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Automatic Volume-Tracking Reconstruction of Interfaces in Multi-material Elements

R. M. J. Kramer and S. J. Mosso

Sandia National Laboratories, Albuquerque, NM

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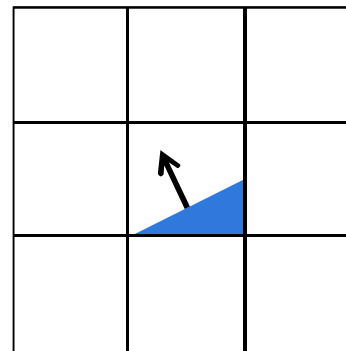


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Interface Reconstruction

- Young's Method for interface reconstruction (1982):
 - Volume-of-fluid method: discretely mass conserving
 - *Only data available for reconstruction are the volume fractions*
 - Interface normal computed from gradient of volume fraction

0.0	0.0	0.0
0.0	0.4	0.8
0.8	1.0	1.0

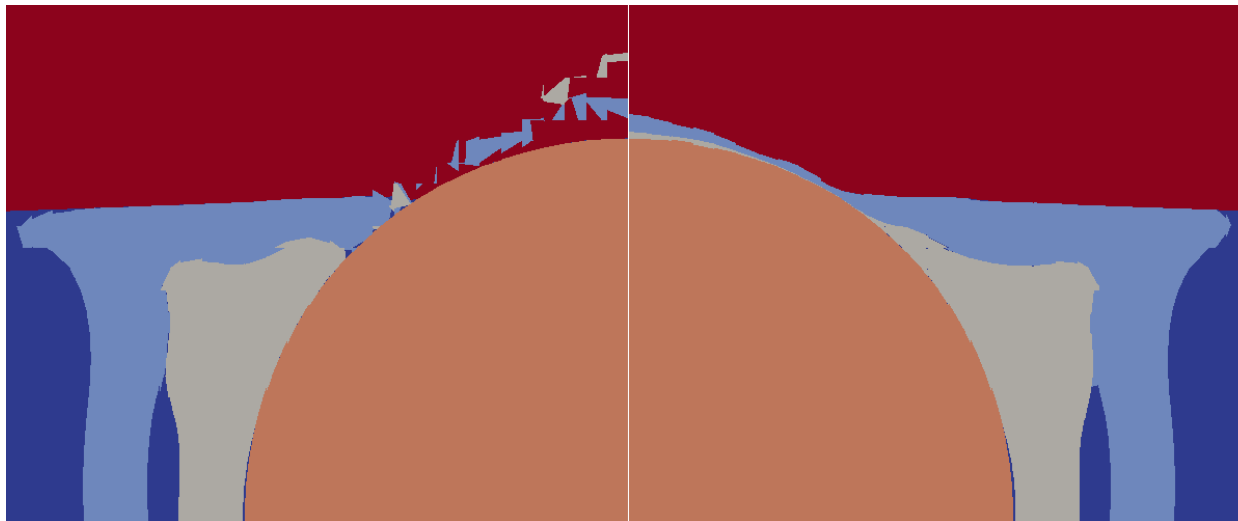


$$\mathbf{n} = -\nabla V$$

- For more than two materials, an ordering is required
- Extended to allow intersecting and terminating interfaces by selective gradient calculation (Mosso & coworkers)
 - Pattern Interface Reconstruction (PIR)

The XFEM in ALEGRA

- ALEGRA: multiphysics Arbitrary Lagrangian-Eulerian simulation software developed at Sandia
- The eXtended Finite Element Method for material interfaces:
 - Enrichment of velocity field for each material
 - Effectively an adaptive refinement technique: material interfaces are resolved in multi-material elements, avoiding mixed-material models
- XFEM demands accurate interface reconstruction

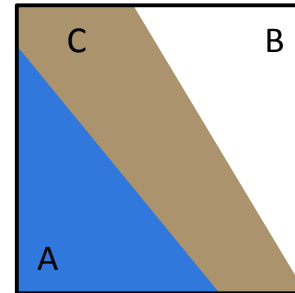
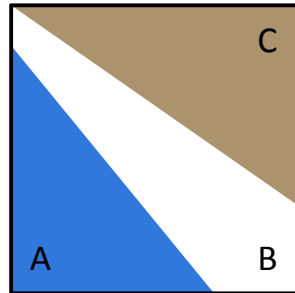


The Ordering Problem

- A-B-C or A-C-B? Accumulate volume fractions?
 - Each interface is computed from an A | not A proposition

$$\mathbf{n}_A = -\nabla V_A$$

$$\begin{aligned}\mathbf{n}_B &= -\nabla(V_A + V_B) \\ &= \nabla V_C\end{aligned}$$



$$\mathbf{n}_A = -\nabla V_A$$

$$\begin{aligned}\mathbf{n}_C &= -\nabla(V_A + V_C) \\ &= \nabla V_B\end{aligned}$$

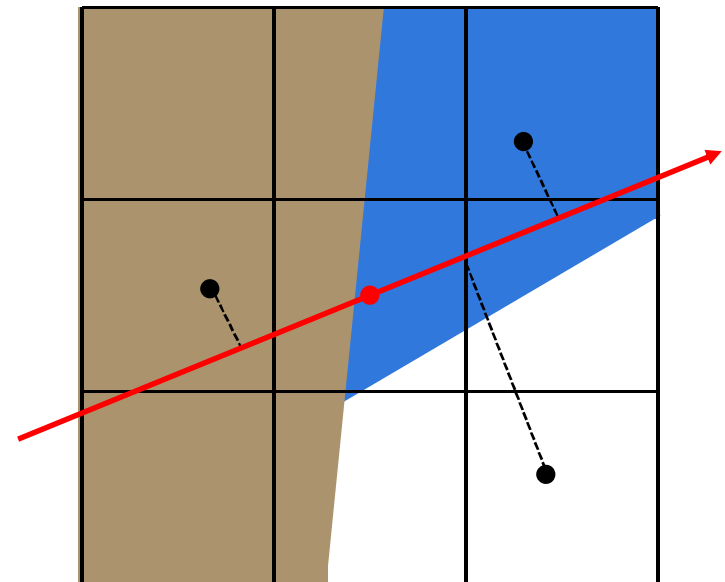
- For N materials, there are $(N-2)N!$ ordering combinations
 - Quickly becomes burdensome for users running complex problems
- Automatic ordering: Mosso & Clancy (1994), Benson (1998)

Manual Priorities	Automatic Priorities
Specified by user	No <i>a priori</i> input required
Global material ordering	Local material ordering
Static	Dynamic

Algorithm (2-D)

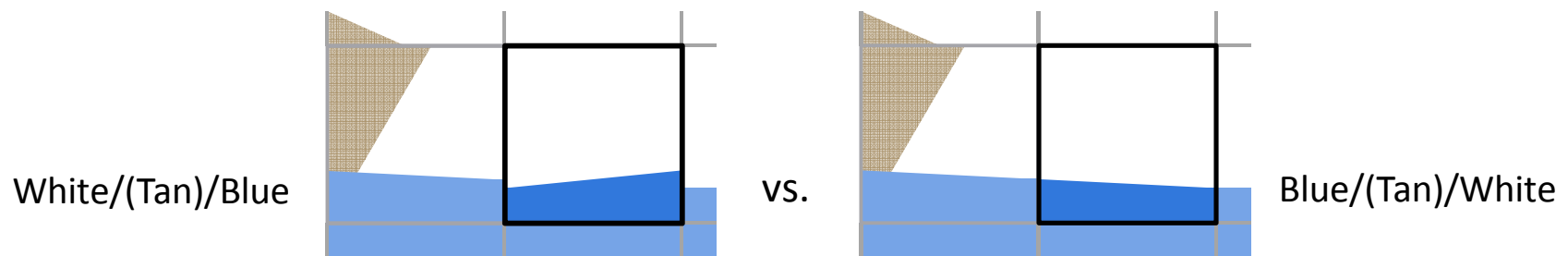
1. Calculate local material centroid approximations
 - Approximate materials as located at centroid of each neighbor
2. Fit a line to the centroids
 - Volume-fraction weighted least squares fit
 - Perpendicular distance regression for grid independence
3. Define ordering by distances along line of projected material centroids
 - Choice of ordering direction: material closest to the line determines direction
4. For certain cases, modify ordering or gradient to improve interfaces
 - Choice of gradient approximation:

$$-\nabla V_f \quad \text{or} \quad -\nabla (\sum V_f)$$

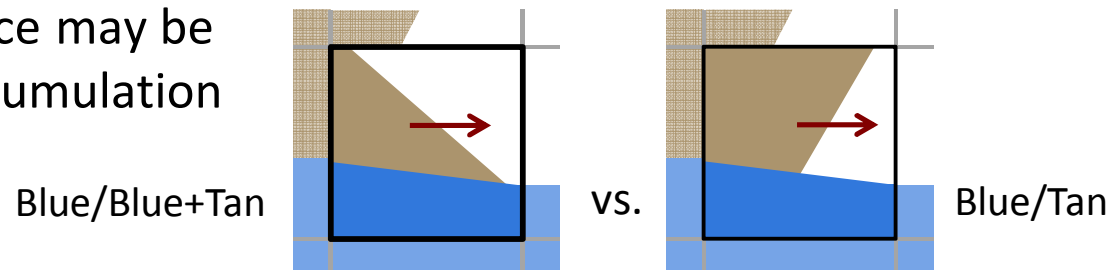


Ordering 'Fixes'

- Effectively a low-order smoothing: improving gradients
- Ordering direction choice:
 - Largest volume material usually closest to the line, ordered first
 - Can be distorted by appearance of another material in neighborhood

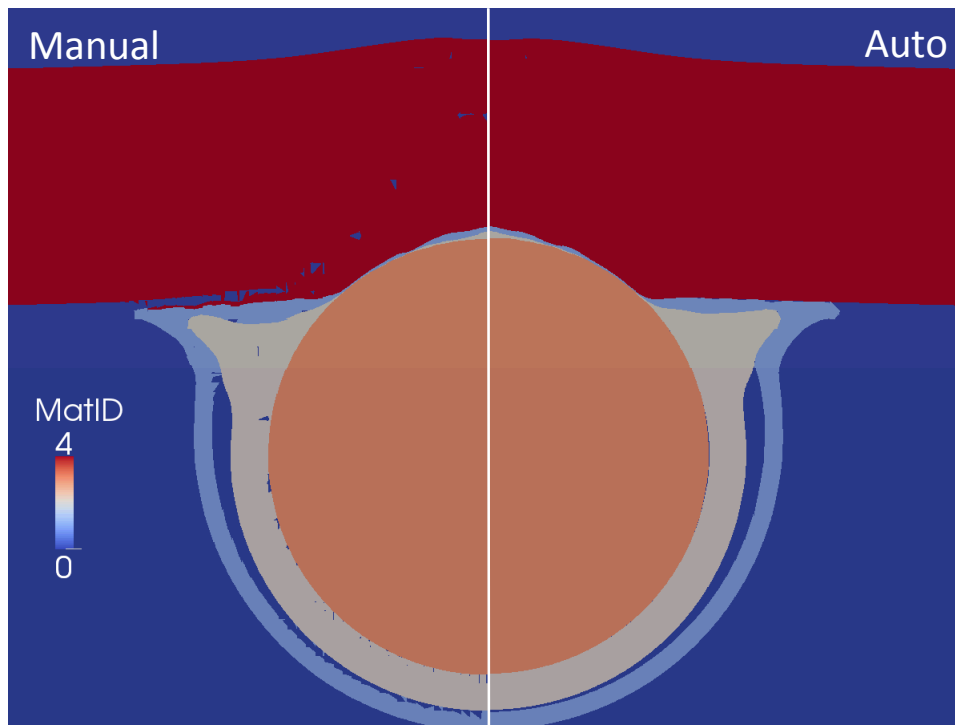


- Accumulating gradient choice at T-intersections:
 - Usually accumulation is best for the second material (e.g., layers)
 - Terminating interface may be 'better' without accumulation

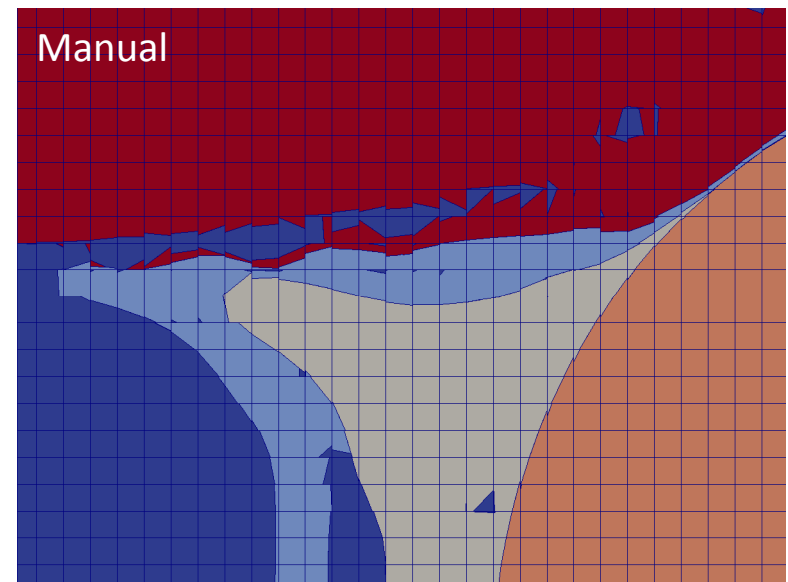
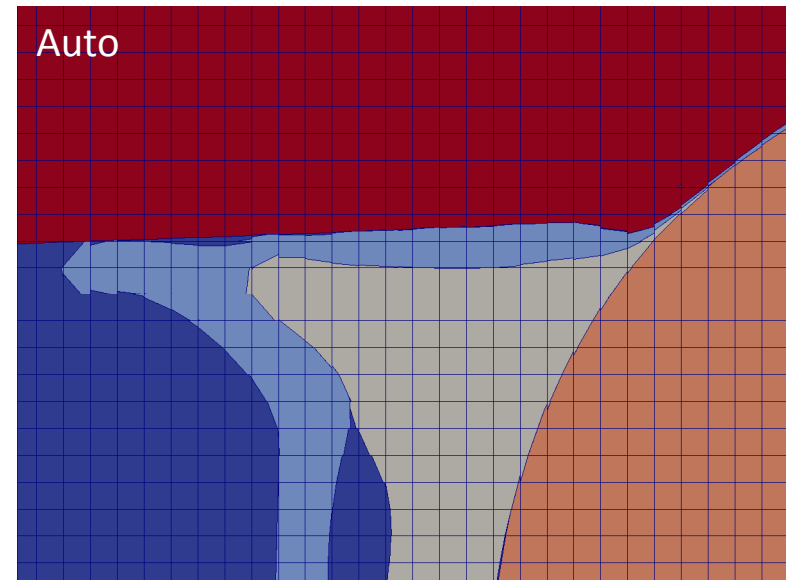


An Example

- Nested spheres striking a plate
- 4 materials + void



$$V_{\text{impact}} = 427 \text{ m/s}$$

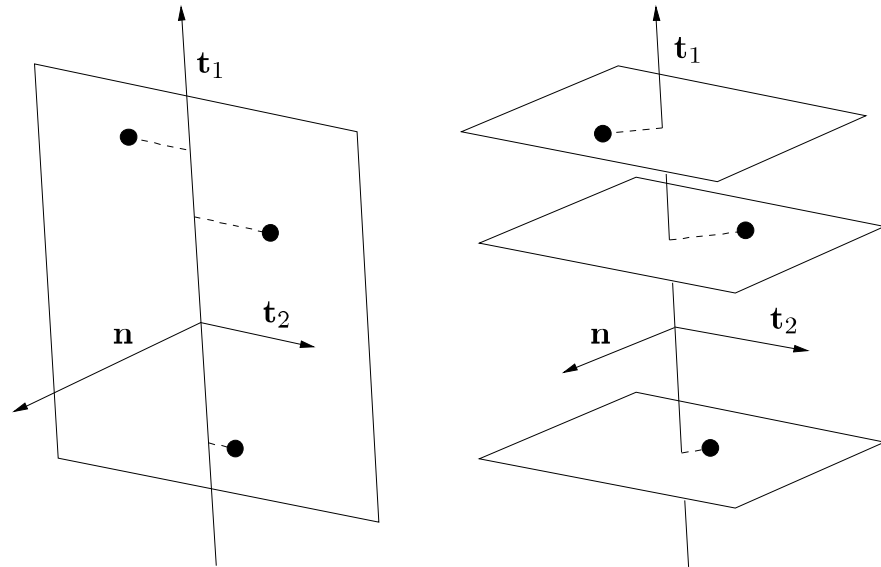


Extension to 3-D

- Need an ordering direction: start by fitting a basis

- Error equation:
normal of the plane
- Residual equation:
tangential direction

- Extreme points coincide to define the basis directions

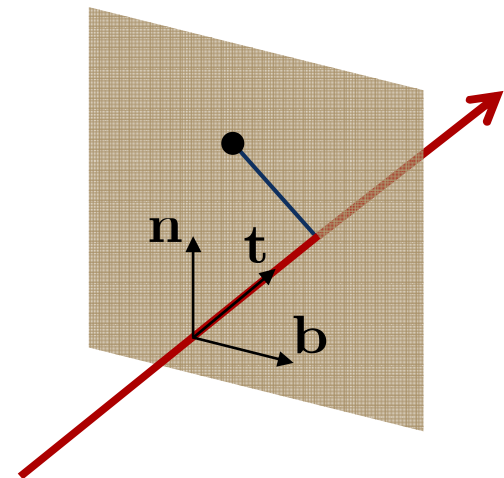


$$\text{SSE} = \sum_{m=1}^M w_m \left[(x_m - \hat{x}_m)^2 + (y_m - \hat{y}_m)^2 + (z_m - \hat{z}_m)^2 \right] = R_n$$

$$\text{SSR} = \sum_{m=1}^M w_m \left[(\hat{x}_m - \bar{x})^2 + (\hat{y}_m - \bar{y})^2 + (\hat{z}_m - \bar{z})^2 \right] = R_t$$

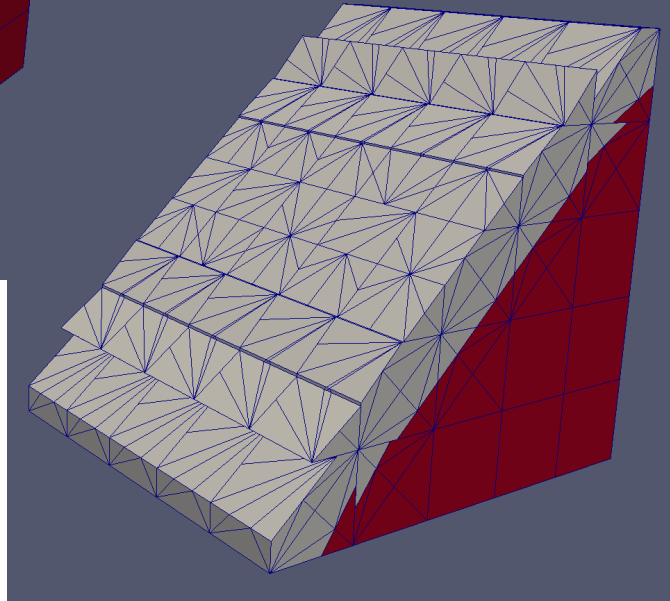
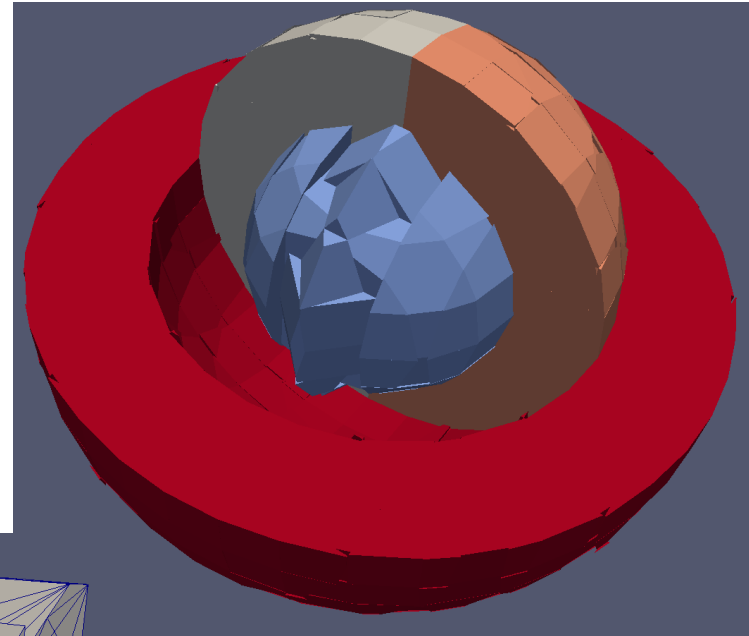
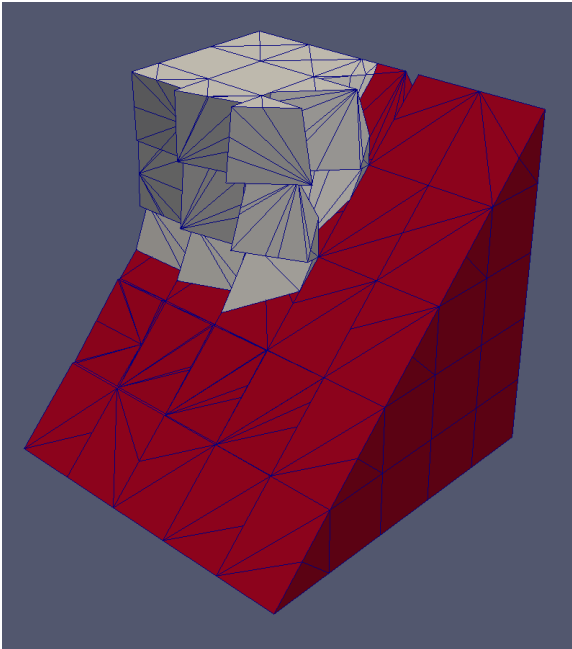
Algorithm (3-D)

1. Calculate local material centroid approximations
2. Fit a basis to the centroids
 - Newton method for initial solution, then complete the basis
 - Fail-safe sequence to ensure a solution is found
3. Identify tangential direction (ordering line)
4. Define ordering by distances along line of projected material centroids
 - Same logic as 2-D, based on distance on the intersection plane
5. Modify ordering if necessary
 - Accumulation flag at T-intersections



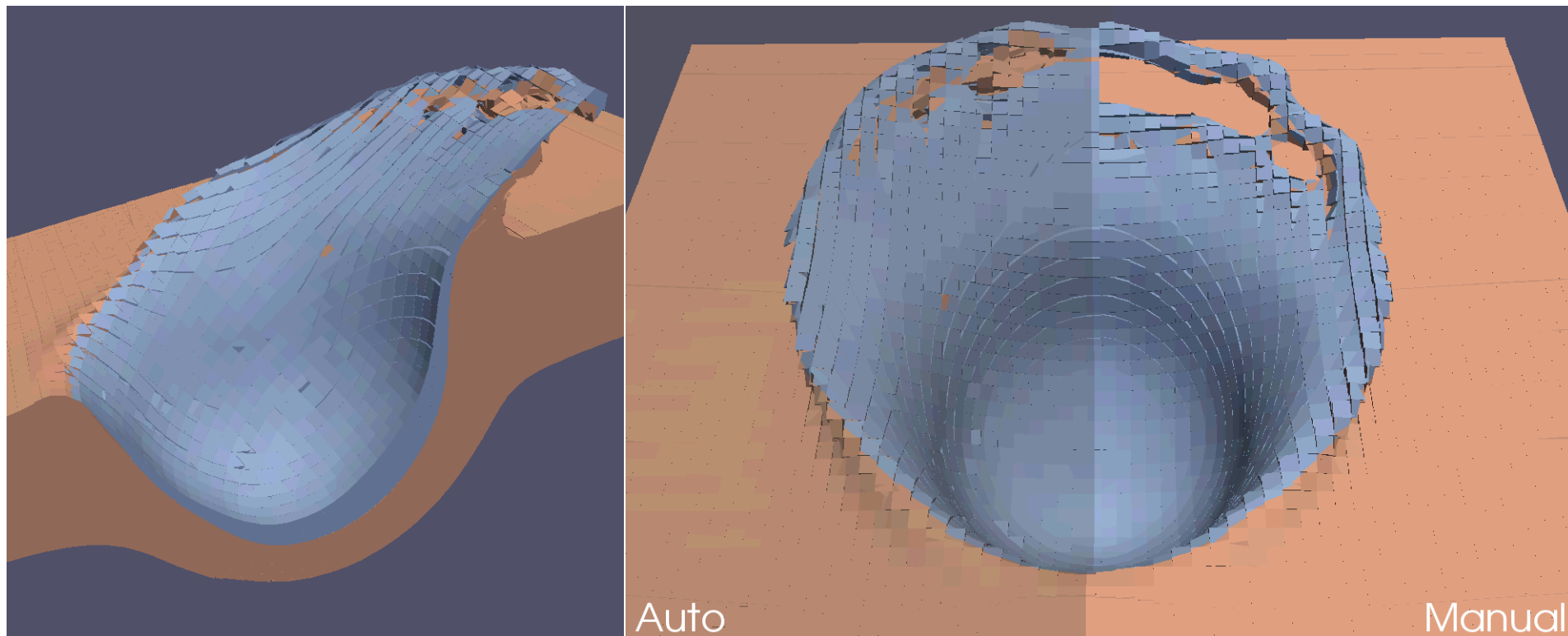
3-D Demonstrations

- Verification tests



3-D Results

- Preliminary demonstration: Whipple shield



- An enabling feature for 3-D Eulerian XFEM in ALEGRA