

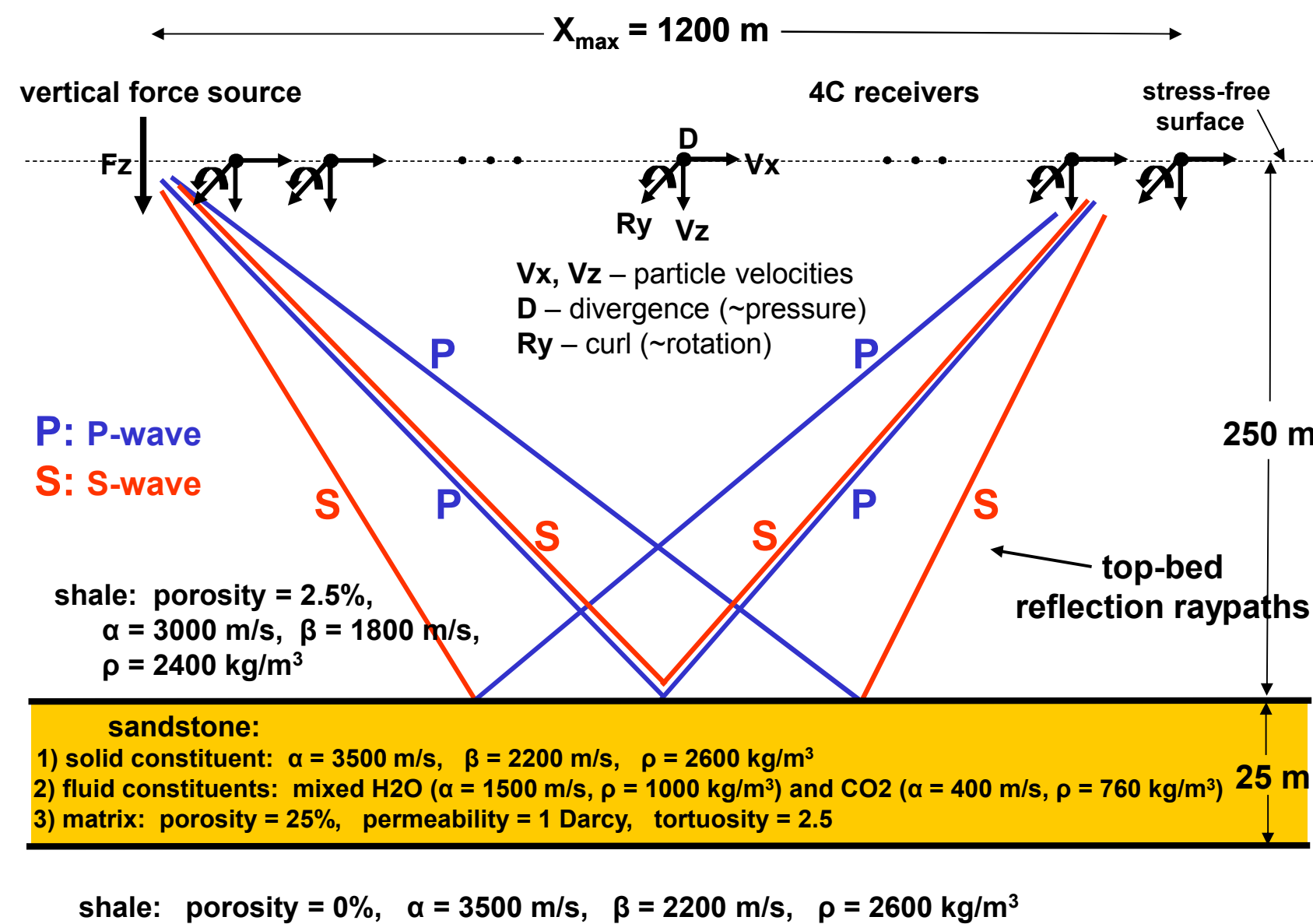
Introduction and Summary

Long term geologic sequestration of carbon dioxide (CO2) is increasingly considered a viable approach for removing large amounts of excess carbon from the earth's surface environment. As CO2 is injected into a porous subsurface formation, it displaces (or mixes with) existing *in situ* pore fluids such as brine, oil, or methane. The seismic reflection and transmission responses of the formation depend on the degree of CO2 substitution. Additionally, geochemical reactions involving CO2 and mineral grains alter the bulk and shear moduli of the solid constituent and/or the matrix of the porous medium. In this study, we examine full waveform, wide-angle, amplitude vs. offset (AVO) responses of a sandstone layer. Synthetic seismic data are calculated with a 3D poroelastic wave propagation algorithm that solves Biot's governing system of 13 coupled partial differential equations via an explicit, time-domain, finite-difference method. All of the common seismological phases (primary and multiple reflections, mode conversions, head waves, surface and interface waves, etc.) are generated with fidelity, provided spatial and temporal intervals are sufficiently fine.

Initial calculations indicate that full or partial replacement of H2O by CO2 is readily detected by the AVO recording configuration, particularly with the long offset shear events. Difference seismogram amplitudes of surface-recorded multi-component particle velocities range up to 25%. A sharp CO2/H2O front generates weak diffractions that may not be readily detected by AVO recording. Poroelastic sensitivity modeling experiments of this type need to be extended to carbonate layer geology, higher spectral bandwidths, and a vertical seismic profiling (VSP) acquisition configuration.

Earth Model and Reflection AVO Data Acquisition Configuration

Earth Model: a homogeneous porous sandstone layer (25 m thick) overlain and underlain by homogeneous shales. Top of layer is 250 m below horizontal stress-free surface.



Data Acquisition Geometry:

- 1) Vertical force source applied to stress-free surface (mimics Vibroseis source acquisition). Source pulse is 30 Ricker wavelet.
- 2) Four-component (4C) receivers deployed on surface record inline horizontal and vertical particle velocities, crossline particle rotation, and displacement divergence.
- 3) Maximum source-receiver offset of 1200 m simulates wide-angle AVO recording (offset-to-depth ratio ~5:1).

Acknowledgements

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Poroelastic Wave Equations and 3D Finite-Difference Grid

Thirteen, coupled, first-order, non-homogeneous, partial differential equations:

$$\rho_{11} \frac{\partial v_s}{\partial t} + \rho_{12} \frac{\partial v_f}{\partial t} + b(v_s - v_f) - (1 - \phi) \nabla \cdot \sigma = (1 - \phi)(f_s + \nabla \cdot m_i^{\text{sym}})$$

$$\rho_{12} \frac{\partial v_s}{\partial t} + \rho_{22} \frac{\partial v_f}{\partial t} - b(v_s - v_f) + \phi \nabla p = \phi(f_f + \nabla \cdot m_i^{\text{sym}})$$

$$(1 - \phi) \frac{\partial \sigma}{\partial t} + A(\nabla \cdot v_s) - Q(\nabla \cdot v_f) - \mu(\nabla v_s + \nabla v_s^T) = \frac{\partial m_i^{\text{sym}}}{\partial t}$$

$$\phi \frac{\partial p}{\partial t} + Q(\nabla \cdot v_s) + R(\nabla \cdot v_f) = -\frac{\phi}{3} \frac{\partial}{\partial t} \text{Tr}\{m_i^{\text{sym}}\}$$

Wavefield Variables:

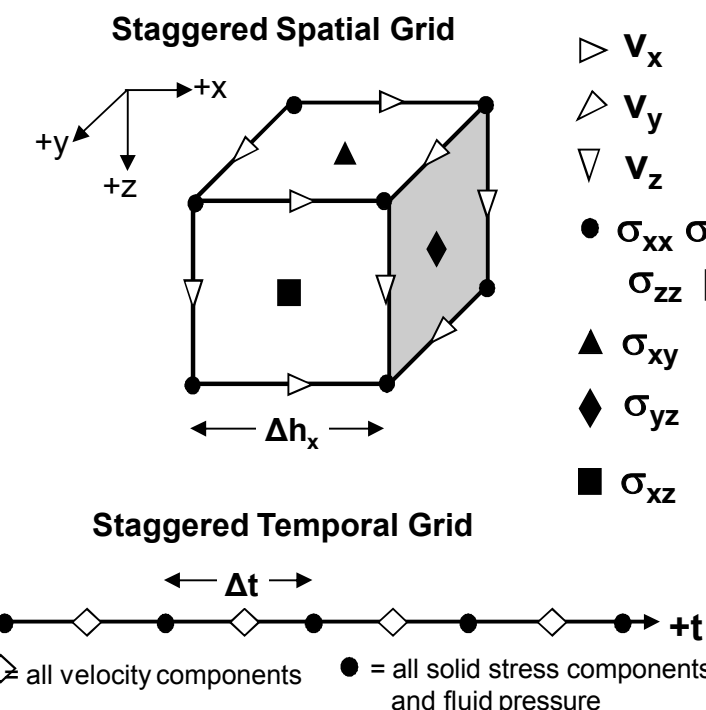
$v_s(x, t)$ – solid velocity vector
 $v_f(x, t)$ – fluid velocity vector
 $\sigma(x, t)$ – solid stress tensor
 $p(x, t)$ – fluid pressure

Poroelastic Earth Model Parameters:

$\phi(x)$ – porosity
 $\rho_{11}(x), \rho_{12}(x), \rho_{22}(x)$ – inertial coupling coefficients
 $b(x)$ – viscous coupling coefficient
 $A(x), Q(x), R(x), \mu(x)$ – moduli

Seismic Body Sources:

$f_s(x, t)$ – solid force density vector
 $f_f(x, t)$ – fluid force density vector
 $m_s(x, t)$ – solid moment density tensor
 $m_f(x, t)$ – fluid moment density tensor

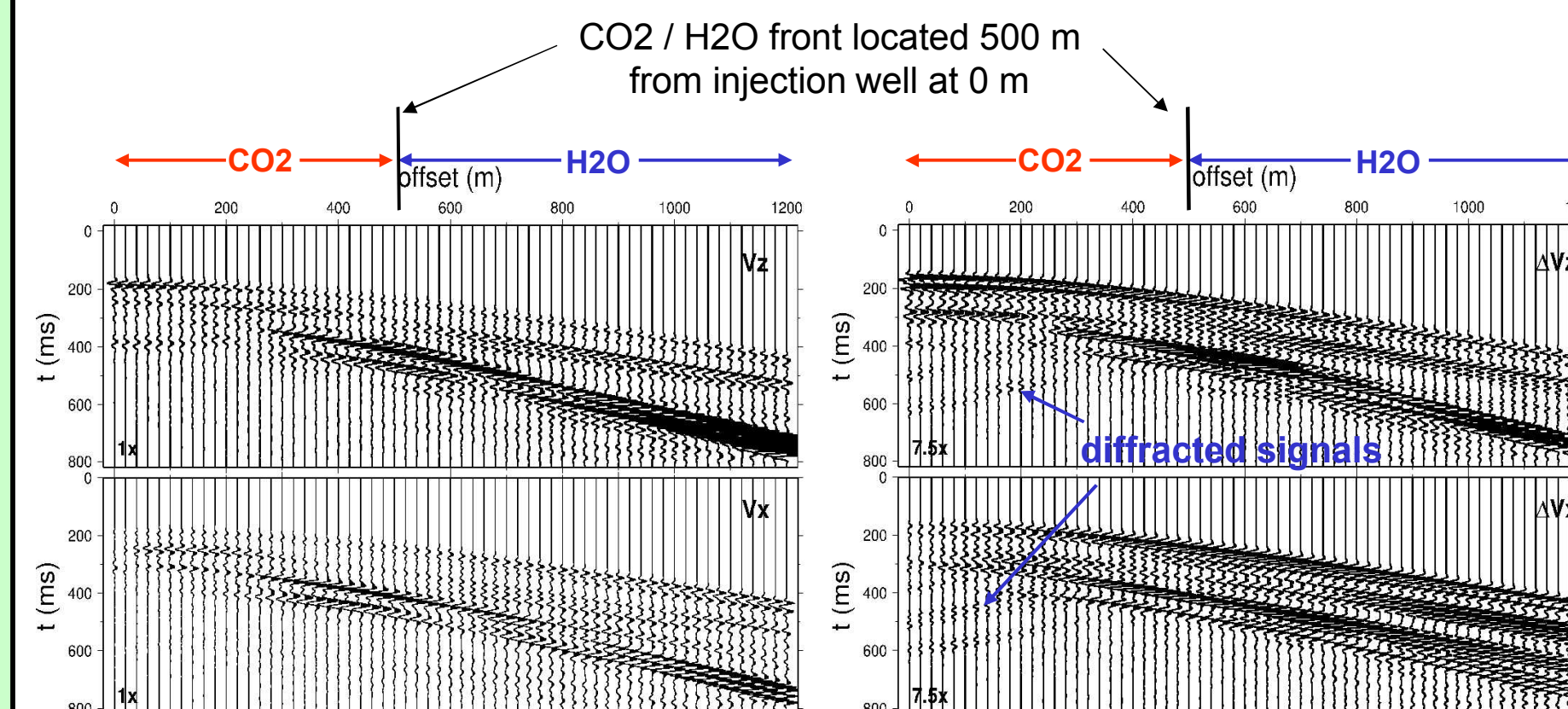


This 3D **velocity-stress-pressure** system is numerically solved with an explicit, time-domain, staggered-grid, O(2,4) finite-difference algorithm.

Advantage: Wave propagation physics in two-phase media is properly accounted for. No need to resort to "effective elastic medium" representation of a fluid-saturated porous body.

Disadvantage: Computational cost, in terms of memory and execution time, is significantly greater than for isotropic elastic modeling. There are *thirteen* dependent variables and *nine* medium parameters.

CO2 Injection Front Model



Actual CO2 / H2O front will be diffuse rather than sharp, indicating that diffraction signals will be even weaker! Hence, reflection AVO configuration may not be able to resolve front location well.

Uniformly Saturated Sandstone Layer Model

