

# A Discontinuous Phase-Space Finite Element Discretization of the Linear Boltzmann Equation with EM Fields for Charged Particle Transport

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# Outline

- Background
- Incorporation of EM terms into Boltzmann equation
- Discretizations
- Results
- Conclusions

# Background/motivation

- Some radiation transport problems involve charged particles within electromagnetic fields
- Much existing work on charged particle transport without EM field effects, or on plasma/EM modeling without certain transport effects
- ITS Monte Carlo code can handle transport of charged particles in materials without EM effects, or streaming in voids with EM effects
- LDRD project to develop deterministic solvers to handle EM effects in transport codes (e.g. Sceptre)



# Challenges

- Various properties break paradigm of existing deterministic approaches/codes
  - Curved trajectories instead of straight-line path between collisions
  - Continuously changing energies rather than discrete changes
  - Relativistic effects – must be explicitly aware of energies, masses, etc.

$$\frac{1}{c\beta} \frac{\partial \psi}{\partial t} + [\vec{\Omega} \cdot \nabla + \sigma_t(r, E)] \psi(r, E, \vec{\Omega}, t) + \nabla_v \cdot \frac{\vec{a}}{v} \psi(r, E, \vec{\Omega}, t) \\ = \int dE' \int d\vec{\Omega}' \sigma_s(r, E' \rightarrow E, \vec{\Omega}' \rightarrow \vec{\Omega}) \psi(r, E', \vec{\Omega}', t) + S(r, E, \vec{\Omega}, t)$$

# Expansion of acceleration term

$$\nabla_v \cdot \frac{\vec{a}}{v} \psi = \nabla_v \cdot \vec{a} N = \vec{a} \cdot \nabla_v N + (\nabla_v \cdot \vec{a}) N$$

$$\vec{a} \cdot \nabla_v N = (\vec{a} \cdot \vec{\Omega}) \frac{\partial N}{\partial v} + \frac{1}{v} [a_x - \mu(\vec{a} \cdot \vec{\Omega})] \frac{\partial N}{\partial \mu} + \frac{1}{v(1 - \mu^2)} (\vec{\Omega} \times \vec{a})_x \frac{\partial N}{\partial \varphi}$$

$$\nabla_v \cdot \vec{a} = \frac{\partial(\vec{a} \cdot \vec{\Omega})}{\partial v} + \frac{1}{v} \left[ (1 - \mu^2) \frac{\partial a_x}{\partial \mu} - \mu \eta \frac{\partial a_y}{\partial \mu} - \mu \xi \frac{\partial a_z}{\partial \mu} \right] + \frac{1}{v(1 - \mu^2)} \left[ -\xi \frac{\partial a_y}{\partial \varphi} + \eta \frac{\partial a_z}{\partial \varphi} \right]$$

# Boltzmann equation with acceleration term (change of variables)

$$\begin{aligned} & \frac{1}{v} \frac{\partial \psi}{\partial t} + \vec{\Omega} \cdot \nabla \psi + \sigma \psi + \frac{\vec{a} \cdot \vec{\Omega}}{v} \left( \frac{\partial \psi}{\partial v} - \frac{1}{v} \psi \right) \\ & + \frac{1}{v^2} \left[ a_x - \mu (\vec{a} \cdot \vec{\Omega}) \right] \frac{\partial \psi}{\partial \mu} + \frac{1}{v^2 (1 - \mu^2)} (\vec{\Omega} \times \vec{a})_x \frac{\partial \psi}{\partial \varphi} + (\nabla_v \cdot \vec{a}) \frac{\psi}{v} = S \end{aligned}$$

# Dynamics of Lorentz force

$$\vec{F} = q(\vec{\mathcal{E}} + \vec{v} \times \vec{\mathcal{B}})$$

$$\begin{aligned} \vec{a} &= \frac{1}{\gamma m_o} [\vec{F} - \beta^2 (\vec{F} \cdot \vec{\Omega}) \vec{\Omega}] \\ &= \frac{1}{\gamma m_o} \{ q(\vec{\mathcal{E}} + \vec{v} \times \vec{\mathcal{B}}) - \beta^2 [q(\vec{\mathcal{E}} + \vec{v} \times \vec{\mathcal{B}}) \cdot \vec{\Omega}] \vec{\Omega} \} \\ &= \frac{q}{\gamma m_o} \left\{ (\vec{\mathcal{E}} + \vec{v} \times \vec{\mathcal{B}}) - \left[ (\vec{\mathcal{E}} + \vec{v} \times \vec{\mathcal{B}}) \cdot \frac{\vec{v}}{c} \right] \frac{\vec{v}}{c} \right\} \\ &= \frac{q}{\gamma m_o} \left[ \vec{\mathcal{E}} + \vec{v} \times \vec{\mathcal{B}} - \frac{\vec{\mathcal{E}} \cdot \vec{v}}{c} \frac{\vec{v}}{c} \right] \\ &= \frac{q}{\gamma m_o} [\vec{\mathcal{E}} + v \vec{\Omega} \times \vec{\mathcal{B}} - \beta^2 (\vec{\mathcal{E}} \cdot \vec{\Omega}) \vec{\Omega}] \end{aligned}$$



# Components of Lorentz force

$$\frac{\vec{a} \cdot \vec{\Omega}}{v} \frac{\partial \psi}{\partial v} = q(\vec{\mathcal{E}} \cdot \vec{\Omega}) \frac{\partial \psi}{\partial E}$$

$$(\vec{a} \cdot \vec{\Omega}) \frac{\psi}{v^2} = \frac{q(\vec{\mathcal{E}} \cdot \vec{\Omega})}{E + m_o c^2} \frac{1 - \beta^2(E)}{\beta^2(E)} \psi$$

$$(\nabla_v \cdot \vec{a}) \frac{\psi}{v} = - \frac{5q(\vec{\mathcal{E}} \cdot \vec{\Omega})}{E + m_o c^2} \psi$$

# Components of Lorentz force

$$\begin{aligned} & \frac{1}{v^2} [a_x - \mu(\vec{a} \cdot \vec{\Omega})] \frac{\partial \psi}{\partial \mu} + \frac{1}{v^2(1 - \mu^2)} (\vec{\Omega} \times \vec{a})_x \frac{\partial \psi}{\partial \varphi} \\ &= \frac{q}{\mathcal{D}(E)} [\varepsilon_x(1 - \mu^2) - \varepsilon_y \mu \eta - \varepsilon_z \mu \xi + c\beta(E)(\mathcal{B}_z \eta - \mathcal{B}_y \xi)] \frac{\partial \psi}{\partial \mu} \\ &+ \frac{q}{(1 - \mu^2)\mathcal{D}(E)} [\varepsilon_z \eta - \varepsilon_y \xi + c\beta(E)[\mathcal{B}_y \mu \eta + \mathcal{B}_z \mu \xi - \mathcal{B}_x(1 - \mu^2)]] \frac{\partial \psi}{\partial \varphi} \end{aligned}$$

$$\mathcal{D}(E) \equiv \frac{E(E + 2m_o c^2)}{E + m_o c^2}$$

# Final Boltzmann-EM equation

$$\begin{aligned}
 & \frac{1}{c\beta} \frac{\partial \psi}{\partial t} + [\vec{\Omega} \cdot \nabla + \sigma_t(r, E)] \psi(r, E, \vec{\Omega}, t) + \\
 & \quad q(\vec{\varepsilon} \cdot \vec{\Omega}) \left[ \frac{\partial \psi}{\partial E} - \frac{1 + 4\beta^2(E)}{D(E)} \right] + \\
 & \quad \frac{q}{D(E)} [\varepsilon_x(1 - \mu^2) - \varepsilon_y\mu\eta - \varepsilon_z\mu\xi + v(B_z\eta - B_y\xi)] \frac{\partial \psi}{\partial \mu} + \\
 & \quad \frac{q}{D(E)(1 - \mu^2)} [\varepsilon_z\eta - \varepsilon_y\xi + v(B_y\mu\eta + B_z\mu\xi - B_x(1 - \mu^2))] \frac{\partial \psi}{\partial \varphi} \\
 & = \int dE' \int d\vec{\Omega}' \sigma_s(r, E' \rightarrow E, \vec{\Omega}' \rightarrow \vec{\Omega}) \psi(r, E', \vec{\Omega}', t) + S(r, E, \vec{\Omega}, t)
 \end{aligned}$$

# Spatial and energy discretization: discontinuous finite elements

- Spatial FEM well-known, already implemented in Sceptre
- Energy FEM relatively easy to implement in multigroup code

# Angular discretization: discrete ordinates (?)

- Treat the *angular* redistribution terms from electromagnetic acceleration as “scattering”:

Discretize the differential operators involving  $\frac{\partial \psi}{\partial \mu}$  and  $\frac{\partial \psi}{\partial \phi}$  by

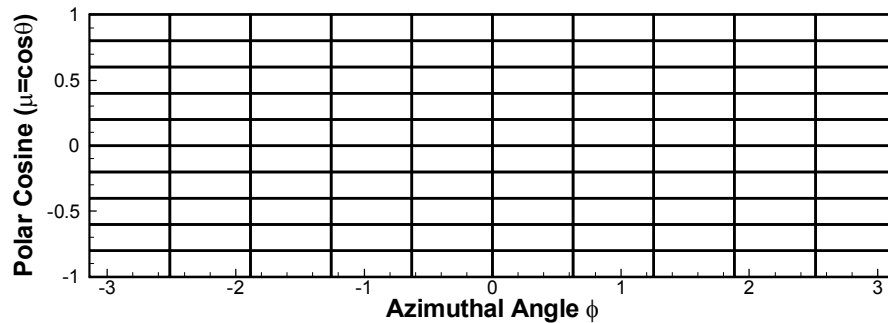
- Expanding angular flux in terms of spherical harmonics in angle
- Using properties of harmonics to create expansion of derivatives
- Applying quadrature rule to evaluate the angular moments

- Allows us to leverage existing discrete ordinates codes
- Difficult to solve
  - Source iteration of these “scattering” terms is unstable
  - Full matrix is asymmetric

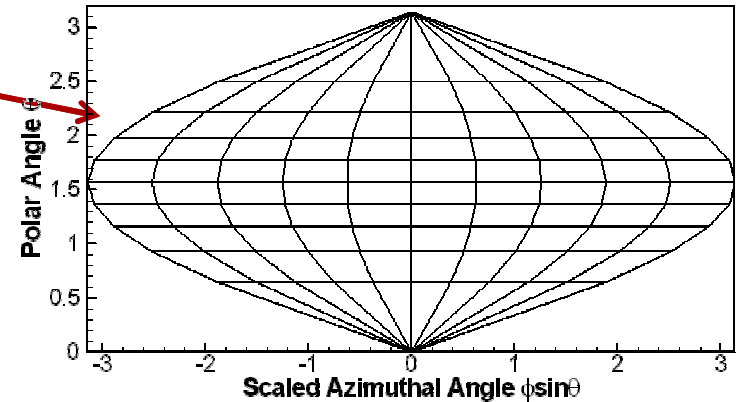
# Angular discretization: finite elements

- Finite element in angle is not new but doesn't exist in any production transport codes
- Allows us to directly treat angular derivatives
- Need to create angular mesh

# Angular meshes

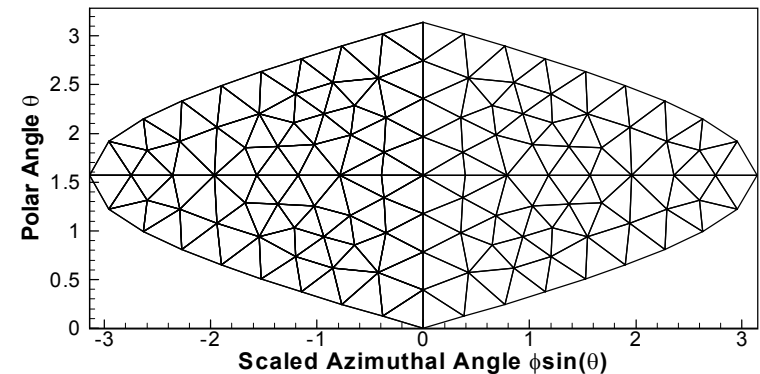


Regular mesh in  $\mu$ - $\phi$  space



Mapped from  $\mu$ - $\phi$  space mesh

- Problems with meshing  $\mu$ - $\phi$  space:
  - Elements mapped to a single point at the poles
  - Non-uniform mesh
- Alternative: use sinusoidal projection and then mesh



Mesh of sphere mapped to planar region

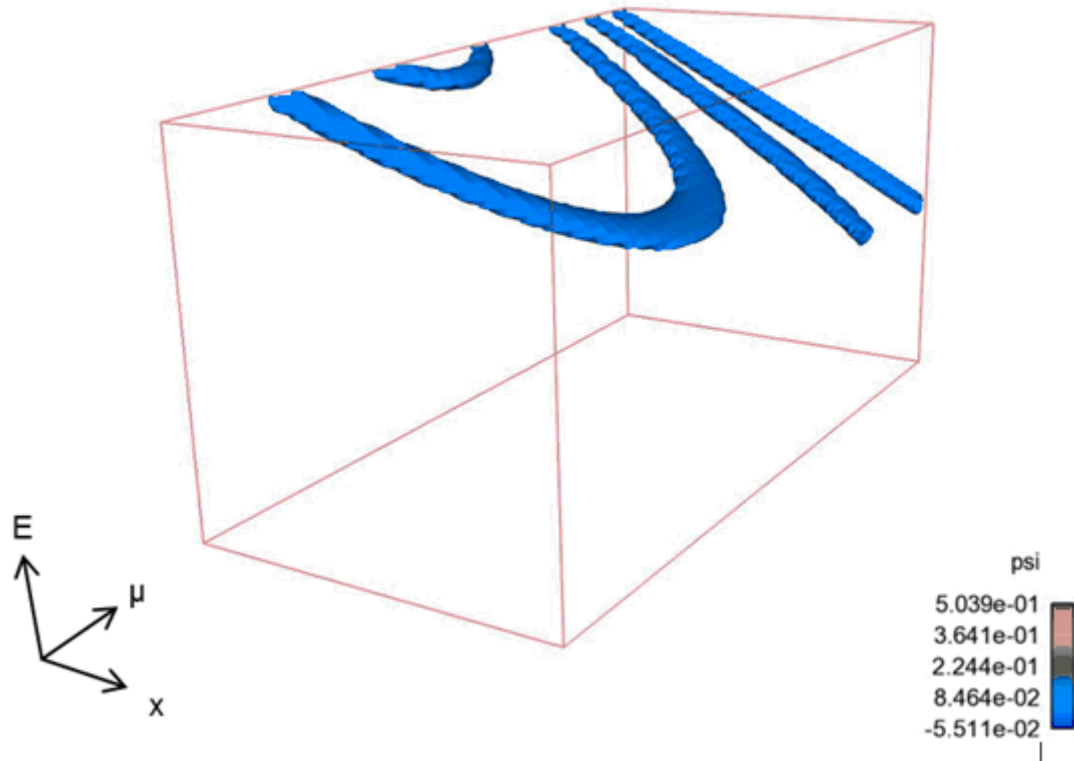
# Final method: fully discontinuous FEM in all phase-space variables

$$\psi(\vec{r}, E, \vec{\Omega}) = \sum_{i=1}^I H_i(\vec{r}) \sum_{j=1}^J G_j(E) \sum_{k=1}^K W_k(\vec{\Omega}) \psi_{ijk}$$

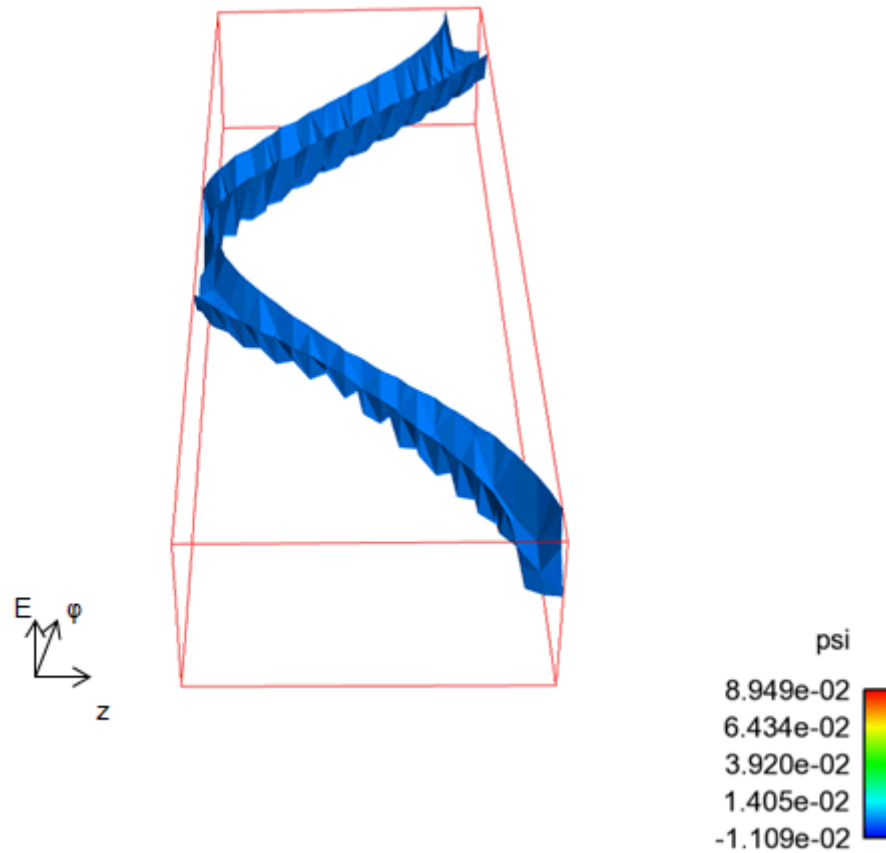
- Large number of unknowns
  - $N_{\text{spatial element}} \times N_{\text{spatial basis}} \times N_{\text{group}} \times N_{\text{energy basis}} \times N_{\text{angular element}} \times N_{\text{angular basis}}$
  - $10^4 \times 4 \times 50 \times 2 \times 100 \times 3 = O(10^9)$
- Extremely complex elemental equations and lots of new code
  - 800 new components
  - 100,000 lines of additional C++ code – split between Sceptre code base (“radlib”) and research code base (radlibEM)



# Results: Electron Transport in Void Constant Electric Field

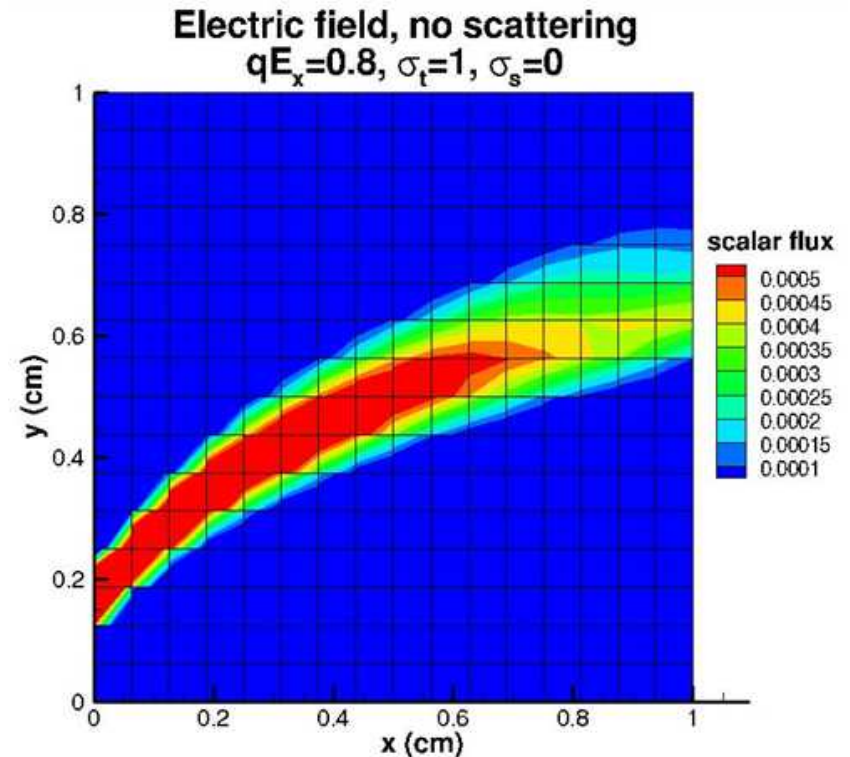
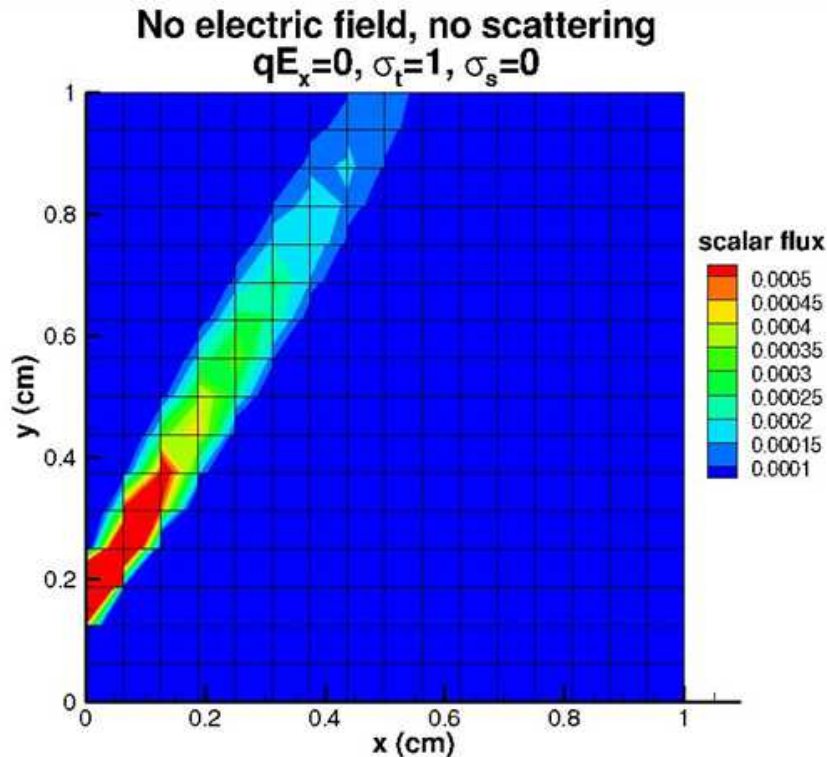


# Results: Electron Transport in Void Constant Magnetic Field

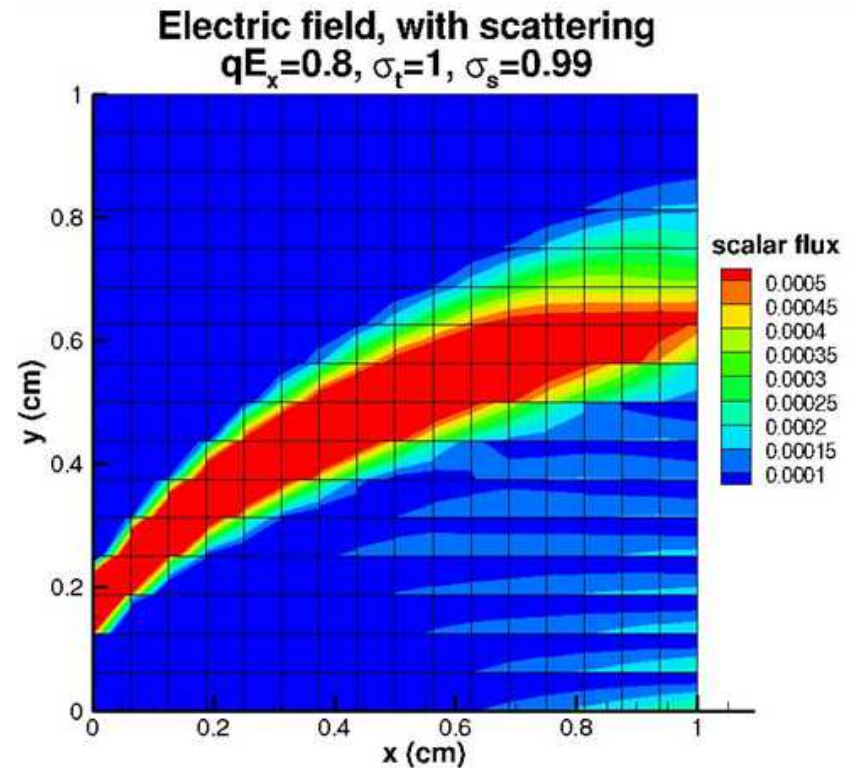
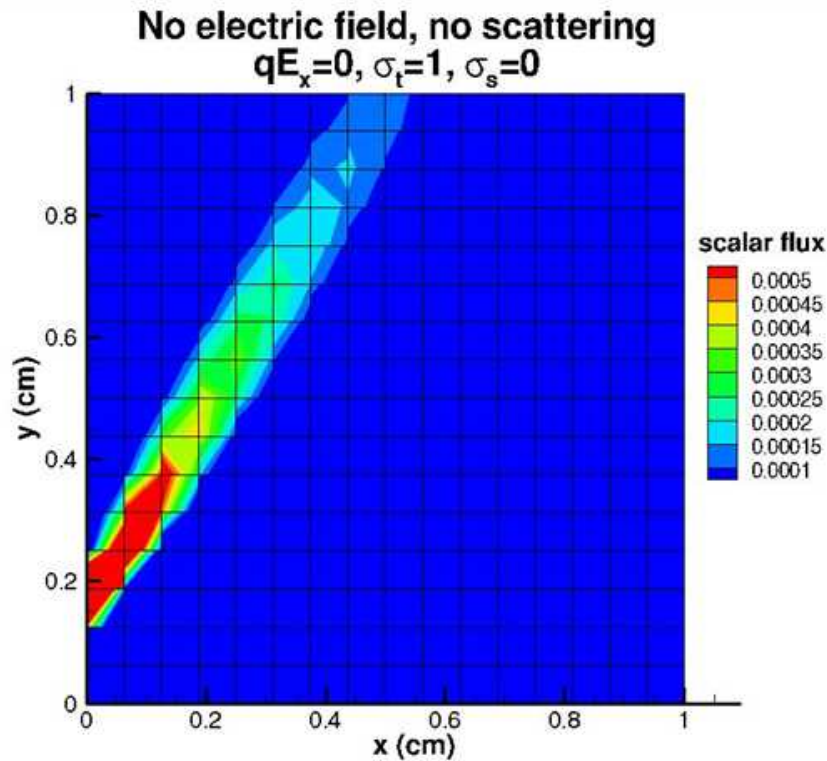


# Results: Electron Transport in Pure Absorber

- Unit square region, unit total cross section, incident electron beam at an oblique angle



# Result: Electron Transport with Scattering



# Order of convergence tests

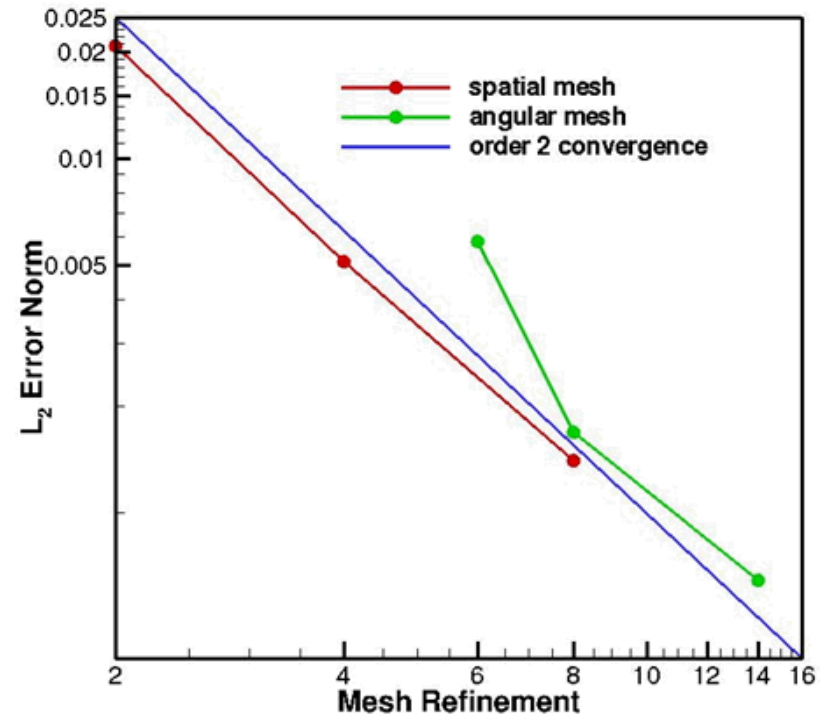
- Method of Manufactured Solutions (MMS)
- Convergence rate analyses for MMS test problem w.r.t. space/angle mesh refinement

$\sigma_t = 10, \sigma_s = 9.99$ , Isotropic scattering with Unit Electric Field in +X Direction

Analytic Solution

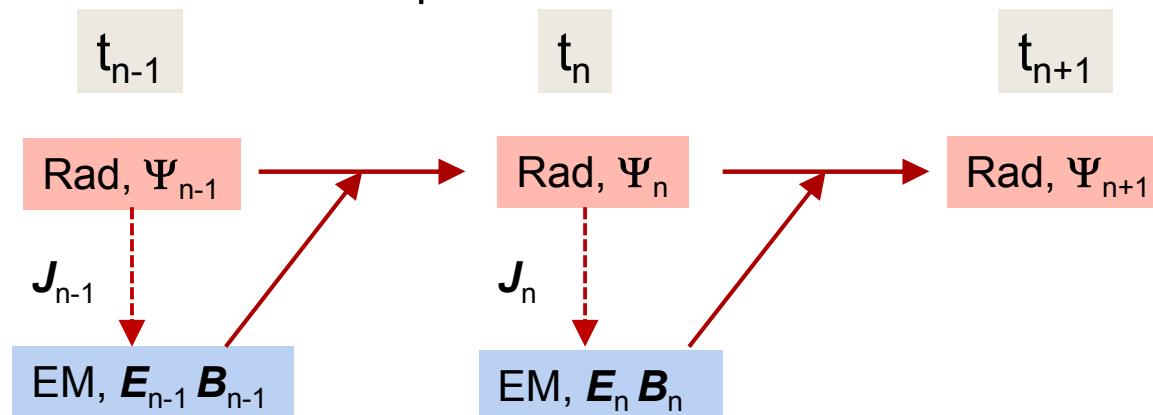
$$\psi(x, y, \mu, \varphi, E) = x^2(1 + \mu)\sqrt{E}$$

Spatial Mesh	Angular Mesh	$L_2$ Error Norm
2x2	16x16	0.0207081
4x4	16x16	0.00512301
8x8	16x16	0.00140234
16x16	6x6	0.00582827
16x16	8x8	0.00168432
16x16	14x14	0.000646928



# Time-dependent coupling with EM solver

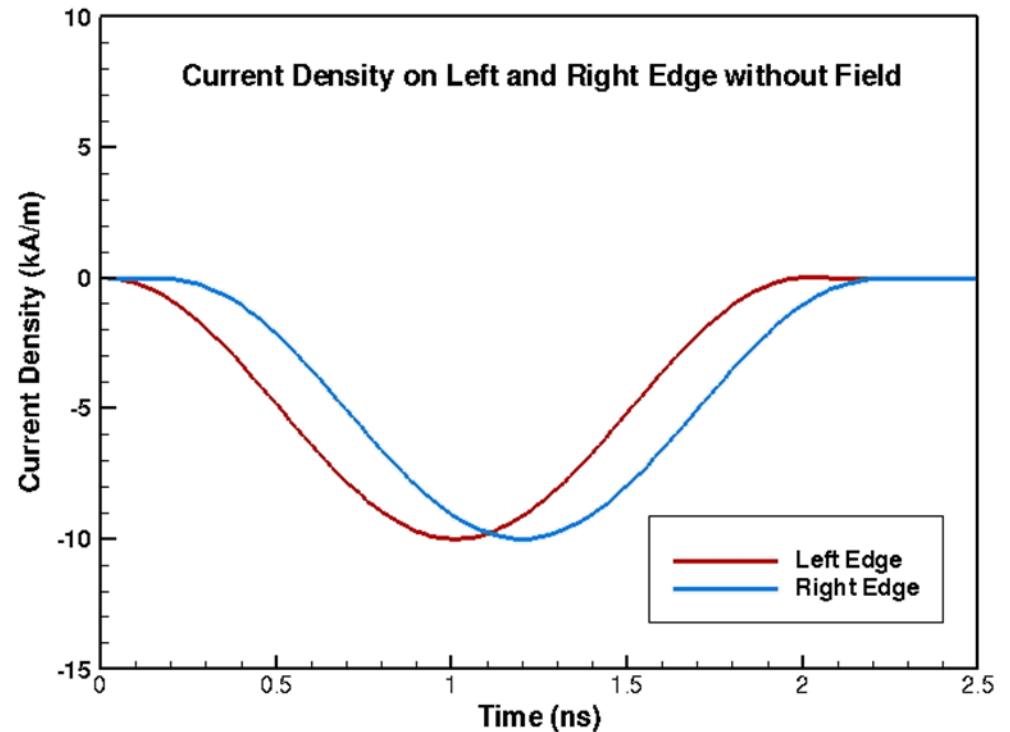
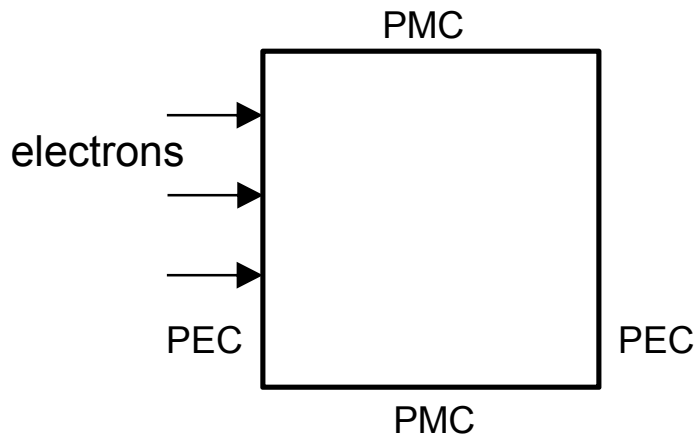
- Time advancement in a staggered order (Operator Split)
  - Fully implicit differencing for electron transport
  - Newmark beta method for electromagnetics
  - Limitation on time-step size



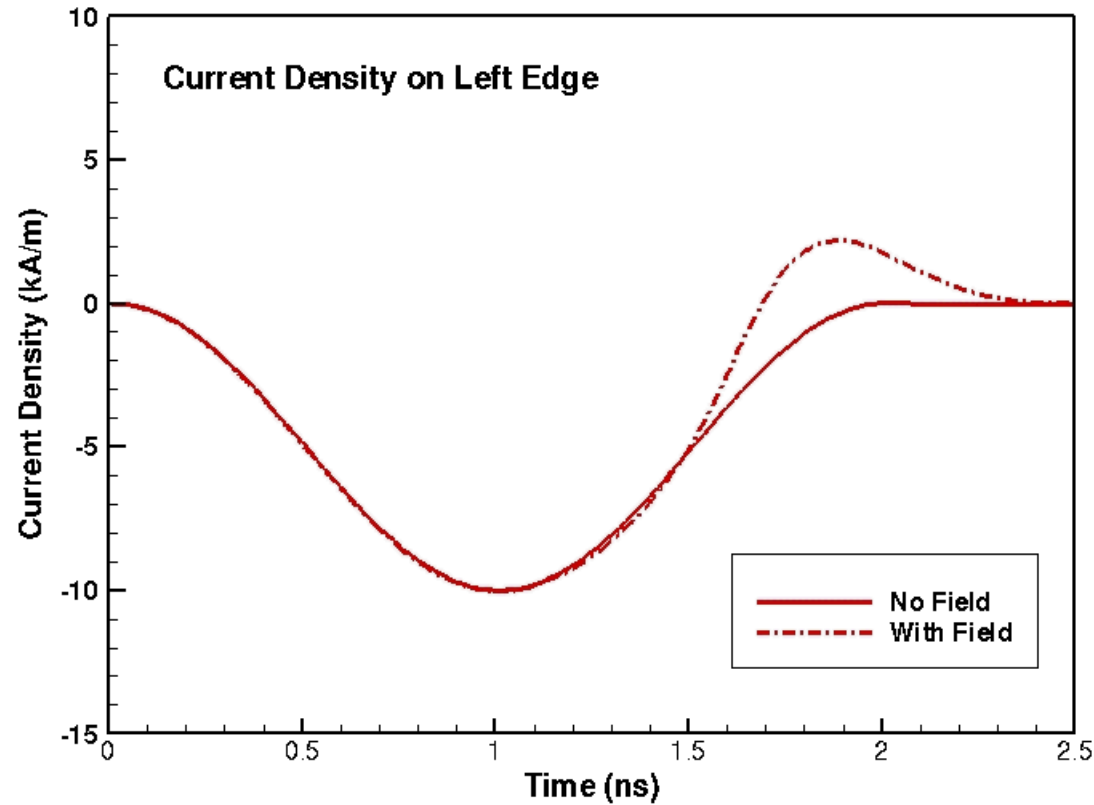
$\Psi$  Electron Angular Flux  
 $J$  Electron Current Density  
 $E$  Electric Field  
 $B$  Magnetic Flux Density

# Result: Capacitor charging

- 1 cm x 1 cm square of void
- 10 kA/m peak current
- 2-ns wide sine-square pulse
- Electron energy = 10 keV

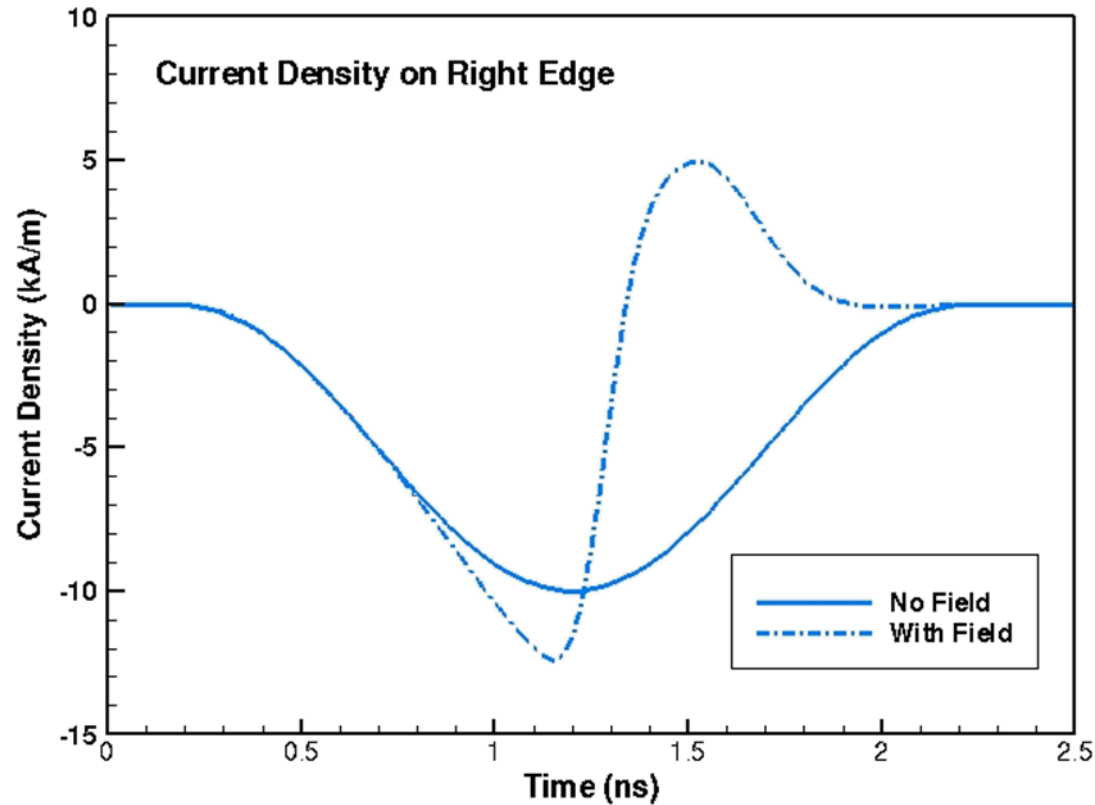


# Result: Capacitor charging





# Result: Capacitor charging



# Future work

- Need to “productize” the research code – packaging, refactoring, testing
- Desire to integrate with more sophisticated EM solvers
- Finite elements in energy can improve our transport even without EM fields, particularly for cross sections (e.g. CSD operator)
- Finite elements in angle can improve our transport for streaming-dominated problems (mitigate ray-effects)

# Conclusions

- We have derived a form of the Boltzmann equation that includes the effects of electromagnetic fields on relativistic charged particle transport
- We have developed a deterministic discretization and solution technique to model charged particle transport with EM fields
- We have demonstrated coupled electron transport and consistent electric field with a simple time integration scheme