

The Derivation of Maximum Predicted Environments for Externally Carried Stores from a Small Number of Flight Tests*

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Outline

- **Purpose of Work**
- **Definition of Approach**
- **Raw Data Ensemble**
- **Scaling Model**
- **Homogeneous Ensemble**
- **Maximum Predicted Environment**



Purpose of Work

- **Stores that are carried externally on high performance aircraft are exposed to intense vibroacoustic excitation**
- **The best approach to quantify this environment is to perform flight tests using instrumented stores**
 - **However, flight tests are costly and therefore one almost never has data from repeated flights**



Purpose of Work

- **We needed to generate a Maximum Predicted Environment (MPE) having a 99% probability of occurrence and a 90% confidence (denoted as P99/90) using the data from 8 flights with 3-4 widely assorted test conditions per flight**
 - **A heterogeneous database does not lend itself to developing extreme statistical estimates of the MPE**



Definition of Approach

- **This study will focus on the straight and level flight events associated with a single station on one type of aircraft**
 - The primary remaining source of variation is the wide range of flight conditions
- **The solution was to create a model that could extrapolate the data for any given flight condition to any other flight condition**
 - The selected model was based on the fact that References [1,2] indicated that the rms vibration was linearly proportional to the dynamic pressure (Q)



Definition of Approach

- If all of the data lay exactly on a linear curve relating Q and Grms then one could infer that there was no flight-to-flight variability
- Conversely, the differences between the raw data points and the linear Q curve are assumed to represent the flight-to-flight variability
 - Measurement errors and small differences in aircraft configuration will introduce “phantom” variability

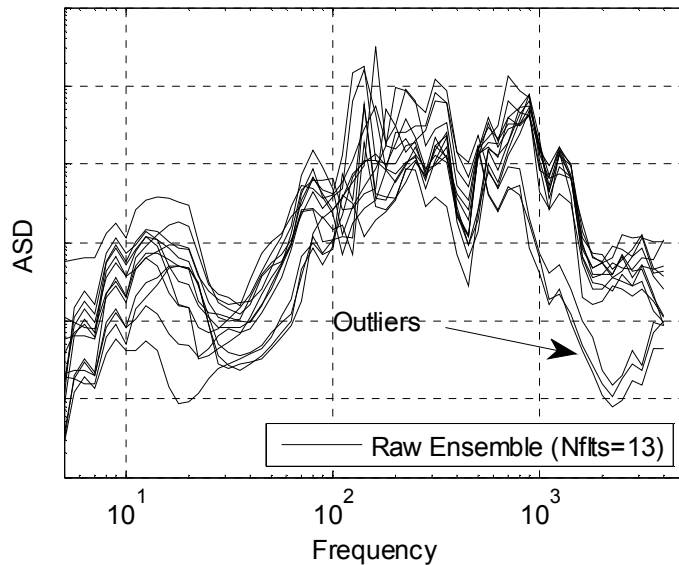


Raw Data Ensemble

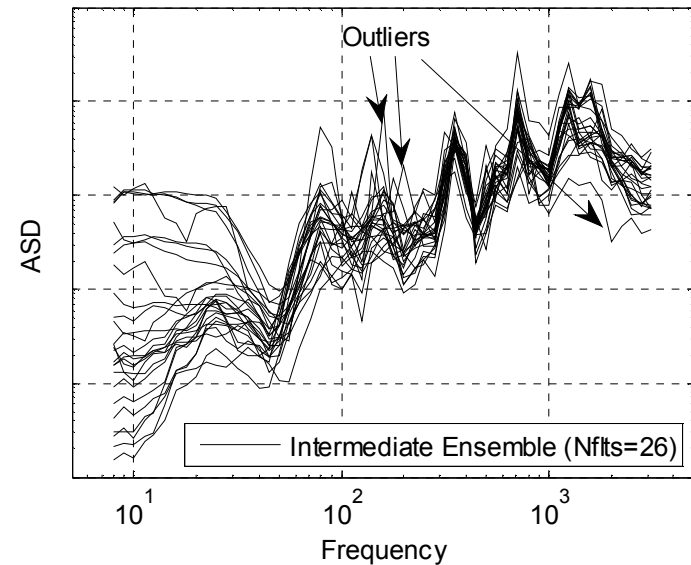
- **Upwards of 25-30 straight and level flight events were available**
 - The available data were ranked according to the dynamic pressure, Q
 - Mach number was also tracked as a possible model parameter but no discernible pattern was observed
- **The ensembles had some uncertainty**
 - The measurement locations were not always obvious
 - The upper cut-off frequency may have changed over time
- **The ensembles were scrubbed and obvious outliers were removed**

Raw Data Ensemble

Major Outliers



Minor Outliers

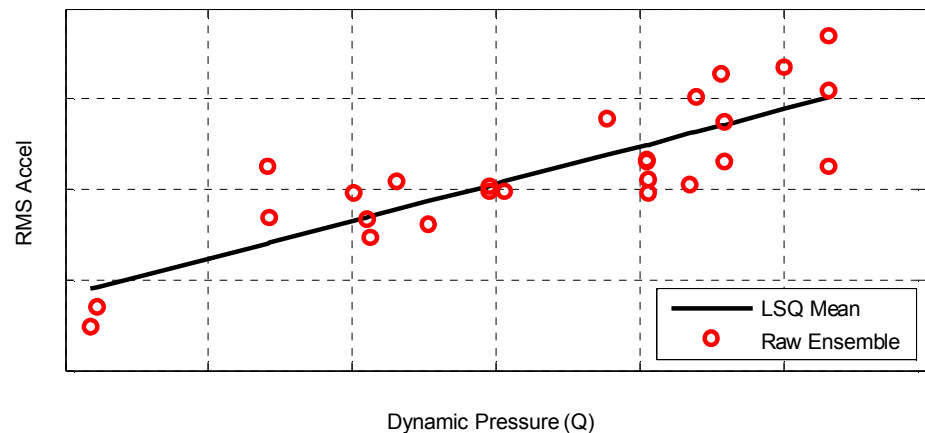


ASDs with major outliers were completely removed from ensemble
ASDs with minor outliers only have the narrow band anomaly removed

Scaling Model

- The decision was made to start with a simple first order model relating the rms G to the dynamic pressure, Q
 - Used rms G instead of the ASDs because the scrubbed ensemble of ASDs have a similar spectral content
 - The y-intercept was set to zero (in reality it should have a small positive value due to engine noise)

$$G_{MN} = m_{MN} Q$$



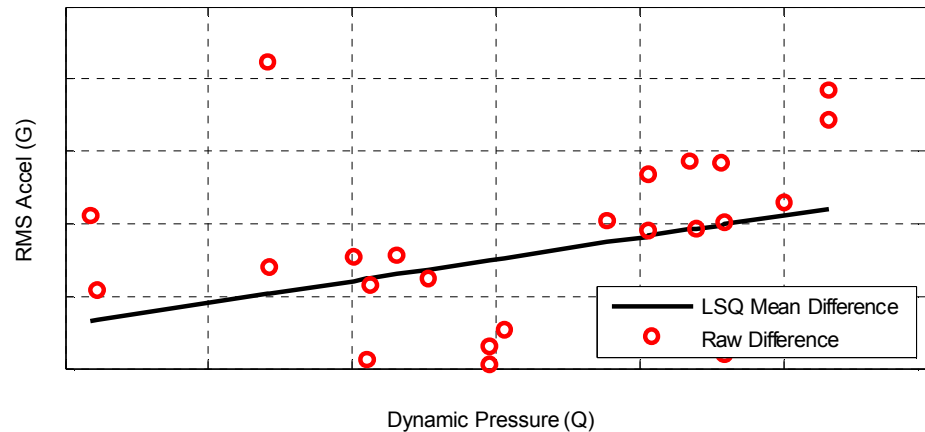
Scaling Model

- There appeared to be some dispersion that increased proportional to Q so the difference between the measured values of the rms G and the mean rms G was also fit with a first order linear model

$$G_{DF} = m_{DF} Q$$

Where

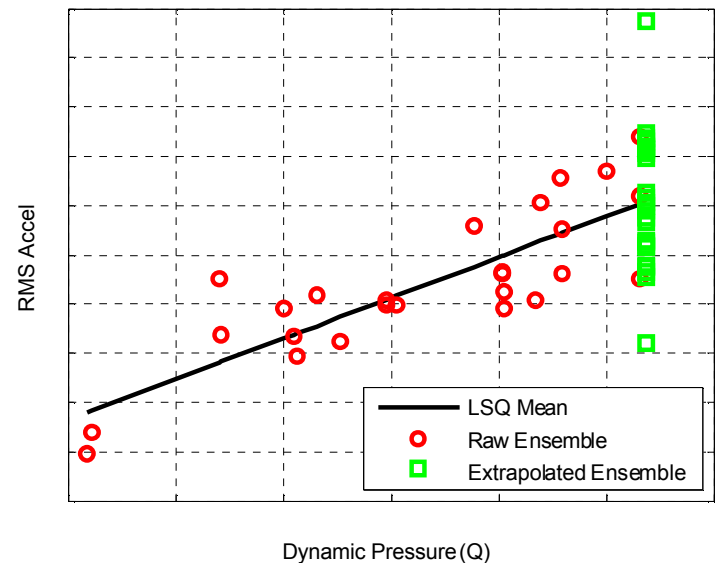
$$m_{DF} = (G_{MEAS} - G_{MN}) / Q$$



Extrapolated Ensemble

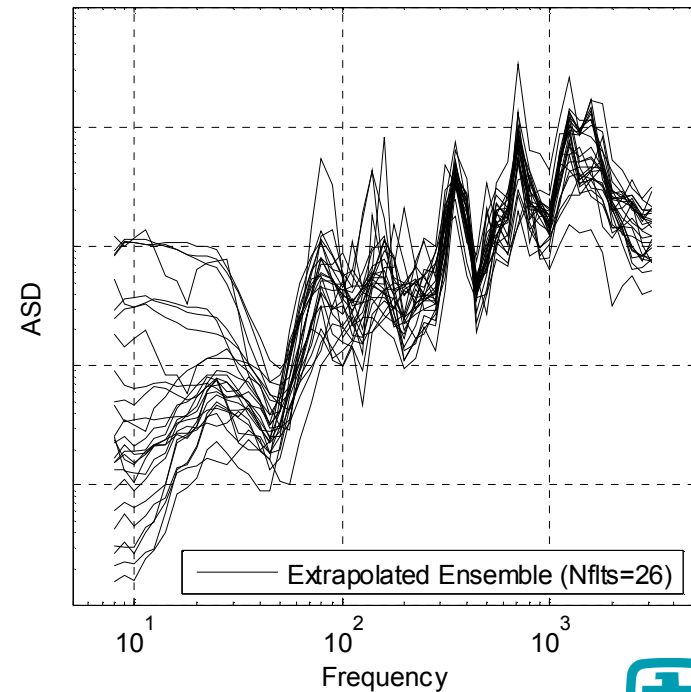
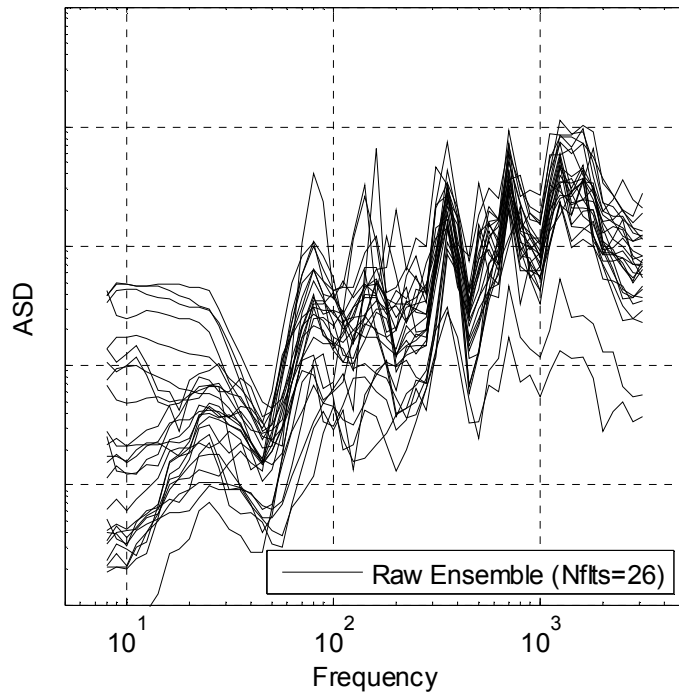
- The extrapolated Grms values, G_E , for the desired dynamic pressure, Q_E , were computed from the corresponding raw values, Q_R and G_R

$$G_E = G_R + m_{MN}(Q_E - Q_R) + m_{DF}(Q_E - Q_R)$$



Extrapolated Ensemble

- The raw ASDs were scaled to match the extrapolated Grms values
 - If the process is working the variance in the ensemble should be reduced





Maximum Predicted Environments

- The final step was to generate the MPE responses
- Based on guidelines in NASA 7005 [3] the extrapolated ASDs, S_{XX} , were assumed to be lognormal distributed
 - The mean is computed as

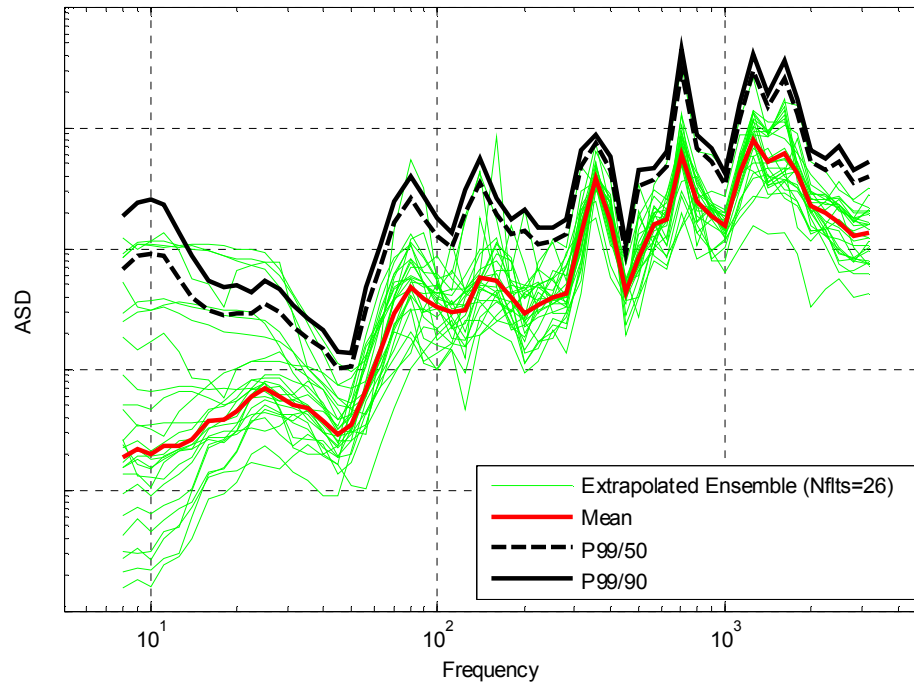
$$S_{XXM} = 10^{(\text{mean}(\log(S_{XX})))}$$

- The response for a given probability and confidence is computed as

$$S_{XXU} = 10^{(\text{mean}(\log(S_{XX})) + k * \text{std}(\log(S_{XX})))}$$

- Where k is defined in NASA 7005

Maximum Expected Environments





Summary

- **The extrapolation model presented in this study is considered to be a useful tool for developing statistically significant MPEs for a sparse data set**
- **In the future we intend to gather more test conditions spanning the possible range of flight conditions**
 - **Special attention will be given to gathering data that can be used to determine if the Mach number should be included in the scaling model**
- **It might be appropriate to use a non parametric statistical model such as Karhunen-Loeve**
- **Consider performing the analysis using the ASDs rather than the rms G**



References

- **[1] MIL-STD-810E; "Environmental Test Methods and Engineering Guidelines."**
- **[2] Technical report AFFDL-TR-71-158; "Vibration and Acoustic Test Criteria for Captive Flight of Externally Carried Stores"**
- **[3] NASA Handbook 7005; "Dynamic Environment Criteria"**