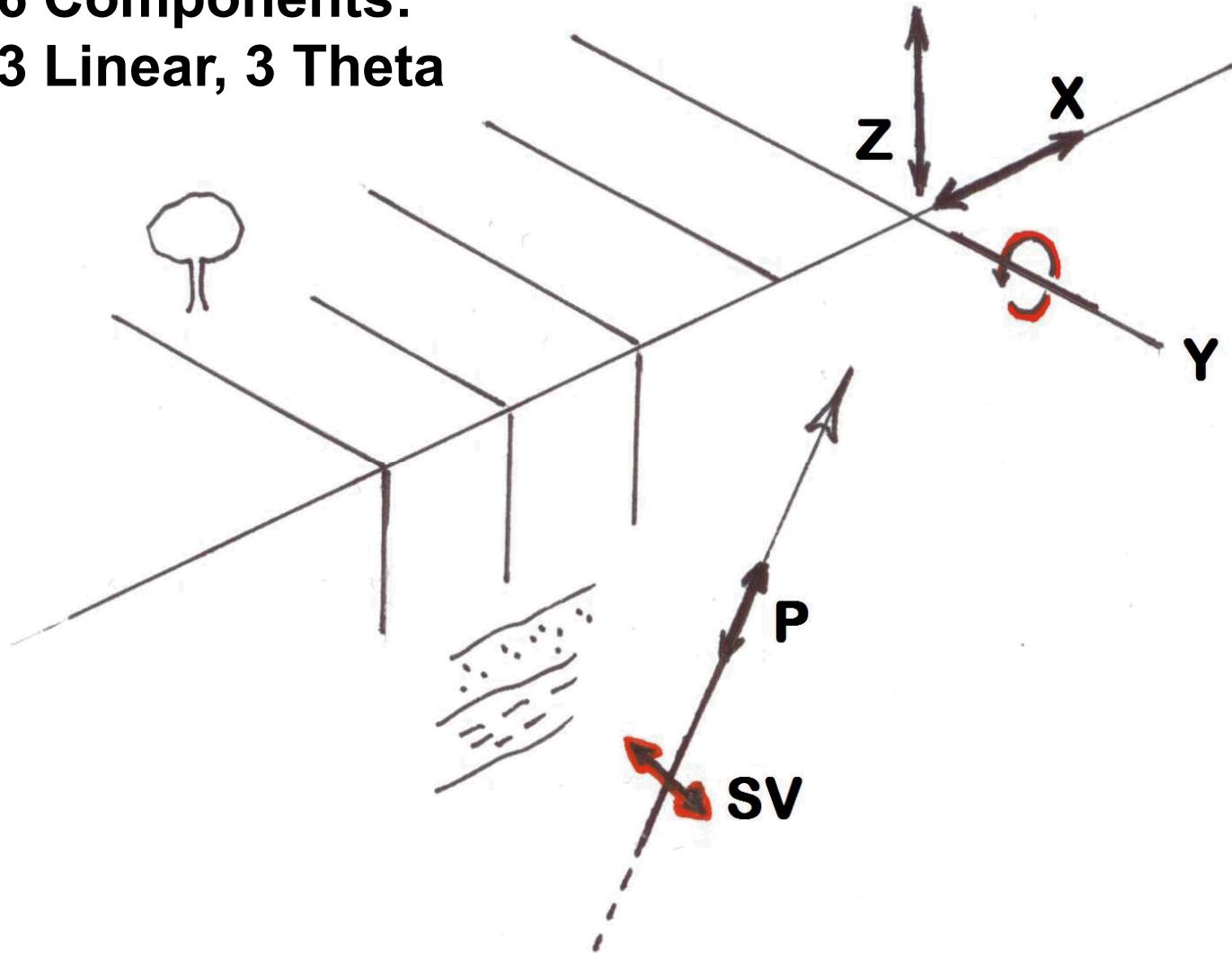


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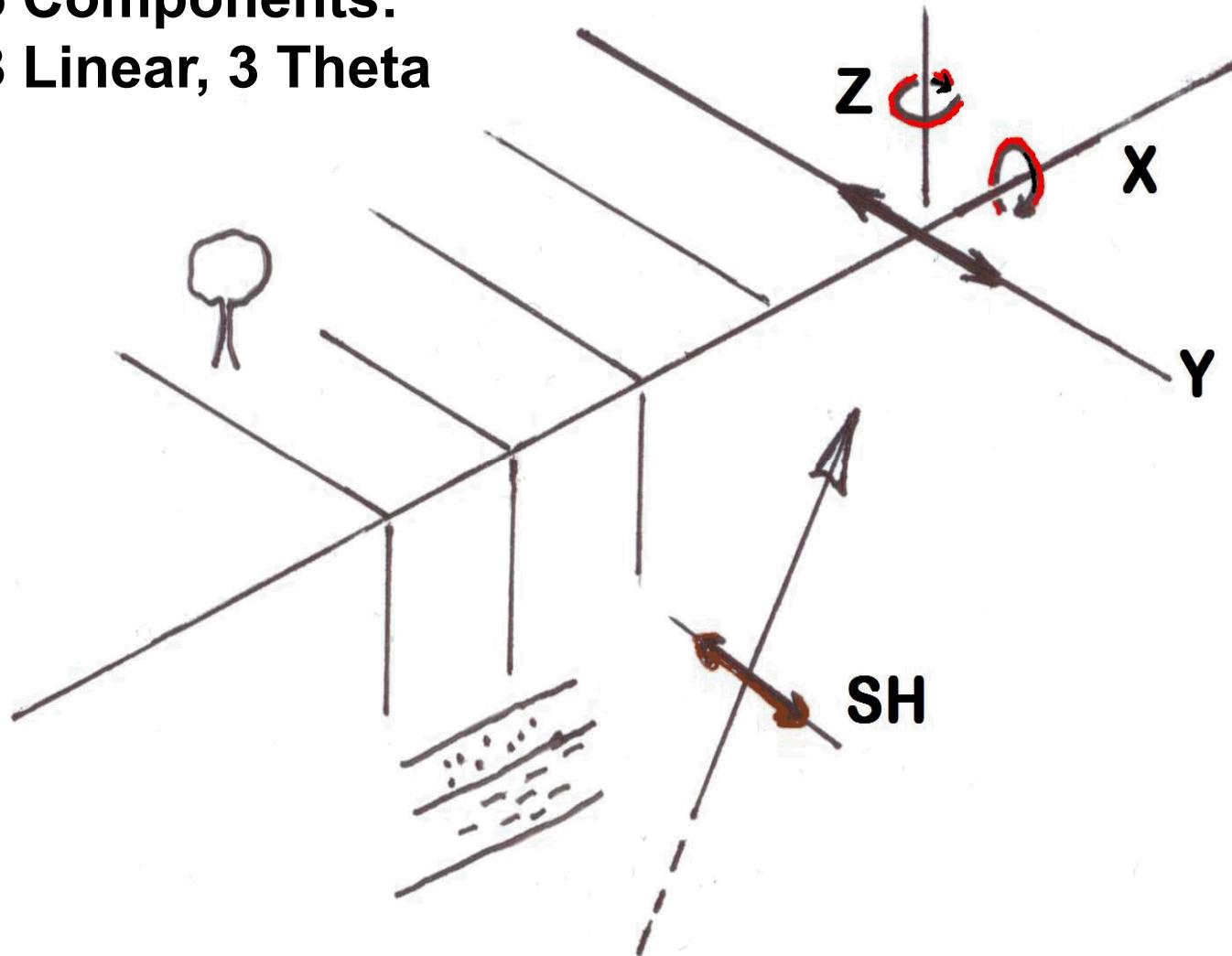
Transverse Rotational – TR Mode

6 Components:
3 Linear, 3 Theta

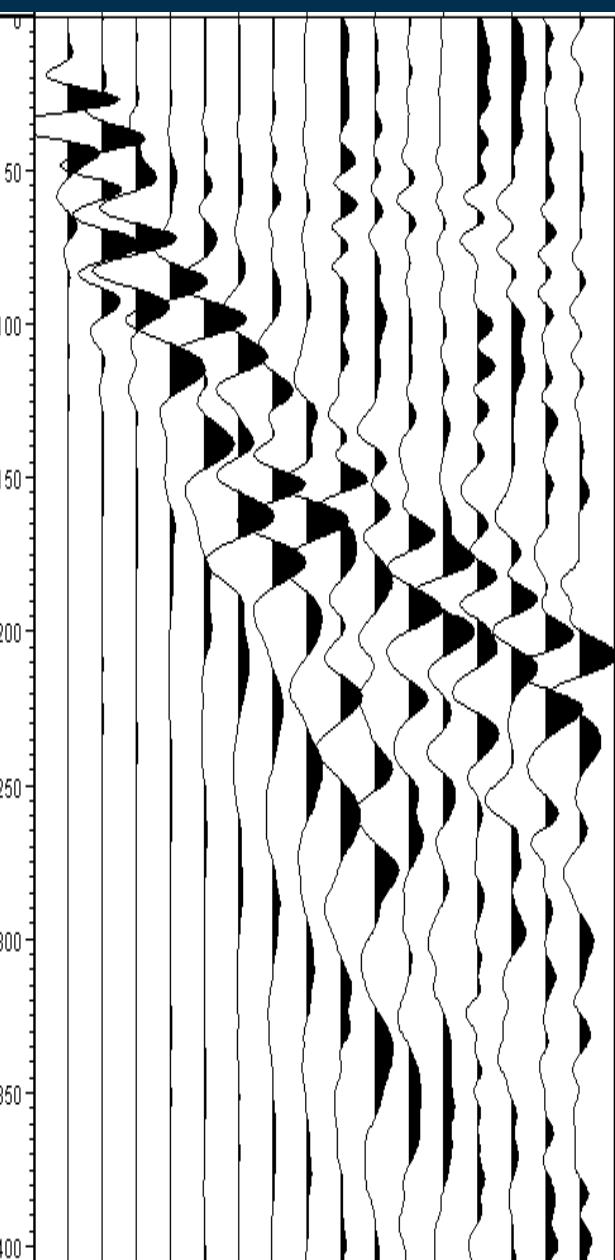
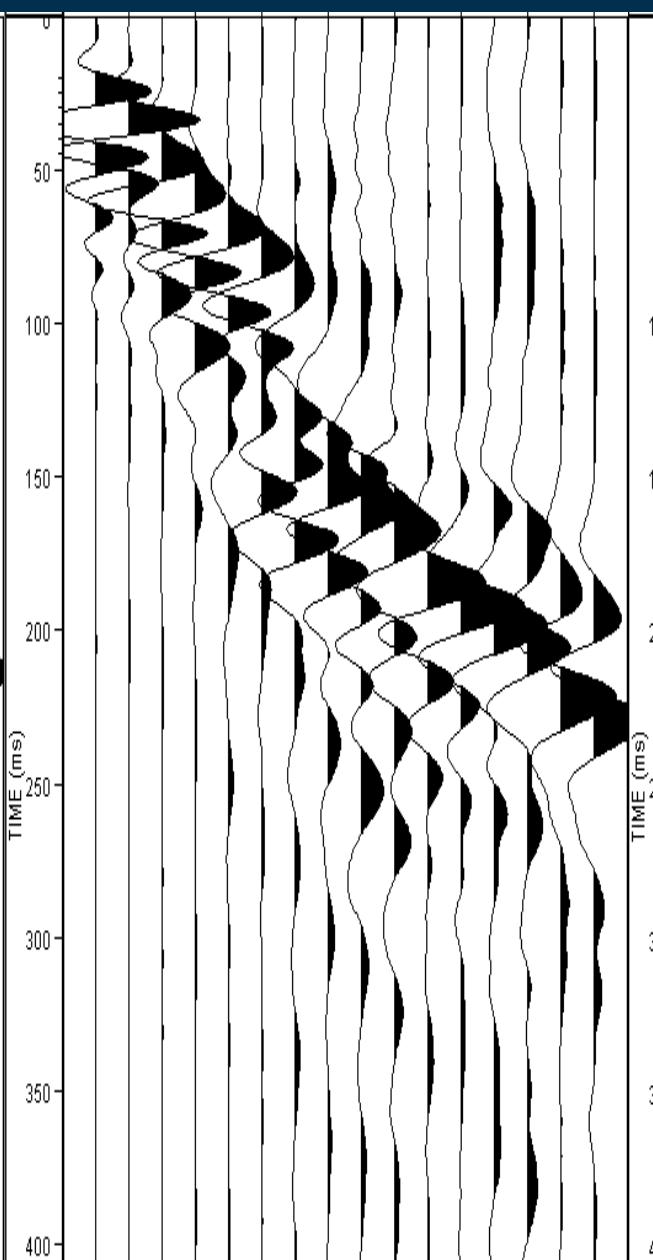
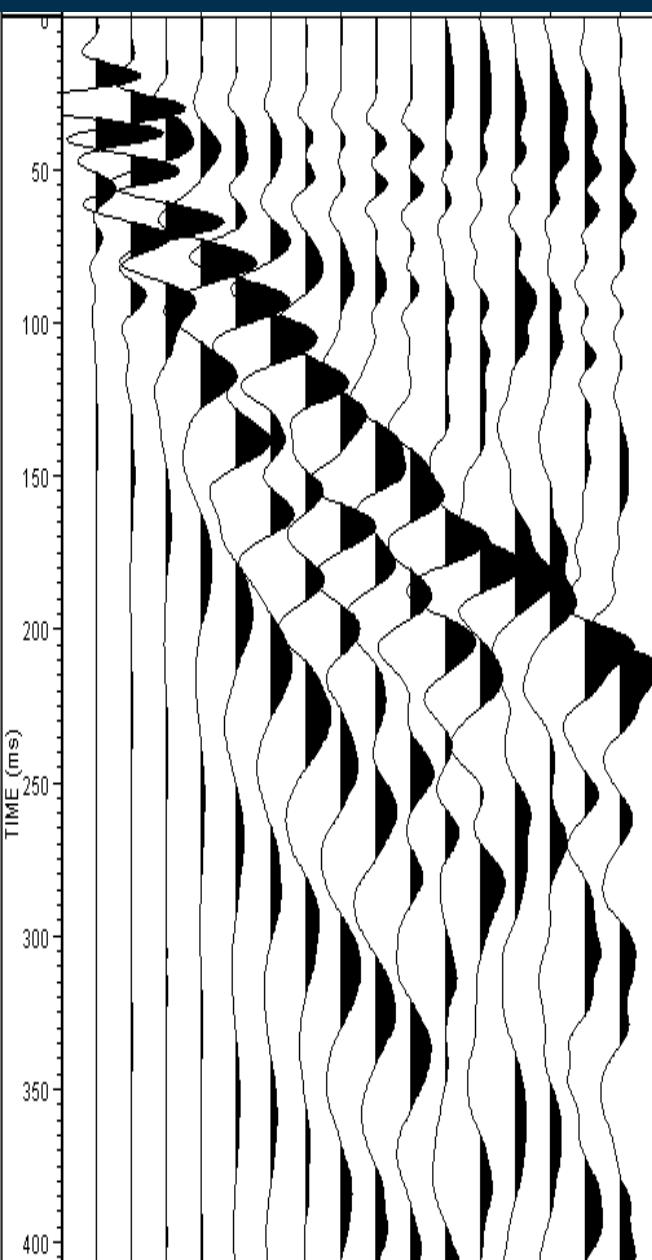


Transverse Linear - *TL Mode*

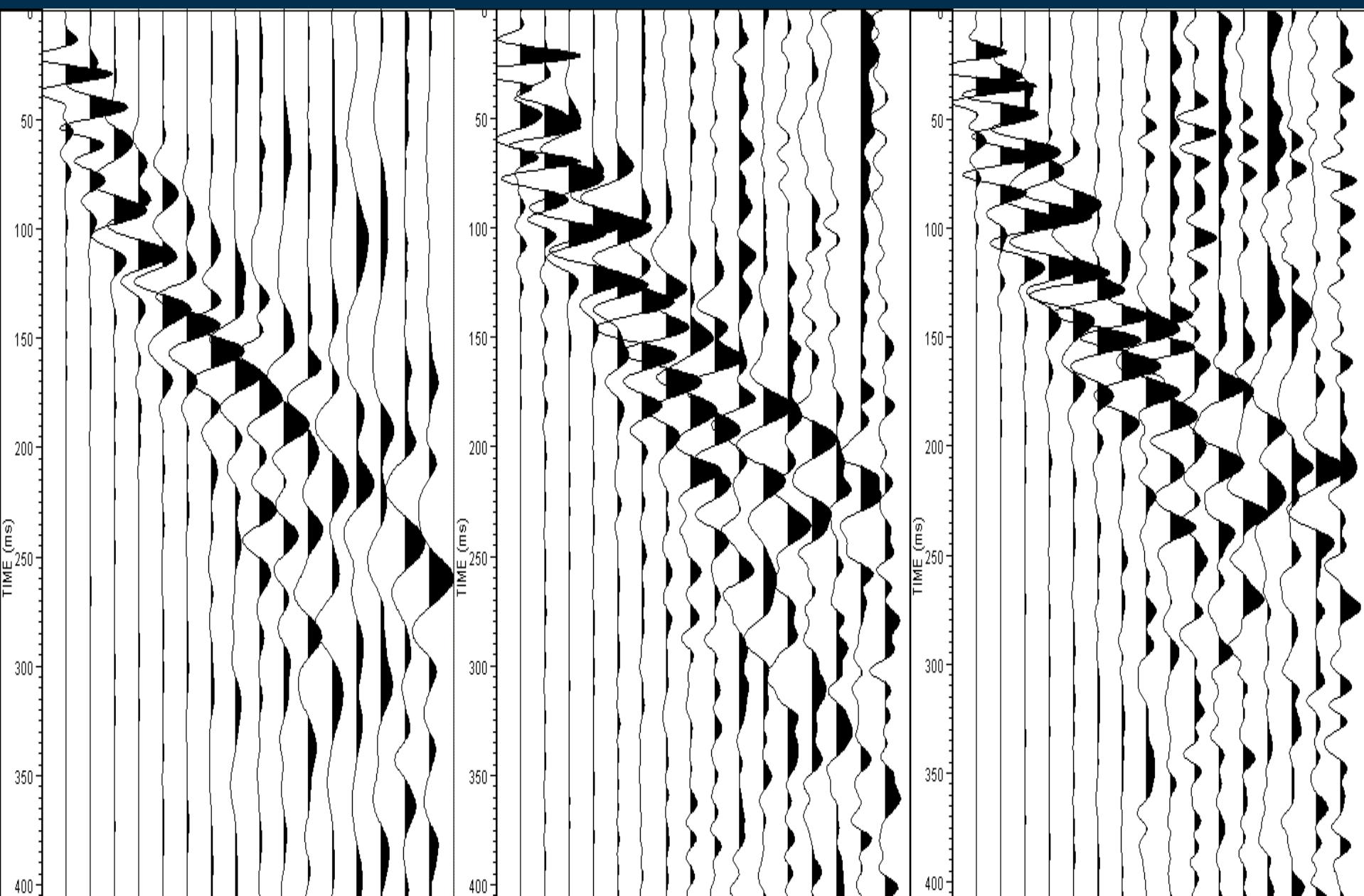
6 Components:
3 Linear, 3 Theta



PSV - 3C-Vert., 3C-Radial, 3θ-Trans.



SH - 3C-Trans., 3θ-Vert., 3θ-Radial

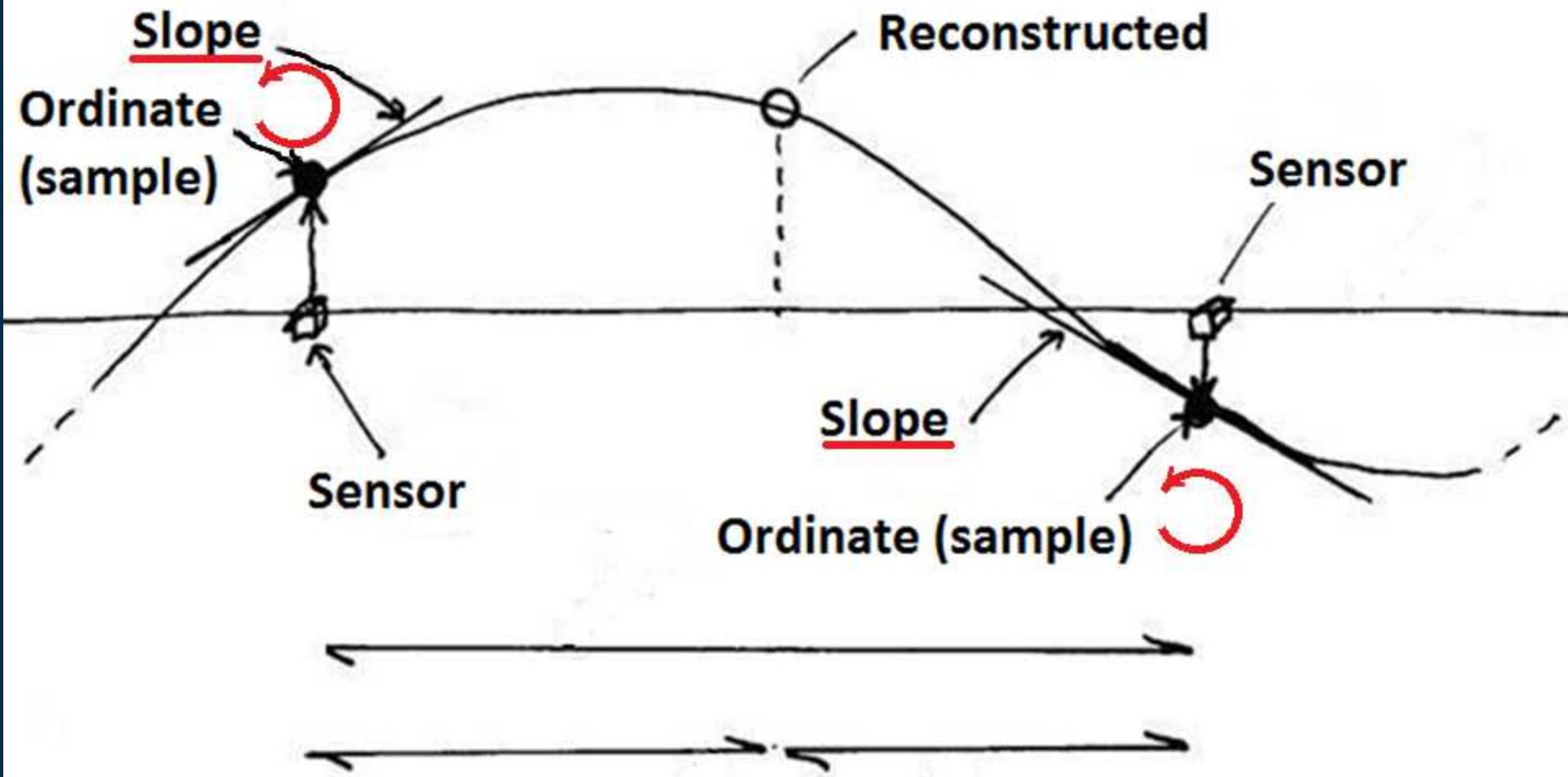


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Ordinate and Slope Sampling

DOUBLE the Effective Spatial Nyquist



For Z linear component:

Rotational yields the Spatial Slopes

At **Free Surface**, or **Water**

Bottom, have zero

traction/stress component,
and thus zero strain
component:

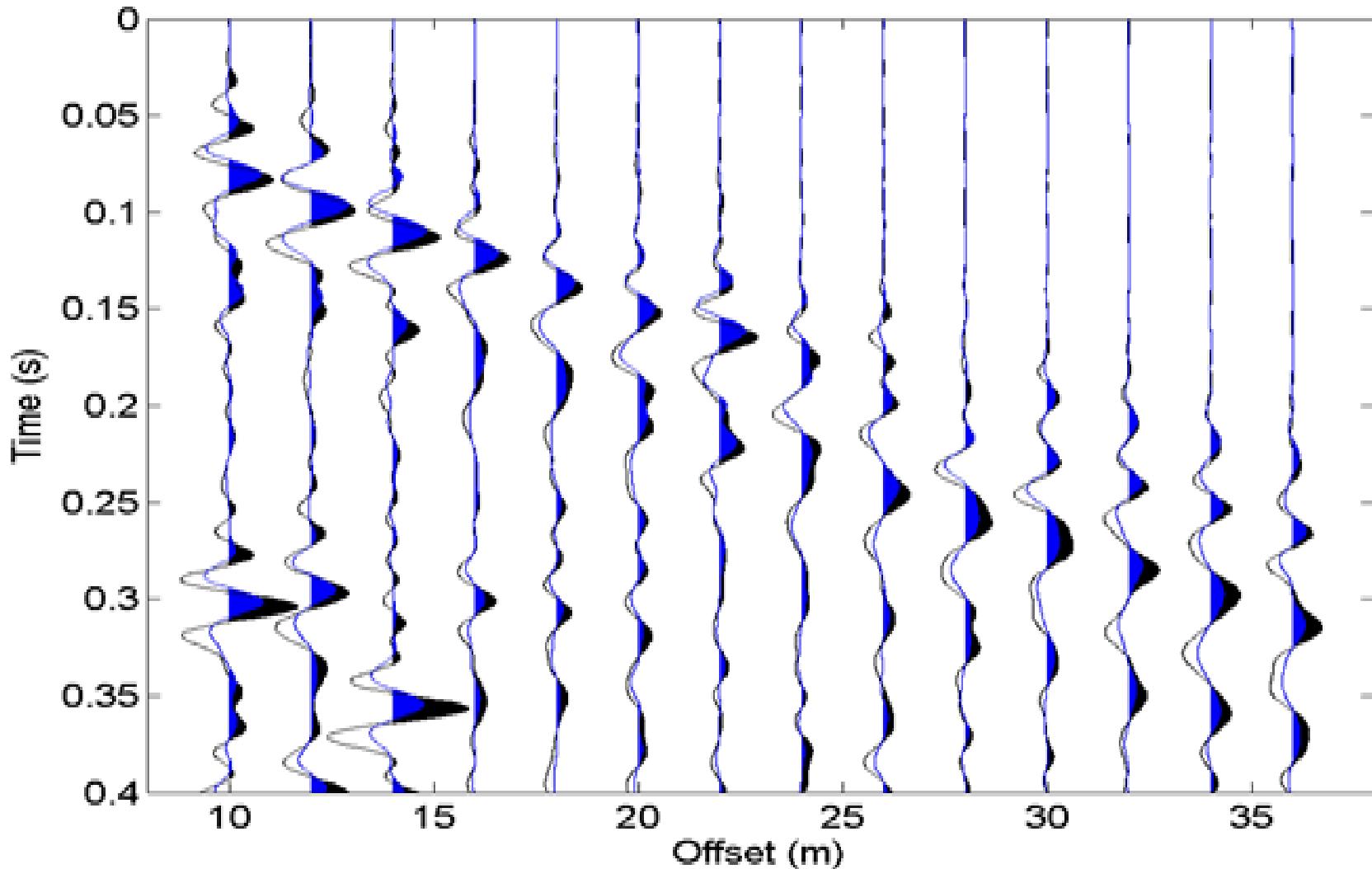
$$e_{yz} = \frac{1}{2} \left(\frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \right) = 0$$

Thus we have the **y spatial gradient**
of the vertical linear component of
displacement, w, given by the **x**
component of rotational Theta Data:

$$\theta_x = \frac{\partial w}{\partial y}$$

Rotational Spatial Sampling – Horizontal Gradients of Linear Z

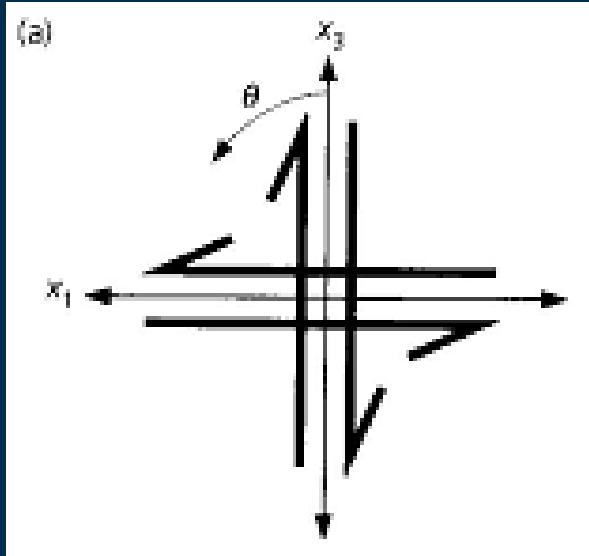
Everhard Muyzert, Schlumberger, EAGE, 2012



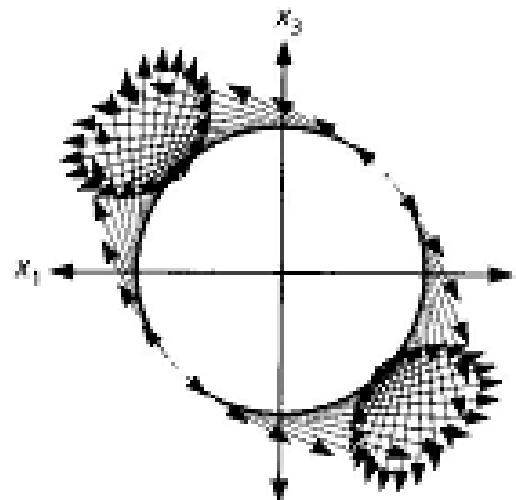
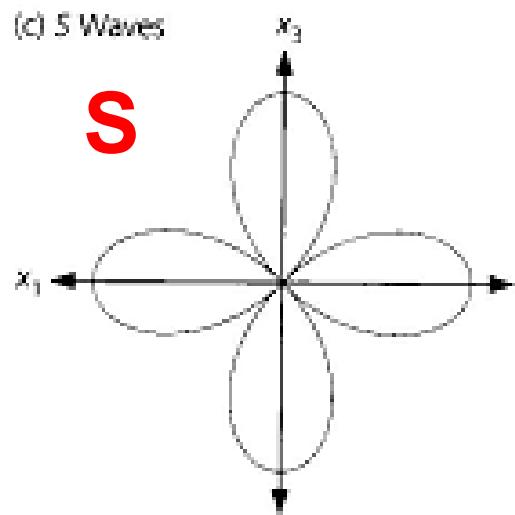
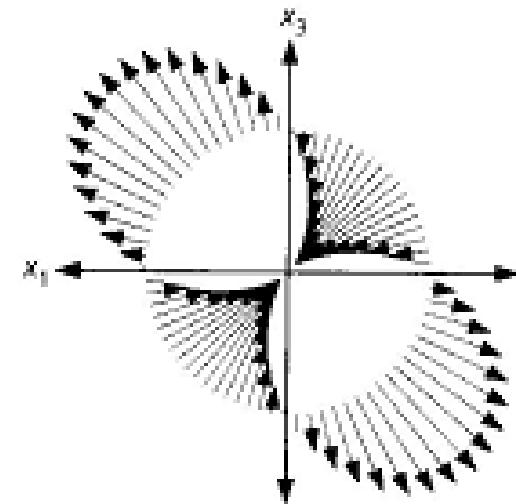
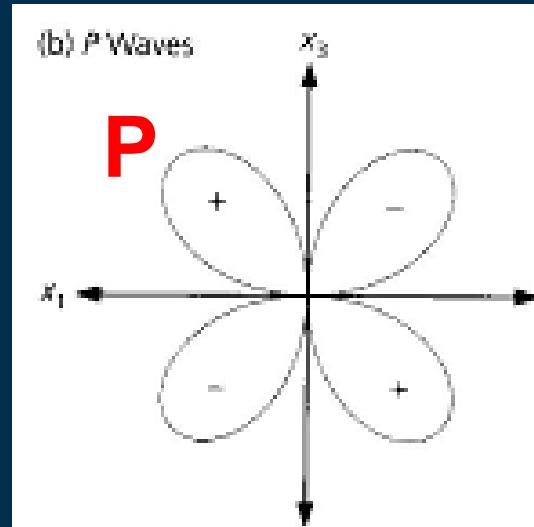
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Frac'ing / Micro-Seismic – Double Couple



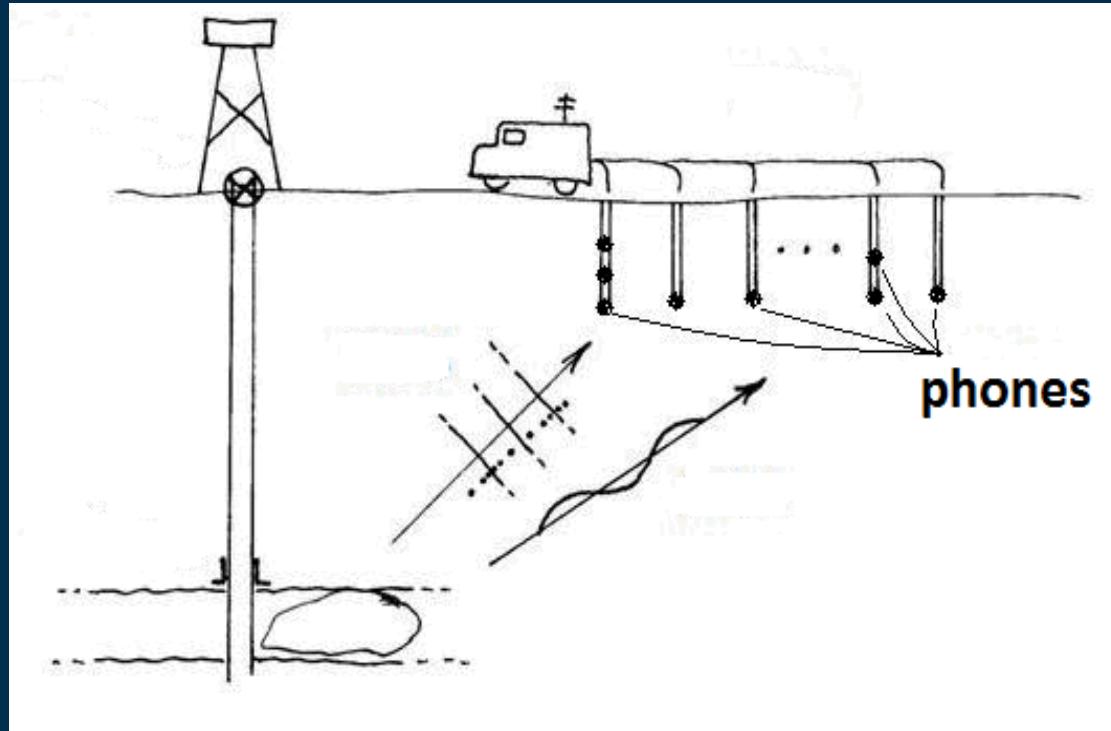
P and S body waves
Motion Amplitude
And
Motion Direction
S is STRONGER



Micro-Seismic / Double Couple – Shear Detection

**Rotational phones
below the free
surface, away from
strong interfaces,
and the associated P
& S conversions.**

**Shear Selectivity of
Theta Data possibly
may enhance
extraction of shear
body wave data**



Induced Seismicity: Frac Rotational Monitoring ?

From earthquake seismology:

“Observations . . . showed that the amplitudes of rotations can be one to two orders of magnitude greater than expected from the classical elasticity theory”

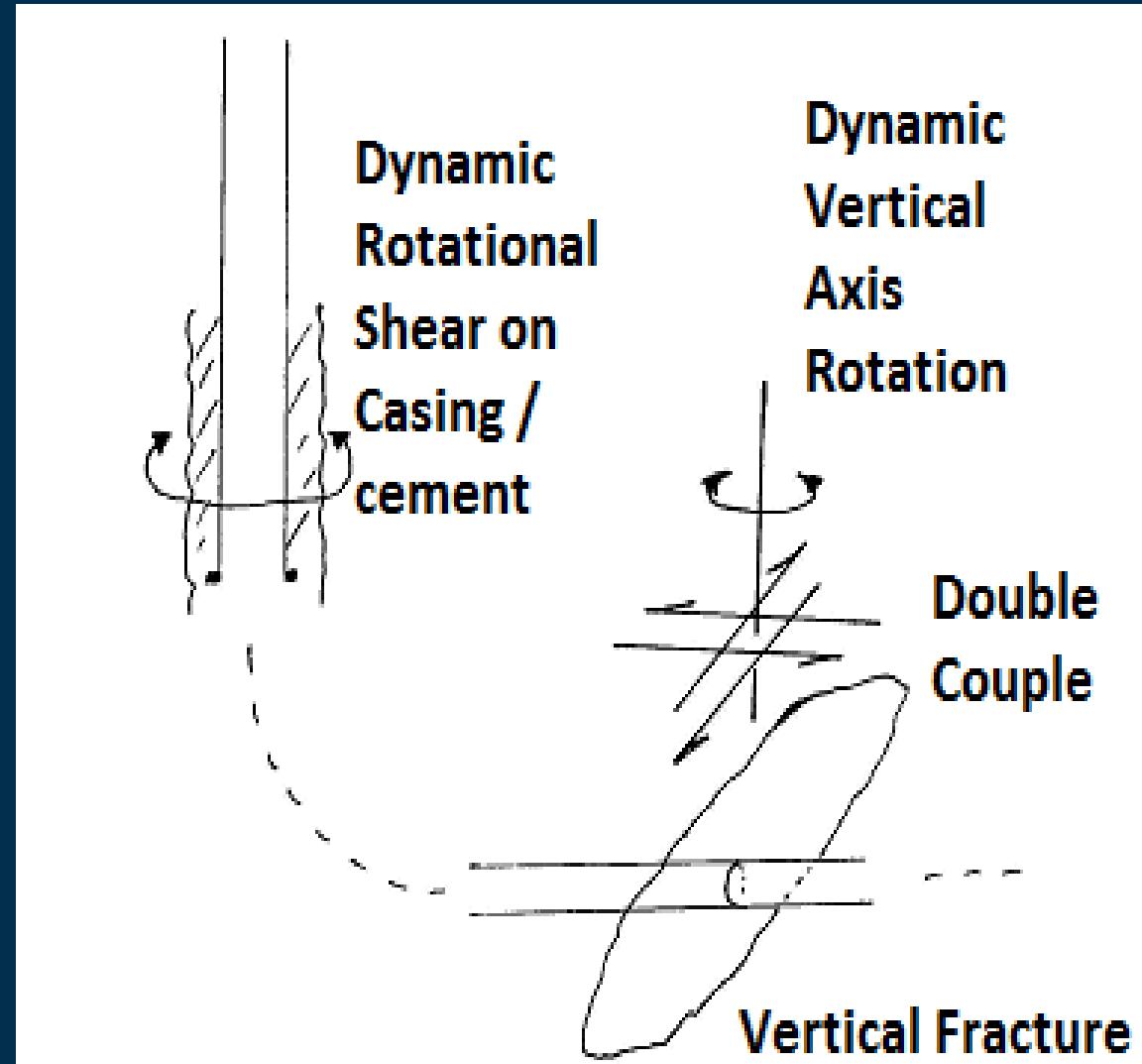
Lee, Igel, & Trifunac, 2009, “Recent Advances in Rotational Seismology”, *Seis. Res. Ltrs.*, vol. 80,no. 3, May/June

Frac Rotational Monitoring ?

Vertical axis
dynamic rotation.

Release pre-
existing tectonic
stress.

Shear bond
strength of
cement-casing is
comparatively
weak.



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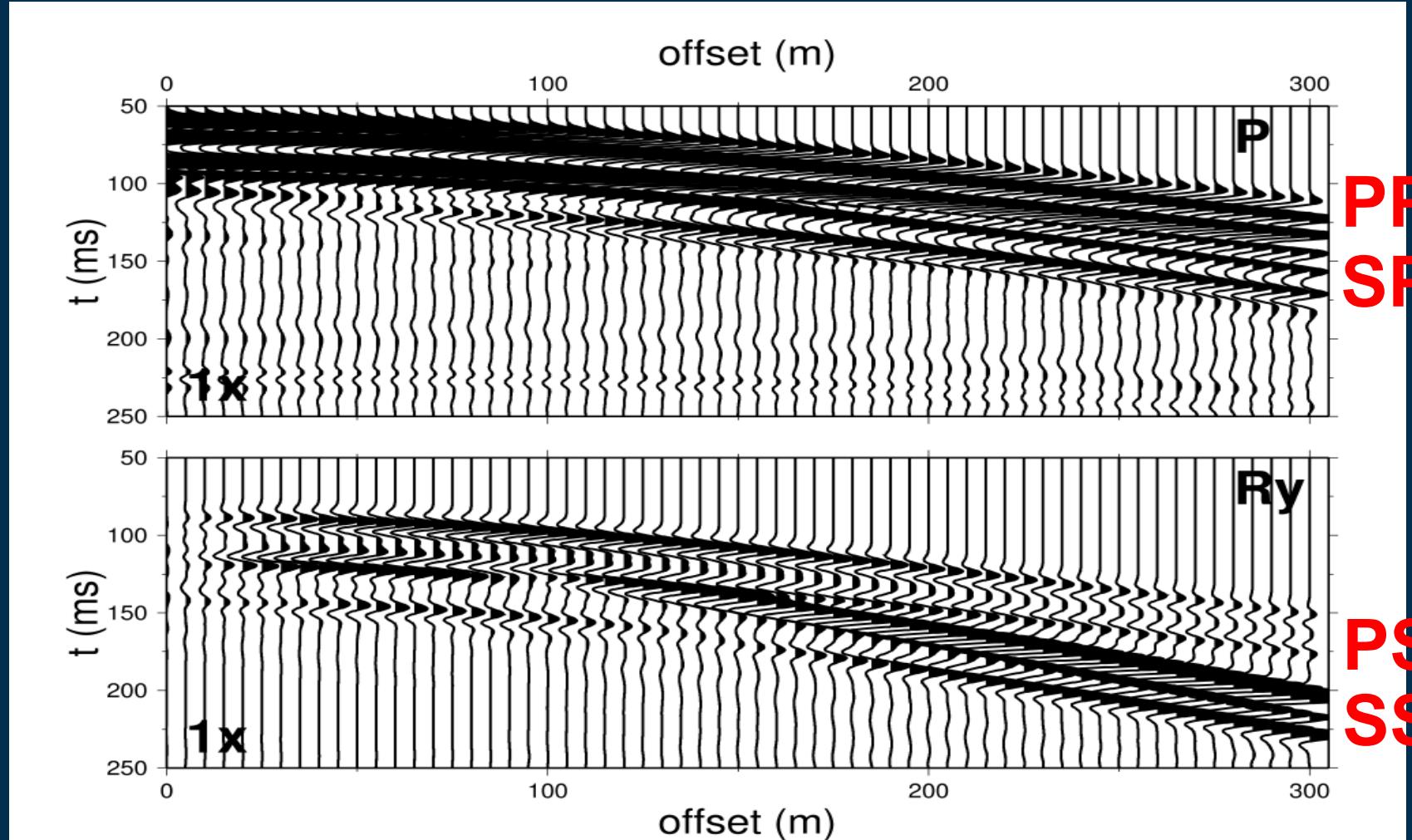
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Pressure (P wave only) + TR-Theta (S wave only)

AVO for gas sandstone

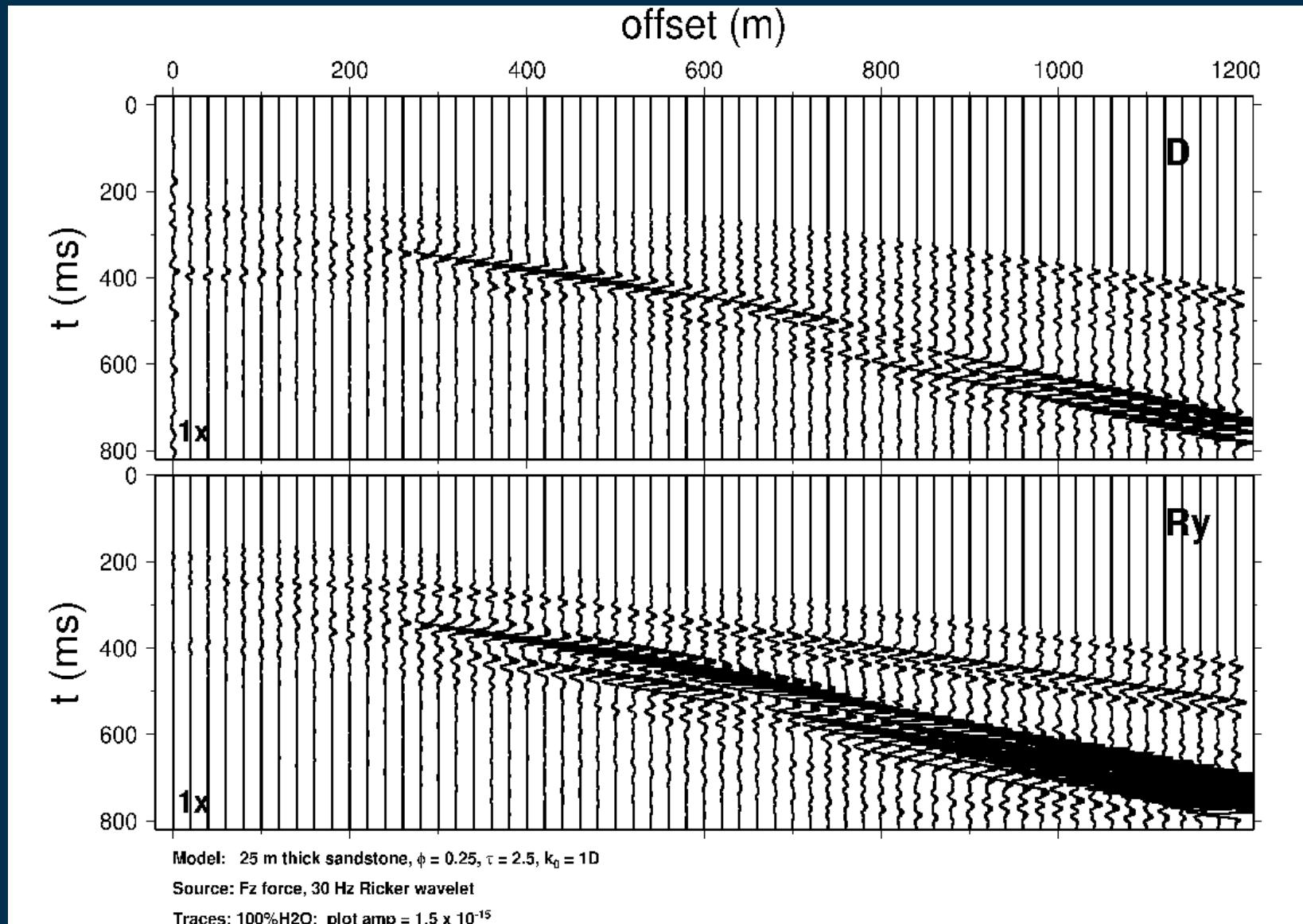
No Free Surface, buried phones

David Aldridge, et al., Sandia National Laboratories, 2007-2009



Pressure (P wave only) + TR-Theta (S wave only) Free Surface, AVO for brine saturated sandstone

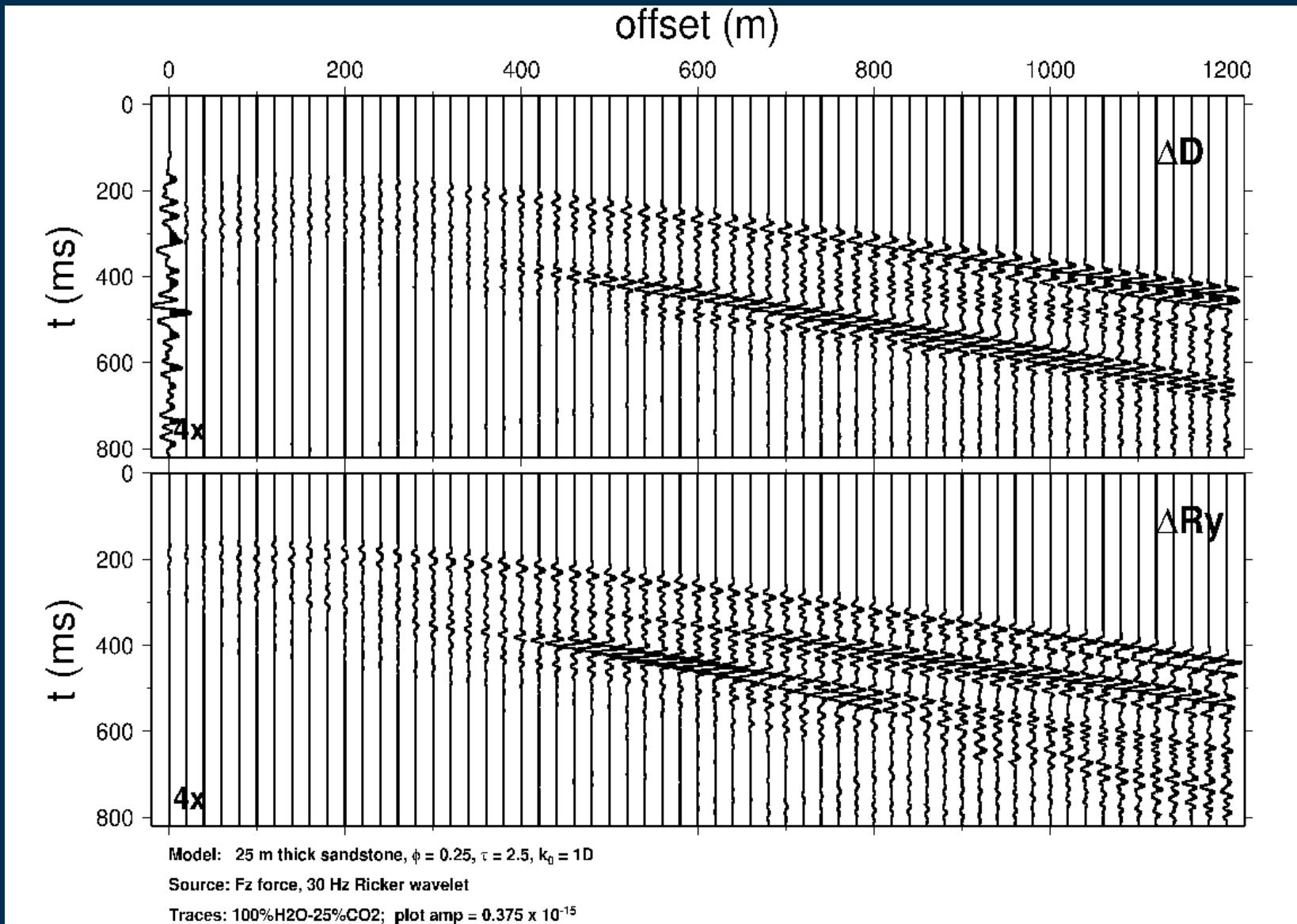
David Aldridge, et. al., Sandia National Lab, 2007-2009



Pressure (P wave only) + TR-Theta (S wave only)

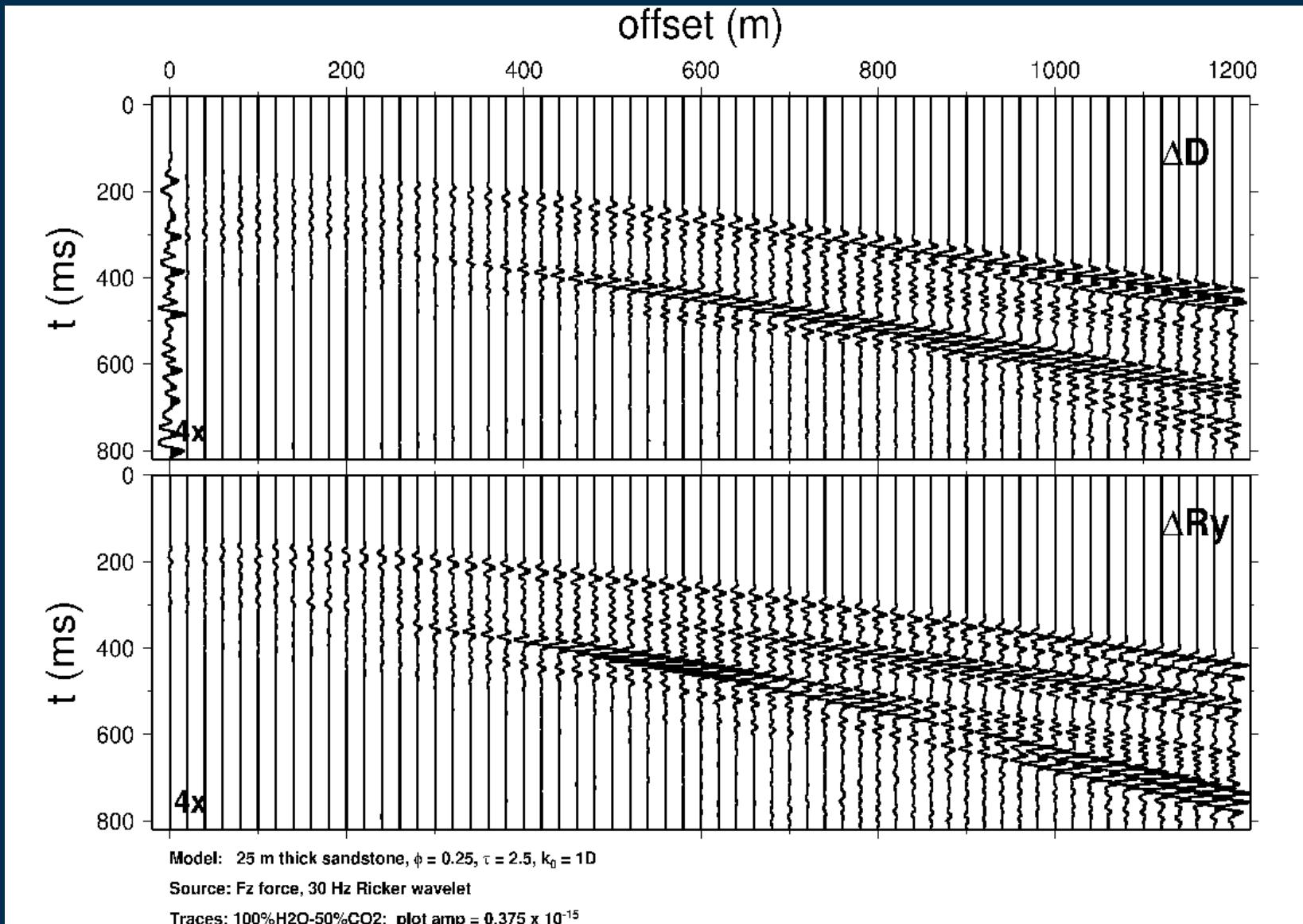
Delta AVO for 25% CO₂ saturated sandstone

David Aldridge, et. al., Sandia National Lab, 2007-2009



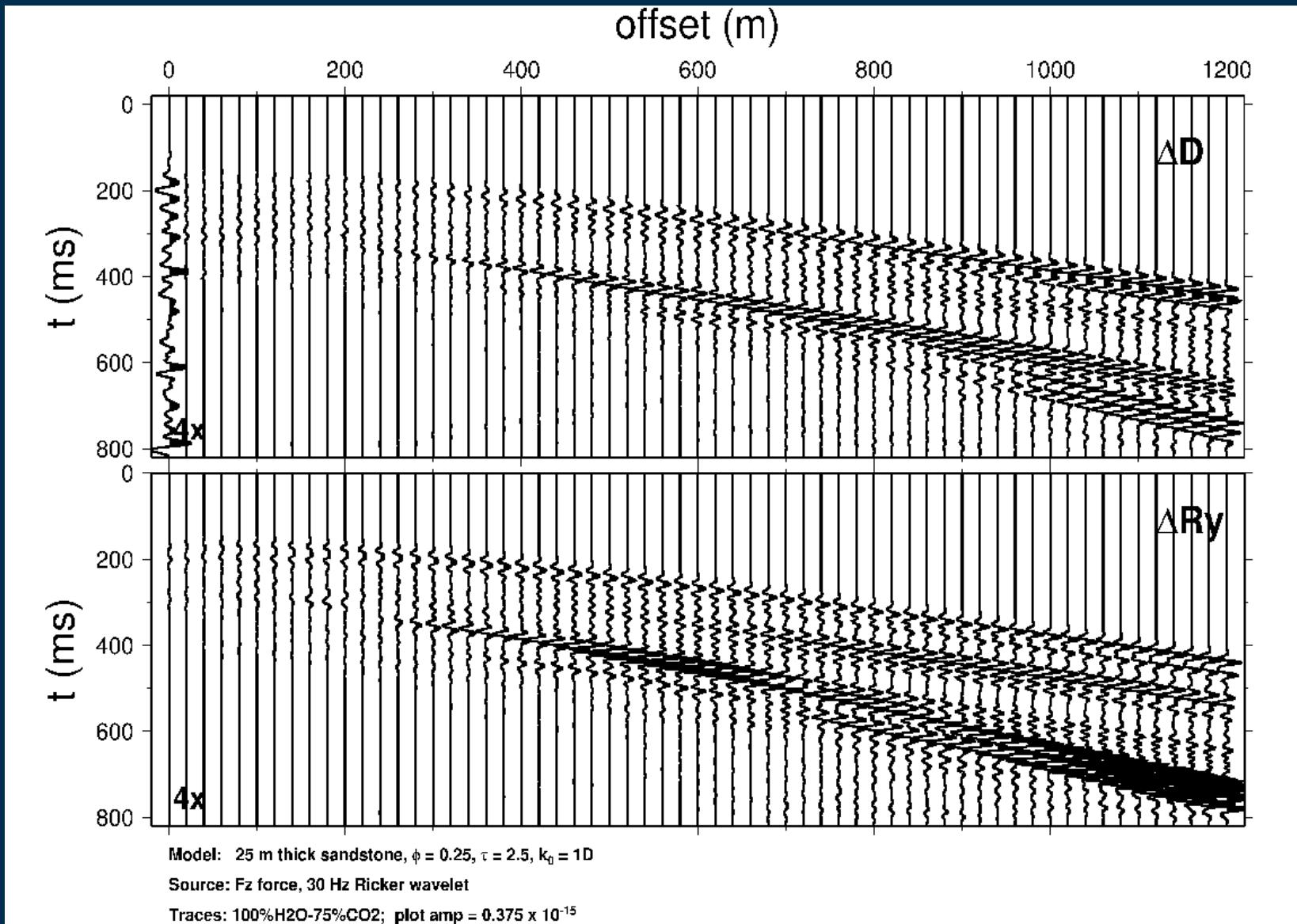
Pressure (P wave only) + TR-Theta (S wave only) Delta AVO for 50% CO₂ saturated sandstone

David Aldridge, et. al., Sandia National Lab, 2007-2009



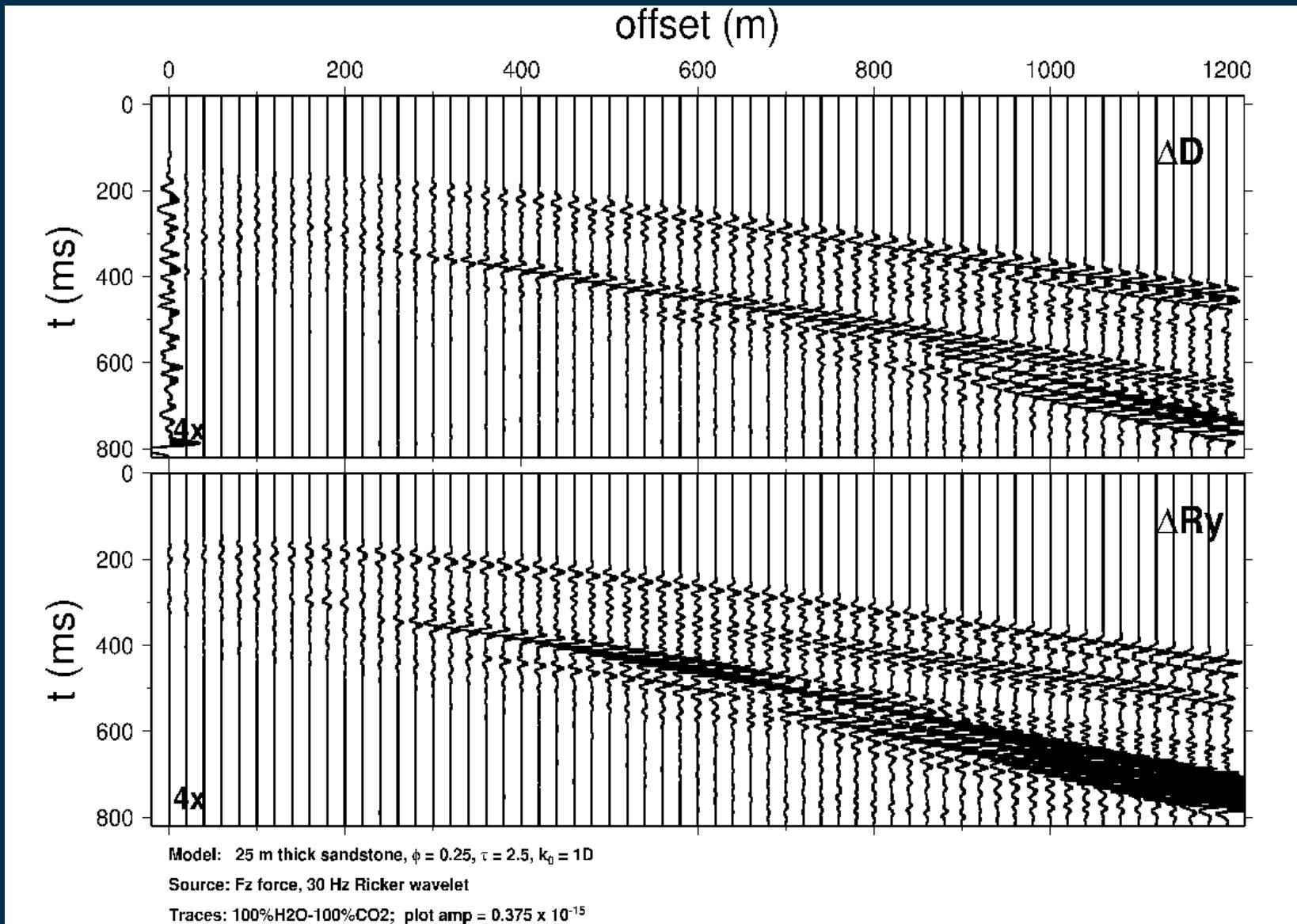
Pressure (P wave only) + TR-Theta (S wave only) Delta AVO for 75% CO₂ saturated sandstone

David Aldridge, et. al., Sandia National Lab, 2007-2009



Pressure (P wave only) + TR-Theta (S wave only) Delta AVO for 100% CO₂ saturated sandstone

David Aldridge, et. al., Sandia National Lab, 2007-2009



Igel / Aldridge Point Array

At a **single** 3-C / 3- Θ sensor:

$$\text{S VELOCITY} = \frac{\text{transverse linear acceleration}}{\text{orthogonal transverse rotational velocity}}$$

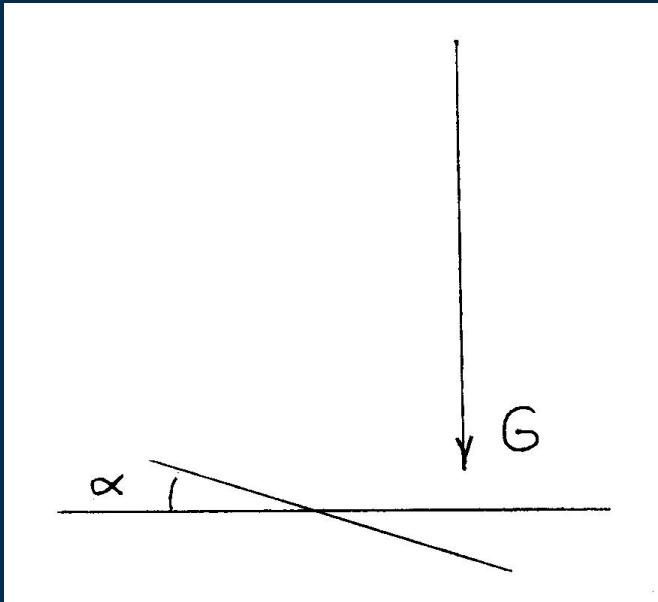
Potential use for shear statics:
get shear velocity around each 6-C phone.

From 3-C *and* 3- Θ data can determine direction **AND**
velocity of shear wave propagation.

Shear Waves / C-Waves

- Great effort in the 1980's pursuing shear sources, *but always* with 3-C linear phones that didn't differentiate P from S.
- Now we can use **Rotational Phones** to get pure shear **3- Θ** data as a 3-component vector.
- Related concept: use **Pressure Gradients** to get pure compressional **3- ∇P** data as a 3-component vector.
- **Processing** issues:
3 components with mode purity (gain, decon).
Direction and propagation velocity.

Tilt Correction of Linear using Rotation



If a **Horizontal Linear** Phone tilts by angle α , then it picks up error:

$$\text{Gravity} * \sin(\alpha)$$

Micro- or milli-radians of tilt give a potentially significant error compared to weak seismic reflections (C-waves).

Consider a worse case:
weak C-wave data on horizontal phone at
same time as strong ground roll in
uncorrelated vibroseis data

Possibly(?) Map Frac Density

Some precedent: Lg Scattering measurements in earthquake seismology & use of vertical rotation

Perhaps we can use rotation measurements to map scattering / fracture density:

- Use time, offset windows to target shales in Resource Plays. Compare Polarization modes.
- Azimuthal Anisotropy of 6-C (3-C and 3-Θ):
 - Amplitude Anisotropy
 - Velocity Anisotropy
 - Shear splitting

Ground Roll – Rayleigh Waves

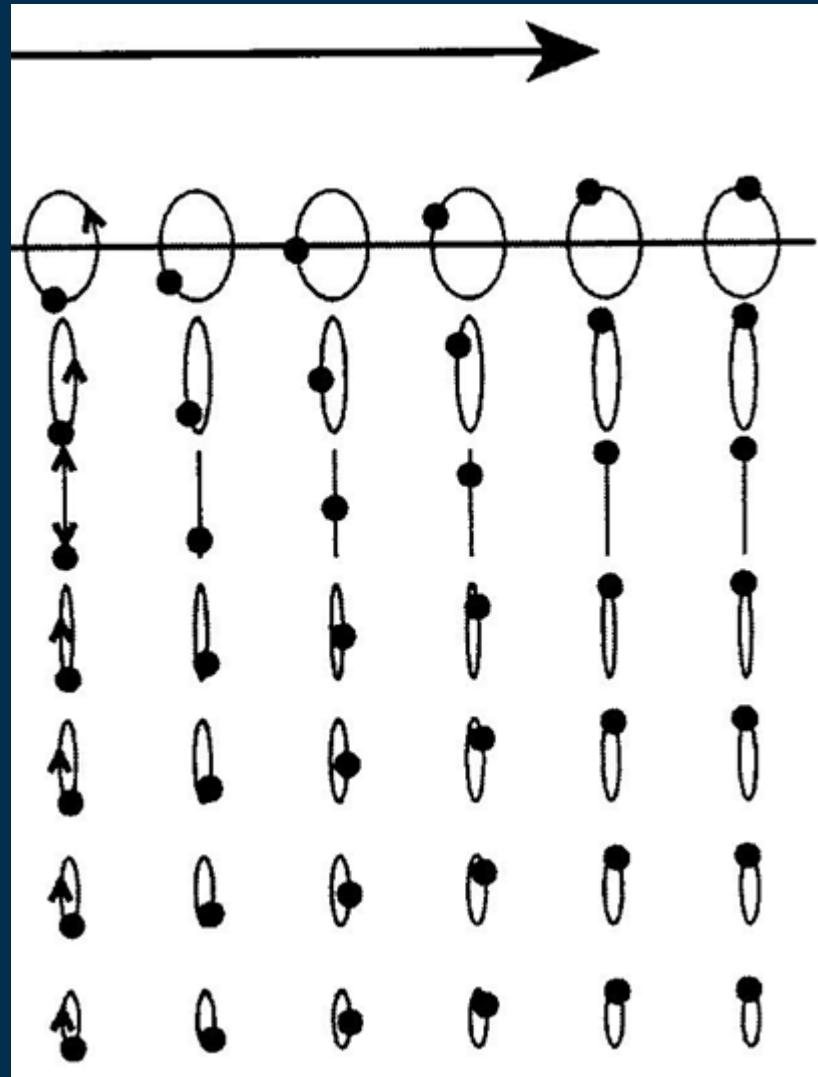
Classic Rayleigh Retrograde
Elliptical motion:

only for Poisson Solid (0.25)

For Poisson Ratio above
0.265, have **3 modes** of
polarization.

Hodograph of point is not
actually 'true' rotation.

Rayleigh wave / Rotational
Seismic: not simple.

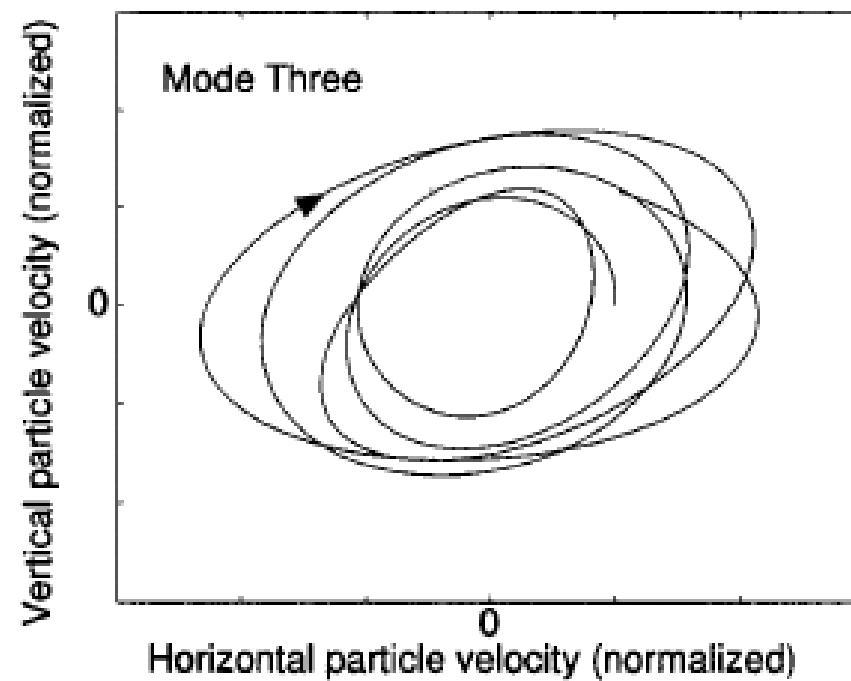
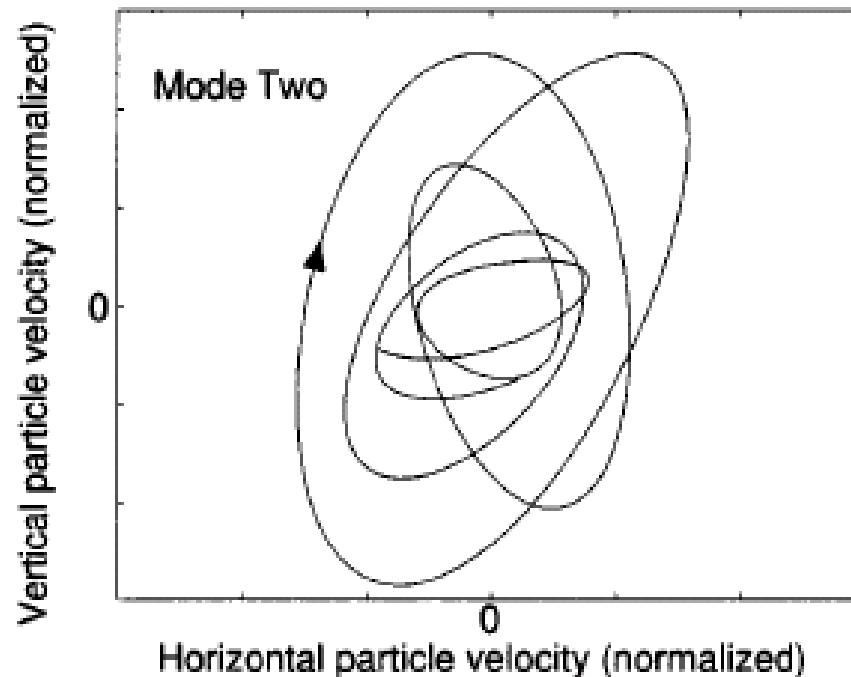
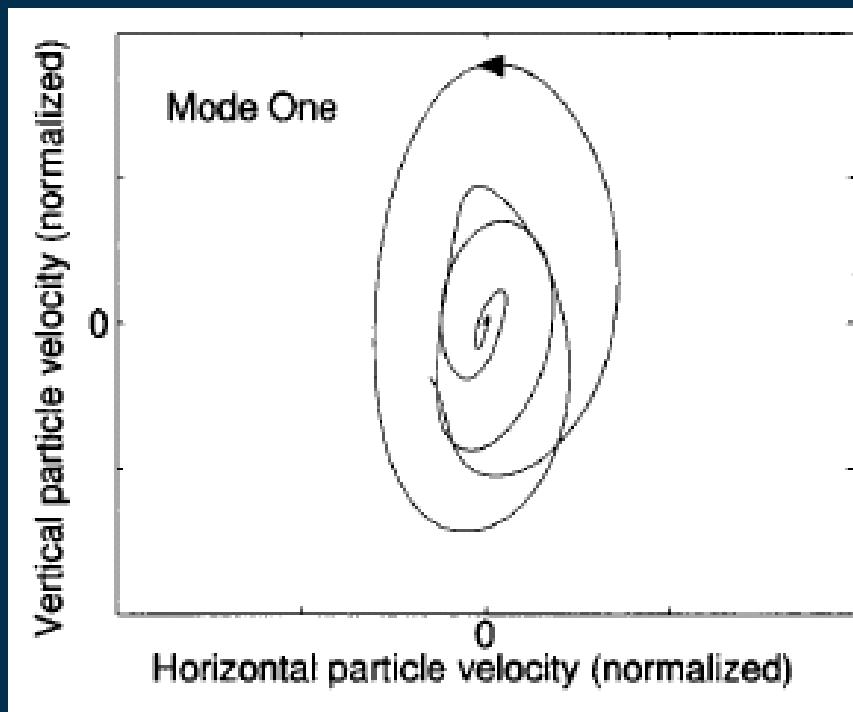


Rayleigh Modes: Hodographs

High Poisson Ratio Near Surface

Mode 1 – Retrograde Modes 2 & 3 – Prograde

Smith, et. al., JASA 1998



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Rotational Seismic – ‘Status’

- **E&P Operating Companies**
 - Activity in only very few (~1) Companies.
 - No testing to date
- **Geophysical (Equipment/Contractor) Cos.**
2 [3] contractors have done small scale tests
- **3 +/- Rotational Phone manufacturers**
- **Patent Status (8 companies)**
 - Defensive
 - Perception that Rotational Seismic has potential to be a significant technology, *but . . .*

Rotational Seismic – ‘Failures’

- **Failure in Market Research**
 - Confuse technical enthusiasm vs. willingness for expenditures / investment
- **Not Backward Compatible**
- **No incremental path / no retrofit**
- **Not Market Driven – no user requests**
- **Not Proven –**
 - **Wavefield Scale** in multiple locations
 - **Meaningful Geological Scale**

Thank you for your attention !

- **Rotational sensor prototypes**
- **Limited data** - no geological scale data
- **Many Applications** possible:
 - Spatial Sampling
 - Shear Selectivity – micro-seismic & C- wave
 - “Other” – AVO, Point Array, Tilt correction, Frac density, Rayleigh wave(?), etc.
- **Technically attractive for multiple purposes**
- **BUT, commercially ‘challenged’**

ROAD AHEAD ?

Acknowledgements

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