

LA-UR- 11-02358

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*Title:* Boettger-Wallace Phase Transition Model Revisited

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*Intended for:* JOWOG 32 Mat  
May 9 - 13, 2011  
Los Alamos National Laboratory



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# Boettger-Wallace Phase Transition Model Revisited

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The Boettger-Wallace phase transition model is reviewed. The nuts and bolts of implementing the metastability and kinetics models in a simulation code are described in detail. The limitations of the BW model are discussed.

\*Work supported by the U.S. Dept. of Energy under contract DE-AC52-06NA25396.

# Boettger-Wallace Phase Transition Model Revisited

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# Motivation

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## Why talk about work that was completed more than 10 years ago?

The nuts and bolts of implementing the Boettger-Wallace phase transition model (**metastability** and **kinetics**) in a numerical simulation code never has been presented in a comprehensive form.

# Metastability Model

## Assumptions

- There are two phases, a low P phase (**1**) and a high P phase (**2**).
- The equations of state (**EOSs**) for both phases are known.
- LTE is maintained during transition;  $P = P_1 = P_2$  and  $T = T_1 = T_2$ .
- The instantaneous mass fraction of the 2 phase is denoted by  $\lambda$ .
- The metastable mass fraction of the 2 phase is denoted by  $\lambda_m$ .
- The metastable state is **long-lived** compared to the duration of the experiment.

# Metastability Under Loading

Incremental load increase  $\rightarrow$  incremental ( $\Delta G = G_2 - G_1$ ) increase  $d\Delta G$   
 $\rightarrow$  incremental  $\lambda_m$  increase  $d\lambda_m$ . Material transformed also should be proportional to  $(1 - \lambda_m)$ . Try

$$B d\lambda_m = (1 - \lambda_m) d\Delta G.$$

Integrating yields the **metastability equation**.

$$\lambda_m = 1 - \exp[1 - \exp(A - \Delta G / B)]$$

$A = (+)$  energy barrier or  $(-)$  shear stress enhancement

$B$  = energy width of the transition.

An equivalent expression can be deduced for the reverse transition.

## Solving for P, T, and $\lambda_m$ Given V and E in a Cell

1. Estimate P, T, and  $\lambda_m$  – Taken from previous time step.
2. Determine P and T with  $\lambda_m$  fixed – Solve four equations in four unknowns ( $V_1, V_2, E_1, E_2$ ) **iteratively** using Newton's method

$$0 = (1 - \lambda_m) V_1 + \lambda_m V_2 - V$$

$$0 = (1 - \lambda_m) E_1 + \lambda_m E_2 - E$$

$$0 = P_1(V_1, E_1) - P_2(V_2, E_2)$$

$$0 = T_1(V_1, E_1) - T_2(V_2, E_2)$$

3. Determine  $\lambda_m$  with P and T fixed – Solve metastability equation.

**Problem** – Nested do loops for each cell and time step. Outer loop over  $\lambda_m$  is unstable unless damped and then has **slow convergence**.

## Step 2: Solving the set of 4 equations

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Write equations in matrix form as

$$\mathbf{F}(\mathbf{x}) = \mathbf{0}$$

$$\mathbf{F}(\mathbf{x}) = \begin{bmatrix} (1-\lambda)V_1 + \lambda V_2 - V \\ (1-\lambda)E_1 + \lambda E_2 - E \\ P_1 - P_2 \\ T_1 - T_2 \end{bmatrix} \quad \mathbf{x} = \begin{bmatrix} V_1 \\ E_1 \\ V_2 \\ E_2 \end{bmatrix}$$

Make an initial guess for unknowns,  $\mathbf{x}_0$ , and expand  $\mathbf{F}(\mathbf{x})$  about  $\mathbf{x}_0$ .

$$\mathbf{F}(\mathbf{x}) = \mathbf{F}(\mathbf{x}_0) + \mathbf{A} \cdot (\mathbf{x} - \mathbf{x}_0)$$

## Step 2: Solving the set of 4 equations

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$$\mathbf{A}(\mathbf{x}) = \begin{bmatrix} (1-\lambda) & 0 & \lambda & 0 \\ 0 & (1-\lambda) & 0 & \lambda \\ \frac{\partial P_1}{\partial V_1} & \frac{\partial P_1}{\partial E_1} & -\frac{\partial P_2}{\partial V_2} & -\frac{\partial P_2}{\partial E_2} \\ \frac{\partial T_1}{\partial V_1} & \frac{\partial T_1}{\partial E_1} & -\frac{\partial T_2}{\partial V_2} & -\frac{\partial T_2}{\partial E_2} \end{bmatrix}$$

Slow for tabular EOS

Solve for  $\mathbf{X}$ .

$$\mathbf{x} = \mathbf{x}_0 - \mathbf{A}^{-1} \cdot \mathbf{F}(\mathbf{x}_0).$$

Now replace  $\mathbf{x}_0$  with  $\mathbf{x}$  and iterate to convergence.

**Step 2 is slow but the outer do loop over  $\lambda$  can be accelerated.**

# Accelerating the Outer Loop Over $\lambda_m$

**Use an iterative procedure similar to Newton's method**

1. Input  $\lambda_{i1} = \lambda_m$  from last time step (or 0)  $\rightarrow$  output =  $\lambda_{o1}$ .
2. Input  $\lambda_{i2} = 0.5 (\lambda_{i1} + \lambda_{o1})$   $\rightarrow$  output =  $\lambda_{o2}$ .
3. Assume  $\lambda_o = \alpha + \beta \lambda_i$ , with  $\alpha$  and  $\beta$  from last two iterations.  
Input  $\lambda_{i3}$  from intercept with  $\lambda_o = \lambda_i \rightarrow$  output =  $\lambda_{o3}$ .
4. Now iterate to convergence,  $\Delta\lambda < 0.01$ .

**In most cases this procedure converges after 3 iterations.**

**The overall metastability calculation is still very slow.**

# Metastability Model

## Some observations

- Must track whether each cell is **loading or unloading**. I tracked V using a tolerance of  $\Delta V = 0.00005$  to avoid spurious switching due to ringing or numerical noise; i.e., reversal by less than  $\Delta V$  is ignored.
- Calculations are much faster for analytic EOS than for tabular EOS, but are still **slow** compared to single phase EOS look-up.

# Metastability Model

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Could make metastability tractable with tabular EOS

- Pre-calculate  $\lambda_m(V,E)$ ,  $P_m(E,V)$ , and  $T_m(E,V)$  for loading and unloading on a dense mesh, then interpolate using standard tabular EOS software.

# Phase Transition Kinetics

## Characteristic assumptions of BW model

- System drives toward **metastable** state not equilibrium state.
- The transition rate is **linear** in distance from metastable state.
- Driving force is  $\Delta G(P, T)$  → distance measured at **fixed (P, T)**.

This gives the **kinetics equation**.

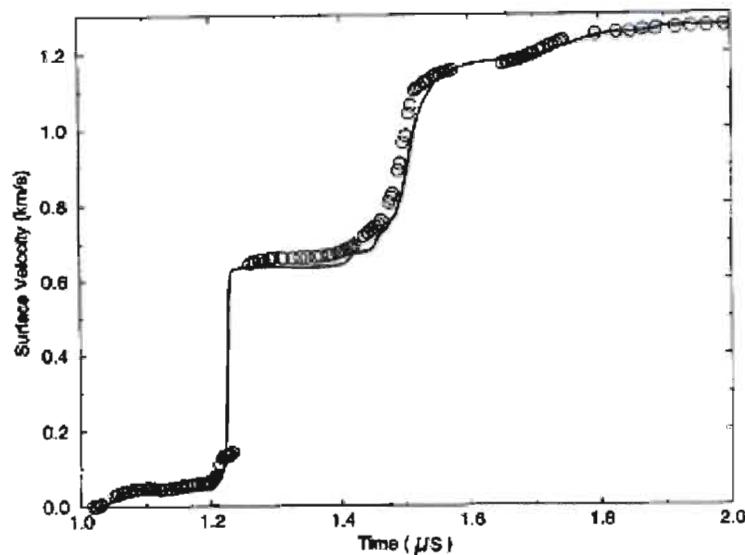
$$\frac{d\lambda}{dt} = \frac{\lambda_m(P, T) - \lambda(P, T)}{\tau}$$

# Phase transition kinetics

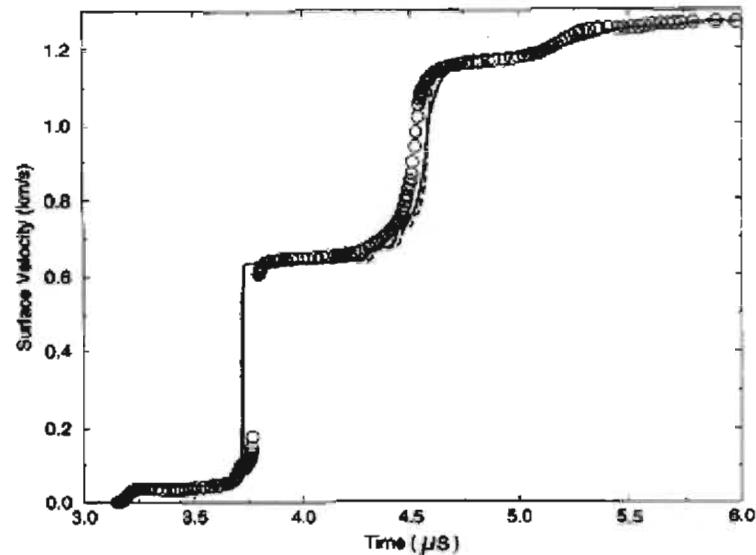
## Some observations

- The maximum amount of material transformed in a given time step  $\Delta t$  is calculated as  $\Delta\lambda = (d\lambda/dt)_{avg} \Delta t$ , where  $(d\lambda/dt)_{avg}$  is an average of rates calculated before and after the time step.
- Adding kinetics to the metastability model **does not slow down** the simulations.
- The kinetics model is however **fundamentally flawed**.

## Application to Fe free surface experiments



Peak stress 23.6 GPa, sample thickness 6.370 mm – Best fit with  $\tau = 30$  ns.



Peak stress 23.7 GPa, sample thickness 19.14 mm – Best fit with  $\tau = 50$  ns.

# Phase transition kinetics

## A major problem with the kinetics equation

- For Fe, the relaxation time  $\tau$  appears to depend on **peak stress** and **sample thickness**, and has to be fitted for each experiment.
- $\tau$  is not a constant as in BW model or a thermodynamic function  $\tau(P, T)$  as in some other models.
- $\tau$  is a **constitutive property** that depends on microstructure and strain rate.