

# Automatic Coarsening of the Particle Interaction Mesh in a Hybrid PIC-DSMC Simulation

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# Introduction

- Hybrid particle-in-cell (PIC) and direct simulation Monte Carlo (DSMC) methods are frequently used to simulate low density interacting plasmas
- A single mesh is often used for both PIC and DSMC calculations
- The mesh size for PIC is often limited by the Debye length
- The collision cell size for DSMC is limited by the mean free path (can be much larger than the Debye length)
- Too few computational particles per DSMC collision cell can lead to errors
- Therefore, the optimal PIC mesh may be suboptimal for calculating DSMC collisions





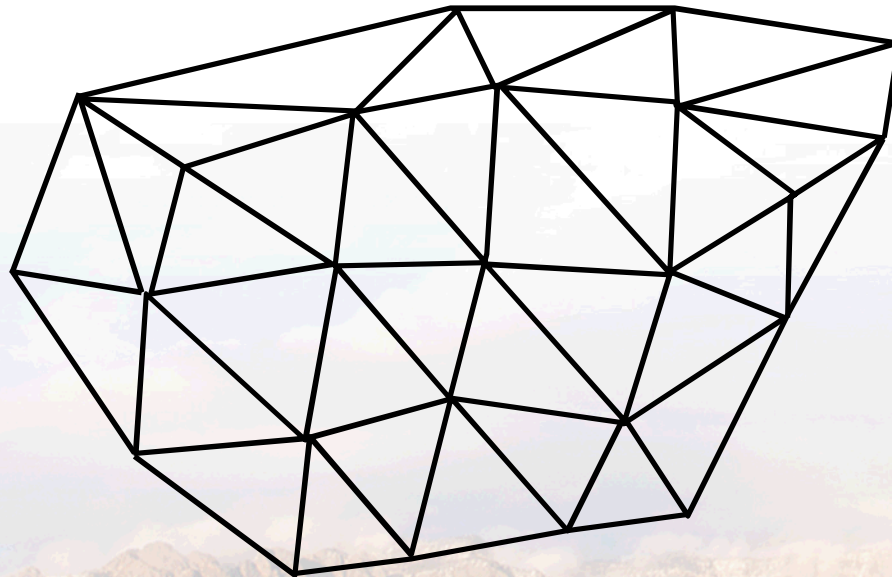
# Overview of New Patching Method

- Use a fine mesh for PIC (unstructured)
- Use a rectangular grid to conglomerate many PIC elements into a single DSMC collision cell
- Size DSMC collision cells based on mean free path,  $\lambda_{\text{mfp}}$
- Use oct-tree algorithm to adjust the size of DSMC collision cells on the fly



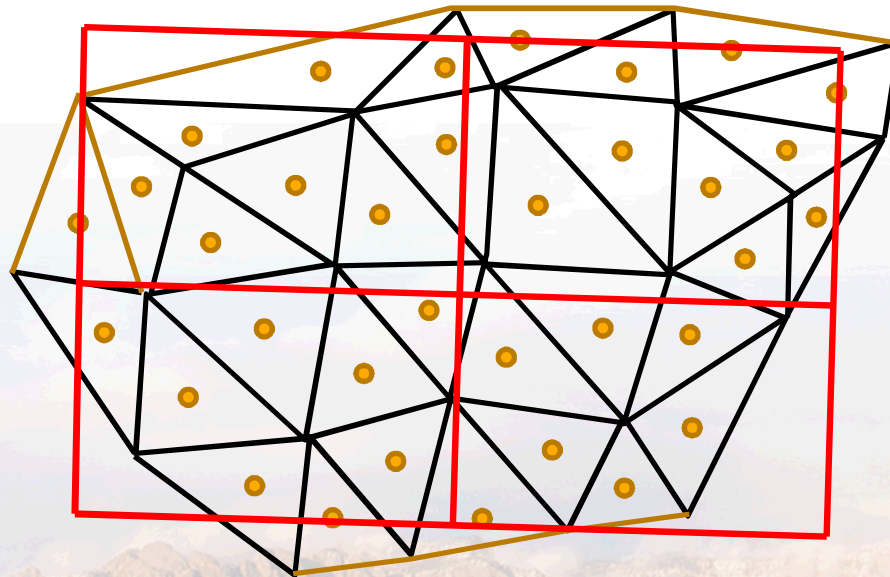
# Patch Method

- Original (unstructured) PIC mesh



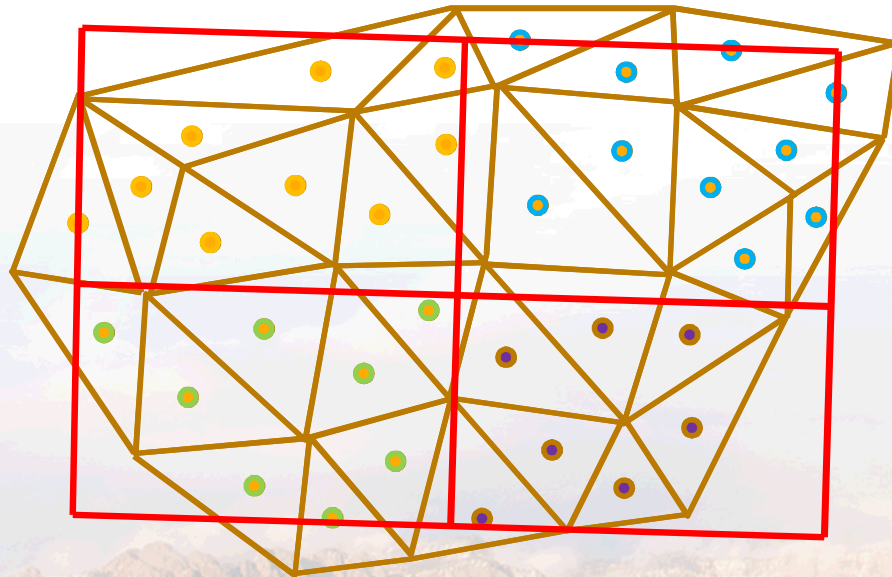
# Patch Method

- Apply rectilinear grid based on element centroid

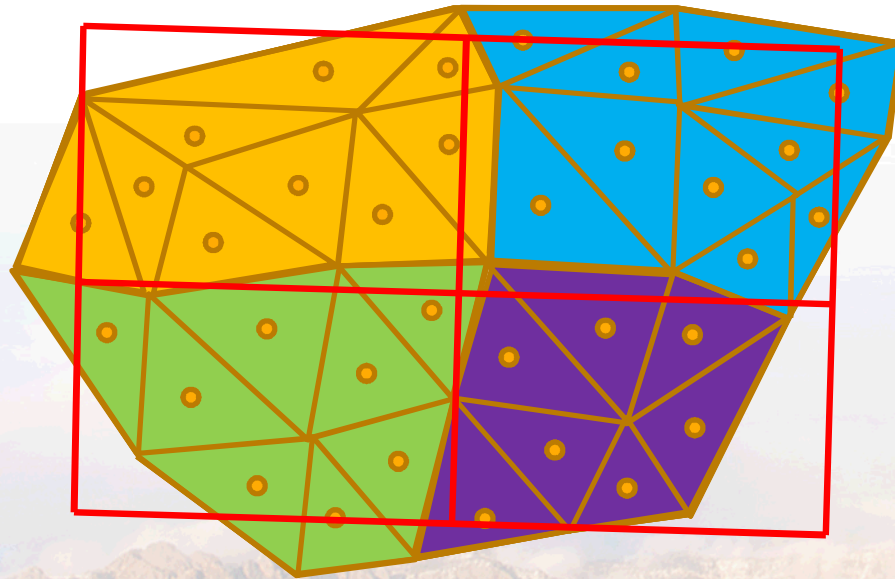


# Patch Method

- Assign elements to patches (based on element centroid)

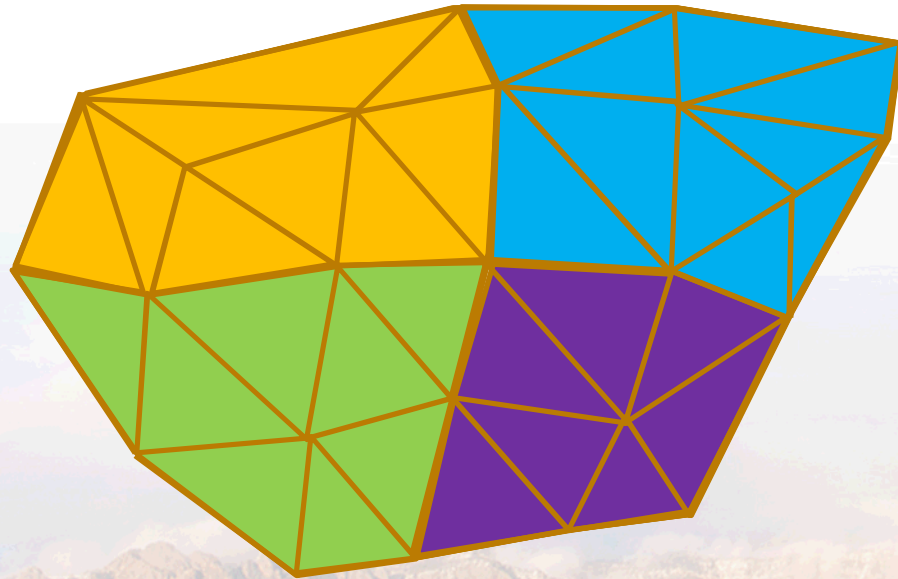


# Patch Method



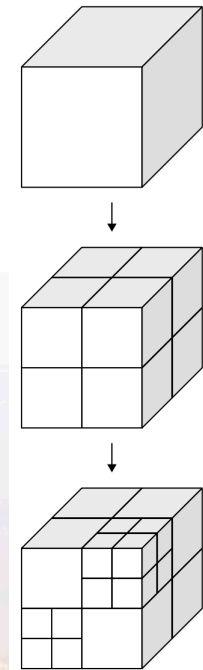
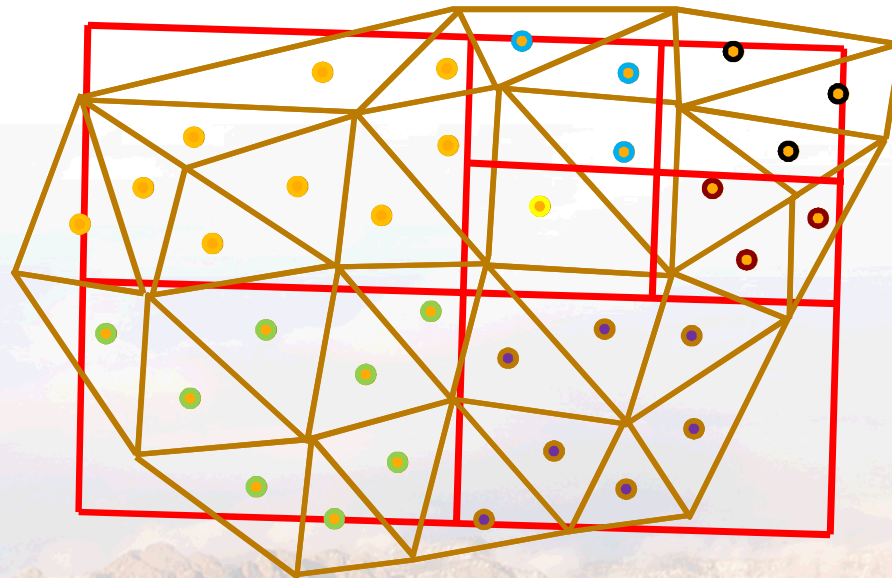
# Patch Method

- Patched mesh
- Use patches to compute DSMC collisions



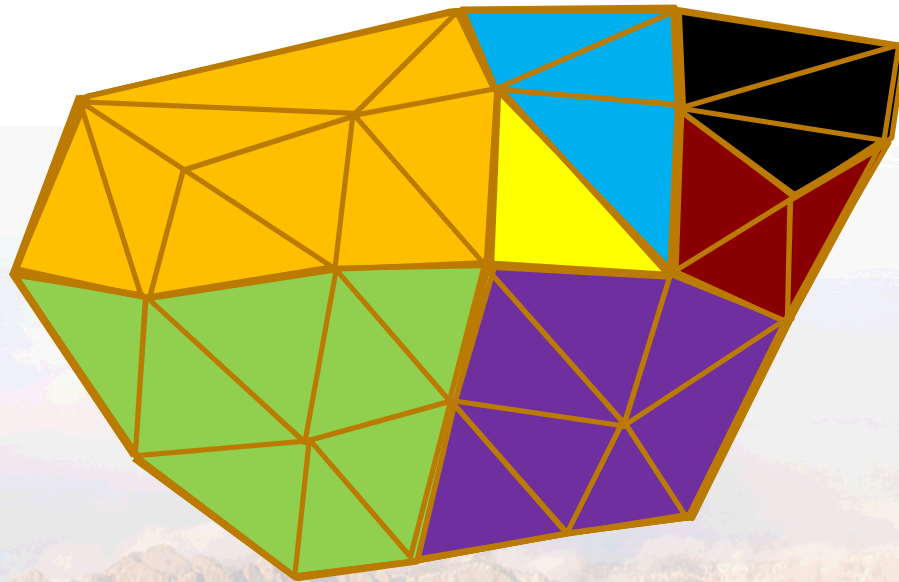
# Oct-tree Refinement

- Use oct-tree algorithm to refine mesh based on mean free path



# Oct-tree Refinement

- Refined mesh





# Automatic Sizing of Patches

Patch size is dynamically adjusted based on the local mean free path  $\lambda_{\text{mfp}}$ :

1. Compute  $\lambda_{\text{mfp}}$  for each interaction on an elemental basis (using all species)
2. For each interaction, average  $\lambda_{\text{mfp}}$  over elements in the oct-tree cell
3. Take the minimum of all the average  $\lambda_{\text{mfp}}$  and divide by 2, use this to size patches using the oct-tree algorithm



# Temporal Averaging

- Calculate  $\lambda_{\text{mfp}}$  for each element as:

$$\lambda_{\text{mfp}} = \frac{v}{Z} n$$

$v$  = velocity  
 $Z$  = interaction frequency  
 $n$  = number of particles

- With a high computational particle weighting, temporal smoothing is needed. Can use either:

$$\langle \lambda_{\text{mfp}} \rangle = \left\langle \frac{v}{Z} n \right\rangle \qquad \langle \lambda_{\text{mfp}} \rangle = \frac{\langle v \rangle}{\langle Z \rangle} \langle n \rangle$$

- Sometimes can get zero interactions in a timestep. With the first option, this leads to division by zero
- Found that the second option works much better



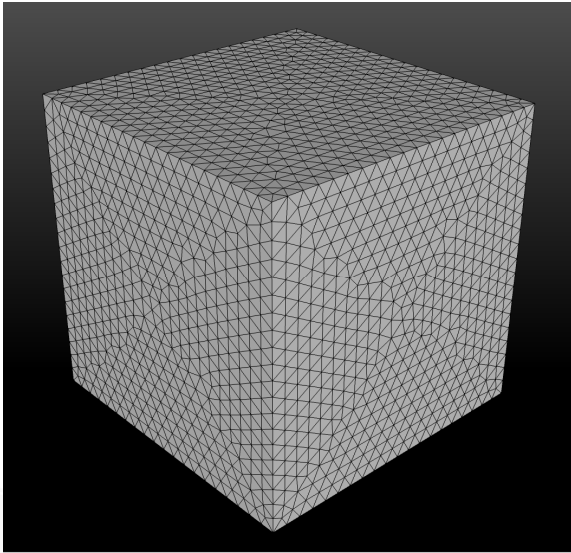


# HI Test Problem

- Hydrogen iodide (HI) molecules interacting with elastic collisions
- Use variable hard sphere (VHS) interaction cross section
- $T = 594.6 \text{ K}$ ,  $n = 10^{20} \text{ m}^{-3}$
- 3D cubic system,  $L = 5 \text{ cm}$
- Analytic  $\lambda_{\text{mfp}} = 3.67 \text{ cm}$
- $0.5 * \lambda_{\text{mfp}} \Rightarrow$  minimum of 27 patches, but oct-tree on cube uses powers of 8  $\Rightarrow$  64 patches



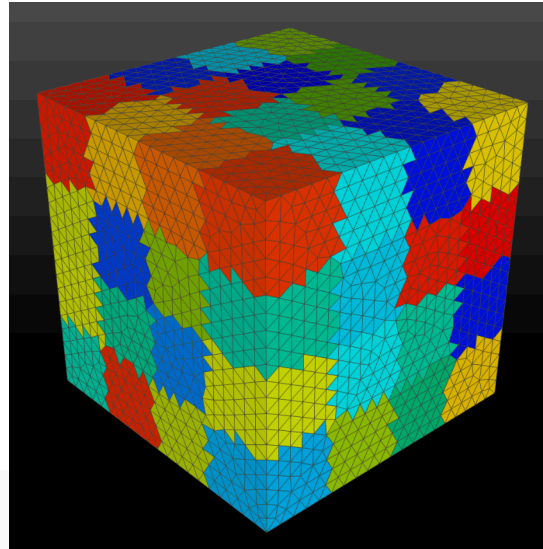
# 3 Meshes



*fine* mesh

56,557 elements

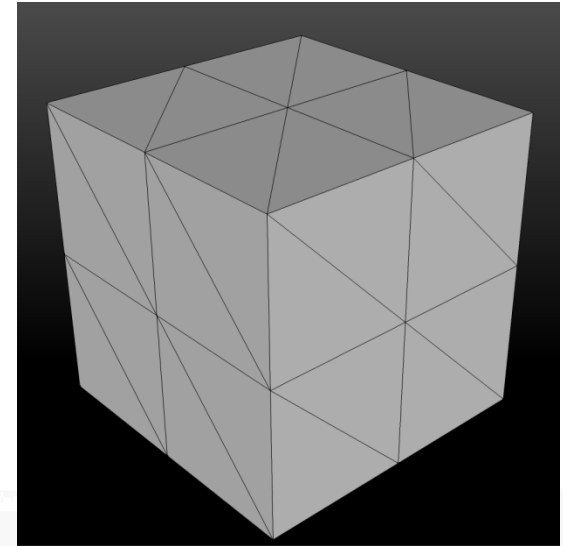
1,696,710 particles



*patched* mesh

64 patches

1,920 particles



*coarse* mesh

96 elements

2,880 particles

- Adjust particle weighting → approximately 30 particles per element or patch





# Accuracy Comparison

Ran each simulation for 3 hours ( $\Delta t = 10^{-5}$  s) on one processor, repeated 6 times with a different random number seed

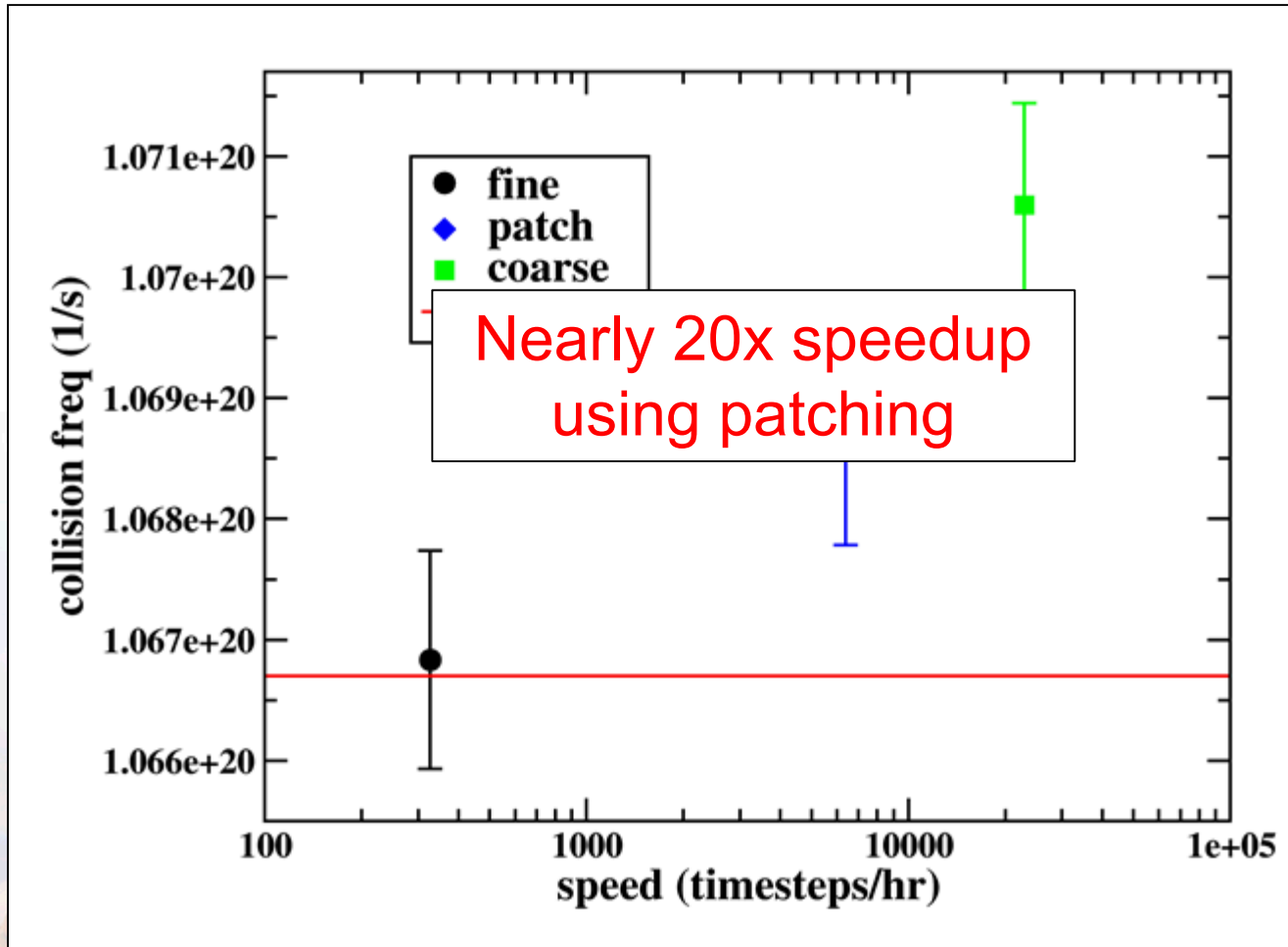
## Average Collision Frequency:

- $f_{\text{analytic}} = 1.0667 \cdot 10^{20} \text{ s}^{-1}$
- $f_{\text{fine}} = 1.0668 \cdot 10^{20} \text{ s}^{-1} \rightarrow 0.01\% \text{ relative error}$
- $f_{\text{patch}} = 1.0686 \cdot 10^{20} \text{ s}^{-1} \rightarrow 0.18\% \text{ relative error}$
- $f_{\text{coarse}} = 1.0703 \cdot 10^{20} \text{ s}^{-1} \rightarrow 0.33\% \text{ relative error}$

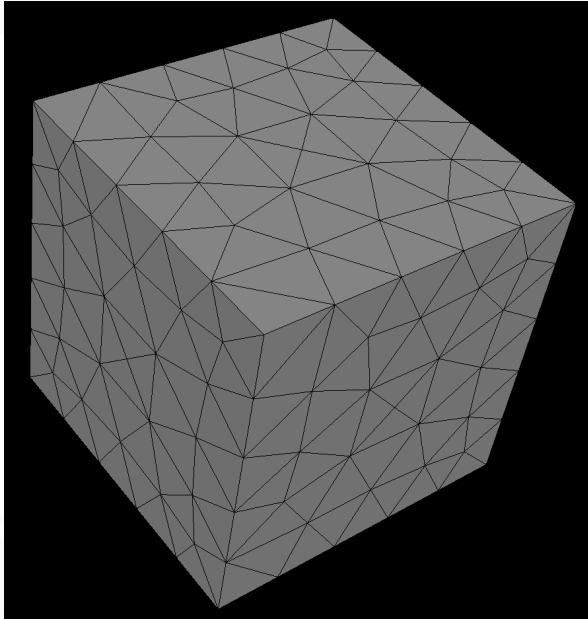


# Results for the HI Test Problem

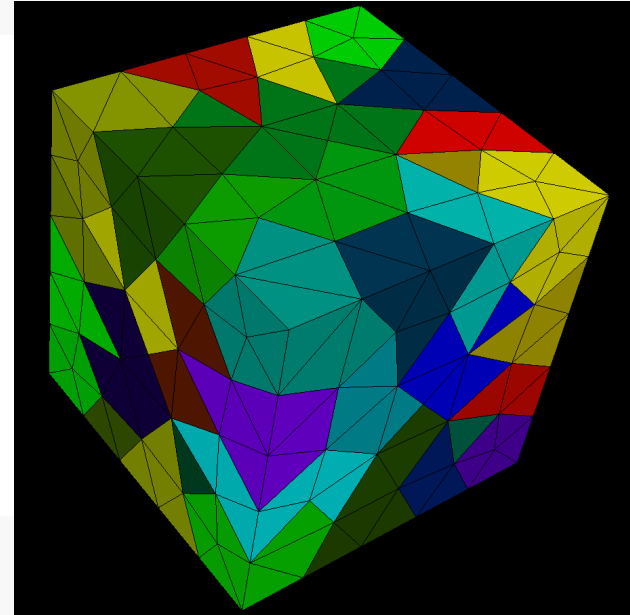
- Error bars represent 95% confidence intervals



## Another 2 Meshes



*fine* mesh  
1,184 elements  
1,223 particles



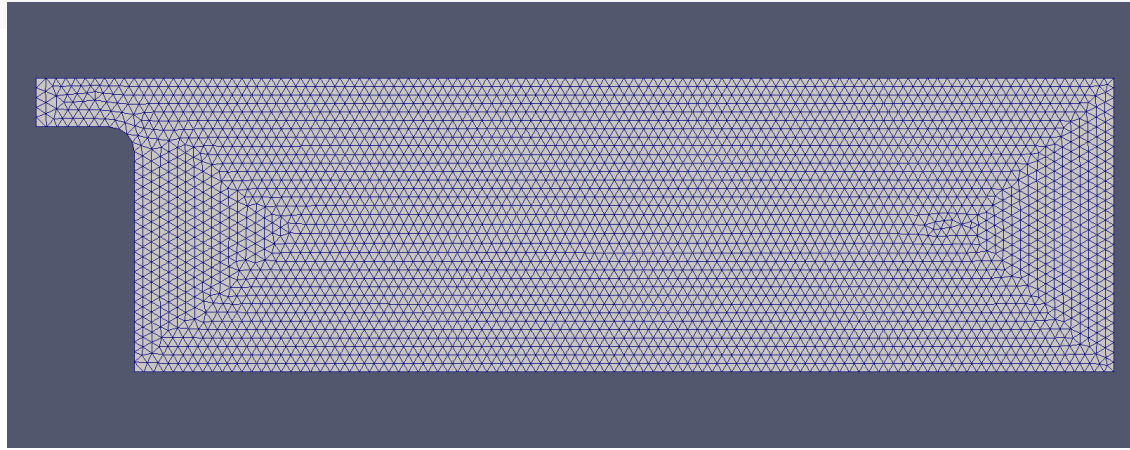
*patched* mesh  
64 patches  
1,223 particles

- Same HI test problem (ran for 2000 timesteps)
- Patched mesh runs nearly **4x** faster (with virtually the same accuracy)



# 2D Vacuum Gap Breakdown

Anode  
350 V

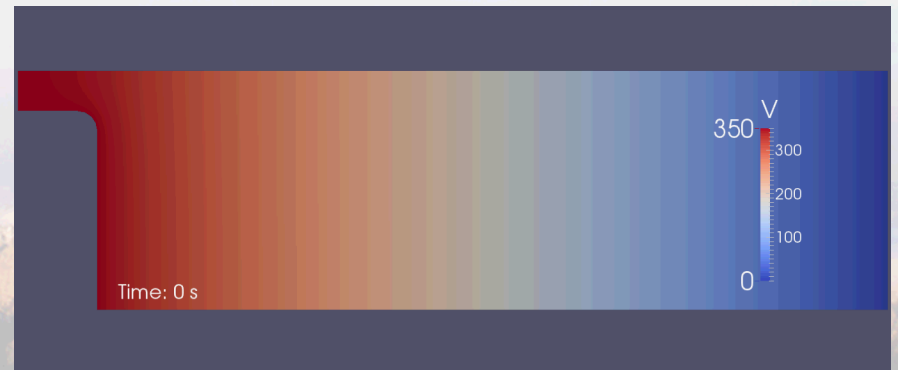


Cathode  
0 V

- Air injected at high velocity and high temperature from the anode
- Low density electrons injected from the cathode
- Air ionizes and eventually will form plasma and break the gap



# Species Densities ( $\text{m}^{-3}$ )



# Dynamic Sizing of DSMC Collision Cells





# Conclusions

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- **Developed a new method (patching) to enhance hybrid PIC-DSMC simulations**
- **Using fewer particles with patching gives similar accuracy and uncertainty as using a fine mesh with many particles**
- **Allows one to dramatically speed up the simulation if the PIC mesh is too small for DSMC collisions**
- **Allows one to dynamically adjust the size of DSMC collision cells on the fly (based on mean free path)**





**Thank You**

**Questions or comments?**

