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Poroelastic Seismic Wave Propagation Modeling of CO₂ Sequestration Effects

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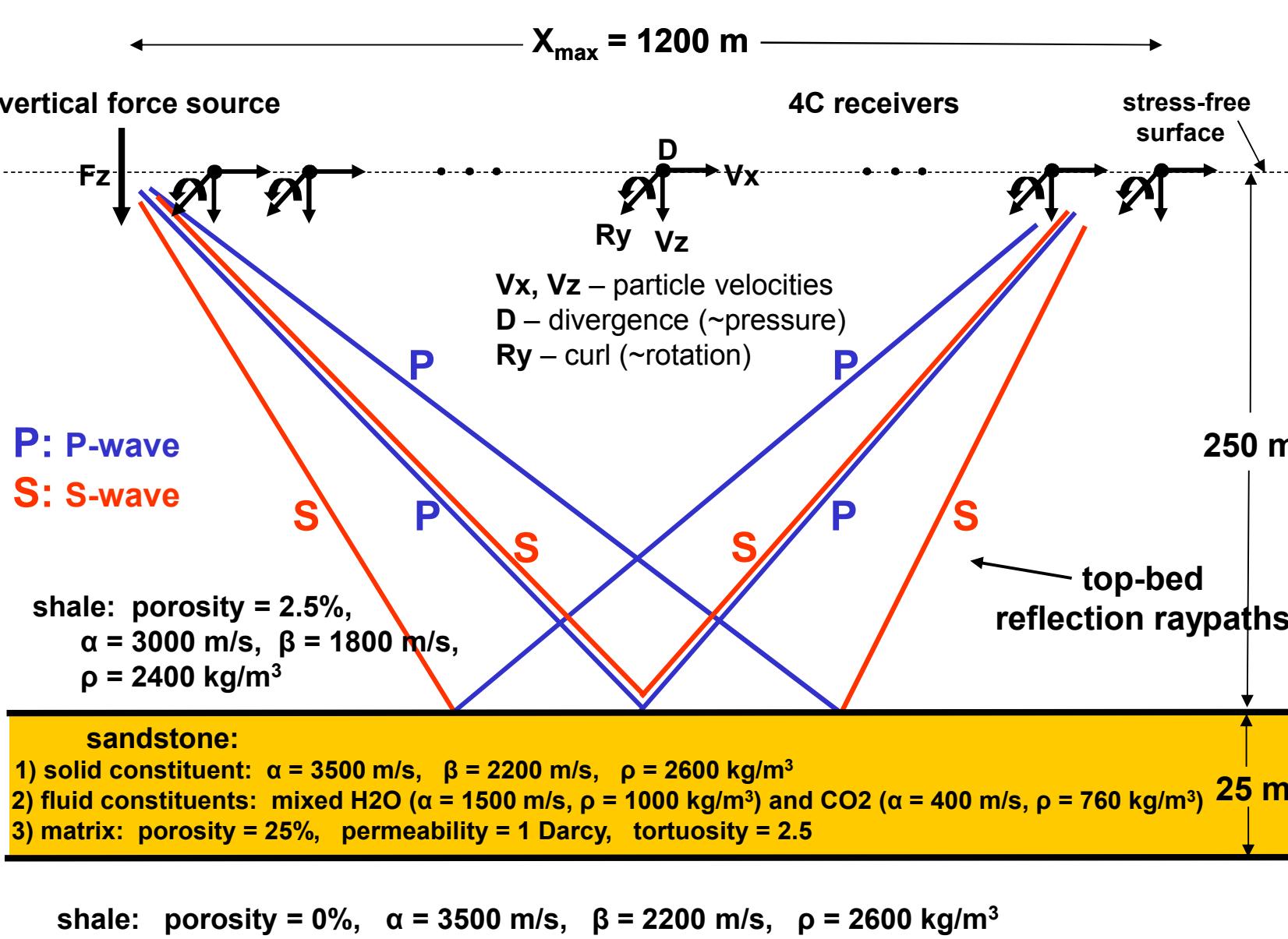
Introduction and Summary

Long term geologic sequestration of carbon dioxide (CO₂) is increasingly considered a viable approach for removing large amounts of excess carbon from the earth's surface environment. As CO₂ is injected into a porous subsurface formation, it displaces (or mixes with) existing *in situ* pore fluids such as brine, oil, or methane. The seismic reflection and transmission responses of the formation depend on the degree of CO₂ substitution. Additionally, geochemical reactions involving CO₂ and mineral grains alter the bulk and shear moduli of the solid constituents and/or the matrix of the porous medium. In this study, we examine full waveform, wide-angle, amplitude vs. offset (AVO) responses of a sandstone layer. Synthetic seismic data are calculated with a 3D poroelastic wave propagation algorithm that solves Biot's governing system of 13 coupled partial differential equations via an explicit, time-domain, finite-difference method. All of the common seismological phases (primary and multiple reflections, mode conversions, head waves, surface and interface waves, etc.) are generated with fidelity, provided spatial and temporal intervals are sufficiently fine.

Initial calculations indicate that full or partial replacement of H₂O by CO₂ is readily detected by the AVO recording configuration, particularly with the long offset shear events. Difference seismogram amplitudes of surface-recorded multi-component particle velocities range up to 25%. A sharp CO₂/H₂O front generates weak diffractions that may not be readily detected by AVO recording. Poroelastic sensitivity modeling experiments of this type need to be extended to carbonate layer geology, higher spectral bandwidths, and a vertical seismic profiling (VSP) acquisition configuration.

Earth Model and Reflection AVO Data Acquisition Configuration

Earth Model: a homogeneous porous sandstone layer (25 m thick) overlain and underlain by homogeneous shales. Top of layer is 250 m below horizontal stress-free surface.



Data Acquisition Geometry:

- 1) Vertical force source applied to stress-free surface (mimics Vibroseis source acquisition). Source pulse is 30 Ricker wavelet.
- 2) Four-component (4C) receivers deployed on surface record inline horizontal and vertical particle velocities, crossline particle rotation, and displacement divergence.
- 3) Maximum source-receiver offset of 1200 m simulates wide-angle AVO recording (offset-to-depth ratio ~5:1).

Acknowledgements

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Poroelastic Wave Equations and 3D Finite-Difference Grid

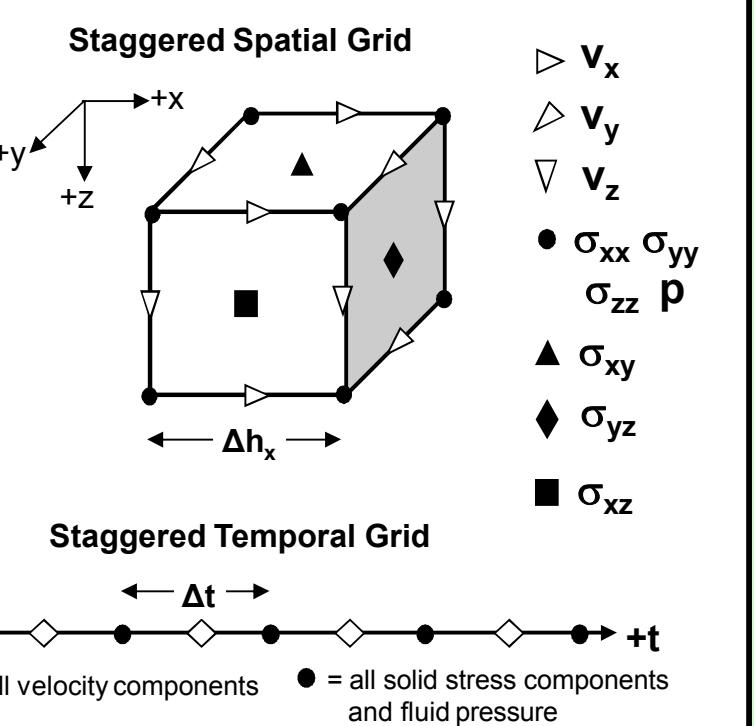
Thirteen, coupled, first-order, non-homogeneous, partial differential equations:

$$\rho_{11} \frac{\partial \mathbf{v}_s}{\partial t} + \rho_{12} \frac{\partial \mathbf{v}_f}{\partial t} + b(\mathbf{v}_s - \mathbf{v}_f) - (1-\phi) \nabla \cdot \boldsymbol{\sigma} = (1-\phi) (\mathbf{f}_s + \nabla \cdot \mathbf{m}_s^{\text{asym}})$$

$$\rho_{12} \frac{\partial \mathbf{v}_s}{\partial t} + \rho_{22} \frac{\partial \mathbf{v}_f}{\partial t} - b(\mathbf{v}_s - \mathbf{v}_f) + \phi \nabla p = \phi (\mathbf{f}_f + \nabla \cdot \mathbf{m}_f^{\text{asym}})$$

$$(1-\phi) \frac{\partial \boldsymbol{\sigma}}{\partial t} - A(\nabla \cdot \mathbf{v}_s) \mathbf{I} - Q(\nabla \cdot \mathbf{v}_f) \mathbf{I} - \mu (\nabla \mathbf{v}_s + \nabla \mathbf{v}_f^T) = \frac{\partial \mathbf{m}_s^{\text{sym}}}{\partial t}$$

$$\phi \frac{\partial p}{\partial t} + Q(\nabla \cdot \mathbf{v}_s) + R(\nabla \cdot \mathbf{v}_f) = -\frac{\phi}{3} \frac{\partial}{\partial t} \text{Tr} \{ \mathbf{m}_s^{\text{sym}} \}$$



Wavefield Variables:
 $\mathbf{v}_s(x,t)$ – solid velocity vector
 $\mathbf{v}_f(x,t)$ – fluid velocity vector
 $\boldsymbol{\sigma}(x,t)$ – solid stress tensor
 $p(x,t)$ – fluid pressure

Poroelastic Earth Model Parameters:
 $\phi(x)$ – porosity
 $\rho_{11}(x), \rho_{12}(x), \rho_{22}(x)$ – inertial coupling coefficients
 $b(x)$ – viscous coupling coefficient
 $A(x), Q(x), R(x)$ – moduli

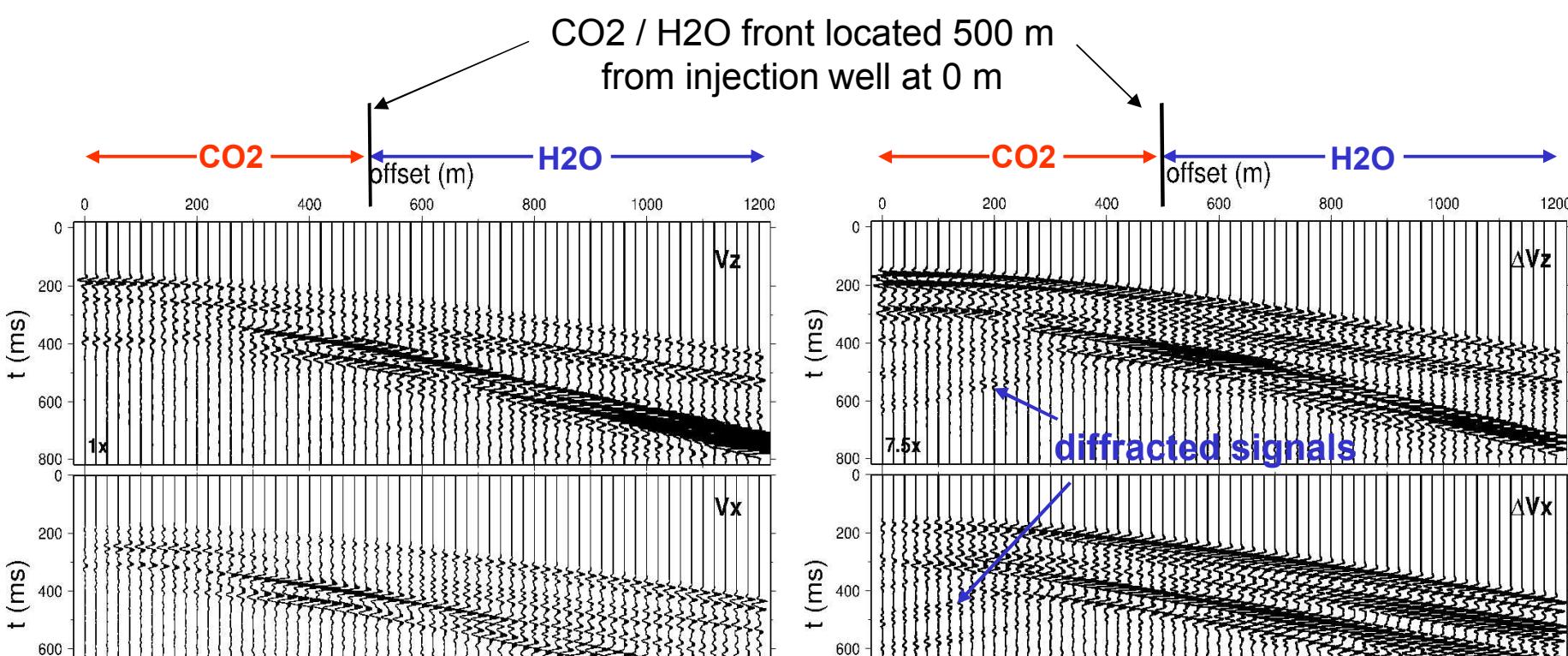
Seismic Body Sources:
 $\mathbf{f}_s(x,t)$ – solid force density vector
 $\mathbf{f}_f(x,t)$ – fluid force density vector
 $\mathbf{m}_s(x,t)$ – solid moment density tensor
 $\mathbf{m}_f(x,t)$ – fluid moment density tensor

This 3D **velocity-stress-pressure** system is numerically solved with an explicit, time-domain, staggered-grid, O(2,4) finite-difference algorithm.

Advantage: Wave propagation physics in two-phase media is properly accounted for. No need to resort to "effective elastic medium" representation of a fluid-saturated porous body.

Disadvantage: Computational cost, in terms of memory and execution time, is significantly greater than for isotropic elastic modeling. There are **thirteen** dependent variables and **nine** medium parameters.

CO₂ Injection Front Model

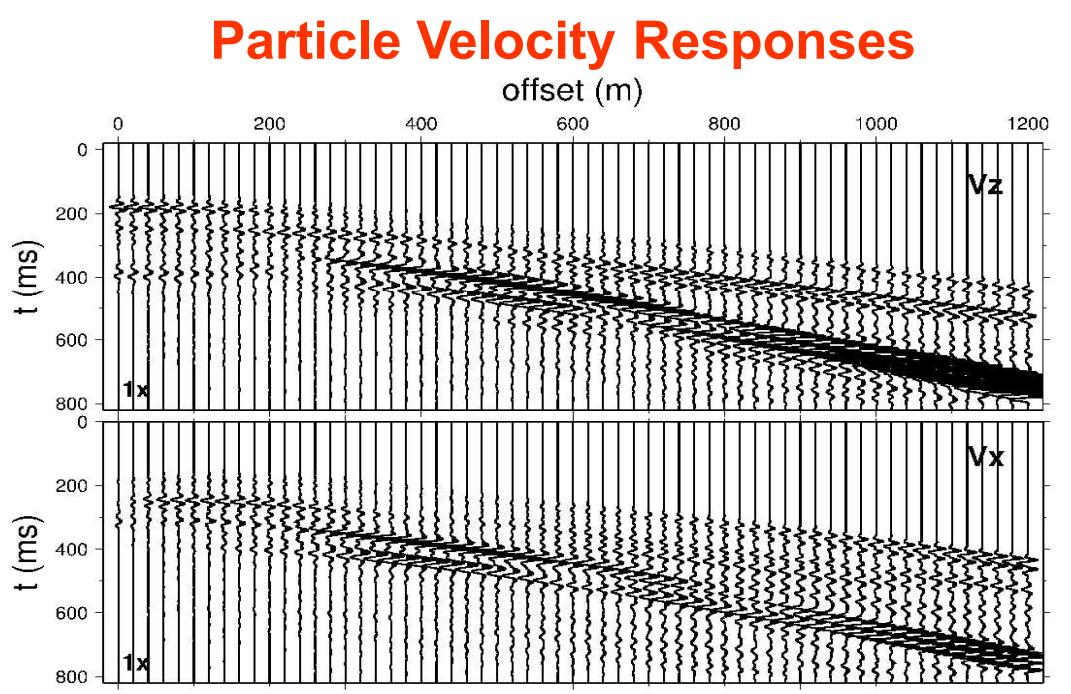


Difference traces, obtained by subtracting off responses for uniform H₂O saturation, reveal weak diffractions emanating from CO₂ front. Note 7.5x plot gain compared to left panel.

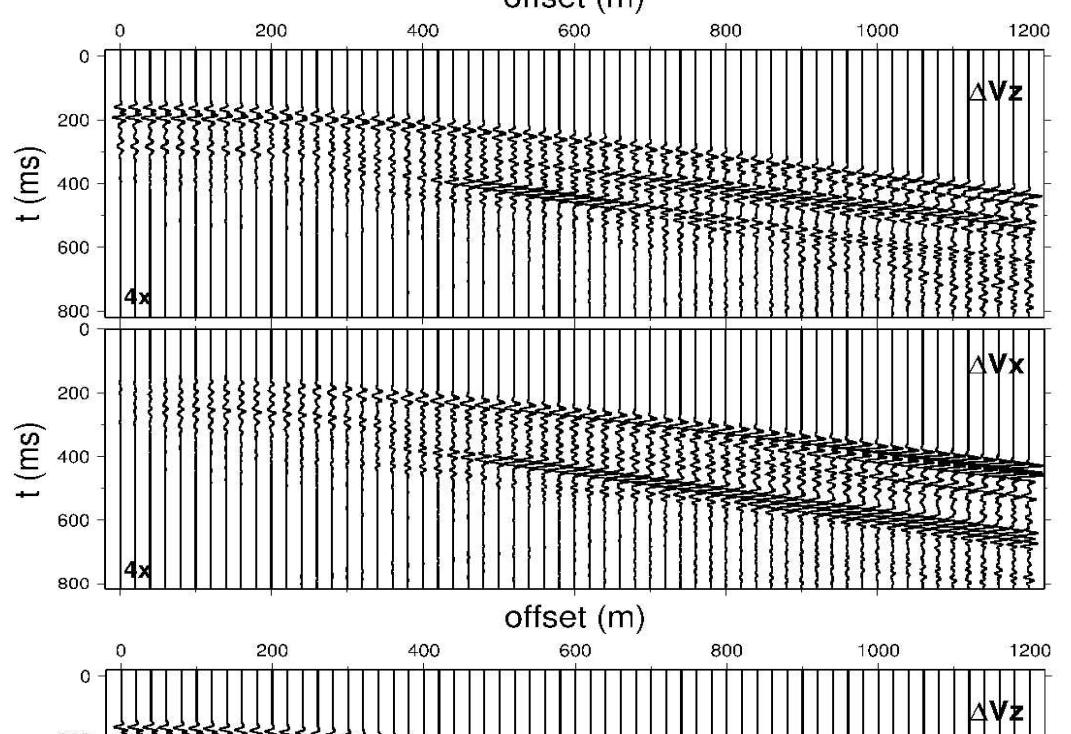
Actual CO₂ / H₂O front will be diffuse rather than sharp, indicating that diffraction signals will be even weaker! Hence, reflection AVO configuration may not be able to resolve front location well.

Uniformly Saturated Sandstone Layer Model

AVO responses for
100% H₂O (= 0% CO₂)
(direct and surface waves removed by subtraction)

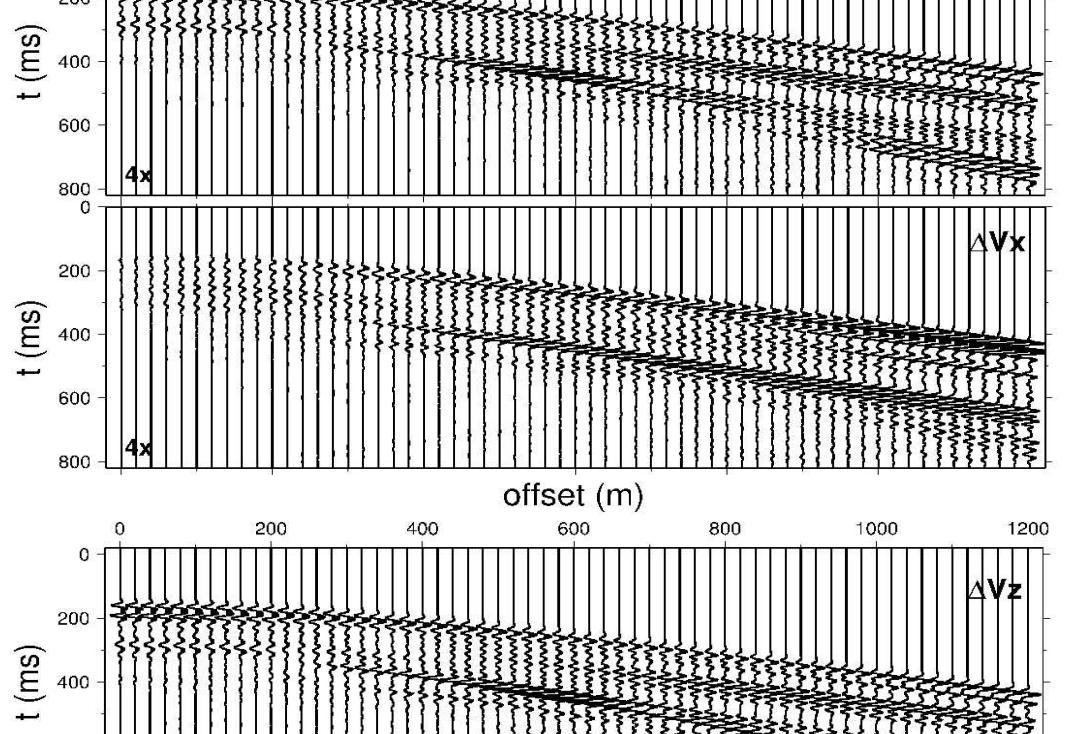


Difference AVO responses (plotted with 4x gain relative to 1x above) ↓
100% H₂O minus 25% CO₂



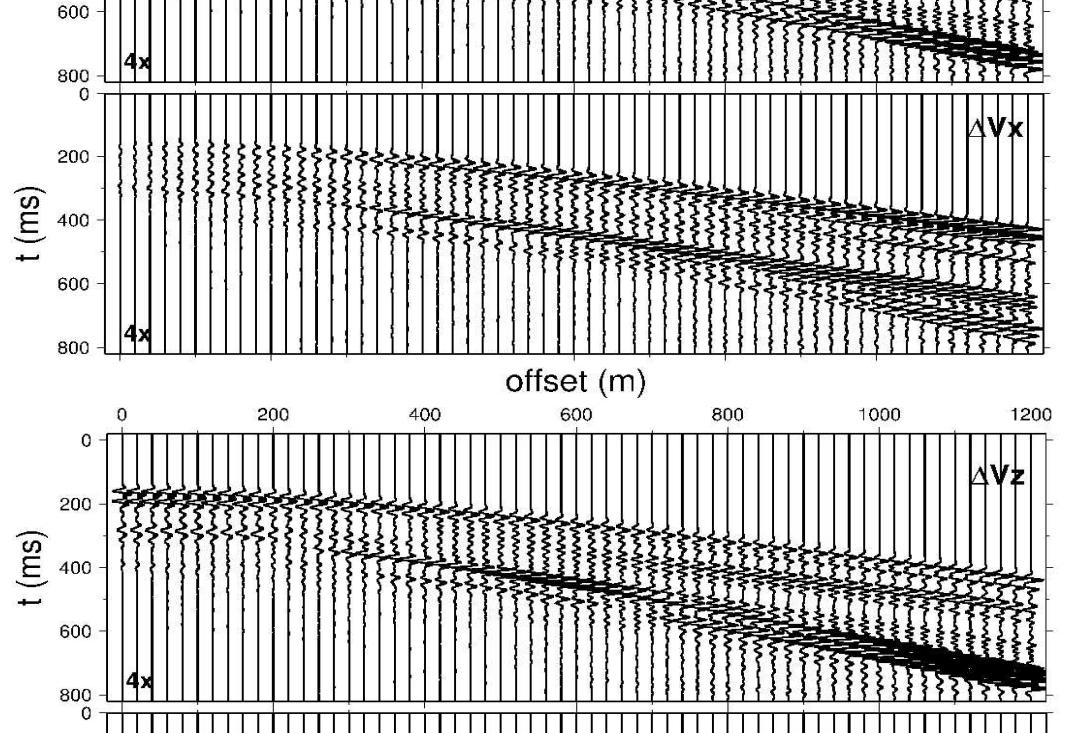
AVO responses consist of top-bed and bottom-bed primary reflections (PP, PS, SP, SS), together with all orders of intrabed multiples.

100% H₂O minus 50% CO₂



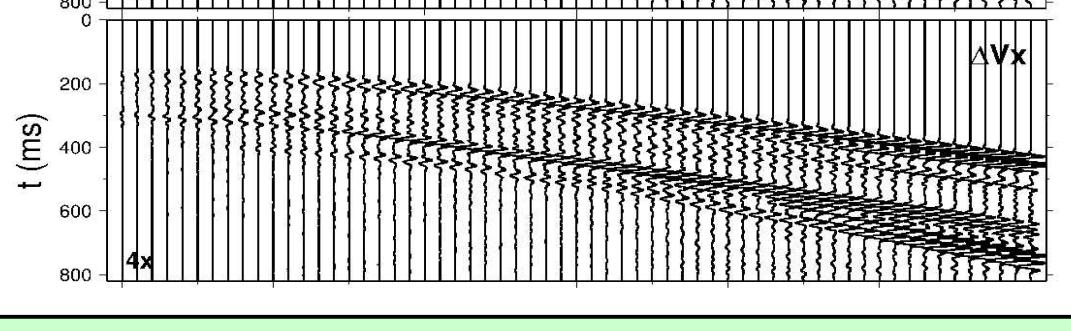
Divergence and rotation receivers tend to isolate P and S arrivals, respectively.

100% H₂O minus 75% CO₂



Amplitude of difference traces are ~1/4 of amplitude of reference traces (100% H₂O).

100% H₂O minus 100% CO₂



Note increasing amplitude of wide-angle AVO responses (particularly SS event) as CO₂ replaces H₂O.

Divergence / Rotation Responses

