

Remeshing and mapping of internal state variables in large deformation processes

Sofie Leon

Mechanics of Materials
Intern

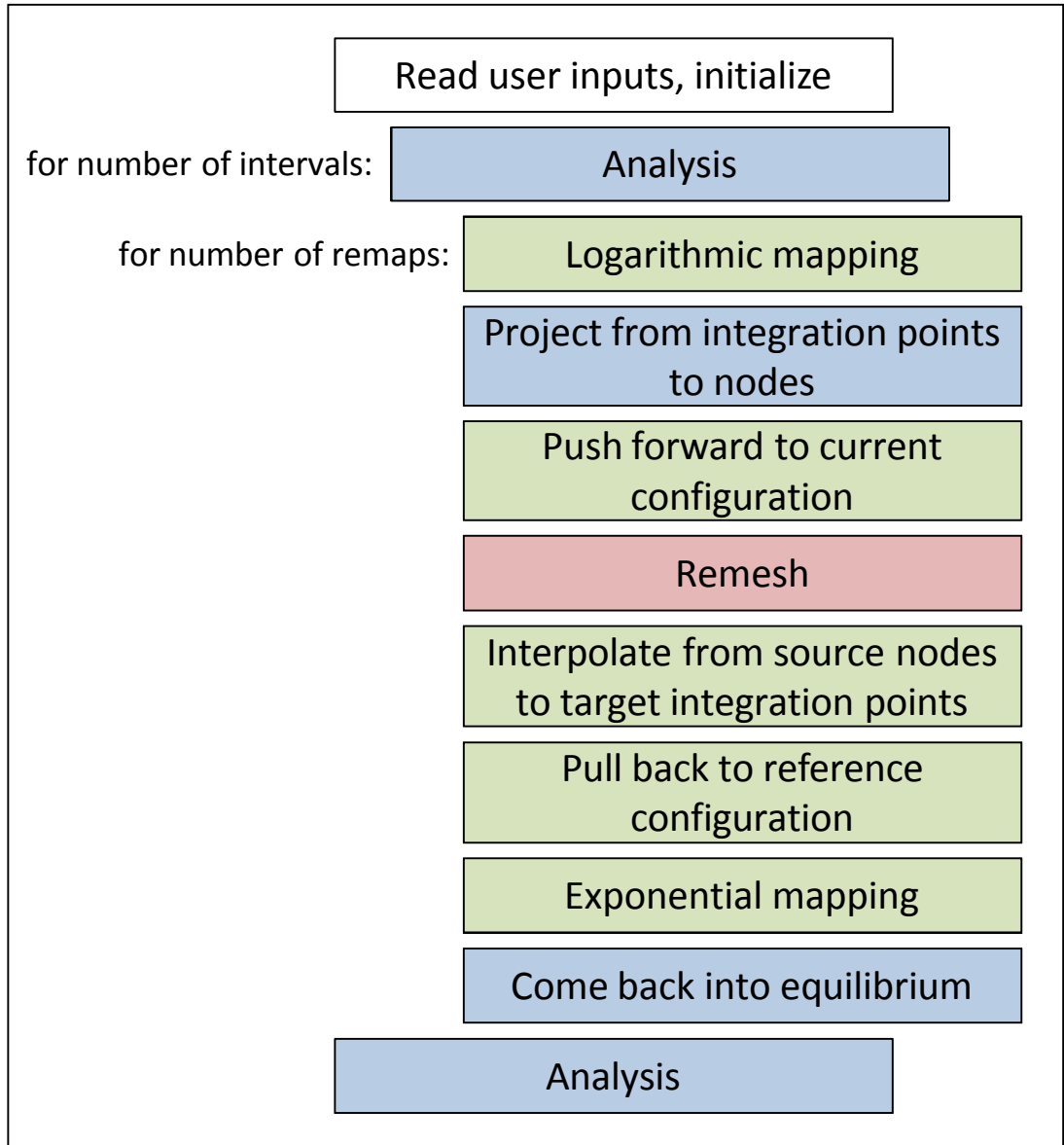
Supervisor: Jay Foulk

Internship summary
Sandia National Laboratory
Livermore, California

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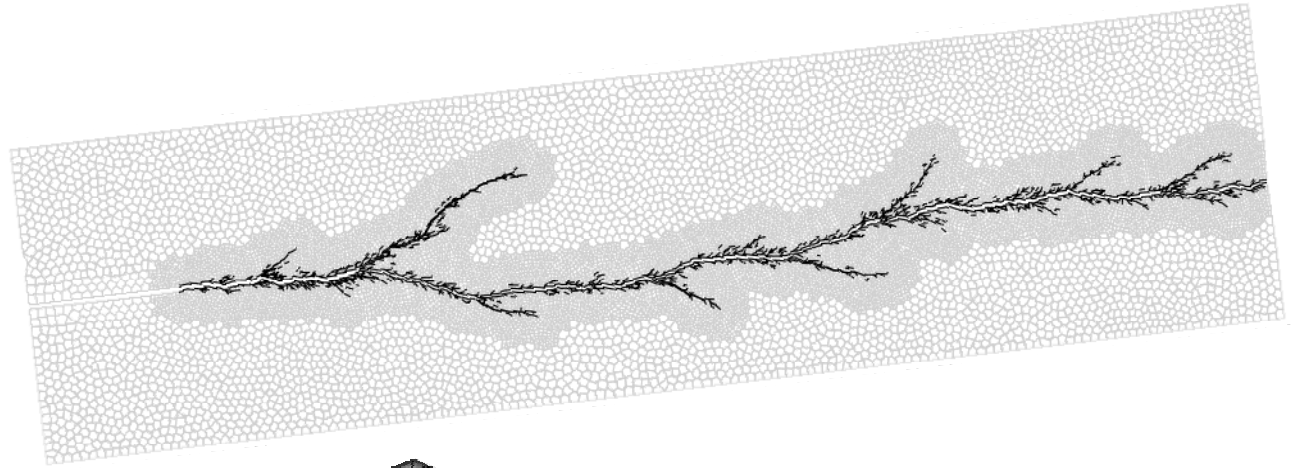


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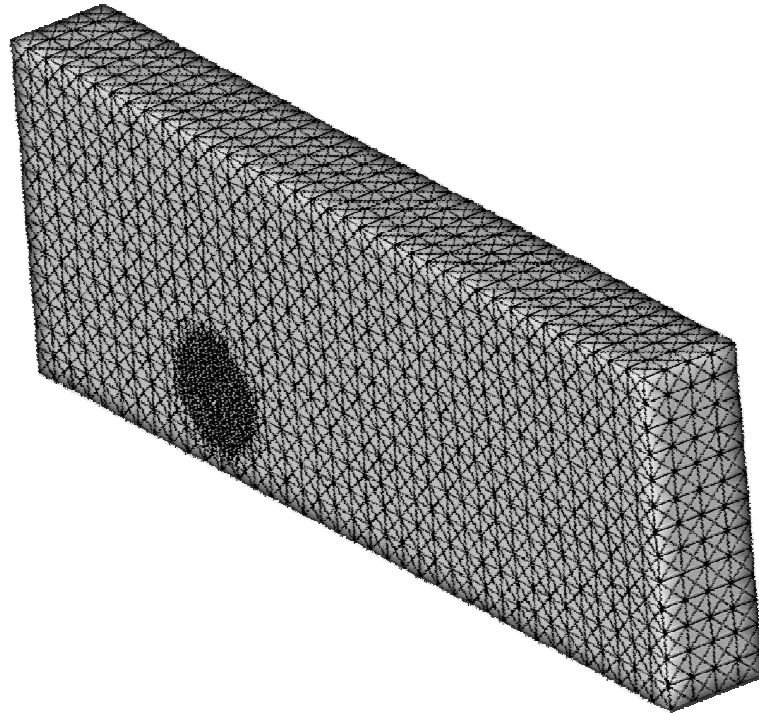


My own research interest is to model crack propagation in large systems with adaptive mesh refinement and coarsening

In my PhD research, I perform dynamic fracture simulation of quasi brittle materials using adaptive mesh operators.



We would like to also investigate crack propagation in materials with internal state variables, but during adaptivity, they would need to be mapped appropriately from one mesh to another.

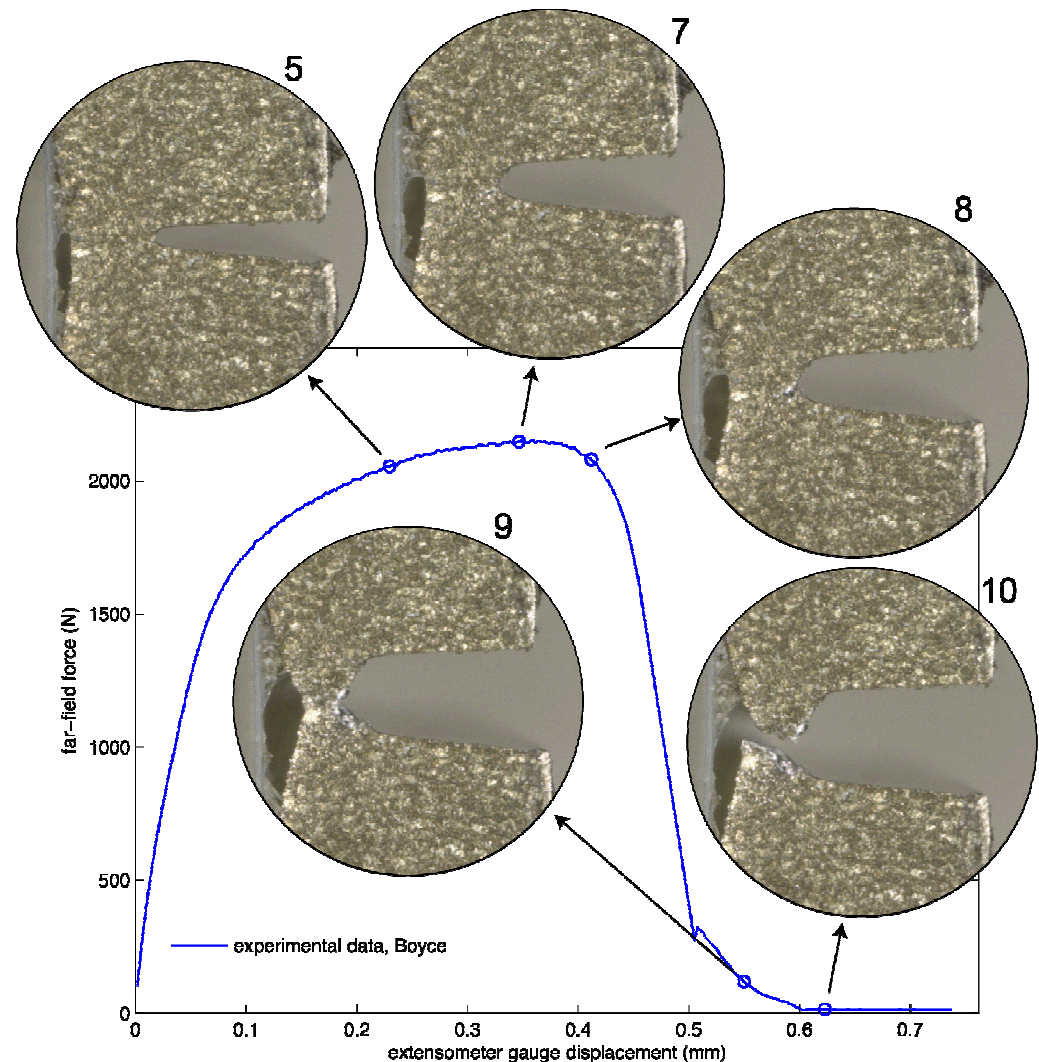
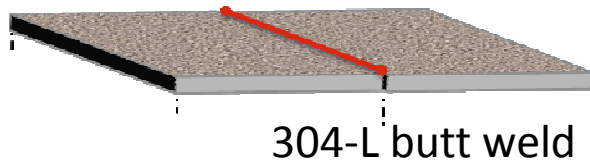


We want to predict the failure of extremely tough material

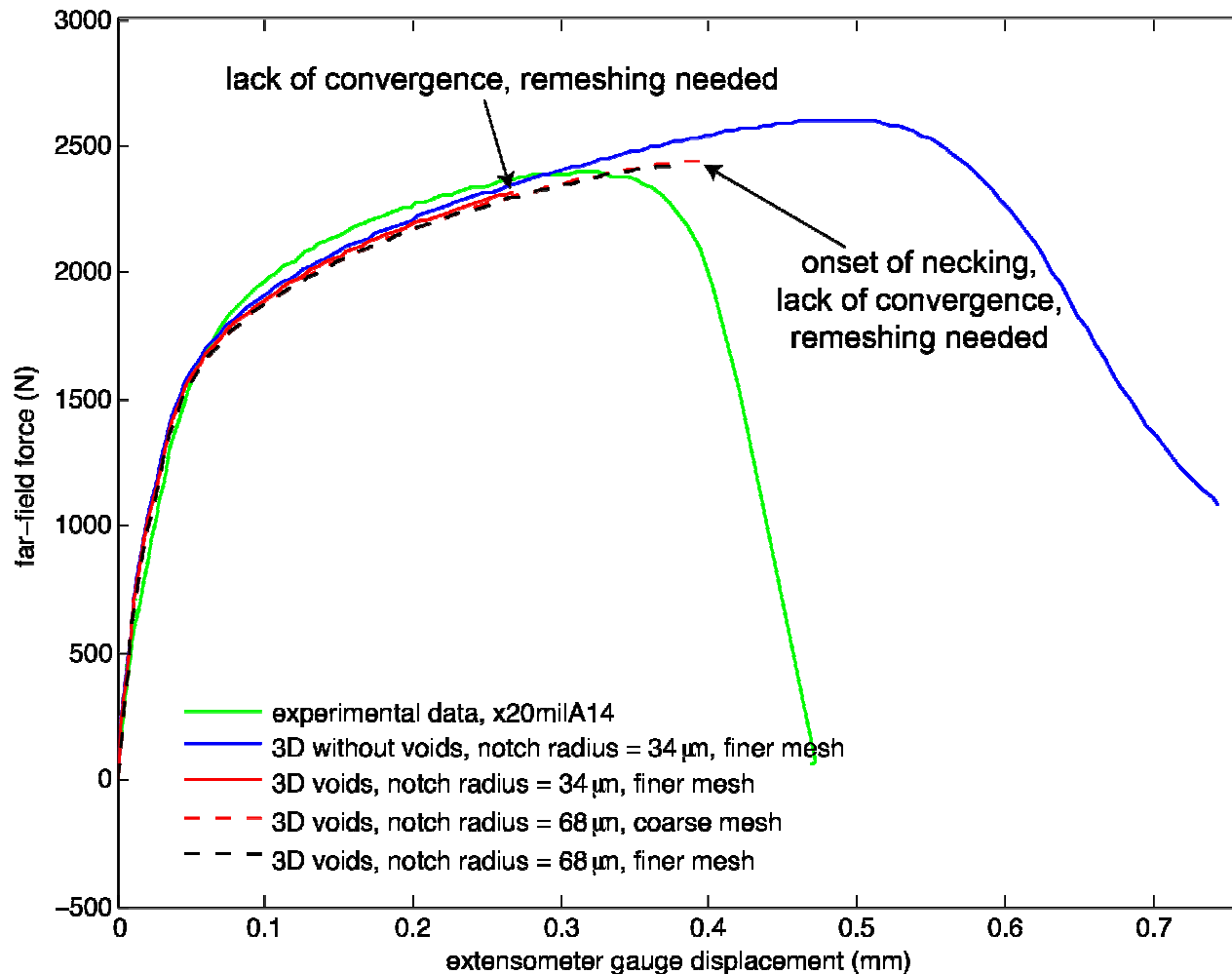
Failure of 304L laser weld is characterized first by necking, then free surface creation is a secondary effect

304L is extremely tough and damage tolerant

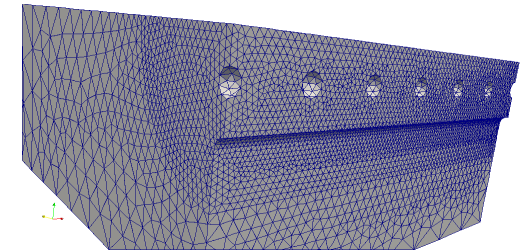
Hypothesis is that void size and distribution within the weld plays a large role in the necking process



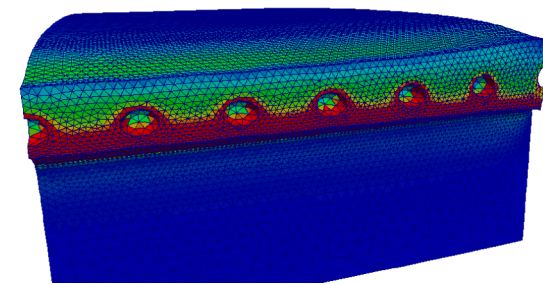
Convergence in the load displacement at onset of necking is not achieved, which may be due to element distortion



Idealized 3D voids



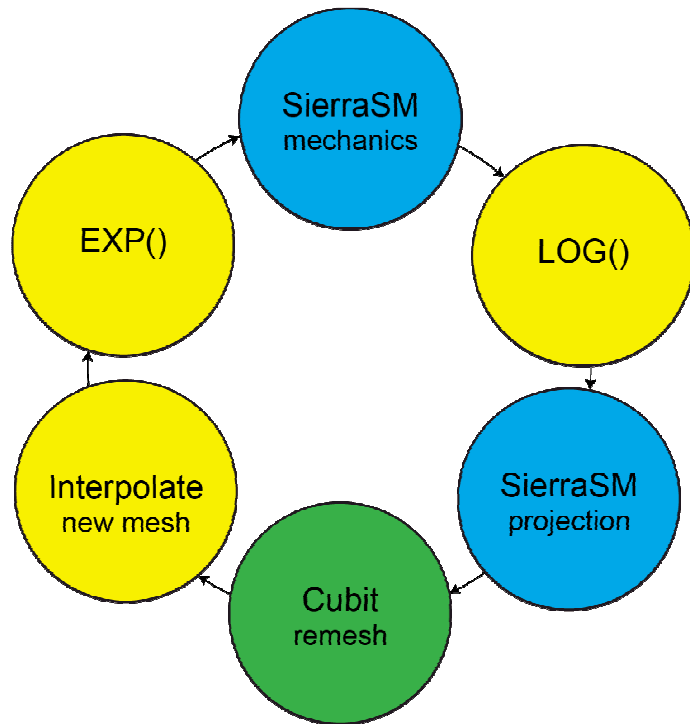
Onset of necking



Remeshing would eliminate element distortion and make convergence possible

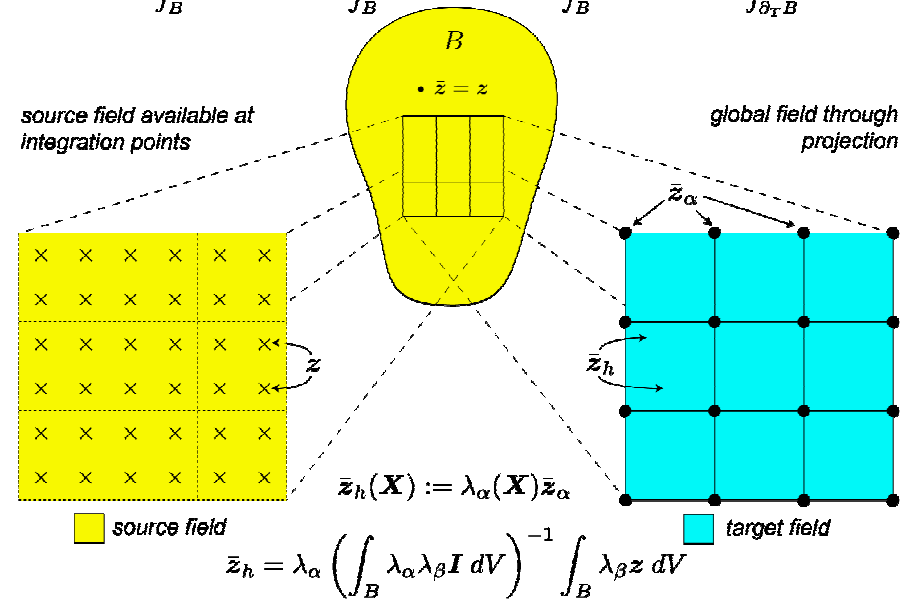
The proposed mapping scheme involves a global L2 projection and Lie-Group interpolation

Overall scheme



Projection from integration points to nodes, then the field is known everywhere

$$\Phi[\varphi, \bar{z}, \bar{y}] := \int_B W(F, \bar{z}) dV + \int_B \bar{y} \cdot (\bar{z} - z) dV - \int_B \rho_0 \mathbf{B} \cdot \varphi dV - \int_{\partial_T B} \mathbf{T} \cdot \varphi dS$$



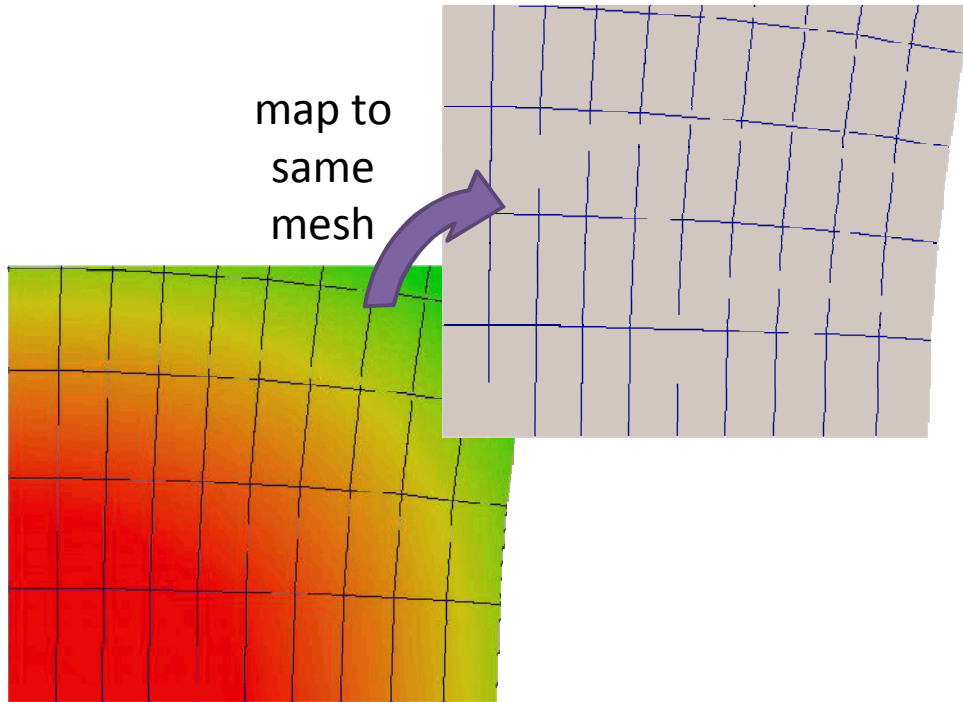
Certain internal variables are members of a Lie Group, which does not admit addition as an operator, therefore we map the Lie Group to its Lie Algebra, then perform the projection and interpolation, then map back to the Lie Group

The remapping studies aim to address some fundamental questions

- How much numerical dissipation does the remapping scheme induce?
- Does the remapping scheme push the system far out of equilibrium? Is it significant?

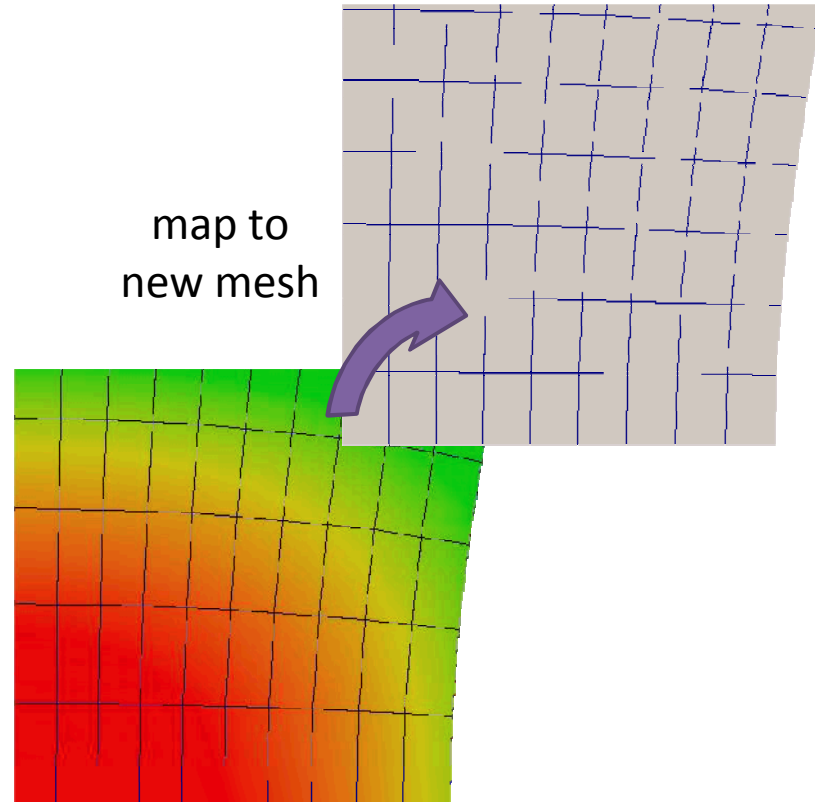
Keep mesh constant and perform mapping from deformed mesh to itself

map to
same
mesh



Remesh after some time and map from the old mesh to a new mesh

map to
new mesh

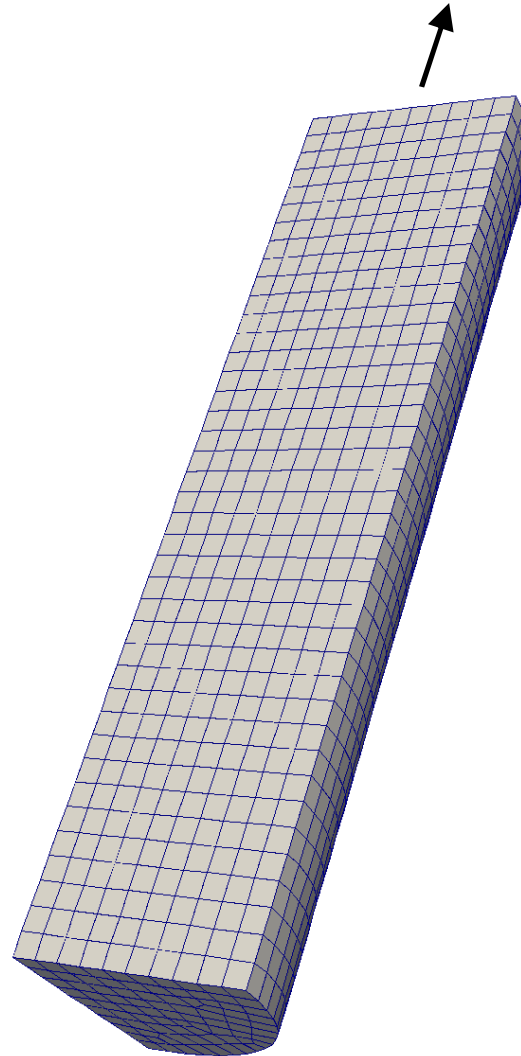


Uniaxial tension of a smooth bar is the representative problem for the numerical studies

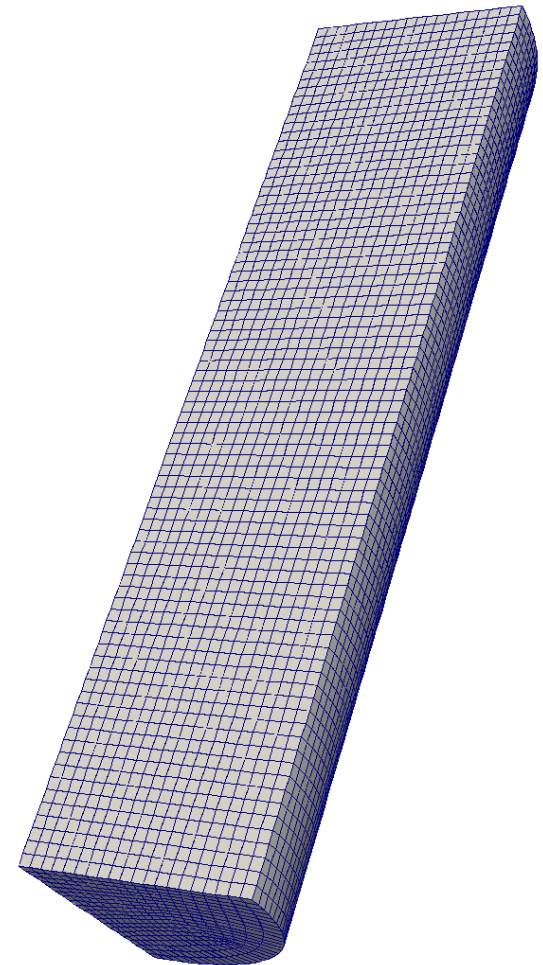
Deformation of a circular bar under far-field tension

Coarse and fine hex8 meshes are investigated

We remesh and map internal state variables to resolve the necking process

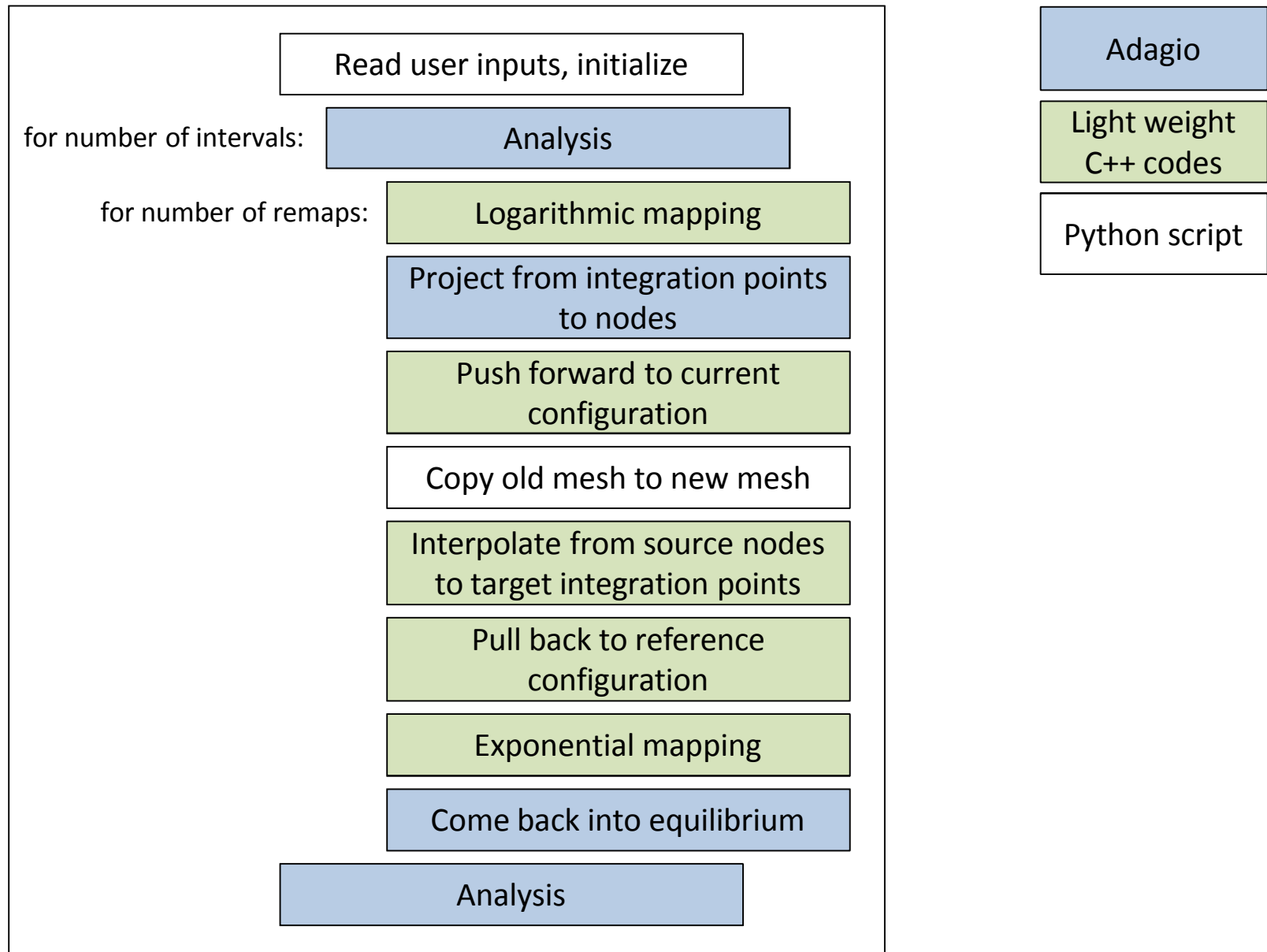


coarse mesh, 10
elements across
thickness



fine mesh, 20
elements across
thickness

Remapping procedure is automated with a python script



Implementation issues in the projection and interpolation were uncovered in the automated remapping process

First problem – After projection the logged rotations were not skew symmetric

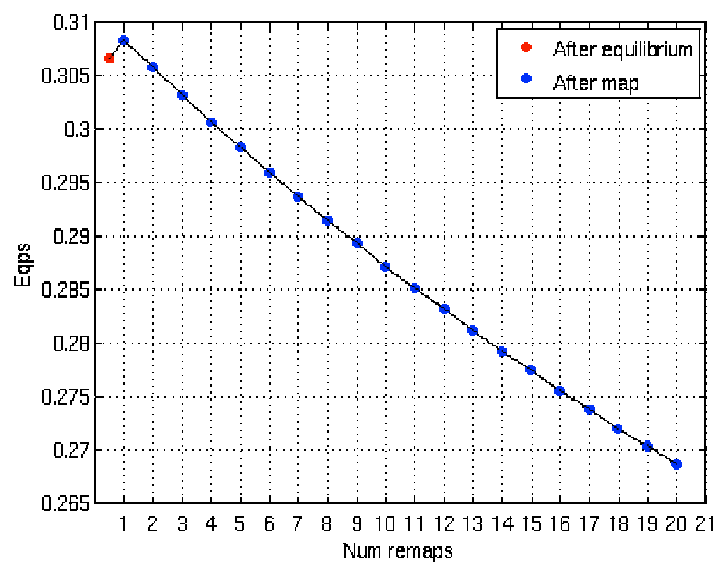
$$\mathbf{R} \in SO(3) = \left\{ \mathbf{A} \in M(n) \mid \mathbf{A}\mathbf{A}^T = \mathbf{I}, \det \mathbf{A} = 1 \right\}$$

Log Rotation

$$\log \mathbf{R} \in so(3) = \left\{ \mathbf{B} = M(n) \mid \mathbf{B} = -\mathbf{B}^T \right\}$$

Project to nodes

$$\log \mathbf{R} \neq -\log \mathbf{R}^T$$



Second problem - Dissipation in internal variables between consecutive remaps due to interpolation

Implementation issues in the projection and interpolation were uncovered in the automated remapping process

First problem – After projection the logged rotations were not skew symmetric

Solution - Tolerance on parallel iterative solver was too loose, switch to parallel direct solver

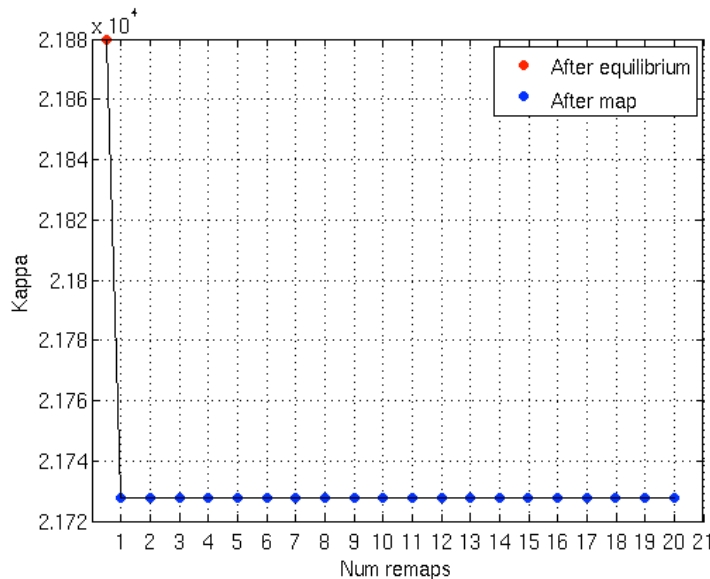
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Log Rotation

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Project to nodes

$$\log \mathbf{R} = -\log \mathbf{R}^T$$

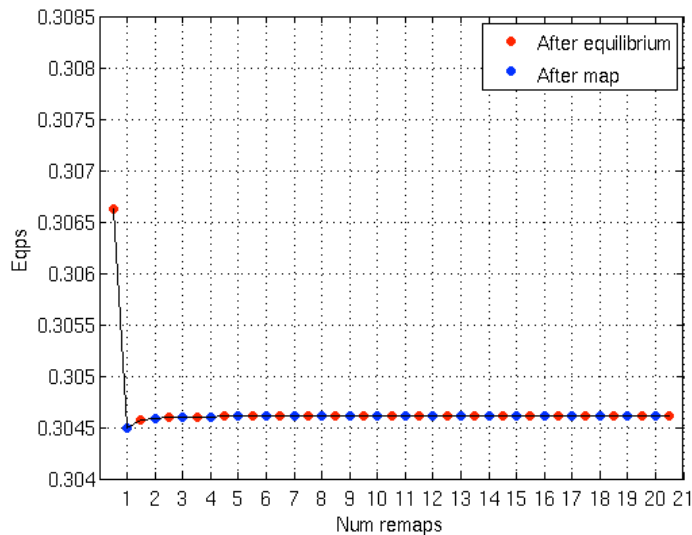


Second problem - Dissipation in internal variables between consecutive remaps due to interpolation

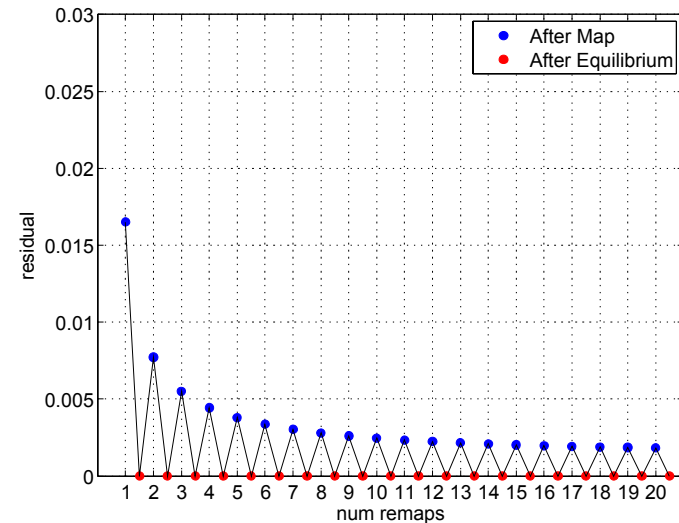
Solution – Numbering of integration points in adagio is different for different elements

Coming into equilibrium after each consecutive remap reveals that the mesh is not converged after remapping

Maximum equivalent plastic strain appears to converge



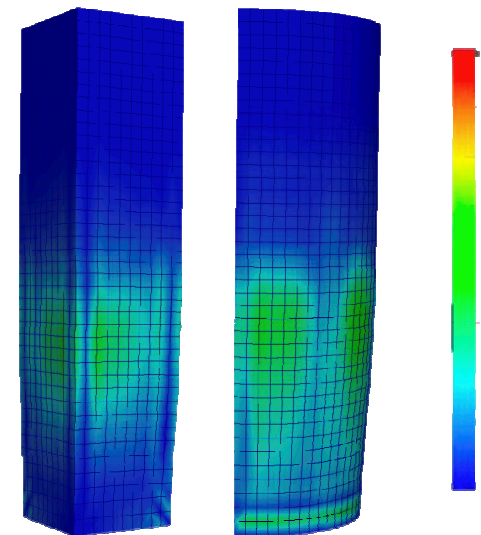
However, the residual reveals that remapping pulls the system out of equilibrium



The system comes back into equilibrium rapidly, i.e. only a few iterations.

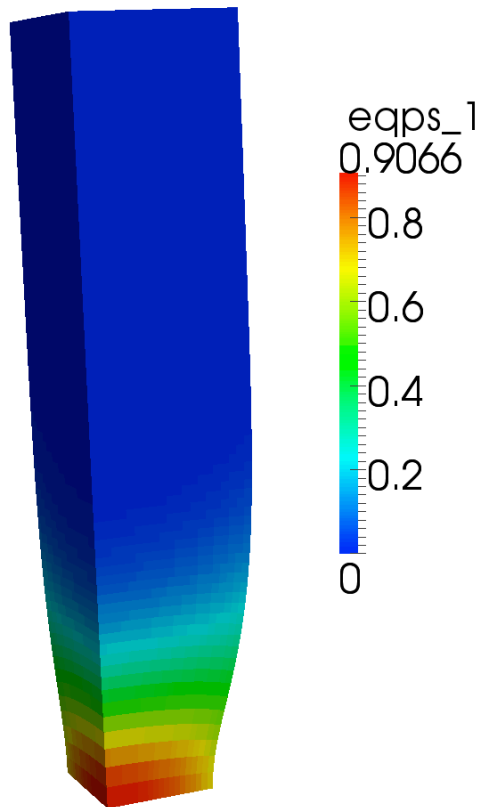
The residual after remapping may be an indication of the discretization error. Further investigation into different levels of refinement are needed.

Difference in magnitude of residual

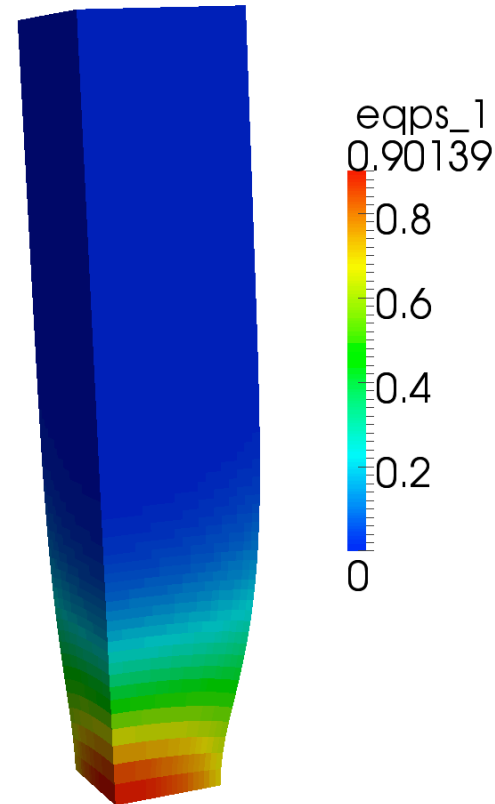


We notice some diffusion in the internal state variables when many remaps are performed

Equivalent plastic strain in fine mesh at one integration point per element at $t = 0.25$



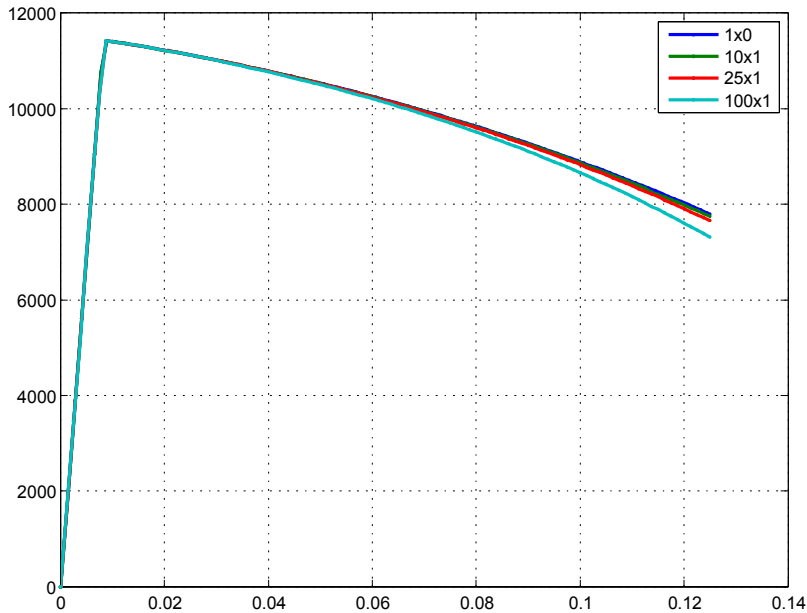
No remapping



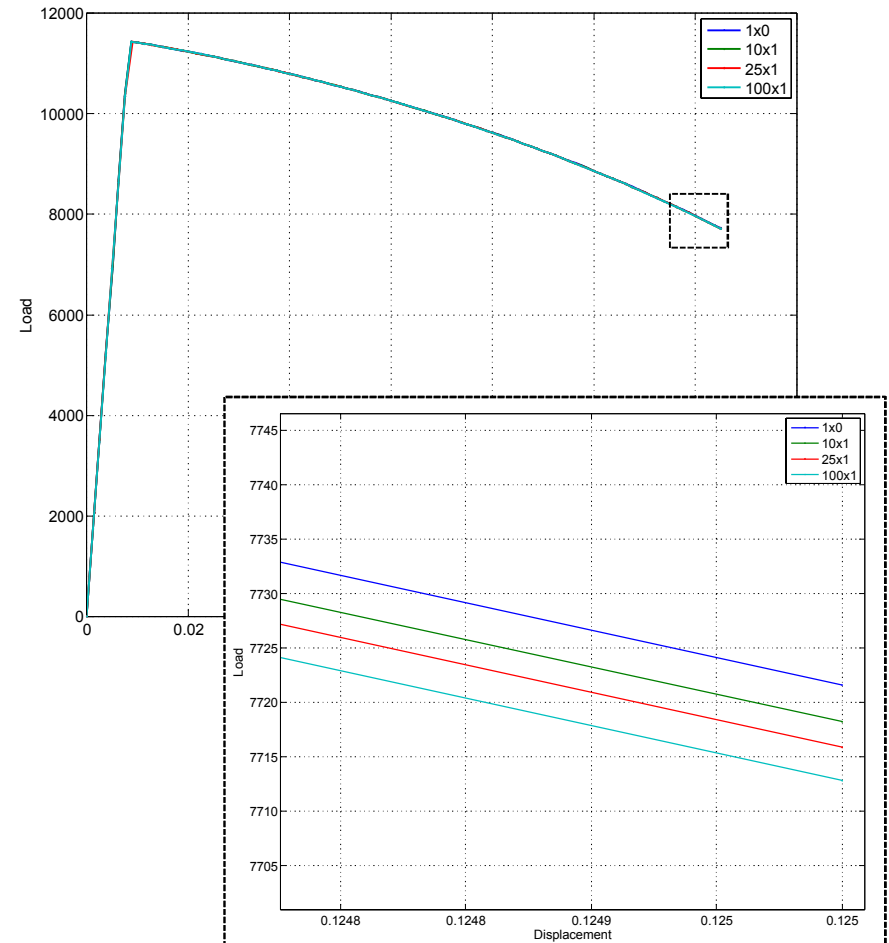
Remap 100 times between $t = 0$ and $t = 0.25$

The dissipation is less prevalent in a fine mesh than in it is in a coarser mesh

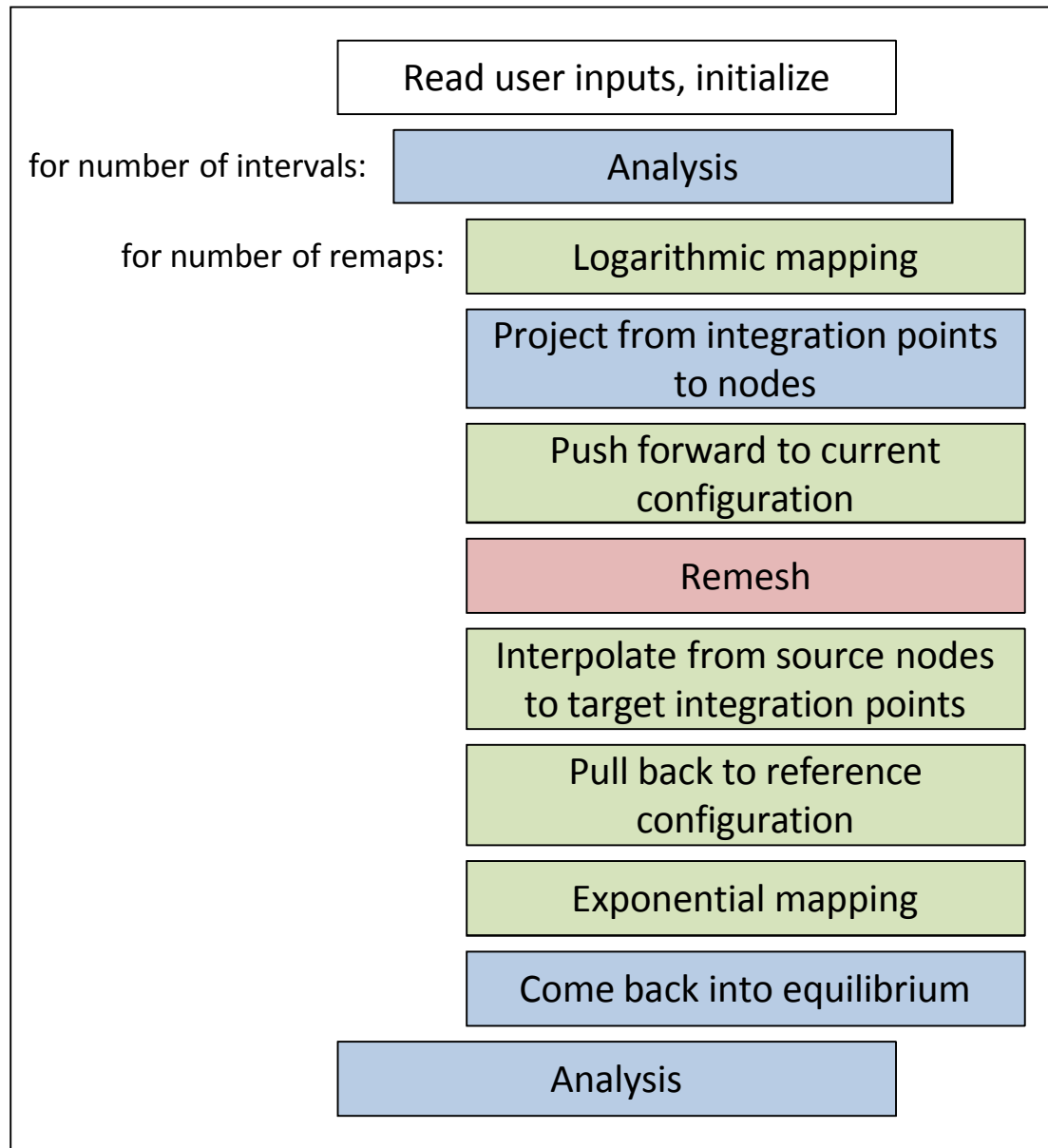
Coarse mesh



Fine mesh



Include remeshing



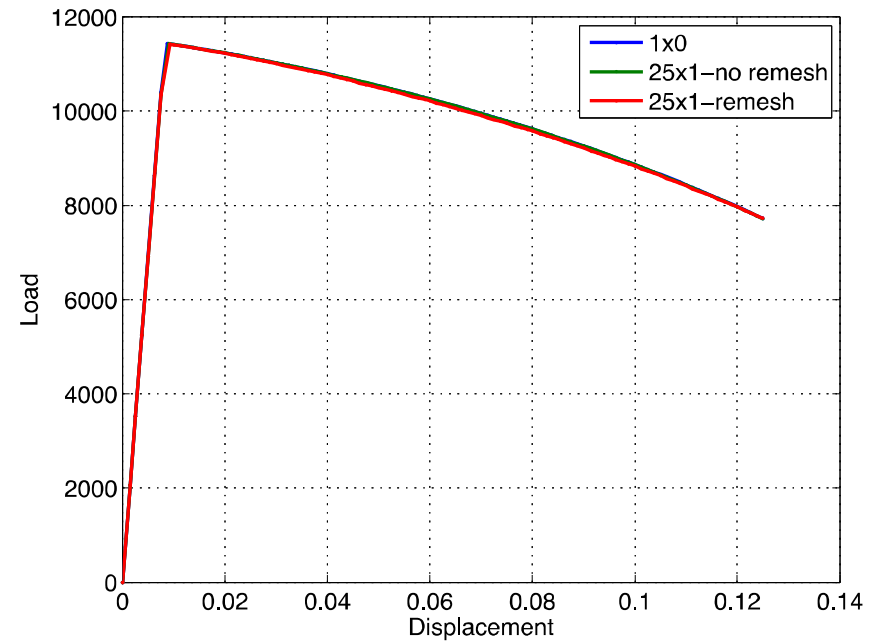
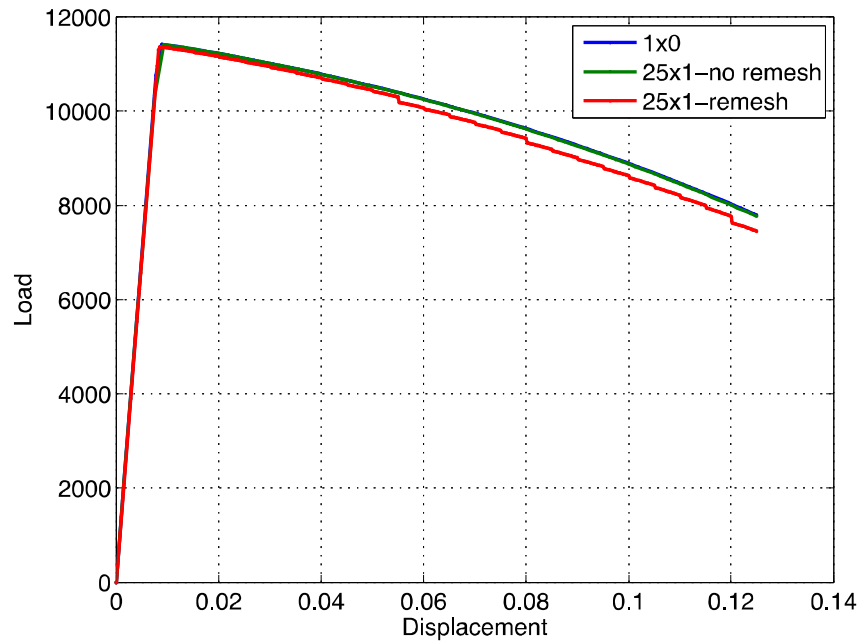
Adagio

Light weight
C++ codes

Python script

Cubit

Some dissipation is present in the load-displacement curve, but it reduces with mesh refinement

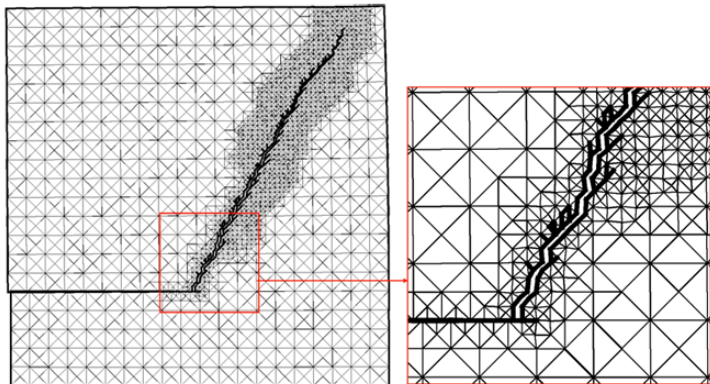
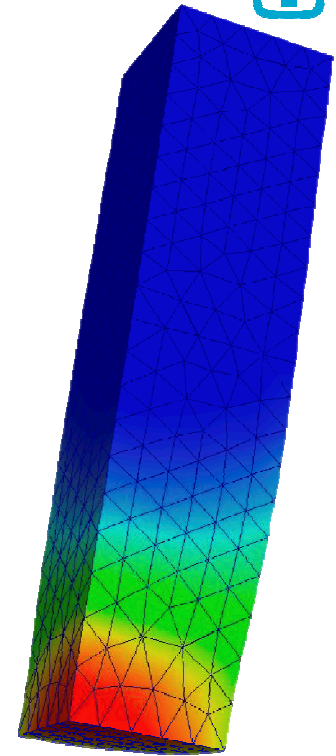


Conclusions and future work

The numerical studies have led to promising results for the hex elements.

The investigation of tet elements is currently underway and will be continued after completion of the internship through an ongoing collaboration.

The welds with voids would then be modeled with tet elements and the mapping scheme employed to capture the specimen failure.

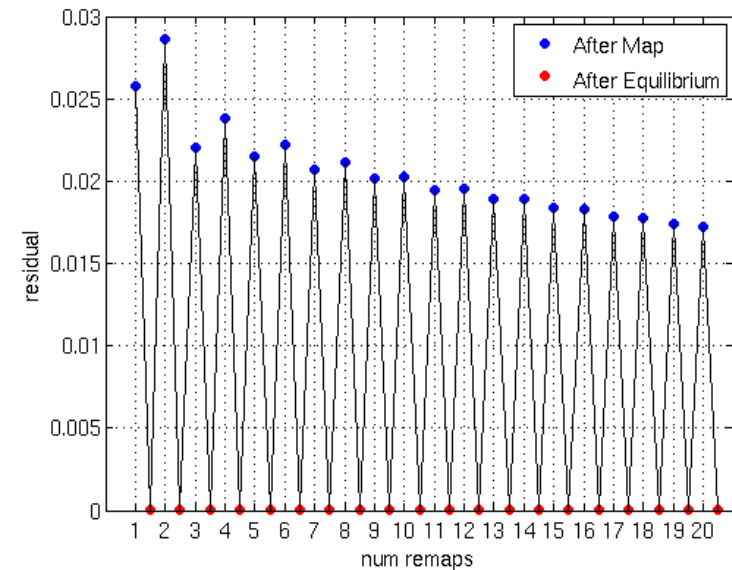


This work will be incorporated into my dissertation and future work will involve performing mapping of internal state variables with crack propagation.

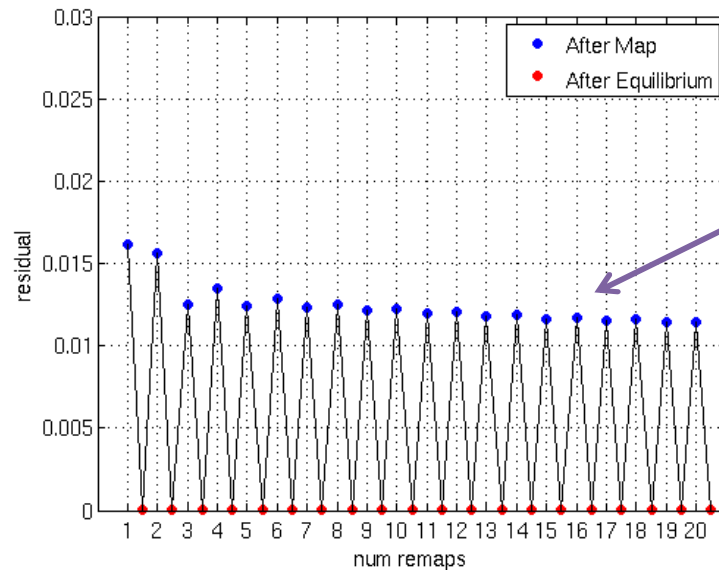
The projection and interpolation scheme proposed here may also be incorporated into mesh coarsening in the quasi brittle crack simulations.

Mesh refinement reduces increase in residual after remapping

Coarse mesh



Fine mesh



Difference in residual is quite stable

The system comes back into equilibrium rapidly, i.e. only a few iterations.

The residual after remapping may be an indication of the discretization error.

Difference in magnitude of residual

