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in FLAG (U)

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Strength and Damage Modeling
in FLAG (U)
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Abstract

Recent improvements to the FLAG code have included a modification of the Preston-Tonks-Wallace (PTW) strength model and a re-factoring the Tensile Elastic-Plastic (TEPla) damage model. The PTW strength model has been modified to enhance modeling through transitions from low strain-rate (thermal activation) regime to the high strain rate (over-driven shock) regime. The presentation discusses the implementation of the modified strength model and some of the computational issues.

Strength and Damage Modeling in FLAG (U)

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June 12, 2012

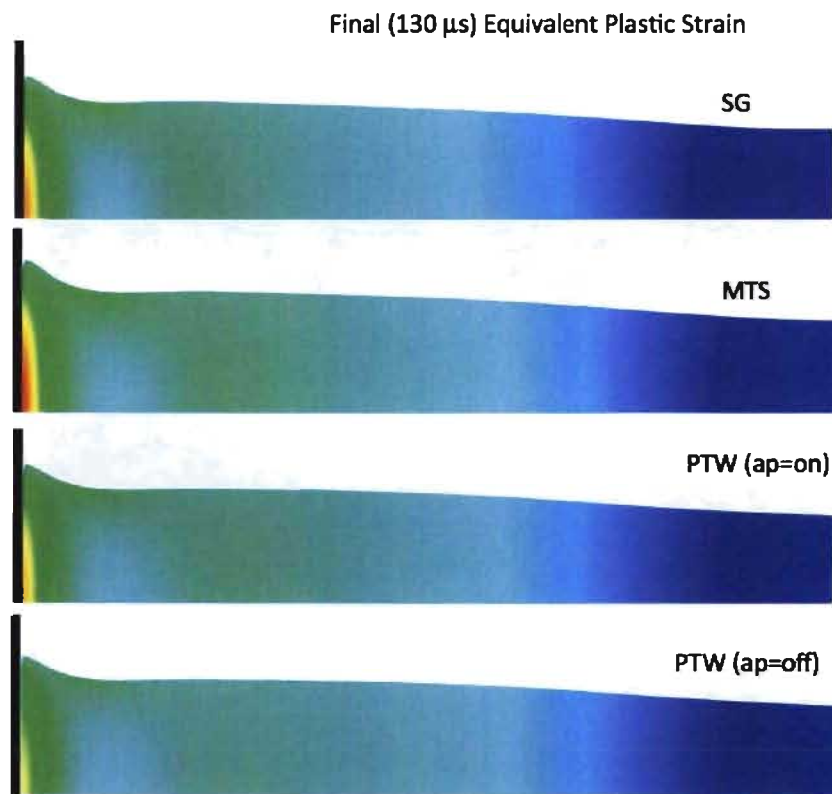
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and James H Cooley (XTD-3)

Strength and Damage Modeling Outline

- Motivation
- PTW Strength Model Modifications
- Density Dependent Melt Temperature and Shear Modulus
- Damage and Failure Models – TEPla
- Discussion and Conclusions
- Future Directions

Strength and Damage Modeling Motivation



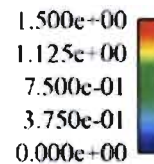
Annealed Cu Taylor Cylinder: Simulation



Cu $\frac{3}{4}$ Hardened Taylor Cylinder



Extended Ta-hemi in an extremely damaged state



Strength and Damage Modeling

Update PTW Model

- New Feature: Smooth interpolation of the saturation flow stress between the low strain-rate (thermal activation) and the high strain-rate regimes
- Fixed a few things
 - Rearranged the order of operations in the calculation of the dimensionless flow stress to insure proper initialization at all strain-rates.
 - Modified the Voce Hardening Law to remove a singularity.

Original PTW Strength Model

- Dimensionless Temperature:

$$\hat{T} = \frac{T}{T_m(\rho)}$$

- Shear Modulus:

$$G(\rho, \hat{T}) = G_0(\rho)[1 - \alpha \hat{T}]$$

- Dimensionless Flow Stress Variable:

$$\hat{\tau} = \frac{\tau}{G(\rho, \hat{T})}$$

- Critical Strain Rate:

$$\dot{\epsilon}_0 = \frac{\gamma}{2} \left(\frac{4\pi\rho}{3M} \right)^{\frac{1}{3}} \sqrt{\frac{G}{\rho}}$$

Original PTW Strength Model

- In the Thermal Activation Regime

- Dimensionless Yield Stress:

$$\hat{\tau}_y^T = y_0 - (y_0 - y_\infty) \operatorname{erf} \left[-\kappa \hat{T} \ln \left(\frac{\dot{\epsilon}}{\dot{\epsilon}_0} \right) \right]$$

- Model for the gap and higher strain rates:

$$\hat{\tau}_y^g = y_1 \left(\frac{\dot{\epsilon}}{\dot{\epsilon}_0} \right)^{y_2}$$

- Dimensionless Saturation Flow Stress:

$$\hat{\tau}_s^T = s_0 - (s_0 - s_\infty) \operatorname{erf} \left[-\kappa \hat{T} \ln \left(\frac{\dot{\epsilon}}{\dot{\epsilon}_0} \right) \right]$$

Original PTW Strength Model

- For strain rates above the threshold for Thermal Activation
 - Dimensionless Saturation Flow Stress:

$$\hat{\tau}_s^H = s_0 \left(\frac{\dot{\epsilon}}{\dot{\epsilon}_0} \right)^\beta$$

Original PTW Strength Model

- For all strain rates
 - Dimensionless Saturation Flow and Dimensionless Yield Stresses:

$$\hat{\tau}_s = \begin{cases} \hat{\tau}_s^T & \dot{\epsilon} < \dot{\epsilon}_0 \\ \hat{\tau}_s^H & \dot{\epsilon} > \dot{\epsilon}_0 \end{cases}$$

$$\hat{\tau}_y = \max \left[\hat{\tau}_y^T, \min \left[\hat{\tau}_y^g, \hat{\tau}_s \right] \right]$$

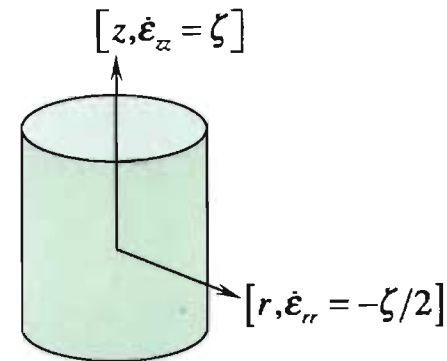
- Modified Voce Hardening Law:

$$\frac{d\hat{\tau}}{d\epsilon} = \theta \frac{\exp \left[p \frac{\hat{\tau}_s - \hat{\tau}}{s_0 - \hat{\tau}_y} \right] - 1}{\exp \left[p \frac{\hat{\tau}_s - \hat{\tau}_y}{s_0 - \hat{\tau}_y} \right] - 1}$$

*Singular when = 0

Original PTW Strength Model

- Numerical experiment to study the model under isovolumetric and constant strain rate conditions
 - Material DU
 - cylindrical pellet centered at the origin.
 - r and z velocities are specified on the surfaces of the 1 element test specimen.
- Dimensionless Flow Stress at Constant Strain Rate:



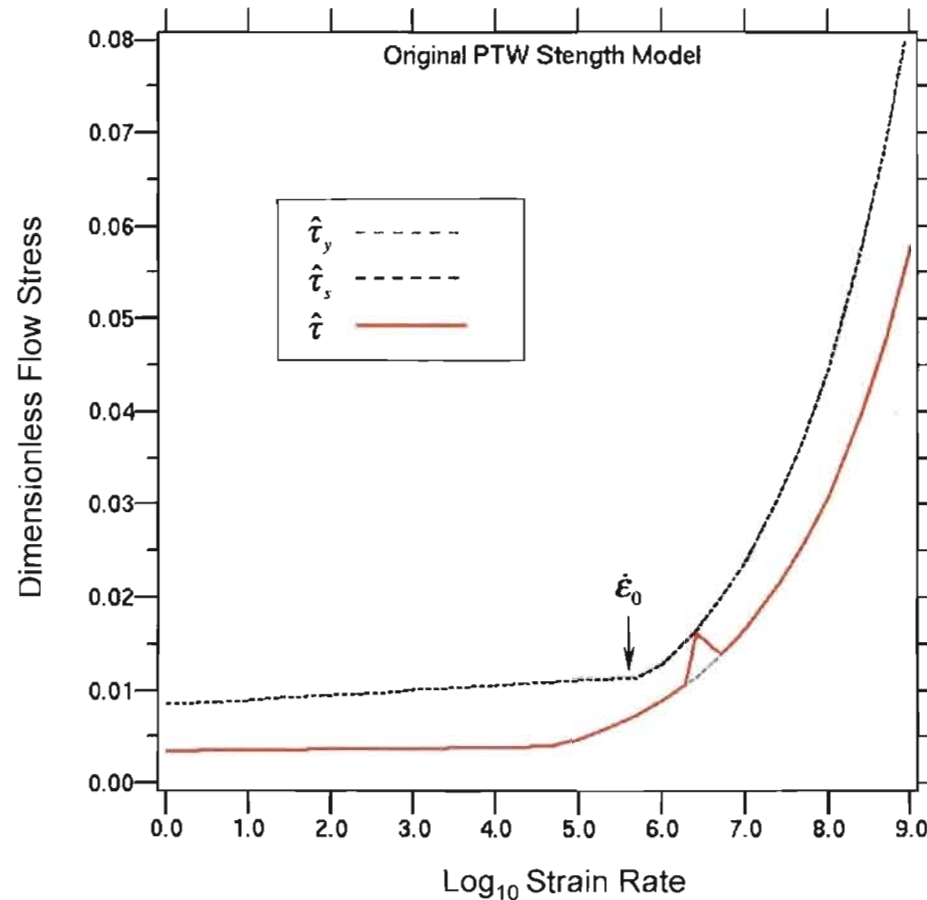
$$\hat{\tau} = \hat{\tau}_s + \frac{s_0 - \hat{\tau}_y}{p} \ln \left[1 - \left(1 - \exp \left\{ -p \frac{\hat{\tau}_s - \hat{\tau}_y}{s_0 - \hat{\tau}_y} \right\} \right) \exp \left\{ - \frac{p \theta \epsilon}{(s_0 - \hat{\tau}_y) \exp \left\{ p \frac{\hat{\tau}_s - \hat{\tau}_y}{s_0 - \hat{\tau}_y} \right\} - 1} \right\} \right]$$

DU PTW Parameters

<i>PTW Parameter</i>	<i>Nominal Value</i>
r	$0 \leq r \leq 4$
θ	0.088
p	3
s_0	0.0115
s_∞	0.0020
κ	0.1
γ	10^{-7}
y_0	0.004
y_∞	0.002
y_1	0.008
y_2	0.27
β	0.27
T_m	1405° K
G_0	1.078 Mbar
a_m	3.954×10^{-22} g/atom

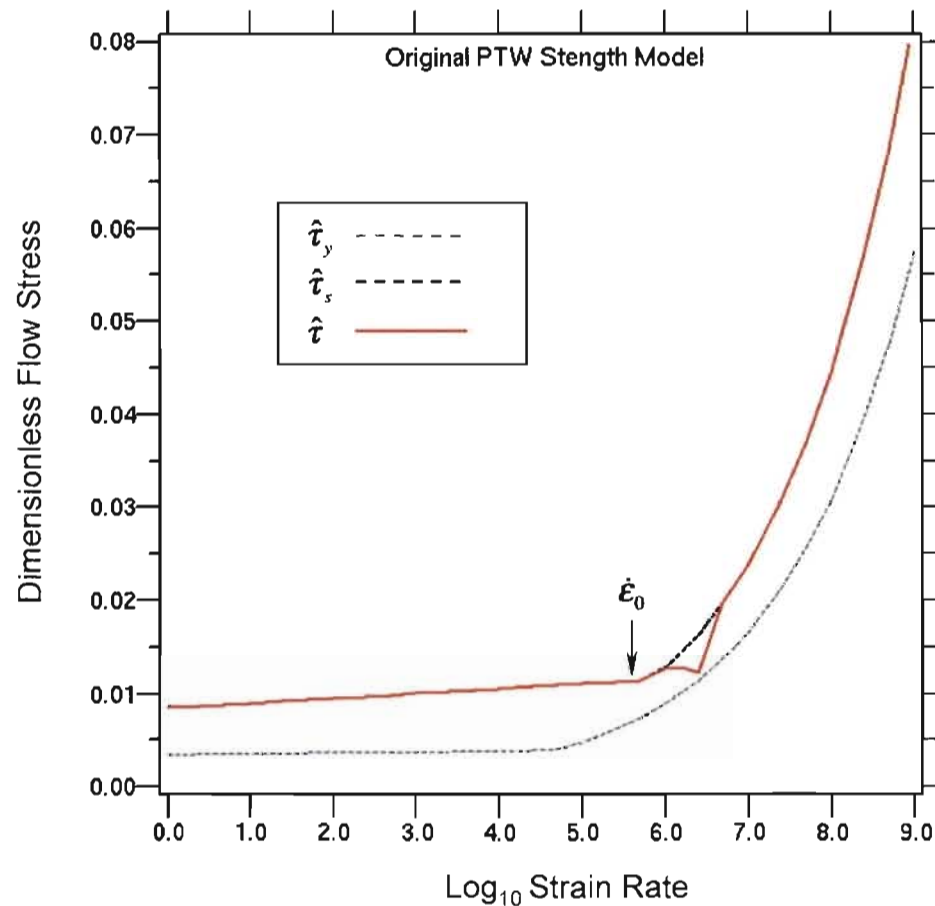
Original PTW Strength Model

Initial Condition ($\epsilon^p=0$)



Original PTW Strength Model

Initial Condition ($\epsilon^p=2$)



Modified PTW Strength Model

Change in the Hardening Rule:

- Subtle change in the VOCE Hardening Rule:

$$\frac{d\hat{\tau}}{d\varepsilon} = \theta \frac{\exp\left[p \frac{\hat{\tau}_s - \hat{\tau}}{\hat{\tau}_{s0} - \hat{\tau}_y}\right] - 1}{\exp\left[p \frac{\hat{\tau}_s - \hat{\tau}_y}{\hat{\tau}_{s0} - \hat{\tau}_y}\right] - 1}$$

where

$$\hat{\tau}_{s0} = \begin{cases} s_0 & \dot{\varepsilon} \leq \dot{\varepsilon}_0 \\ \hat{\tau}_s & \dot{\varepsilon} > \dot{\varepsilon}_0 \end{cases}$$

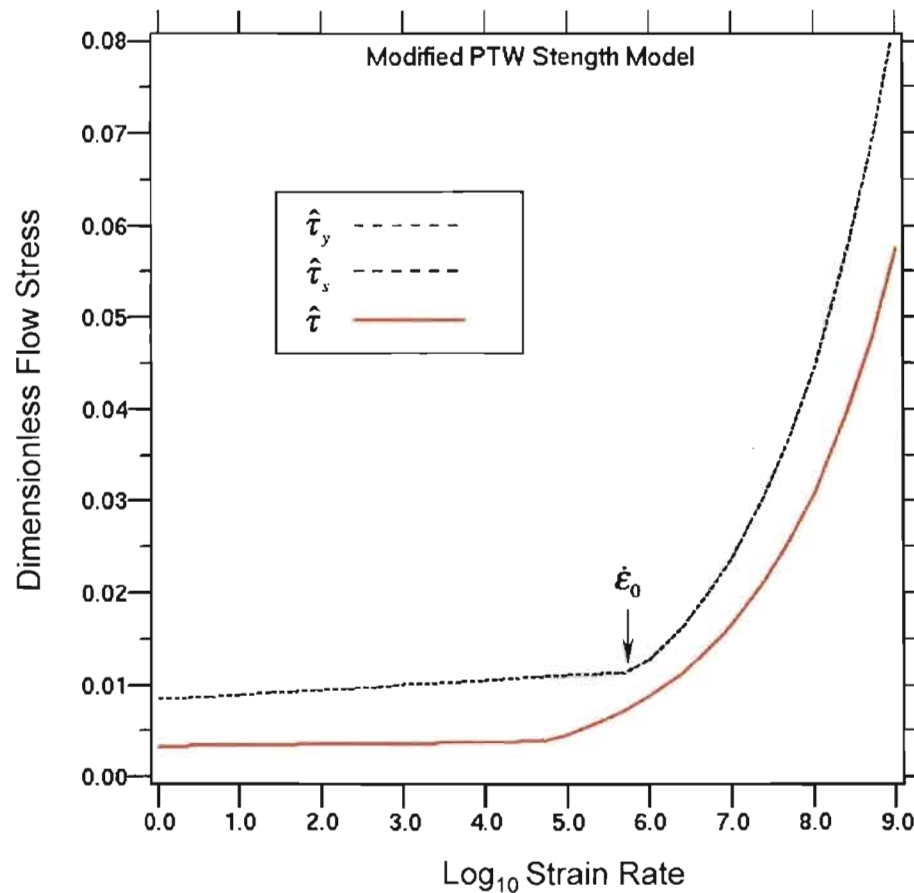
interpolating with respect to r :

$$\hat{\tau}_{s0} = s_0 10^{\frac{1}{4}\beta r (1+\frac{x}{r})^2}$$

$$x = \log_{10} \frac{\dot{\varepsilon}}{\dot{\varepsilon}_0}$$

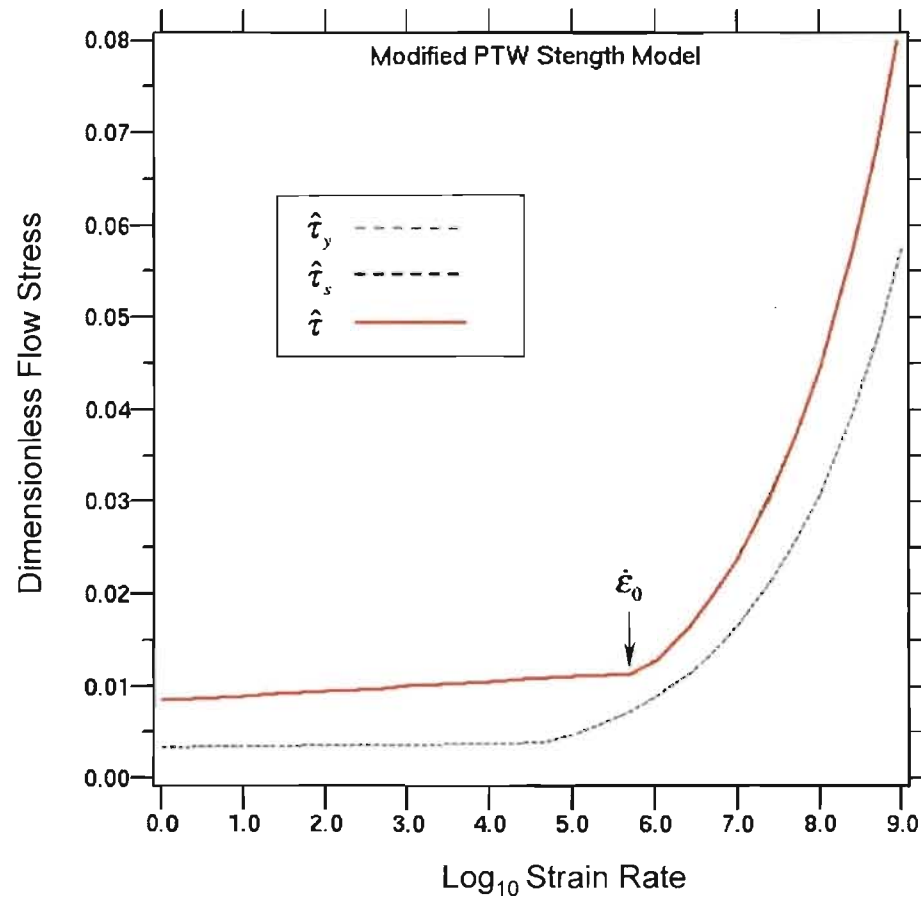
Modified PTW Strength Model

Change in the Hardening Rule - Initial Condition ($\varepsilon^p=0$)



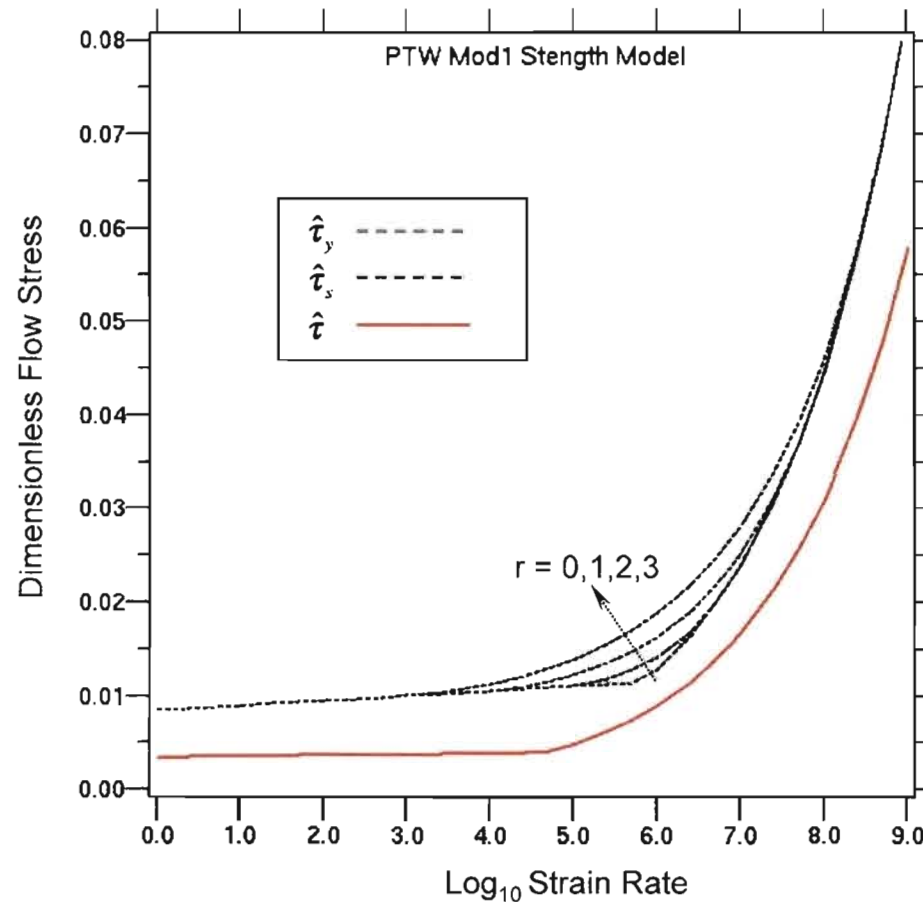
Modified PTW Strength Model

Change in the Hardening Rule - Initial Condition ($\varepsilon^p=2$)



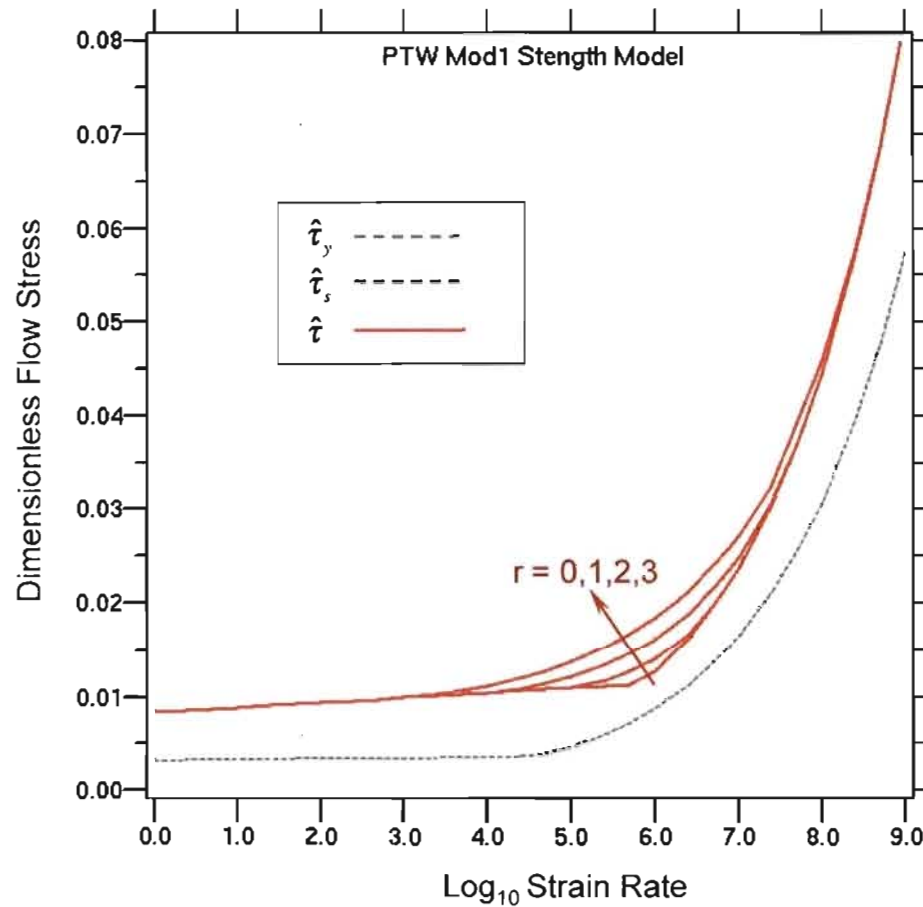
PTW Mod1 Strength Model

Change in the Hardening Rule - Initial Condition ($\epsilon^p=0$)



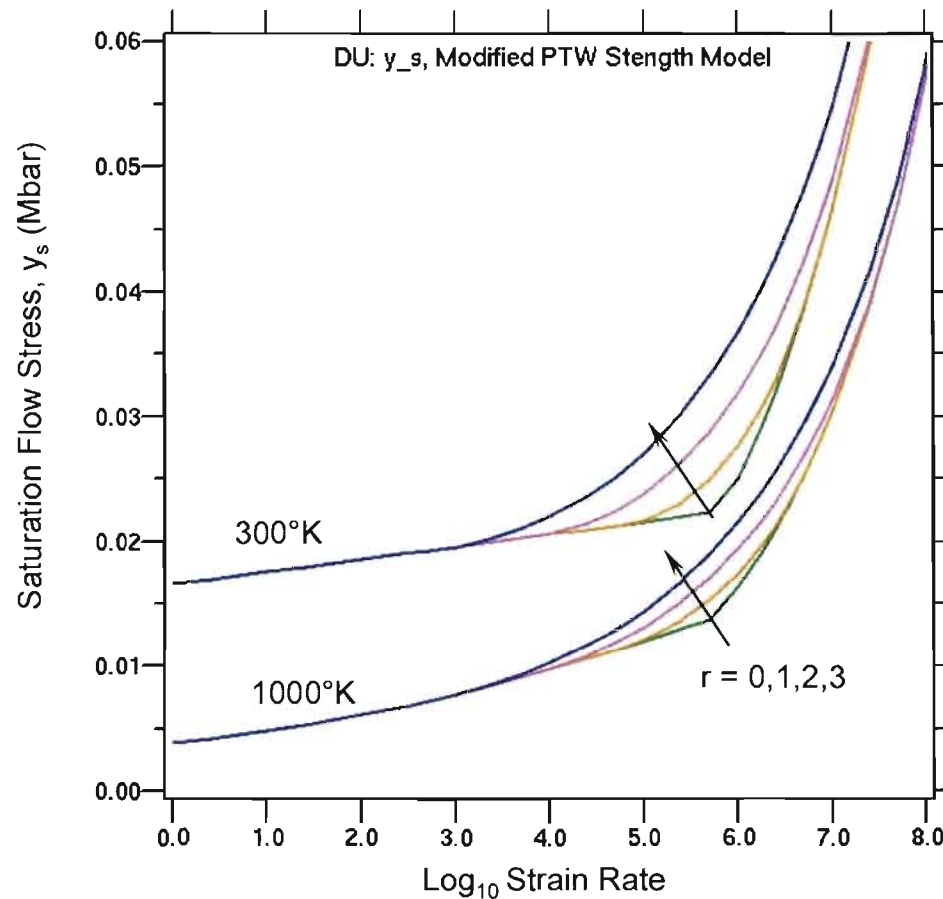
PTW Mod1 Strength Model

Change in the Hardening Rule - Initial Condition ($\epsilon^p=2$)

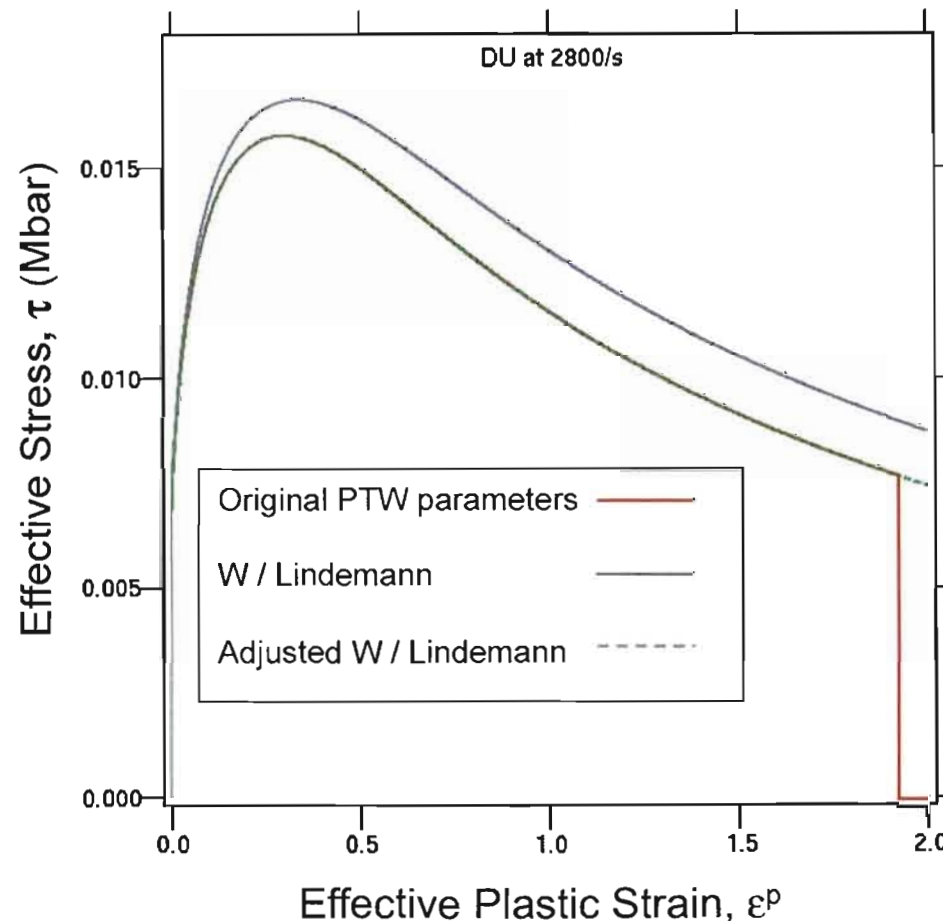


PTW Mod1 Strength Model

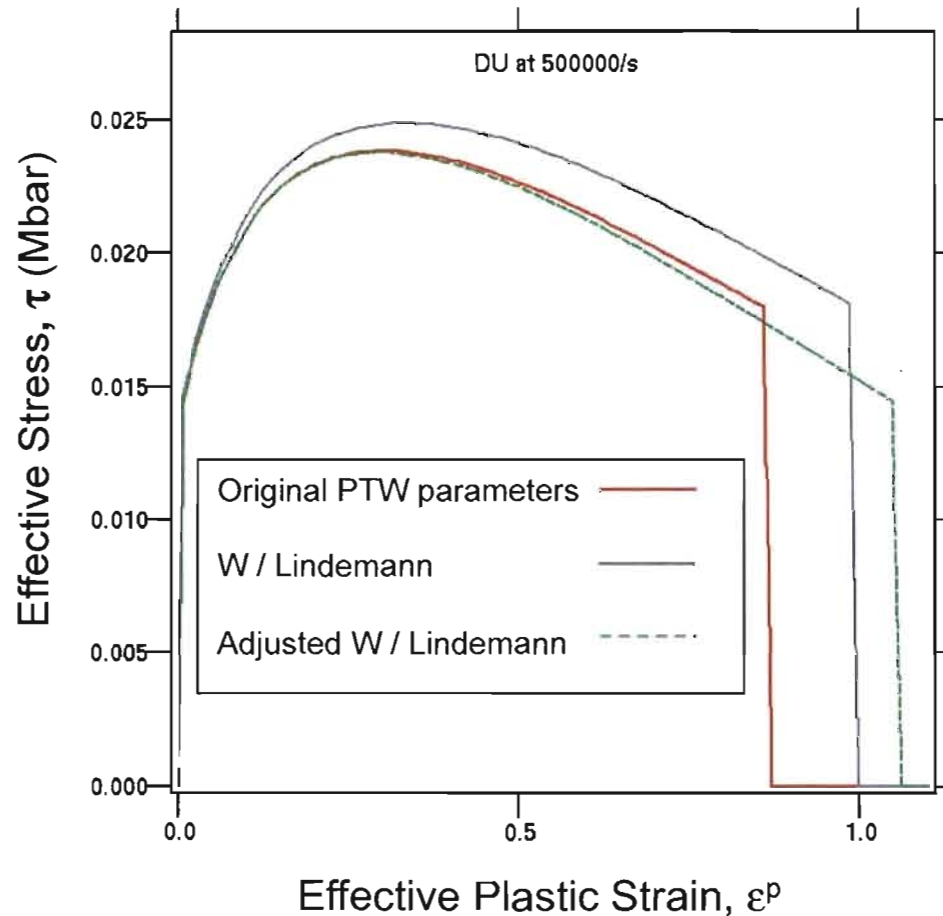
Change in the Hardening Rule - Initial Condition ($\epsilon^p=2$)



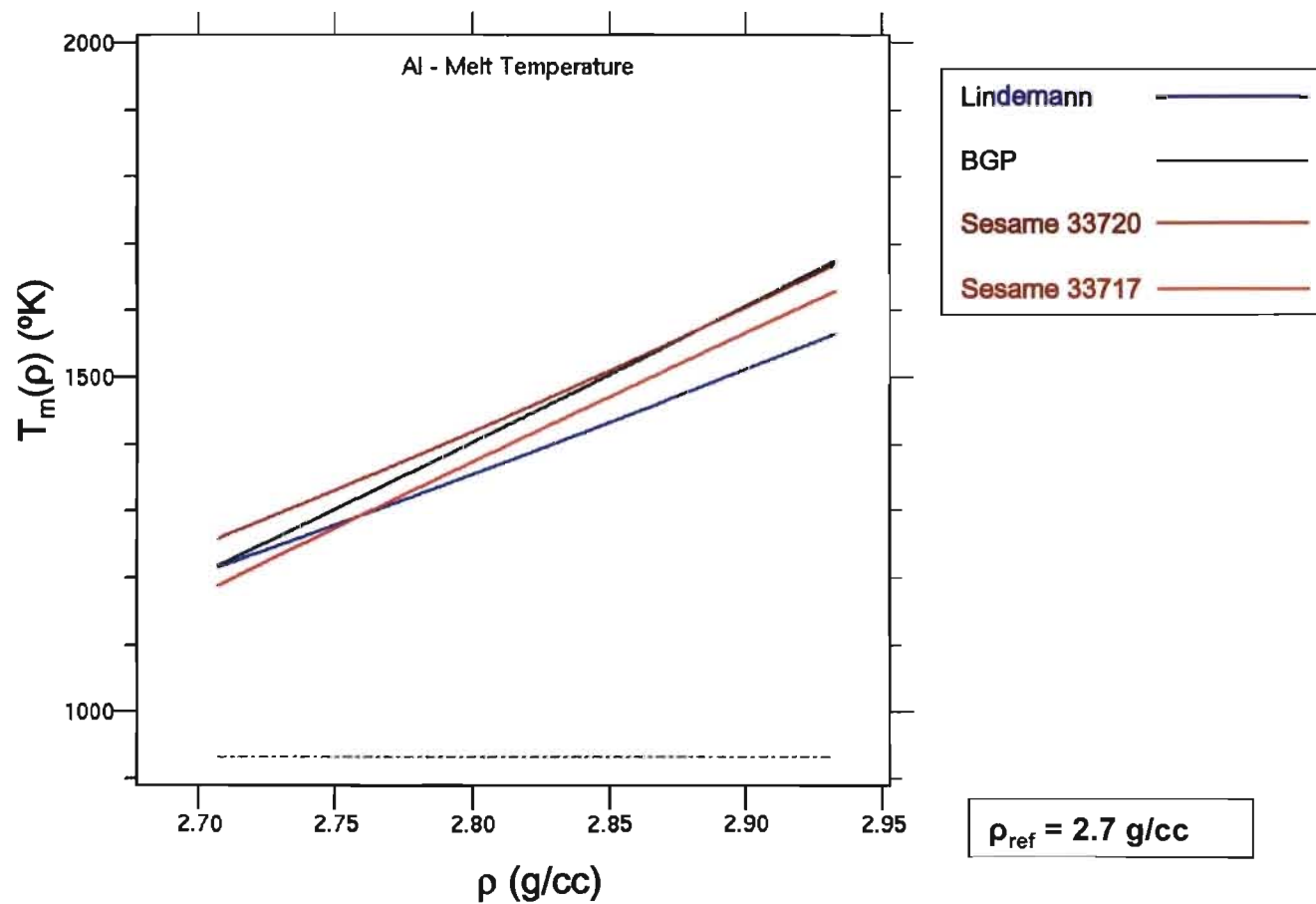
DU Stress-Strain Curve ($d\epsilon^p/dt = 0.0028/\mu s$) with/without a density dependent Lindemann melt



DU Stress-Strain Curve ($d\epsilon^p/dt = 0.5/\mu s$) with/without a density dependent Lindemann melt



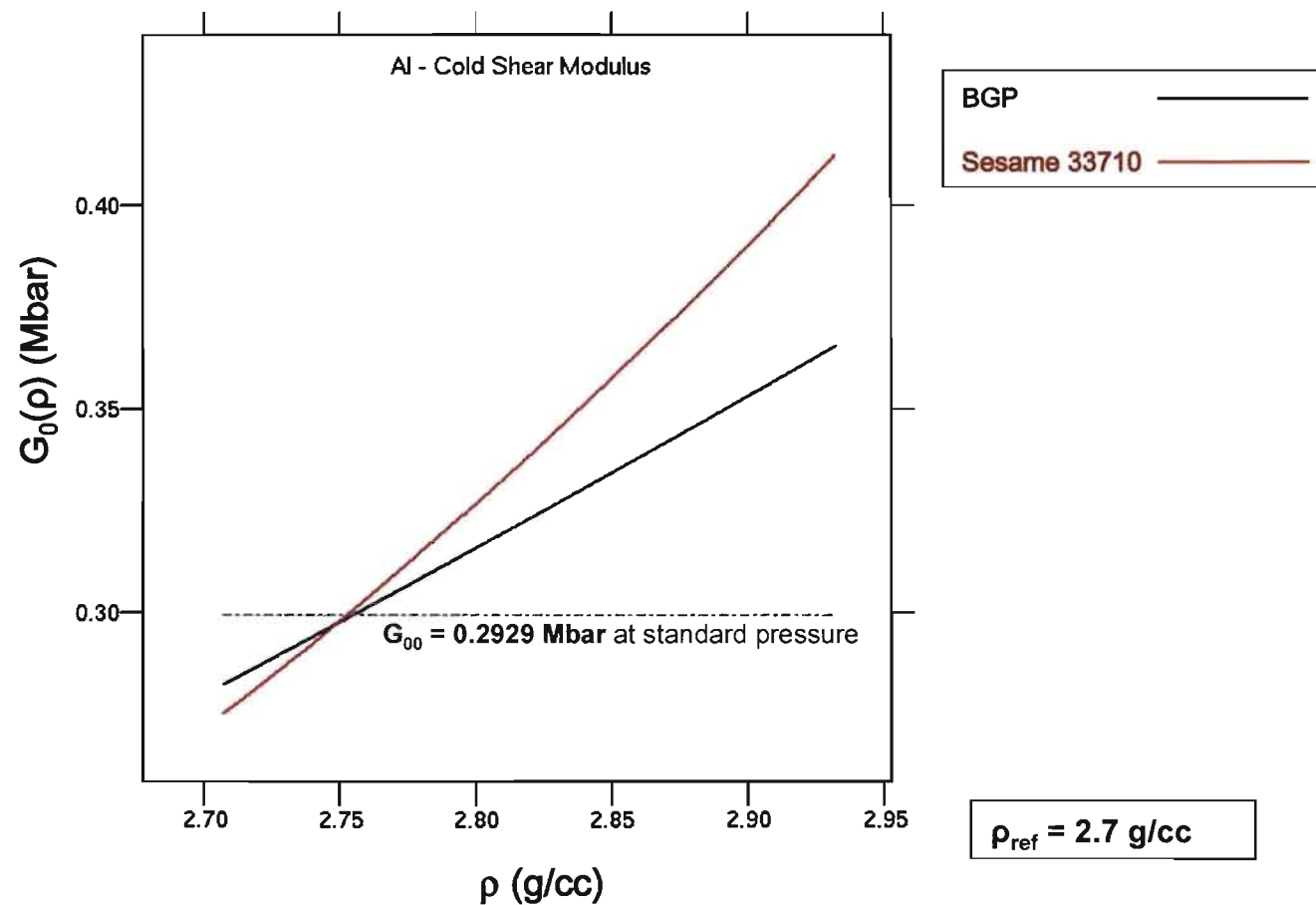
Melt Temperatures for Aluminum



© 932° K

T_m at standard pressure

Shear Moduli for Aluminum



PTW Adjustment for density dependent Shear Modulus

Reasonable assumptions:

- 1) Density changes are small during MST experiments
- 2) Most experiments were performed at ambient temperature and pressure - (ρ_R, T_R)
- 3) Shear modulus of model should equal shear modulus MST parameter fit

$$G_{MST}(T_R) = G_{PTW}(\rho_R, T_R)$$

- 4) Compute adjusted parameters for the model

$$\alpha = \frac{T_m(\rho_R)}{T_R} \left[1 - \frac{G_{0a}}{G_0(\rho_R)} \left\{ 1 - \alpha' \frac{T_R}{T_{ma}} \right\} \right]$$

$$\kappa = \kappa' \frac{T_m(\rho_R)}{T_{ma}}$$

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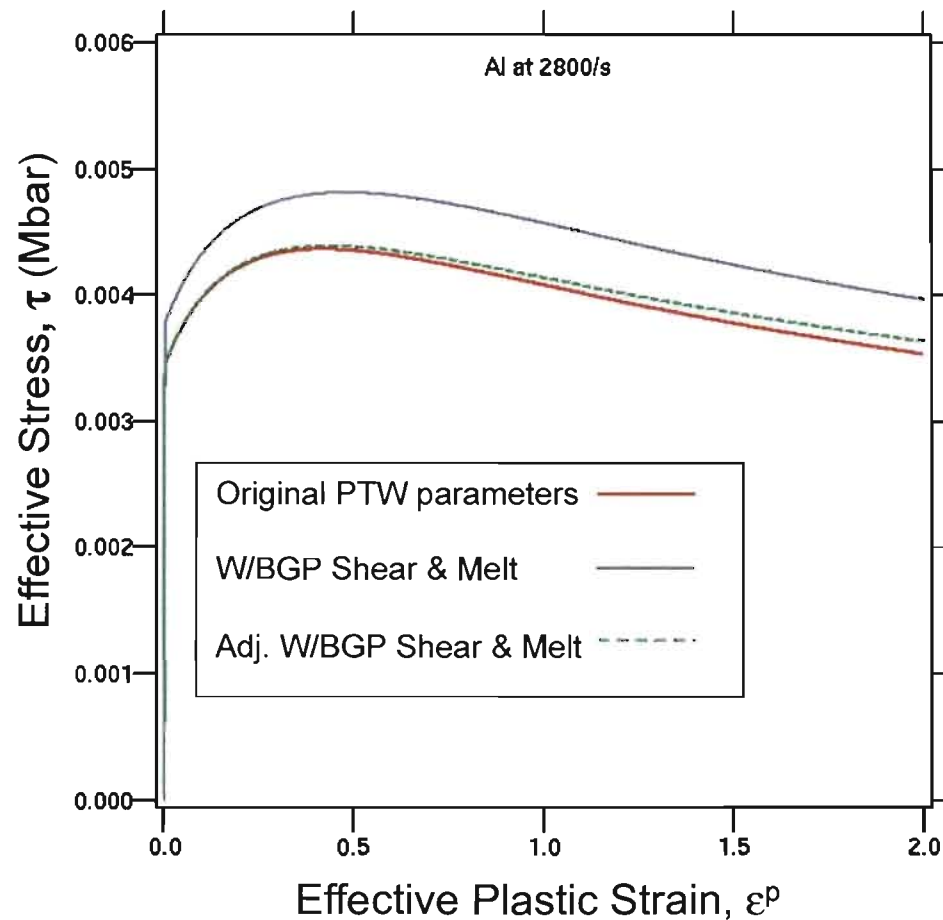
Adjustment of PTW Parameters

Adjustment of the PTW parameters for $\rho_0=2.703 \text{ g/cc}$ at $T_R=298^\circ\text{K}$

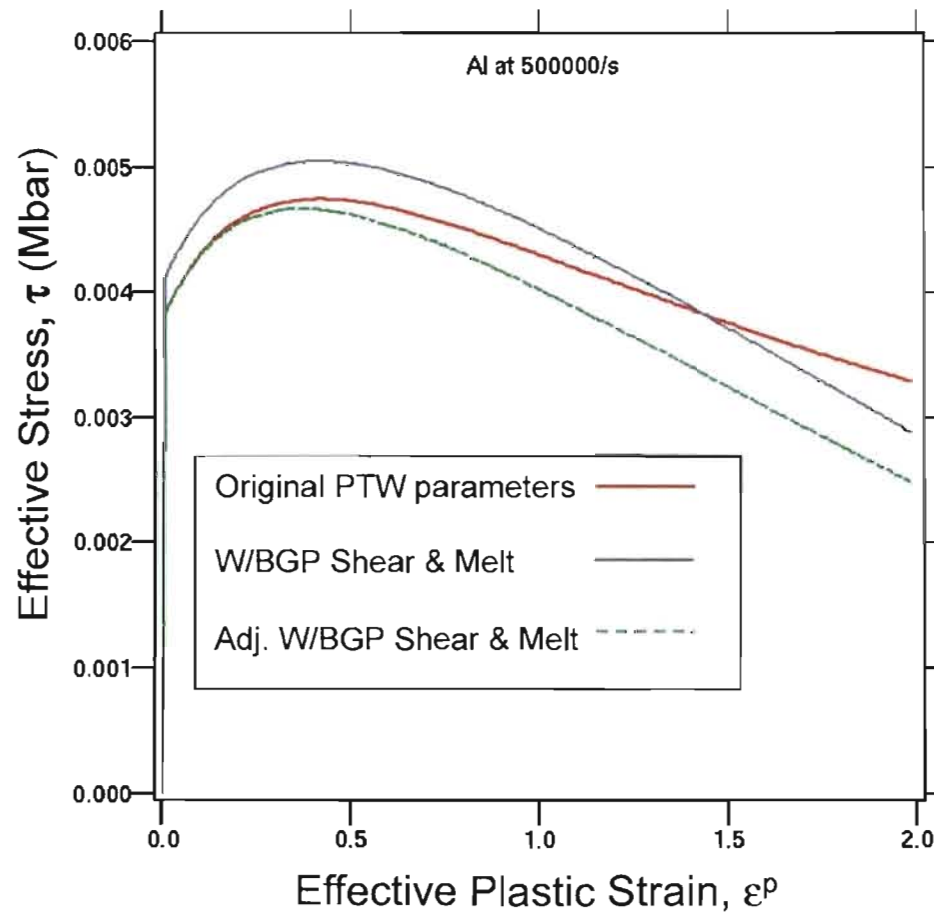
	α	K	G_0 (Mbar)	T_m (°K)	G_R (Mbar)
Original Data Set	0.475	0.200	0.2992	932	0.254
for T_m only	0.651	0.274	0.2992	1277	0.254
for T_m and G_0	0.574	0.274	0.293	1277	0.254

* Steinberg has $G = 0.276 \text{ Mbar}$

Al Stress-Strain Curve ($d\varepsilon^p/dt = 0.0028/\mu s$)



Al Stress-Strain Curve ($d\varepsilon^p/dt = 0.5/\mu s$)



Annealed Cu

Adjustment of PTW Parameters

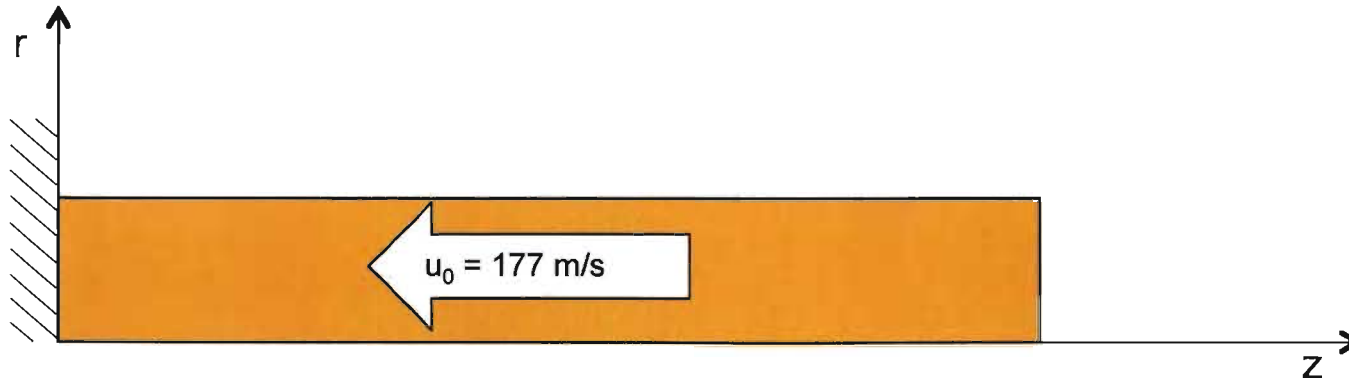
Adjustment of the PTW parameters for $\rho_0=8.93 \text{ g/cc}$ at $T_R=298^\circ\text{K}$

	α	K	G_0 (Mbar)	T_m (°K)	G_R (Mbar)
Original Data Set	0.447	0.170	0.525	1356	0.473
for T_m only	0.534	0.203	0.525	1620	0.473
for T_m and G_0	0.344	0.203	0.293	1620	0.473

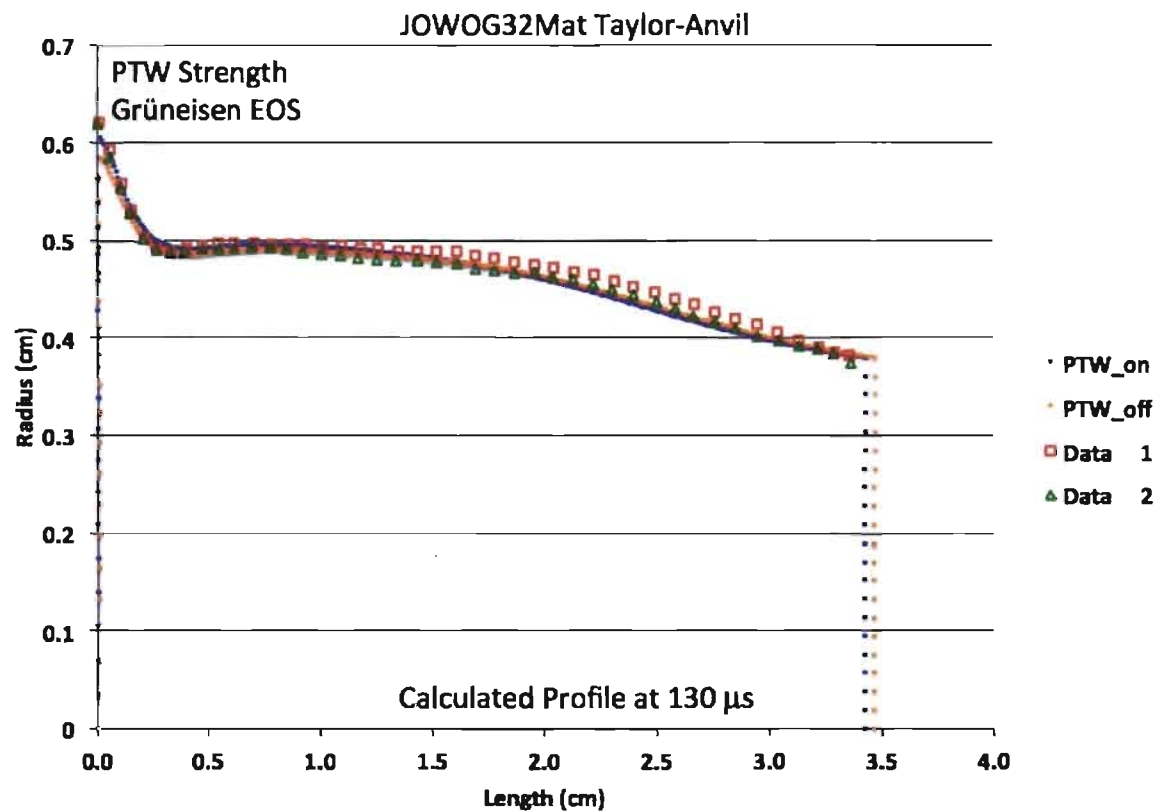
* Steinberg has $G = 0.477 \text{ Mbar}$

Taylor Anvil Test Problem

- 2D Axisymmetric geometry.
- Initial dimensions: $Z_0=5.08\text{cm}$, $R_0=0.381\text{cm}$.
- Impact velocity 177m/s
- Mesh: Regular $200\mu\text{m}$ mesh. (254x20 cells)
- For simplicity, used a zero axial velocity boundary condition at the impact face.



Computed profiles for a Cu Taylor Rod with PTW parameters adjusted for Lindemann $T_m(\rho)$ only.



TEPla (Tensile Elastic-Plastic Damage) Model

The stress bearing capability of a material is reduced by damage.

$$\bar{\sigma}_{ij} = (1 - D)\sigma_{ij}$$

$$\bar{s}_{ij} = (1 - D)s_{ij}$$

$$\bar{p} = (1 - D)p$$

TEPla the damage parameter is the porosity

$$D = \phi = \frac{V_{void}}{V}$$

Refactored Tensile Elastic-Plastic Damage Model

TEPla Residual Equations:

$$\left(1 + \frac{6G \Delta\lambda}{y_f y_f}\right) \frac{\bar{\tau}}{y_f} - \frac{\bar{\tau}'}{y_f} = 0$$

$$\bar{\delta} - \bar{\delta}' + \frac{3q_2 y_f \Delta\lambda}{2 y_s y_f} \left[3q_1 q_2 \frac{\bar{\alpha}}{y_s} \phi \sinh \bar{\delta} + 2\Gamma \left(\frac{\bar{\tau}}{y_f} \right)^2 \right] = 0$$

$$\phi - \phi' - 3q_1 q_2 \frac{y_f \Delta\lambda}{y_s y_f} (1 - \phi) \phi \sinh \bar{\delta} = 0$$

where

$$\bar{\tau} = \sqrt{\frac{3}{2} \bar{s}_{ij} \bar{s}_{ij}}$$

$$\bar{\delta} = -3q_2 \bar{p} / 2y_s$$

$$\bar{\alpha} = \bar{B} - (1 + \Gamma) \bar{p}$$

$$\left(\frac{\bar{\tau}}{y_f} \right)^2 - \left[1 + q_3 \phi^2 - 2q_1 \phi \cosh \bar{\delta} \right] = 0$$

Failure Models

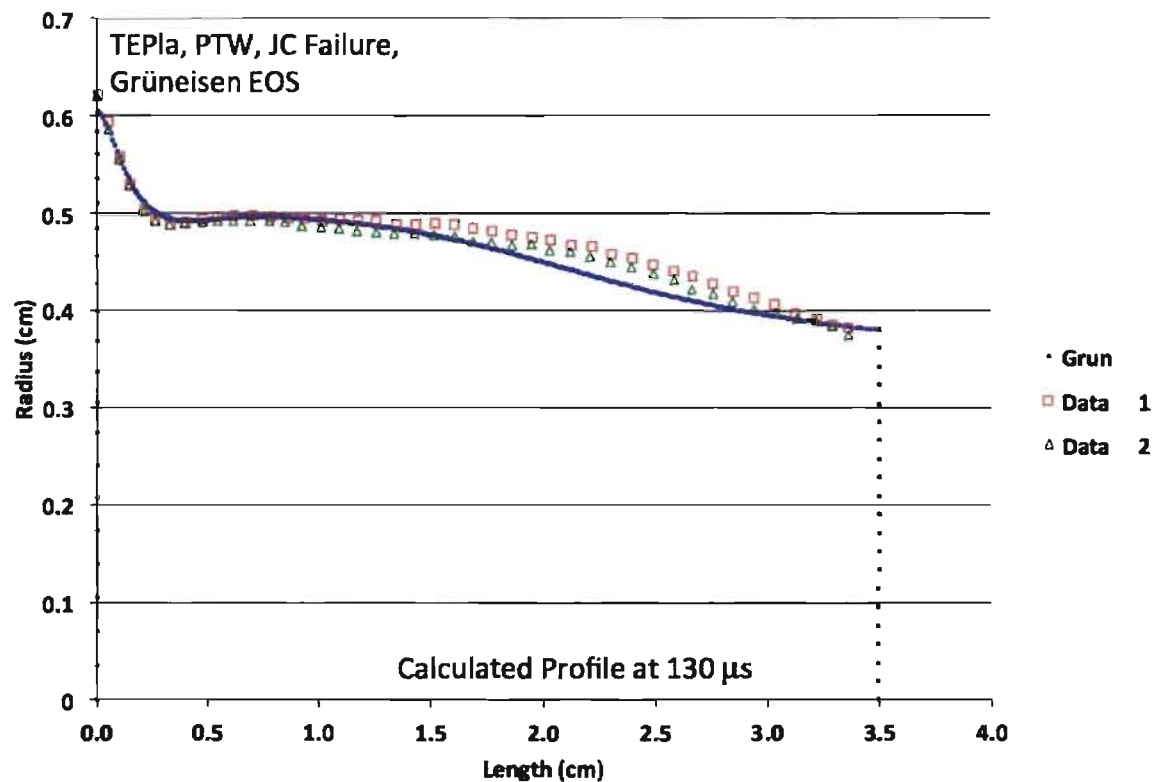
- Modified Johnson-Cook ductile failure model (TEPla)

$$F = \left(\frac{\phi}{\phi_f} \right)^2 + \left(\frac{\gamma}{\gamma_f} \right)^2 \geq 1$$
$$\gamma = \sqrt{\frac{2\varepsilon'_{ij}\varepsilon'_{ij}}{3}}$$
$$\gamma_f = \left[D_1 + D_2 e^{D_3 \rho} \right] \left[1 + D_4 \ln \frac{\dot{\gamma}}{\dot{\gamma}_0} \right] \left[1 + D_5 \frac{T - T_{\text{ref}}}{T_m - T_{\text{ref}}} \right]$$

- Maximum Tensile Stress
- P_{min} Spall

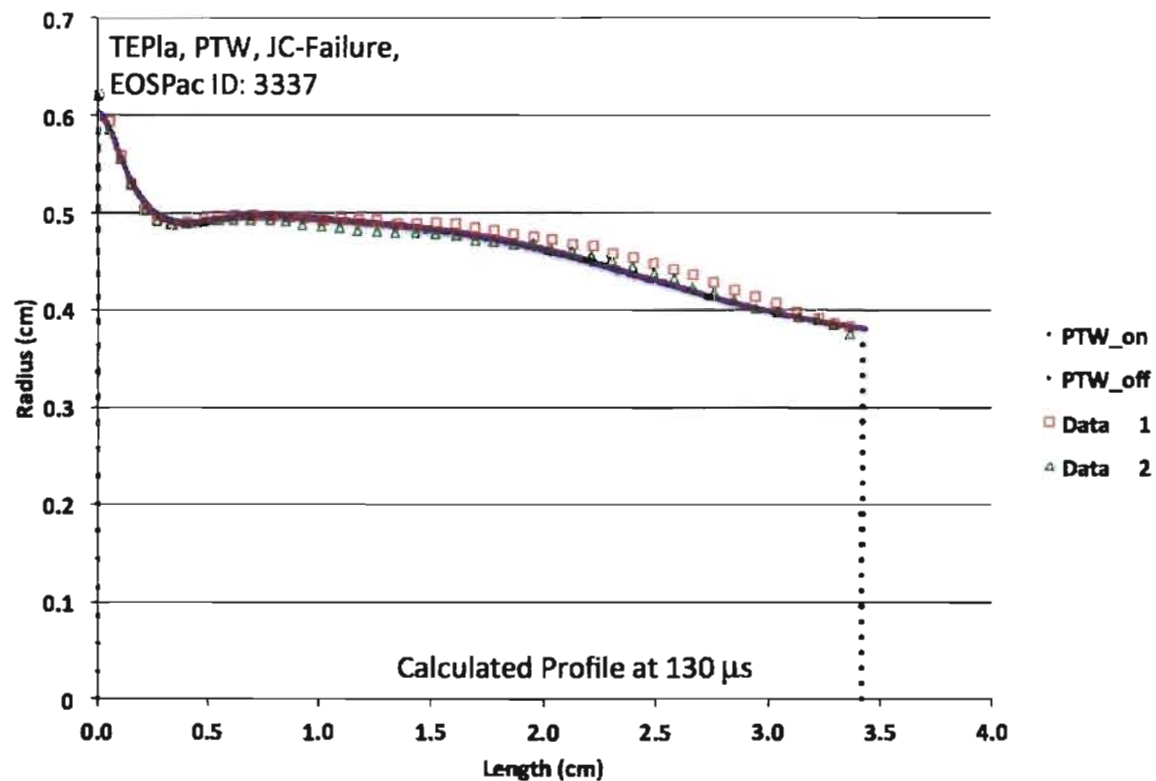
Computed profile of a Taylor Rod

Modeled with Damage, JC Ductile Failure, T_m and G constant.



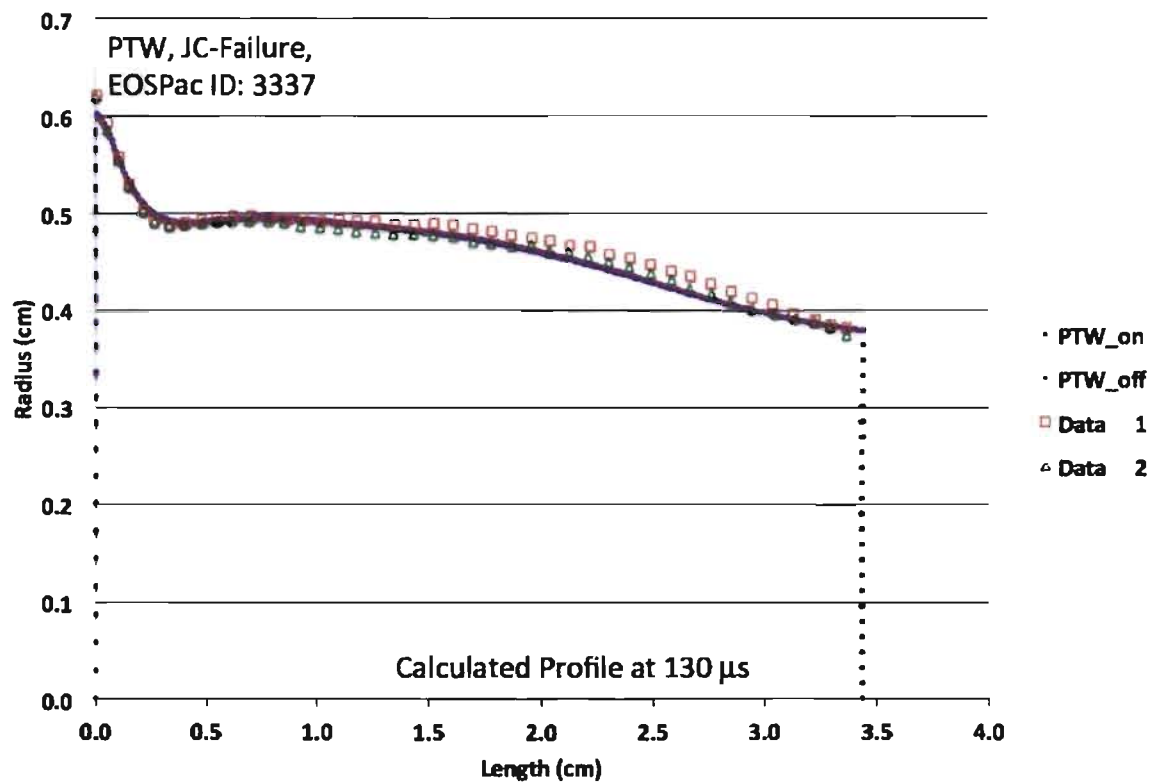
Computed profile of a Taylor Rod

Modeled with Damage PTW Mod 1 and JC Ductile Failure.



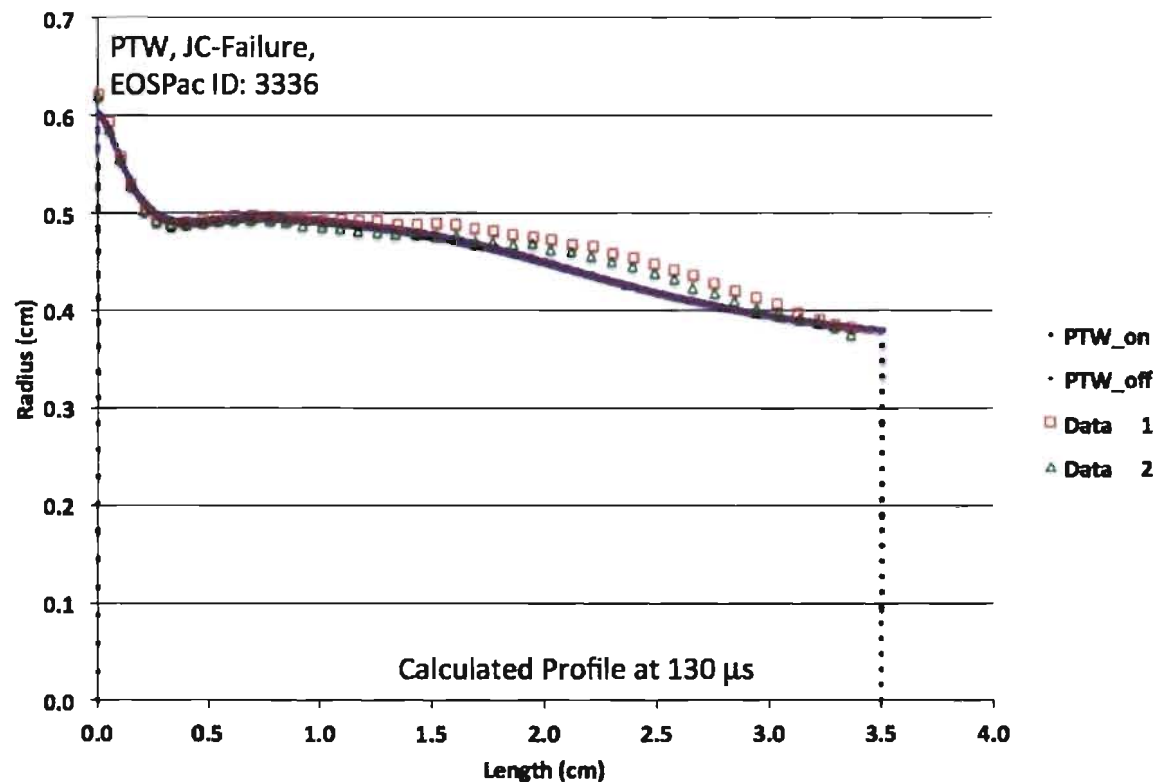
Computed profile of a Taylor Rod

Modeled with PTW Mod 1 and J-C Ductile Failure.



Computed profile of a Taylor Rod

Modeled with PTW Mod 1 and J-C Ductile Failure,



Discussion and Conclusion

■ Updated PTW Model

- It is a more robust implementation of the original model.
- Tested over an extended strain-rate regime.
- Data fits cover a limited range of interest.
- Extension to overdriven stress/high strain-rate regime needs to be re-visited.
- Auto-adjust feature
 - Self correcting
 - Detected compatibility issues with some of the data fits (Stainless-Steel)

■ TEPla Refactor

- Modularity has allowed us to implement alternative solvers (Zou-Rice).
- Used in the Taylor Anvil studies.

Future Directions

■ PTW

- Need to characterize the high strain-rate behavior of the model
 - Revisit overdriven shock experiments
 - DFT Simulations

■ Modeling of Anisotropic Elastic-Plastic Solids

- B-basis solver
- Need to consider coupling between the pressure and deviator components of stress and strain.

■ TEPla

- Continue work on more robust solvers.
- Anisotropic Damage
- Multiphase Damage

References

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6. Q. H. Zou and Jeremy R. Rice, “An explicit algorithm for a rate-dependent ductile failure model”, J. Appl. Physics, V104, 104-112, 2008.