

SAND2010-0740C

## *Computations of Chemically Reacting Flow*

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BES-NERSC Workshop, Washington DC, 2/9-10/2010

# Overview

- Collaborators:
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— Sandia National Labs
  - M. Valorani, Univ. of Rome
  - D. Goussis, Nat. Tech. Univ. of Athens
  - O. Knio, Johns Hopkins Univ.
  - M. Frenklach, UC Berkeley
- Goal: Advance understanding of chemically reacting flows
- Approach:
  - Development of efficient algorithms and codes for multidimensional low Mach number reacting flow computations and analysis
  - Computational studies of low Mach number reacting flow with detailed chemical kinetics
  - Development of validated reduced chemical models

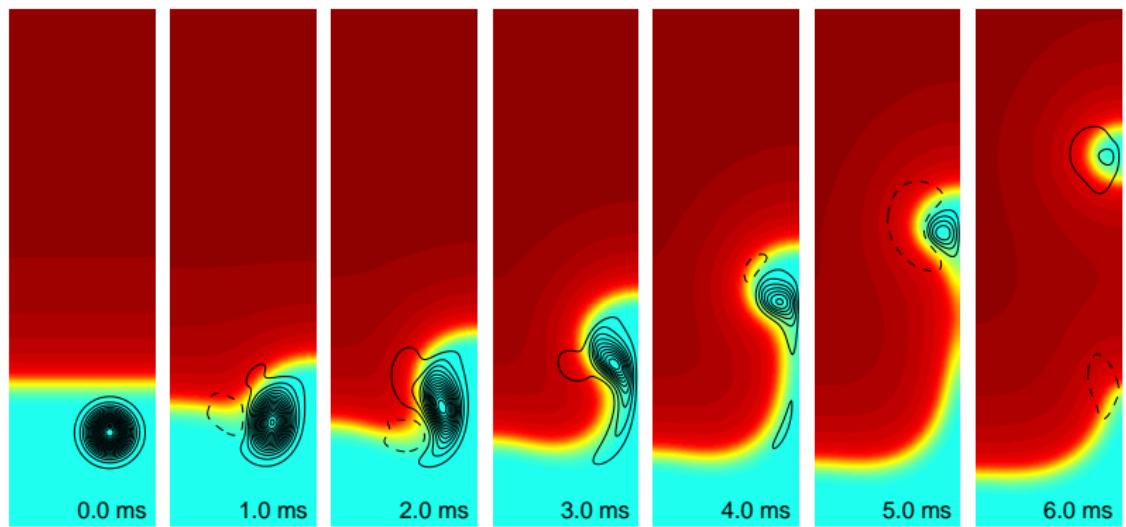
# Science Objectives for the Next 3-5 Years

- Study the structure and dynamics of
  - Edge flames
  - Lifted laminar jet flames
- Address fuels over a range of complexity
  - Methane, nHeptane, isoOctane
- Examine dependence of flame structure/dynamics on mixture composition and flow details
- Experimental comparisons

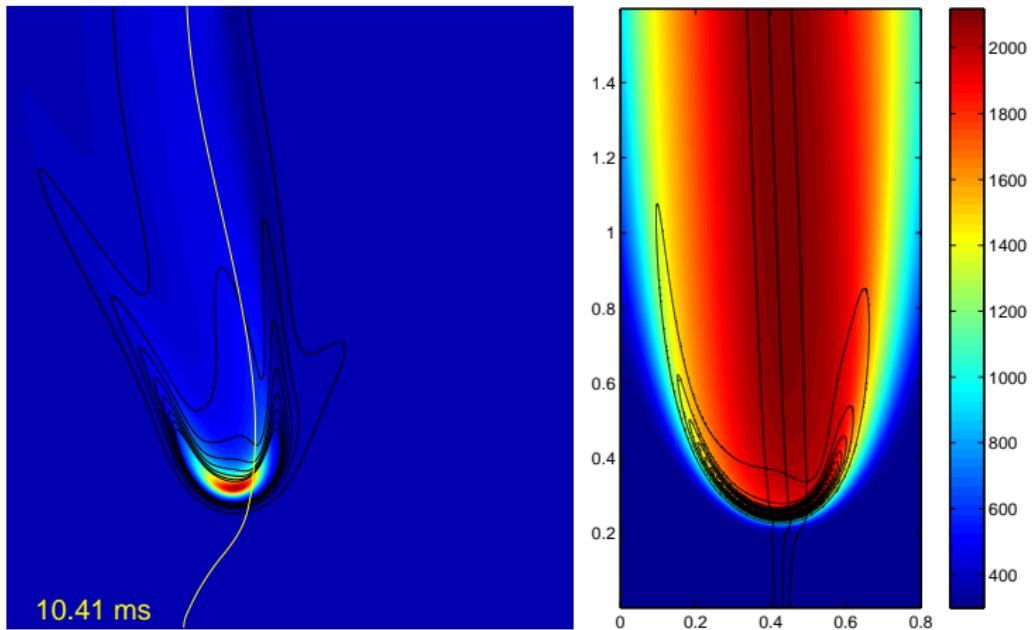
# Computational Challenges in low Mach Number Reacting Flow Modeling

- Large range of length scales
  - Combustion system size  $\mathcal{O}(0.01\text{--}10) \text{ m}$
  - Internal flame structures  $\mathcal{O}(100) \mu\text{m}$
  - Turbulence length scales
    - on the order of flame length scales at high  $\text{Re}$
- Large range of time scales
  - Flow time scales can be slow:  $\mathcal{O}(10) \text{ ms}$
  - Fast chemical time scales:  $\mathcal{O}(1) \text{ ns}$
- Chemical model complexity
  - Methane-air  $\sim 53 \text{ sp}$
  - nHeptane-air  $\sim 560 \text{ sp}$
  - isoOctane-air  $\sim 870 \text{ sp}$
- Multiphase, Radiation, Turbulence

# Flame Vortex Interaction



# Edge Flames



# Dimensionless Low Mach Number Equations

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

$$\frac{\partial(\rho \mathbf{v})}{\partial t} + \nabla \cdot (\rho \mathbf{v} \mathbf{v}) = -\nabla p + \frac{1}{\text{Re}} \nabla \cdot \left\{ \mu [(\nabla \mathbf{v}) + (\nabla \mathbf{v})^T] - \frac{2}{3} \mu (\nabla \cdot \mathbf{v}) \mathbf{U} \right\}$$

$$\rho c_p \frac{DT}{Dt} = \frac{(\gamma - 1)}{\gamma} \frac{dp_o}{dt} + \frac{1}{\text{RePr}} \nabla \cdot (\lambda \nabla T) - \frac{\rho}{\text{ReSc}} \sum_{i=1}^N c_{p,i} \mathbf{V}_i \cdot \nabla T - \text{Da} \sum_{i=1}^N h_i w_i$$

$$\frac{\partial(\rho Y_i)}{\partial t} + \nabla \cdot (\rho \mathbf{v} Y_i) = -\frac{1}{\text{ReSc}} \nabla \cdot (\rho Y_i \mathbf{V}_i) + \text{Da} w_i \quad i = 1, \dots, N$$

$$p_o = \frac{\rho T}{W}$$

- Low Mach No., no body forces, bulk viscosity, or radiation
- Ideal gas, neglect Soret & Dufour effects —  $\mathbf{U}$  is the unit tensor

# Time Integration of Multi-D Low M Reacting Flow

- Density and Species update

$$\frac{\partial \rho}{\partial t} = \rho \left( -\frac{1}{T} \frac{\partial T}{\partial t} - \overline{W} \sum_{i=1}^N \frac{1}{W_i} \frac{\partial Y_i}{\partial t} \right)$$

$$\frac{\partial(\rho Y_i)}{\partial t} = -\nabla \cdot (\rho \mathbf{v} Y_i) - \frac{1}{\text{ReSc}} \nabla \cdot (\rho Y_i \mathbf{V}_i) + \text{Da } w_i \quad i = 1, \dots, N$$

- Projection scheme solution for  $\mathbf{v}$

$$\frac{\partial(\rho \hat{\mathbf{v}})}{\partial t} = -\nabla \cdot (\rho \mathbf{v} \mathbf{v}) + \nabla \cdot \left\{ \mu [(\nabla \mathbf{v}) + (\nabla \mathbf{v})^T] - \frac{2}{3} \mu (\nabla \cdot \mathbf{v}) \mathbf{U} \right\}$$

$$\nabla^2 p = \frac{1}{\Delta t} \left[ \nabla \cdot (\rho \hat{\mathbf{v}}) + \frac{\partial \rho}{\partial t} \right]; \quad \rho \mathbf{v} = \rho \hat{\mathbf{v}} - \Delta t \nabla p$$

- Alternate constructions

- $(T, Y_i)$  rather than  $(\rho, \rho Y_i)$  update
- $\mathbf{v}$  rather than  $(\rho \mathbf{v})$  projection

# Time Integration of Stiff PDEs

- Species and energy conservation equations

$$\frac{du}{dt} = C + D + R$$

- Explicit: Stiffness necessitates  $\sim 1$  ns time steps
- Implicit:
  - Ok w/stiffness, but no need for implicit convection
- IMEX: Additive Implicit  $R$ , Explicit  $C + D$ 
  - Deals well with chemical stiffness
  - Challenged by explicit diffusional stability
- Operator-Split:  $C_{\Delta t/2} D_{\Delta t/2} R_{\Delta t} D_{\Delta t/2} C_{\Delta t/2}$ 
  - Explicit  $C$
  - Explicit Runge Kutta Chebyshev (RKC)  $D$
  - Implicit  $R$

# Computational Performance – NERSC Franklin

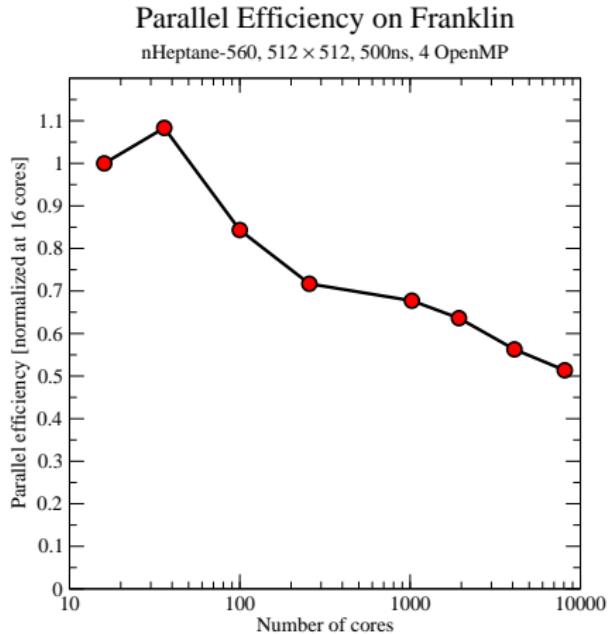
Cray XT4; 9,532 compute nodes; 2.3 GHz quad-core AMD Opt.

CPU Time per time step,  $512 \times 512$  mesh, 100 cores:

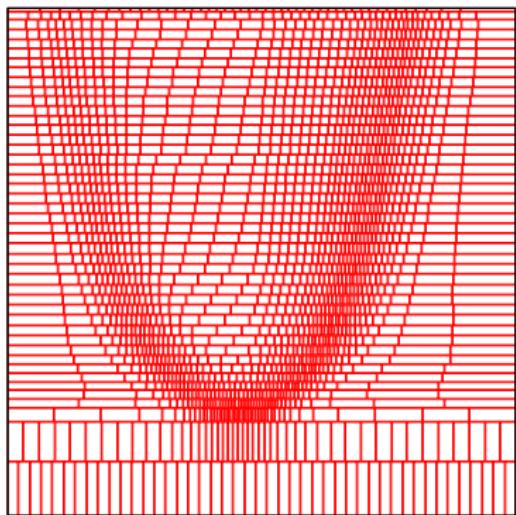
Mech	Parallelism	LINPACK	LAPACK	LAPACK <sup>opt</sup>	LAPACK <sup>opt</sup> <sub>nJ</sub>
M560	MPI/OpenMP	198 min	53 min	22 min	37 min
	MPI only	–	–	25 min	37 min
M139	MPI/OpenMP	79 sec	90 sec	56 sec	121 sec
	MPI only	–	–	67 sec	120 sec
M66	MPI/OpenMP	20 sec	21 sec	17 sec	33 sec
	MPI only	–	–	22 sec	33 sec

# Scalability – NERSC Franklin

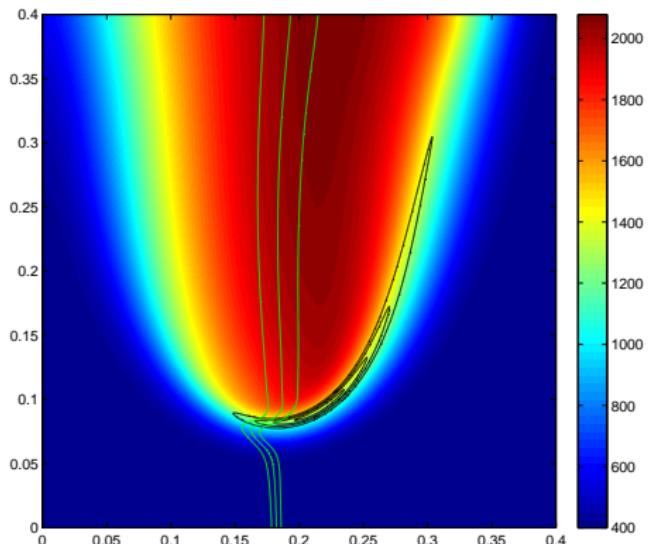
- 2D nHeptane edge flame
- 560 species, 2538 rxns
- Fixed  $512 \times 512$  mesh
- 51% parallel efficiency on 8000 cores



# nHeptane Edge Flame – M560 – NERSC Franklin



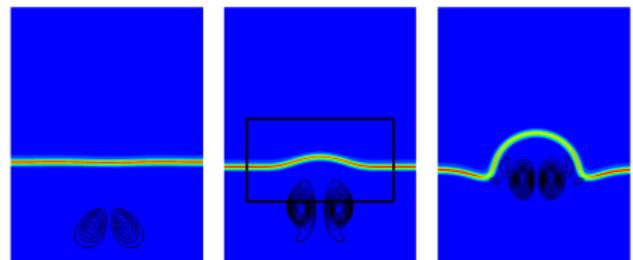
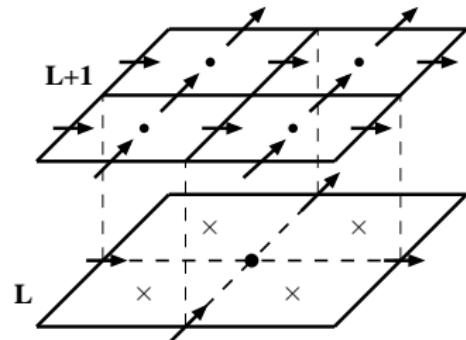
Domain Decomposition



Global Flame Structure

# Adaptive Mesh Refinement

- Structured mesh hierarchy
- Mesh libraries
  - Grace, Chombo
- High order spatial derivatives, interpolants, and filters
- Fourth-order low Mach reacting flow construction



# Current HPC Requirements — Franklin

- Typical problems
  - Methane-air premixed flame-vortex
  - nHeptane edge flame
- # cores: 500-2000
- Aggregate Memory : 24 GB
- I/O per Run: 20 GB, 6 GB checkpoint files
- On-Line Storage: 30 GB
- Software and Services:
  - DVODE/sundials, LAPACK, hypre, Chombo, NERSC Consulting, craypat
- Data Transfer: 80 GB/yr

# Current HPC Requirements — Primary codes

- **dflame:**

- 2D uniform mesh finite-difference Fortran-77
- $2^{nd}$ -order in space and time
- Projection scheme for momentum equations
  - FFT Poisson elliptic pressure solver
- Operator Split implicit/explicit time integration
- MPI+OpenMP parallelism

- **cfrfs:**

- 2D Structured Adaptive mesh finite difference
  - CCA + {C++, C, Fortran-77}
- $4^{th}$ -order in space,  $2^{nd}$  in time
- Projection scheme for momentum equations
  - hypre GMRES elliptic pressure solver
- Operator Split implicit/explicit time integration
- MPI parallelism

# Current HPC Requirements — Limitations

- **dflame:**
  - Uniform mesh
  - 50% strong scalability at 8000 cores
    - Need to evaluate if/how this can be improved
- **cfrfs:**
  - MPI but no OpenMp
  - Dynamic load balancing is more challenging
  - Have yet to explore scalability in the O(10) K core range

# Future HPC Requirements — 3-5 Years

- Methane/nHeptane/isoOctane edge and jet flames
- # cores:  $\sim 100K$
- 35M computational hrs
  - Presuming  $\sim 60\%$  parallel efficiency
- Aggregate Memory : 1-2 TB
- I/O per Run: 1-10 TB, 100-250 GB checkpoint files
- On-Line Storage: 3 TB
- Data Transfer: 10 TB/yr
- Archival Storage: 15 TB

# Impact of 50× NERSC Resources Now

- For a given mesh size, and  $N$  species:
  - Memory  $\propto N$
  - CPU  $\propto N^2$
- $N_{\text{nHeptane}}/N_{\text{methane}} \sim 10$

Factor of 50 enables doing roughly the same methane flame with detailed nHeptane models

Enables parametric runs of laboratory-scale laminar flames with detailed nHeptane chemistry

However, we need to address parallel efficiency before we could go beyond  $\mathcal{O}(10 K)$  cores