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JAMES R. RICE and ROBB THOMSON

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James R. Rice
Brown University
Providence, Rhode Island 02912

and

Robb Thomson
National Bureau of Standards
Washington, D. C. 20234

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I. INTRODUCTION

This paper is concerned with the problem of the ductile vs. brittle response of crystals. There is in the literature of this subject a conventional understanding that a solid will either be ductile or truly brittle depending upon the ratio of theoretical shear strength to theoretical tensile strength. See Kelly (1966). We believe that a correct description of this competition should include actual dislocation processes at cracks, since the ductile response of the solid must produce dislocations in order to yield.

A truly ductile material like pure copper apparently cannot sustain a cleavage crack, but may fail by plastic instability and necking on a gross scale. Stronger materials apparently also exhibit the same essentially plastic necking phenomenon on a more microscopic scale through the process of hole growth, although the macroscopic appearance of the failure is crack-like. On the opposite end of the scale, some materials like diamond and mica apparently can undergo pure brittle cleavage with no discoverable plasticity associated with the process. In between these two extremes, there apparently exists a class of materials where a cleavage crack in the true atomically sharp sense exists, but is surrounded and associated with an atmosphere of dislocations. (Burns and Webb, 1970; Burns, 1970). This intermediate case exhibits many complexities, such as high effective surface energies, plastic zones surrounding the crack tip, etc., but there is no reason to suppose that, provided hole growth is not occurring, the crack tip is not sharp on the atomic level. Of course, experimental proof of this

statement in any given case will be indirect at best; but the theoretical descriptions of cleavage and of hole growth are sufficiently different as to make one wish to distinguish as clearly as possible between the separate physical cases.

Kelly, Tyson and Cottrell (1967) were the first to pose this problem of brittle vs. ductile fracture in an essentially proper way when they attempted to test the self-consistency of the proposition that a cleavage crack can exist in a particular type of crystal. They, in effect, asked: "If a cleavage crack were created by some process in a crystal, would the tip spontaneously blunt as the result of shear by the atoms of the tip region?" They then postulated that such would be the case if the highest shear stress in the vicinity of the crack exceeded the theoretical shear strength of the material. However, this criterion cannot be sufficient for the crack to blunt, because the shear stress near a crack is not everywhere constant on the shear plane as it would have to be to cause the atoms to shear past one another uniformly. Instead, the stress is highly localized in the vicinity of the crack tip. By geometrical necessity, localized shear on a plane intersecting the crack tip caused by the high shear stresses there, matched to a non-sheared region at greater distances on the same plane, where the stress is below the theoretical strength simply defines a dislocation. Hence, a blunting reaction at the crack tip requires the production (or annihilation) of dislocations.

Kelly, Tyson, and Cottrell indeed discussed one kind of dislocation reaction for NaCl. They calculated the approximate energy to form a full metastable loop of dislocation near the crack in NaCl, and found the energy to be prohibitively high. Others have also discussed dislocation formation near crack tip. (Armstrong, 1966; Kitajima, 1966) Armstrong has, in particular, estimated the formation energy of a dislocation dipole loop completely surrounding a circular crack in a crystal. However, this type of dislocation interaction does not correspond to a blunting reaction and does not directly address the question we pose.

In this paper, we shall propose models for the production of a dislocation from the tip of the crack in such a way that after the dislocation expands under the external stress field as concentrated by the presence of the crack, an atomically sharp crack will have been blunted by one atomic plane, Figure 1. This blunted crack will then be trapped at the original lattice position until the external stress is increased substantially (when probably further dislocation blunting may be possible). Crystals for which dislocation emission is spontaneous can be expected to be good candidates for essentially plastic opening of the crack. Crystals for which there exists a large energy barrier for this emission can be expected to be good candidates for brittle cleavage (but perhaps where the crack has associated with it clouds of dislocations which are formed or captured through other processes in the nearby lattice). In order for a dislocation to blunt a crack, it is necessary for the Burgers vector to have a component normal to the crack plane, and for the slip plane to intersect the crack line (or crack front) along its whole length, i.e. the crack line must be contained within the slip plane.

It is, of course, possible to conceive of a process by which the crack may be blunted by dislocations which are formed from nearby sources and which are emitted on precisely the right plane to blunt the crack tip. In view of the fact that the stress field in a region surrounding a cleavage crack will be above the macroscopic plastic flow stress for the material, one might suppose this could be an effective blunting mechanism. However, macroscopic yield is a property associated only with regions of the size of many microns, even for fairly ductile materials. Hence, for a random position of the crack tip, the probability of finding a source on the correct plane at a distance from the crack for which the source can operate is small.

The plan of the paper is as follows. In the next section, we shall consider the various forces operating between a crack and a dislocation in two dimensions. These forces are 1) the force on a dislocation due to the stress field surrounding the crack, 2) the surface tension force caused by creating more surface at the blunted crack, and 3) the image force of the dislocation in the free surface of the crack. The first term repels the dislocation, and the latter two attract it toward the crack tip, giving rise to the possibility of a position of unstable equilibrium. In §III we estimate the activation energy for formation of a dislocation half loop out of the crack under the action of these forces when an energy barrier exists. Finally, in §IV we discuss the physical consequences of our calculations.

II. FORCES ON A DISLOCATION NEAR A CRACK TIP

Let us suppose that the loads on the body considered act symmetrically about the plane of a straight crack, so that before emission of the dislocation, only the tensile opening mode of relative crack surface displacement is present. If K_I is the "elastic stress intensity factor" (see, for example, Rice, 1968) due to the loads, then in two dimensions the in-plane shear stress acting at distance ρ on the slip plane of

Figure 2 is

$$\sigma_{\rho\phi} = K_I (8\pi\rho)^{-\frac{1}{2}} \sin \phi \cos \phi/2 \quad (1)$$

For this equation to be valid, ρ must be a small fraction of overall crack length. The anti-plane shear stress component (i.e., in the direction of b_s) is zero. The release of potential energy of the body and load system per unit of new crack area is

$$G = \frac{1-v^2}{E} K_I^2 \quad (2)$$

(E = Young's modulus, v = Poisson ratio.) At the fracture load predicted on the Griffith theory, $G = 2\gamma$ where γ is the true surface energy of the crack plane. Thus, if the applied load on the body is chosen as that which would cause fracture if no dislocations were emitted, then the force (shear stress times Burgers vector) on the dislocation segment shown in Figure 2 due to the applied load is

$$f_\sigma = \sigma_{\rho\phi} b_e = \left[\frac{E\gamma b}{4\pi(1-v^2)} \right]^{1/2} \sin \phi \cos \phi/2 \cos \psi \xi^{-1/2} \quad (3)$$

Here $\xi = \rho/b$ and $b_e = b \cos \psi$ is the edge component. The screw component b_s does not appear since the applied load induces no shear stress in this direction.

There will be an "image" force which tends to pull the dislocation back into the crack. This may be inferred from direct solution of the corresponding elasticity problem, as presented in most general form by Atkinson (1966) for anisotropic materials. A rather different derivation is presented in the Appendix, for a straight dislocation parallel to the crack tip in an isotropic material. (The procedure of the Appendix is based on energy considerations and properties of point functions, rather than on direct solution of the elastic field equations for a dislocation near a crack. The approach is readily generalized to other elastic interaction problems, and may be of some interest in itself.) The resulting image force (Equation A-14) is

$$f_i = -\frac{E b_e^2}{8\pi(1-v^2)\rho} - \frac{E b_s^2}{8\pi(1+v)\rho} \quad (4)$$

This is a remarkable result, because precisely the same expression for the image force is obtained in the case of a dislocation in a half space with its core lying parallel to, and at perpendicular distance ρ from, the free surface (see, for example, Hirth and Lothe, 1968). Both of the above forces are calculated on the assumptions of "infinitesimal" elasticity, and actual geometry changes at the crack tip due to emission of the dislocation have been neglected. The image force term may be rewritten from Figure 2 as

$$f_i = \frac{-E b^2 (1-v \sin^2 \psi)}{8\pi(1-v^2)\xi} \quad (5)$$

$$\xi = \rho/b$$

In Figure 1, as the dislocation is formed, a ledge is left behind, and as the core comes through the surface, forces due to the formation of the ledge must be included. As a function of the position, $\xi = \rho/b$, of the dislocation, the ledge energy is given by

$$v_l = \frac{2}{\pi} \gamma b \cos \psi \sin \phi \tan^{-1} \frac{2\xi}{e^{3/2} \xi_0} \quad (6)$$

In deriving (6), we have used the misfit function for a Peierls model of the dislocation with a width or core cut off ξ_0 , which is consistent with the quantity r_0/b where r_0 is defined by Hirth and Lothe (1963), p. 212. The $\sin \phi$ dependence is taken to approximately represent the modification of ledge energy from γb_e due to slip plane inclination.

The force is consequently

$$f_l = -\frac{2}{\pi} \frac{\gamma a \cos \psi \sin \phi}{\xi^2 + a^2} \quad \text{where } a = e^{3/2} \xi_0/2 \quad (7)$$

Note that the ξ^{-1} and ξ^{-2} attraction back toward crack, due to the image and ledge forces, outweighs the $\xi^{-1/2}$ force resulting from the applied load when ξ is small, whereas just the opposite happens when ξ is large. Hence, the equilibrium position of the dislocation is unstable, and the dislocation will be driven away indefinitely, until it reaches some obstacle, if it ever attains a distance from the crack tip greater than the equilibrium distance.

The critical distance, ξ_c at which a straight dislocation is in unstable equilibrium under these three forces is, from (3), (5), and (6), given by the solution of

$$f_{\text{tot.}} = \mu b \left[-\frac{1}{4\pi\xi} \frac{1-v \sin^2 \psi}{1-v} - \frac{2}{\pi \eta^2 \beta} \frac{a}{\xi^2 + a^2} + \frac{1}{\eta \beta} \left(\frac{1}{2\pi(1-v)\xi} \right)^{\frac{1}{2}} \right] = 0 \quad (7)$$

We have used the following abbreviations,

$$\begin{aligned} \frac{1}{\beta} &= \cos \psi \sin \phi \cos \phi/2, \\ \frac{1}{\beta'} &= \cos \psi \sin \phi, \\ \eta^2 &= \mu b / \gamma, \end{aligned} \quad (8)$$

where μ is the shear modulus. If the value of ξ_c is less than the core cut off, we presumably have a case where the method does not apply, and spontaneous generation is a good possibility. Equations (3) and (5) diverge for $\xi \rightarrow 0$, but, of course, the forces they represent must actually in toto approach zero as $\xi \rightarrow 0$ because of nonlinear core effects.

We display in Table I the relevant physical data with the values we have chosen. The values of γ contain the greatest degree of uncertainty, and we discuss the problems associated with surface energy for our calculation in §IV. Table II displays the results of the solution of Eq. (7) for the various solids, together with suggested values from Hirth and Lothe (1968) for the elastic cut-off for comparison. We also list some cruder estimates of the critical distance, ξ_c' and ξ_c'' . In ξ_c' , we neglect the effect of the ledge in Eq. (7), and then the condition is given by

$$\xi_c' = \frac{(1-\nu \sin^2 \psi)^2}{8\pi(1-\nu)} \quad \beta^2 \quad \frac{\mu b}{\gamma} \quad (9)$$

In the second estimate, we average over the geometrical and crystallographic effects still present in (9), giving an even cruder estimate,

$$\xi_c'' \approx \frac{\mu b}{10\gamma} \quad (10)$$

It is interesting to enquire how splitting the dislocation will affect the calculations, since certainly in the face centered metals, splitting does occur. In this case, the Burgers vector will be lowered in magnitude, and the angle, ψ , will be changed. So far as the size of the Burgers vector is concerned, Eq. (7) is dimensionless, and is not affected. The size of the cut-off is sensitive to b , however, and in fact the value we have chosen is just that appropriate to the split dislocation in the face centered metals. Eq. (7) does contain the crystallography of the Burgers vector through the angle, ψ , however, in a rather complicated manner. For the whole dislocation, $\psi=30^\circ$, and there are two possibilities for the two partials, $\psi=0^\circ$ and $\psi=60^\circ$. For the first value, the ratio of the various terms in Eq. (7) is only changed about 5% from their values for the whole dislocation, thus leaving the results of Table II unchanged. For the second case, where $\psi=60^\circ$, the first term in Eq. (7) becomes about 50% larger than for the whole dislocation, thereby increasing the value of ξ_c . We show a few values for this partial in Table II.

III. ENERGY CONSIDERATIONS

If the equilibrium point, ξ_c , is larger than the core cut-off, then there is an energy hump for the dislocation to jump in order to be emitted from the crack. Clearly, in this case, it will be impossible for a uniform straight line to be emitted from the crack, because for an infinite length of dislocation, the energy diverges. Instead, a local fluctuation in the form of an irregular loop will be formed which, beyond the saddle point configuration, will expand under the external stress. The factors determining the saddle point configuration are the same as before. Image and ledge forces will predominate for small loop sizes, while for larger ones the external stress is dominant.

In the elastic three dimensional problem, even in the isotropic regime, the problem of determining the saddle point configuration and consequently its energy is intractable in part because the force fields are variable, and in part because rigorous treatments of three dimensional dislocation problems are not possible when the shape is complicated. In fact, although we know the image force for a straight dislocation parallel to the crack, image terms are known to be complex when the shape is more complicated, even without the additional complexity of the crack half surface. We shall thus proceed by developing some qualitative insights into the problem, and then make some simplifying assumptions about the saddle point configuration which allow us to make meaningful calculations.

First of all, the stress field due to the applied load is straightforward, and yields a normal force, f_σ , on a dislocation element, $d\ell$, given by the local value of the stress, $\underline{\sigma}$. This force is

$$f_\sigma = (\underline{\sigma} \cdot \underline{b}) \times d\ell \quad (11)$$

The ledge force is always a minor term, except possibly very near the crack surface. It will have the primary effect of drawing together the two ends of the loop where they touch the crack surface. It will act just like a pure surface tension on these ends because of the surface energy required to expose the ledge as the loop expands.

The image force, as mentioned above is more complex. In problems of dislocations interacting with normal surfaces, it is a useful first approximation to simply replace the image terms by the action of an image dislocation reflected in the surface. This replacement is not normally rigorous, but yields a fair approximation. Since in our case of the crack, the straight dislocation yields the same result as for a normal surface, we shall adopt this simple stratagem for the crack. This means that in order to calculate the energy of a dislocation half loop configuration which ends at the crack surface, we need do no more than calculate the energy of a full loop including the reflected image, and take half of the result. This energy will then include the image terms.

One further very important result follows from the presence of the image term. The image term requires that when a dislocation approaches an open surface, it must cut the surface at normal incidence. The predominance of the image term in the immediate vicinity of the crack surface will require the same boundary condition on the dislocation at the crack surface. This condition, in conjunction with the magnitude of the stress in the region beyond ξ_c are the crucial determinants of the total activation energy.

We note one final qualitative characteristic of the two dimensional force field which is very suggestive for our three-dimensional treatment. Except for the ledge term in Eq. (7), which is important only very near the crack tip, the net force is the difference between $1/\xi$ and $1/\sqrt{\xi}$, a very broad function which we have plotted in Fig. 3. The point at which this function reaches one half its maximum value is about $1.5 \xi_c$, and it does not fall below this value again till ξ becomes approximately $50 \xi_c$. Thus, throughout this very broad range, the balance between these two major forces is nearly constant. Under a constant normal force, of course the equilibrium shape of the dislocation has constant curvature, and is circular. For values of ξ less than ξ_c , the force becomes negative, and including the effect of the ledge, the curvature will also reverse. Hence the general shape of the saddle point configuration will be as sketched in Fig. 4.

In view of these qualitative background comments, we feel justified in proceeding with the assumption that the approximate equilibrium shape is the simple half circle depicted in Fig. 4a. In view of the broad maximum in the effective force field, we believe the energy of the activated state thus computed is a reasonable estimate of the true energy, and our use of the circular shape probably introduces no major errors in the calculation.

We thus calculate the total energy of the activated state of the system, which consists of three parts. 1) The self energy of the dislocation half loop. As mentioned before, this energy will automatically include the image term contribution. 2) The energy of the ledge. 3) The energy gained by the dislocation loop as it expands under the influence of the stress surrounding the crack. In order to determine the size of the loop of the activated state, we locate the maximum energy of the loop as a function of the loop radius.

The self energy of a dislocation half loop as given by Hirth and Lothe (1968) is

$$U_{\text{self}} = \mu b^3 r \frac{2-v}{8(1-v)} \ln \frac{8r}{e^2 \xi_0} \quad (12)$$

In this equation, r and ξ_0 are respectively the radii of the half circle and radii of the core cut-off in units of the Burgers vector, b . ξ_0 is the same quantity as used for the core cut-off in §II.

To the self energy must be added the energy of the ledge formed as the loop expands. We write this in the form

$$U_{\text{ledge}} = 2\gamma b^2 \cos \psi \sin \phi (r - \xi_0) \quad (13)$$

Eq. (13) simplifies the expression for a ledge as we used it in §II. Here we assume that when the radius r is greater than the cut-off radius, the ledge is fully formed, and that the energy is linear in the radius of the loop.

Finally, we compute the energy gained by the half loop in the stress field of the crack tip. In terms of Eq. (3) and Figure 5, the energy to expand the loop from the initial radius, ξ_c , to r is

$$U_\sigma = - \left[\frac{E\gamma b}{4\pi(1-\nu^2)} \right]^{\frac{1}{2}} b^2 \cos \psi \sin \phi \cos \phi/2$$

$$\int_{\xi_c}^r dr \int_0^{\pi} d\theta \frac{r}{\sqrt{r \sin \theta}} \quad (14)$$

Noting that

$$\int_0^{\pi} \frac{d\theta}{\sqrt{\sin \theta}} = \frac{1}{2} \pi \frac{r \left(\frac{1}{4}\right)}{r \left(\frac{3}{4}\right)} \quad (15)$$

we then have

$$U_\sigma = -0.9862 \sqrt{\frac{2}{1-\nu}} \mu b^3 \sqrt{\frac{\gamma}{\mu b}} \sin \phi \cos \psi \cos \phi/2$$

$$\left(\frac{3}{r^2} - \frac{3}{\xi_c^2} \right) \quad (16)$$

The total energy change for a crack which has emitted a dislocation loop is then

$$\begin{aligned}
 U_{act.} &= \mu b^3 \left[r U_o \ln \frac{r}{\xi_o} + U_L (r - \xi_o) - \frac{2}{3} U_s \left(\frac{3}{r^2} - \frac{3}{\xi_o^2} \right) \right] \\
 U_o &= \frac{2-v}{8(1-v)} \\
 U_L &= 2 \frac{\gamma}{\mu b} \cos \psi \sin \phi \\
 U_s &= \frac{2.092}{\sqrt{1-v}} \sqrt{\frac{\gamma}{\mu b}} \sin \phi \cos \psi \cos \phi/2
 \end{aligned} \tag{17}$$

From (17), the condition for the activated state is

$$\frac{dU_{act.}}{dr} = 0 = U_o \ln r/\xi_o + U_L + U_s r^{1/2} \tag{18}$$

Schematically, the three terms in (17) are sketched in Figure 6. The stress term eventually always dominates the other two for large r , but depending upon the parameters, the self energy plus the ledge term may be dominant for values near ξ_o . That is to say, depending upon the parameters, there may be a spontaneous emission of a dislocation loop with no activation energy, or there may be a finite activation energy to form the loop whose radius is determined by Eq. (18).

We have solved Eq. (17) for the critical loop size, and calculated the activation energy for the list of materials given in Table I. The results are listed in Table III. Further, the functional variation of the activation energy with $\gamma/\mu b$, ξ_o , and orientation parameters is shown in Figure 7. In this plot, the activation energy [Eq. (17)] is plotted after γ is eliminated through Eq. (18). Here it is convenient to plot the dimensionless energy

$$u_{act.} = \frac{U_{act.}}{\frac{(2-v)^2}{8(1-v)} \frac{\beta^2}{\beta'} \mu b^3} \tag{19}$$

in terms of

$$S = \frac{16(1-v)}{5\beta'(2-v)} \frac{\gamma}{\mu b} \quad \text{and} \quad R_o = \frac{16 \beta'}{5(2-v)\beta^2} \xi_o . \quad (20)$$

Indeed, these forms have been chosen because, for typical values of v and the orientation parameters, they reduce to

$$u_{act.} \approx \frac{U_{act.}}{\mu b^3}, \quad S \approx \frac{\gamma}{\mu b}, \quad R_o \approx \xi_o . \quad (21)$$

It is seen that the behavior divides mainly into two kinds: If the orientation-dependent core parameter, R_o , is small, there is a substantial energy barrier to dislocation nucleation for all values of $\gamma/\mu b$ (i.e., $U_{act.} \geq 0.1 \mu b^3$). On the other hand, if R_o is large there will be an energy barrier only if the surface energy parameter, S , is smaller than that at which the curves cross the S axis; otherwise there is spontaneous nucleation. The curves for the larger values of R_o rise so steeply that there is essentially a critical value of S below which the energy barrier is substantial, and above which there is spontaneous nucleation, although finer examination shows that there is a narrow range of R_o and S values for which $U_{act.}$ is low enough that thermal activation could blunt the crack for sufficiently long time scales of load application.

IV. PHYSICAL RESULTS AND INTERPRETATION

a) Surface Energy. Among the experimentally determined values listed in Table I, the values of γ are the ones for which the only important uncertainties exist.

For tungsten, Cordell and Hull (1969) find that the surface energy varies from a low value of 1700 cgs at low temperature to 6000 cps at higher temperature. The higher value apparently is due to plasticity induced in the vicinity of the moving crack. Other values have been measured by other workers intermediate to these extremes, but we believe the low value listed represents the bare crack.

NaCl is claimed by Class (1964) in his thesis to have a surface energy of 115 cgs, and this value is adopted by Kelly (1966). On the other hand, we believe the value 250 is more likely. It is in the range of the experiments of Gilman (1960), Wiederhorn (1970), and Benson, et al (1955, 1956, and 1959), and is in reasonable agreement with the theoretical calculations, which for this crystal should not have a large error, see Tosi (1964) and MacMillan and Kelly (1972). We list both values, and results for both, however.

For Al_2O_3 , we have a range of values in the literature all the way from 1000 cgs as given by Kingery (1954) for the basal plane to 6000 cgs as determined in cleavage experiments on the rhombohedral planes by Wiederhorn (1969). Wiederhorn also reports that cleavage is not possible on the basal planes, and in a private communication has noted that the cleavage surface energy for these planes must in consequence be in excess of 40,000 cgs! One wonders if the value reported by Kingery (not measured in cleavage) is not actually either that for a restructured surface or a

composite value for a dimpled surface whose average orientation is [0001], but not the true basal plane. Consequently, we use $\gamma = 6000$ cgs in our work.

In Zn, Maitland and Chadwick (1969) have measured a range of values from 100 cgs (confirmed by other previous authors), to 575 cgs, depending upon the technique used for making the measurement. Because of weaknesses in the analysis as applied to the experiments yielding the lower value, they believe the value of 575 cgs is to be preferred.

But experimental difficulties do not exhaust our problems with the surface energy. One must also be certain that the surface energy as measured experimentally and the surface energy as we use it are synonymous. In our work, the correct γ is derived as the energy necessary to break bonds at a crack tip. Even in a pure cleavage event where no dislocations are produced, this process may not correspond to the thermodynamic surface energy because of relaxation effects which are possible on some crystal surfaces, such as Si, where the surface is entirely restructured. For this reason, the value chosen for Si is derived in a cleavage experiment, and for diamond is calculated from the value of the carbon-carbon bond. Unfortunately no cleavage surface energies are available for Ge. We also note a further point of rigor: In very hard crystals where lattice trapping is important, the γ measured to grow a crack is different from the γ measured to heal a crack, Hsieh and Thomson (1973).

b) Two Dimensional Results. The results in Table III suggest that the face-centered crystals, with the possible exception of Ni which has a borderline ξ_c , are unstable to dislocation formation, since the critical distance, ξ_c , is less than the core radius, ξ_0 . Since all the elastic forces become impossible to define inside the core radius, and since the repulsive forces are dominant for all distances larger than the core, we believe a crack in these crystals cannot sustain the large shear forces at its tip without forming the dislocation spontaneously. Na, of the body-centered crystals, probably also spontaneously emits the dislocation because of the small size of ξ_c , and also because we believe that in this case ξ_0 is not so small as $2/3$, as is assumed for the other body-centered cubics. In all other cases, ξ_c is sensibly larger than the core size, and we believe this gives rise to an energy hump the dislocation must negotiate as it is formed.

We have listed in Table II two other cruder estimates of ξ_c . In the first, we neglect the ledge term and in the second average over the geometry. Both are pretty fair approximations to the more accurate values for the brittle materials in the lower half of the table. The ledge term is seen to be important for the softer crystals, as one would expect.

The dimensionless ratio, $\mu b/\gamma$, related to our ξ_c has already entered into Armstrong's (1966) discussion of the brittle vs. ductile competition, and we see that it is indeed explicit in our own work. However, in our theory, as one progresses down the list of crystals in Table II, it is the opposite tendency of the growing value of $\mu b/\gamma$ and the decreasing value of the core cut-off which makes the difference between the ductile face-centered cubics and the more brittle body-centered cubics.

We note in Table II the positions of iron and nickel between the obviously ductile and obviously brittle solids. We give two calculations for iron. In one, the crack line runs along a cube direction, [100], and in the second, the crack line runs along [110]. The second is actually that observed by Tetelman and Robertson (1963) in silicon iron, but it is the former which has the interesting low value of ξ_c .

We have listed the results for a split dislocation for a noble metal and for nickel. (Aluminum has small or no splitting.) The results shown are for only one of the partials. In the case shown, the partial has unfavorable geometrical factors, since it is not oriented to cause the crack to open effectively. In this unfavorable case, the critical radii are slightly increased, but not enough to change our general results.

c) Three Dimensional Results. The three dimensional results for the estimated activation energy as given in Table III confirm the two dimensional findings. We find a negative activation energy for the face-centered cubics, which again means that since all energies are cut off at the core radius, by the time any dislocation is well formed, it is under the primary influence of the repulsive forces. Again, Na would seem to have an essentially spontaneous emission, not only because of the small value of the calculated activation energy, but also because we have probably underestimated the true dislocation core size of this very soft crystal.

The main surprise when comparing the two- with the three-dimensional results is the very large values obtained for the activation energy of the brittle crystals, even though ξ_c is usually a small number. One might suppose that it would take only a small energy to push a local segment of dislocation past ξ_c , say in NaCl, over a small front of the crack tip, and that the repulsive force would then be able to dominate the picture sufficiently to expand the fluctuation indefinitely. However, the reason this is not so is that the dislocation must meet the crack surface at normal incidence. Otherwise, the forces there will collapse the fluctuation no matter what happens to that portion lying over the hump beyond ξ_c . In order for the dislocation to meet the surface perpendicularly, a full half loop of dislocation must be formed in the region of repulsive forces, which is costly in dislocation line energy.

Thus we find a very strong tendency for crystals to be either completely ductile, or completely brittle, so far as dislocation emission is concerned. Iron and nickel are the only interesting cases where our calculations suggest that the activation energy may be sufficiently low that thermal fluctuations could play a role. With the various uncertainties in our calculations, we are unfortunately not able to pin down the values in these cases sufficiently to make a definite prediction.

Except for iron, sodium, and the face-centered cubics, we feel confident in predicting that no spontaneous or thermally assisted blunting of a crack tip can occur in the other crystals investigated. Even with the uncertainties in the γ and the other approximations made, crystals like LiF and NaCl (to say nothing of the hexagonal metals) seem immune enough to this process. This conclusion means that if blunting does occur it must be because of dislocations produced outside the tip region, and which are then attracted toward, and collide with it.

Our conclusions are at variance with the often quoted claim that cracks cannot remain sharp (and the crystals thus be brittle) if the shear stress at the crack tip is larger than the theoretical shear stress of the homogeneous crystal. As we stated in the introduction, a shear stress at the value of the theoretical shear strength will cause the crystal to break down only if the stress is homogeneously applied across an entire plane running through the crystal. If the stress is only applied locally on that plane, then atoms where the stress has dropped below the maximum value will not be displaced from their lattice positions, and atoms where the force is maximum will not necessarily be displaced even though the stress is above the theoretical shear strength because of the resistance offered by atoms in the undeformed region of the plane.

Our conclusions suggest that so far as spontaneous emission is concerned, atomically sharp cleavage cracks are by no means a minority occurrence in materials. When the condition $\mu_b/\gamma > 7.5-10$ is approximately satisfied, we have reason to expect the crack to remain sharp, though geometrical factors and variations in core size make this condition only approximate. This condition, in the cases investigated, is satisfied for all but the face-centered cubic metals, and certain borderline body-centered metals.

Our conclusions leave the precise morphology of cleavage cracks ultimately undetermined, however, because they do not address blunting reactions due to dislocations which might be attracted to the crack top from the surrounding crystal. Processes which lower the cleavability by increasing the effective cleavage surface energy through the action of dislocation atmospheres trapped by the stress field of the crack are also not addressed here. On the other hand, our work does allow an evaluation of environmental effects which can be understood in terms of a lowering of γ . By increasing the ratio μ_b/γ , these could presumably make possible atomically sharp cracking, even in solids such as fcc crystals which normally show ductile response. Then the 'cleavage' is not necessarily fast-running, but can proceed only as fast as reactions take place to bring about the requisite lowering of γ at the tip. It is possible that some environmentally assisted crack growth can be understood in this way.

TABLE I
Physical Parameters of Crystals

Crystal	Cleavage System	Slip System	γ cgs	$\mu \times 10^{11}$	ν	b Angstroms	$\eta =$ $\sqrt{\frac{\mu b}{\gamma}}$
Face Centered Metals							
Pb	(001)	($\bar{1}\bar{1}\bar{1}$)	440 ⁽¹⁾	0.727	0.387	3.49	2.401
Au	[110]	[101]	1418 ⁽²⁾	2.37	0.412	2.87	2.190
Cu			1688 ⁽²⁾	4.05	0.324	2.55	2.473
Ag			1135 ⁽²⁾	2.56	0.354	2.88	2.549
Al			840 ⁽¹⁾	2.51	0.347	2.85	2.918
Ni			1725 ⁽³⁾	7.48	0.276	2.49	3.286
Body Centered Metals							
Na	(001)	(011)	237 ⁽¹⁾	0.243	0.201	3.66	1.937
Fe	[100]	[111]	1975 ⁽⁴⁾	6.92	0.291	2.49	2.954
W			1700 ⁽⁵⁾	16.0	0.278	2.74	5.078
Fe*	(001)/[110]	(110)/[111]	1975 ⁽⁴⁾	6.92	0.291	2.49	2.954
Ionic							
LiF	(001)	(011)	480 ⁽⁶⁾	4.40	0.187	2.848	5.109
NaCl	[100]	[011]	250 ⁽⁷⁾	1.63	0.248	3.988	5.099
			(115) ⁽⁸⁾	"	"	"	(7.518)
MgO			1200 ⁽⁹⁾	11.57	0.173	2.974	5.355
Al ₂ O ₃	(1012)/[1210]	(0001)/[1120]	6000 ⁽¹⁰⁾	23.3	0.200	4.75	4.295
Diamond Cubic							
Si	(111)	($\bar{1}\bar{1}\bar{1}$)	1200 ⁽⁴⁾	6.05	0.215	3.83	4.394
Ge	[011]	[$\bar{1}\bar{1}0$]	600 ⁽¹⁾	4.92	0.200	4.00	5.727
C			5400 ⁽¹²⁾	50.9	0.068	2.52	4.874
Hexagonal Metals							
Be	(0001)	(ijk0)	1620 ⁽¹⁾	15.5	0.333	3.58	5.849
Zn	[0001]	[0001]	575 ⁽⁹⁾	3.83	0.333	4.94	5.736

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TABLE II
Two Dimensional Results

Crystal	Core Cut-Off	ξ_c	Approximate Values	
			ξ_c' w/o ledge	ξ_c'' $\mu b/10\gamma$
Pb	2	1.1	0.88	0.58
Au	2	0.85	0.65	0.48
Cu	2	1.00	0.77	0.61
Ag	2	1.09	0.85	0.65
Al	2	1.4	1.1	0.85
Ni	2	1.7	1.3	1.08
Na	2/3	1.2	0.54	0.375
Fe	2/3	1.9	1.3	0.87
W	2/3	4.0	3.9	2.6
Fe*	2/3	2.7	1.9	0.87
LiF	0.25	3.2	2.9	2.6
NaCl	{ 0.25 } (0.25)	{ 3.4 } (7.0)	{ 3.2 } (7.0)	{ 2.6 } (5.6)
MgO	0.25	3.4	3.2	2.9
Al ₂ O ₃	0.25	2.3	2.1	1.8
Si	0.25	2.2	2.0	1.9
Ge	0.25	3.7	3.3	3.3
C	0.25	2.4	2.2	2.4
Be	2/3	4.5	4.1	3.4
Zn	2/3	4.3	3.9	3.3
Partial dislocations	$b = \frac{1}{\sqrt{12}} [2\bar{1}\bar{1}], \psi=60^\circ$			
Cu	2	1.4	0.91	0.35
Ni	2	2.3	1.6	0.62

TABLE III
Three Dimensional Results

Crystal	Activation Energy (Electron Volts)	Radius of Activated Loop (in units of δ)
Pb		
Au		
Cu		
Ag		
Al		
Ni		
	Spontaneous Emission - No activated state for $r > \xi_0$.	
Na	0.02	1.5
Fe	2.2	5.1
W	329	50.7
Fe*	19	17
LiF	58	32
NaCl	{ 62 } (240)	{ 33 } (95)
MgO	205	37
Al ₂ O ₃	852	20
Si	111	20
Ge	260	42
C	351	27
Be	180	23
Zn	107	21.2

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Appendix: Image Force on Dislocation near a Crack Tip

To compute the image force, consider Figure 8 in which a straight dislocation line lies parallel to a crack front, with the slip plane intersecting the fracture plane at distance α ahead of the tip. We are ultimately interested in the case $\alpha=0$, but by considering α as variable we can use energy methods to compute the force.

Suppose that the body containing the crack is subjected to three generalized boundary forces Q_I , Q_{II} , and Q_{III} , each of which if exerted singly upon a dislocation free body would cause only a Mode I, II, or III crack tip singularity, respectively. Let q_I , q_{II} , and q_{III} be the associated generalized displacements. These are defined so that

$$\sum_J Q_J dq_J$$

is the work of boundary loadings per unit thickness into the plane of the figure. The sum on J extends from I to III. Hence, if we let U be the strain energy of the body per the same unit thickness,

$$dU = \sum_J Q_J dq_J + G d\alpha - f dp, \quad (A1)$$

where the respective contributions to energy changes come from load-point displacements dq_J , crack advance $-d\alpha$, and dislocation glide dp ; G is the crack extension force (or energy release rate) and f is the force on the dislocation.

The last equation may be rewritten as

$$d(U - \sum_J Q_J q_J) = -\sum_J q_J dQ_J + G d\alpha - f dp.$$

Further, since the terms on the right constitute an exact differential, we may write the Maxwell relation

$$\left(\frac{\partial G}{\partial p}\right)_{\alpha, Q} = -\left(\frac{\partial f}{\partial \alpha}\right)_{p, Q} \quad (A2)$$

This is a fundamental relation for it allows us to compute the force on the dislocation solely from a knowledge of elastic fields induced by each of the forces Q_J . To see this, recall that the crack energy release rate is given by (e.g., Rice, 1968)

$$G = \frac{1-\nu^2}{E} (K_I^2 + K_{II}^2) + \frac{1+\nu}{E} K_{III}^2 , \quad (A3)$$

where the K 's are stress intensity factors for the three modes. These are due both to the boundary forces Q_J and to the interaction of the dislocation stress field with the crack, and take the forms

$$K_J = k_J(\alpha) Q_J + L_J(\alpha, \rho), \quad J=I, II, III \quad (A4)$$

Here each k_J is the Mode J stress intensity factor induced per unit of the corresponding boundary force. Each is assumed to be known for all crack lengths and hence can be considered as given function of α . The unknown functions L_J are the stress intensity factors induced by the dislocation. The force on the dislocation is given by

$$f = b_e [t_I(\alpha, \rho) Q_I + t_{II}(\alpha, \rho) Q_{II}] + b_s t_{III}(\alpha, \rho) Q_{III} + g(\alpha, \rho) \quad (A5)$$

Here b_e is the edge and b_s the screw Burgers vector component; t_I and t_{II} are the shear stresses induced on the glide plane, at the dislocation position, in the edge direction per unit boundary force Q_I and Q_{II} , respectively; t_{III} is the shear stress in the screw direction induced per unit force Q_{III} . These shear stresses are to be considered as known functions of crack length and dislocation position, and hence of α and ρ . The unknown force term g is that due to the dislocation itself, i.e., the image force, and our object is to compute it.

By substituting for G and f as above in the Maxwell relation (A2), we obtain

$$\frac{2(1-v^2)}{E} [(k_I Q_I + L_I) \frac{\partial L_I}{\partial \rho} + (k_{II} Q_{II} + L_{II}) \frac{\partial L_{II}}{\partial \rho} + \frac{1}{1-v} (k_{III} Q_{III} + L_{III}) \frac{\partial L_{III}}{\partial \alpha}] \\ = -b_e \frac{\partial t_I}{\partial \alpha} Q_I - b_e \frac{\partial t_{II}}{\partial \alpha} Q_{II} - b_s \frac{\partial t_{III}}{\partial \alpha} Q_{III} - \frac{\partial g}{\partial \alpha}$$

This must hold for all values of the Q 's. Hence by equating coefficients of each Q_J ,

$$\frac{\partial L_J}{\partial \rho} = \frac{-E b_e}{2(1-v^2) k_J} \frac{\partial t_J}{\partial \alpha}, \text{ for } J=I, II; \frac{\partial L_{III}}{\partial \rho} = \frac{-E b_s}{2(1+v) k_{III}} \frac{\partial t_{III}}{\partial \alpha}. \quad (A6)$$

And by equating sides when each $Q_J = 0$,

$$\frac{\partial g}{\partial \alpha} = -\frac{1-v^2}{E} \frac{\partial}{\partial \rho} (L_I^2 + L_{II}^2 + \frac{1}{1-v} L_{III}^2) \quad (A7)$$

The calculation of the image force now involves simple integrations:

(i) First, we note that the right sides in (A6) involve known functions of α and ρ ; each L_J is determined by integrating these at fixed α from the ρ of interest to a large value of ρ , say to ∞ or to the specimen boundary, at which the L 's may be taken as zero. (ii) Thus the right side of (A7) is determined, and g is obtained by integration from the α value of interest (zero in our case) to a large value of α at which g may be taken as zero.

Now, since we are interested in a dislocation rather near to the crack tip, it will suffice to consider a semi-infinite crack in an infinite body. Also, the solution for the L 's and g cannot depend on the particular nature of the load systems denoted by the Q 's. Indeed, the right sides of (A6) are universal functions, the same for all load systems inducing a given crack tip mode (see Rice, 1972). Hence, for simplicity, we can choose load systems which act so far from the crack

tip that the characteristic inverse-square-root elastic stress distribution gives the entire stress field, and that the k 's are virtually constant, for all crack distances a of interest. Let $(\sigma_{ij})_J$ denote the stress field for a given loading mode, J ; this will be of the form

$$(\sigma_{ij})_J = \frac{k_J Q_J}{\sqrt{r}} [F_{ij}(\theta)]_J, \quad i,j=x,y,z. \quad (A8)$$

Here the F 's are functions of θ , particular to each mode, that are tabulated e.g. by Rice, 1968, pp. 216-217. From these the shear stresses on the dislocation, per unit boundary loads, are identified from

$$Q_J t_J = \frac{(\sigma_{yy})_J - (\sigma_{xx})_J}{2} \sin 2\phi + (\sigma_{xy})_J \cos 2\phi,$$

for $J = I, II$, and

$$Q_{III} t_{III} = (\sigma_{yz})_{III} \cos \phi - (\sigma_{xz})_{III} \sin \phi.$$

Upon substitution from (A8), these give

$$\begin{aligned} t_I &= k_I (8\pi)^{-1/2} \sin \phi \operatorname{Re} [e^{i\phi} (\xi^{-1/2} - a \xi^{-3/2})] \\ t_{II} &= k_{II} (8\pi)^{-1/2} \operatorname{Re} [2e^{2i\phi} \xi^{-1/2}] + \sin \phi \operatorname{Im} [e^{i\phi} (\xi^{-1/2} - a \xi^{-3/2})] \quad (A9) \\ t_{III} &= k_{III} (2\pi)^{-1/2} \operatorname{Re} [e^{i\phi} \xi^{-1/2}], \end{aligned}$$

where i is the unit imaginary number, Re and Im denote real and imaginary parts, and where

$$\xi = r e^{i\theta} = a + \rho e^{i\phi}.$$

Hence the first of (A6) becomes

$$\begin{aligned} \frac{\partial L_I}{\partial \rho} &= - \frac{Eb}{2(1-v^2)k_I} \left\{ k_I (8\pi)^{-1/2} \sin \phi \frac{\partial}{\partial a} \operatorname{Re} [e^{i\phi} (\xi^{-1/2} - a \xi^{-3/2})] \right\} \\ &= \frac{3 Eb}{8(2\pi)^{1/2} (1-v^2)} \sin \phi \operatorname{Re} [e^{i\phi} (\xi^{-3/2} - a \xi^{-5/2})] \end{aligned}$$

Multiplying by $d\rho$ and recognizing that $e^{i\phi}d\rho = d\xi$, so that integration on ρ becomes integration on ξ inside the brackets, we have

$$\begin{aligned} L_I &= \frac{3 E b_e \sin \phi}{8(2\pi)^{1/2} (1-v^2)} \operatorname{Re}[-2 \xi^{-1/2} + \frac{2}{3} a \xi^{-3/2}] \\ &= \frac{-E b_e}{4(1-v^2) (2\pi r)^{1/2}} [3 \sin \phi \cos \frac{\theta}{2} - \sin(\phi-\theta) \cos \frac{3\theta}{2}] , \end{aligned} \quad (A10)$$

where the constant of integration is chosen so that L_I vanishes at $\rho=\infty$.

In a similar way we find

$$\begin{aligned} L_{II} &= \frac{-E b_e}{4(1-v^2) (2\pi r)^{1/2}} [2 \cos \phi \cos \frac{\theta}{2} - \sin \phi \sin \frac{\theta}{2} + \sin(\phi-\theta) \sin \frac{3\theta}{2}] \\ L_{III} &= \frac{-E b_s}{2(1+v) (2\pi r)^{1/2}} \cos \frac{\theta}{2} \end{aligned} \quad (A11)$$

Now that the L 's are known, we have determined the effect of the dislocation on the stress intensity factors K_J (A4) and, further, we can substitute into (A7) to determine the image force. Since each of the L 's is proportional to $r^{-1/2}$, (A7) is of the form

$$\begin{aligned} \frac{\partial g}{\partial \alpha} &= - \frac{\partial}{\partial \rho} \left[\frac{Q(\theta, \phi)}{r} \right], \\ \text{where } Q(\theta, \phi) &= \frac{1-v^2}{E} r (L_I^2 + L_{II}^2 + \frac{1}{1-v} L_{III}^2) . \end{aligned} \quad (A12)$$

But by using the relations

$$\frac{\partial}{\partial \alpha} = \cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta}, \quad \frac{\partial}{\partial \rho} = \cos(\phi-\theta) \frac{\partial}{\partial r} - \frac{\sin(\phi-\theta)}{r} \frac{\partial}{\partial \theta}$$

between partial derivatives, one may readily derive the identity

$$- \frac{\partial}{\partial \rho} \left[\frac{Q(\theta, \phi)}{r} \right] = \frac{\partial}{\partial \alpha} \left[\frac{\sin(\phi-\theta)}{\sin \theta} \frac{Q(\theta, \phi)}{r} \right]$$

This lets us integrate (A12) immediately. We must, however, append a 'constant' of integration, which may depend on ρ ($= r \sin \theta / \sin \phi$), and which assures that $g \rightarrow 0$ as $\alpha \rightarrow \infty$. This means that $g \rightarrow 0$ as $r \rightarrow \infty$, $\theta \rightarrow 0$ in such a way that $r \sin \theta$ remains finite. Integration of (A12) subject to this condition gives the image force

$$g = \frac{\sin(\phi-\theta) Q(\theta, \phi) - \sin \phi Q(0, \phi)}{r \sin \theta}, \quad (A13)$$

where Q is defined from (A10,11) via (A12).

In the text of the paper we were concerned with the case $\alpha=0$, so that $\theta=\phi$ and $r=\rho$. In that case

$$g = -\frac{Q(0, \phi)}{\rho} = -\frac{E b_e^2}{8\pi(1-v^2)\rho} - \frac{E b_s^2}{8\pi(1+v)\rho}, \quad (A14)$$

where the latter form comes from identifying $Q(0, \phi)$, which is found to be independent of ϕ . Remarkably, this is the same image force as for a dislocation line at distance ρ along its slip plane from the boundary of a half-space. In fact, the result for this latter case is also obtainable from (A13) by letting the crack tip pass far beyond the site of the dislocation, $\alpha \rightarrow \infty$. This means that we let $\theta \rightarrow \pi$, $r \rightarrow \infty$ while keeping $r \sin \theta$ finite (it equals $\rho \sin \phi$). By direct evaluation one finds that $Q(\pi, \phi) = 0$, so that the image force from the half-space boundary is also given by (A14).

FIGURE CAPTIONS

Figure 1. An atomically sharp crack is blunted when a dislocation is emitted from the tip when the Burgers vector has a normal component to the fracture plane.

Figure 2. Geometry of the dislocation, crack configuration in two dimensions. b_e and b_s are perpendicular and parallel components of the Burgers vector relative to the crack.

Figure 3. The function $f = -A/\xi + B/\sqrt{\xi}$ plotted to show its broad maximum.

Figure 4. Schematic representations of saddle point dislocation configurations. At distances greater from the crack than ξ_c , the curvature is positive, while at less than ξ_c , the curvature is negative. The dislocation always has normal incidence at the surface because of the preponderance of the image term near the surface. a) ξ_c is small and the region of negative curvature is negligible. b) Intermediate ξ_c . c) Large ξ_c .

Figure 5. Configuration for calculating the work done under the crack stress by the expanding dislocation. The work integration has the lower limit shown when $r=\xi_o$.

Figure 6. Schematic variation of the three terms in Eq. (17) as a function of the radius.

Figure 7. Dependence of activation energy for dislocation nucleation on $S (\approx \gamma/\mu b)$ and $R_o (\approx \xi_o)$; exact definitions of S and R_o , and normalization of energy, are given in text.

Figure 8. Configuration of crack and dislocation for computation of the image force.

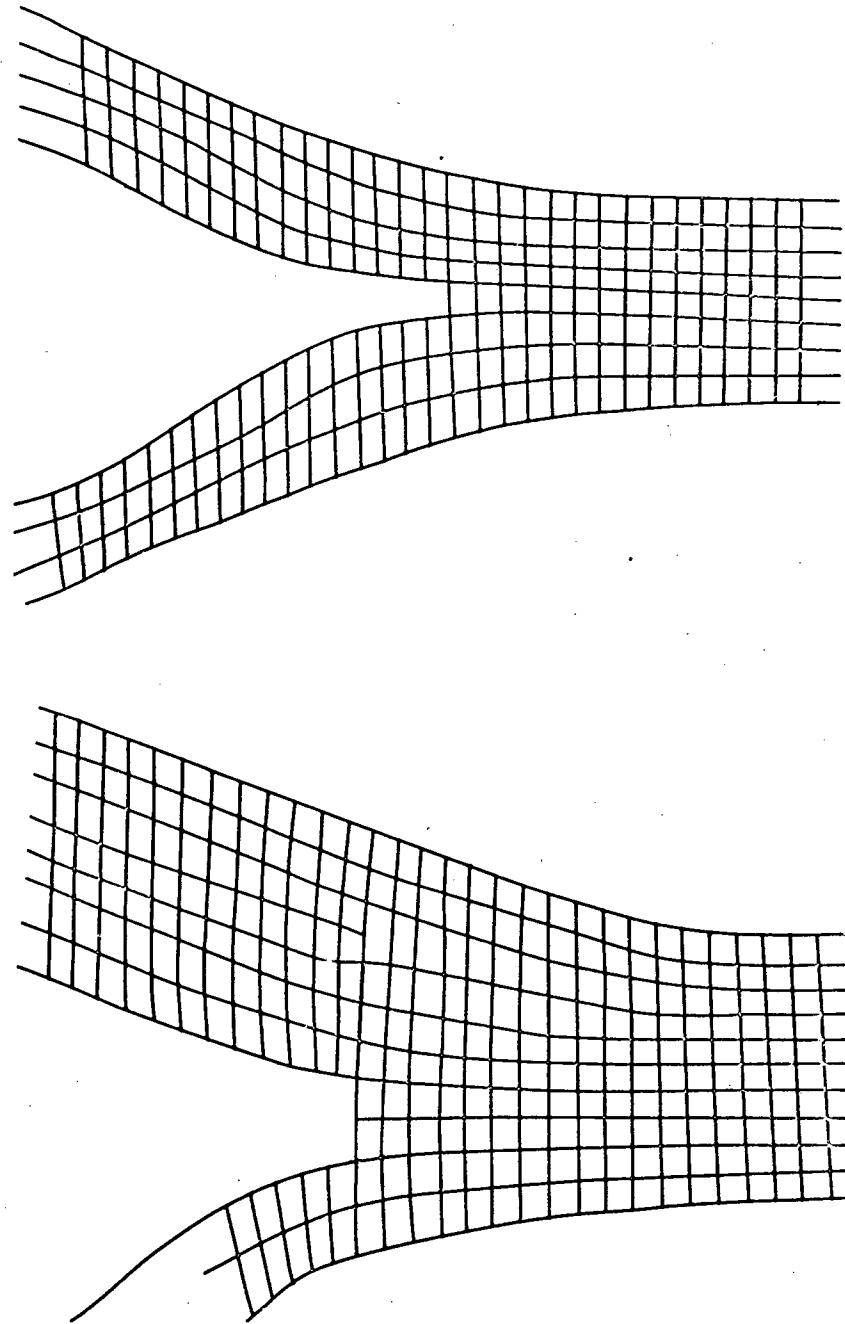


Fig. 1

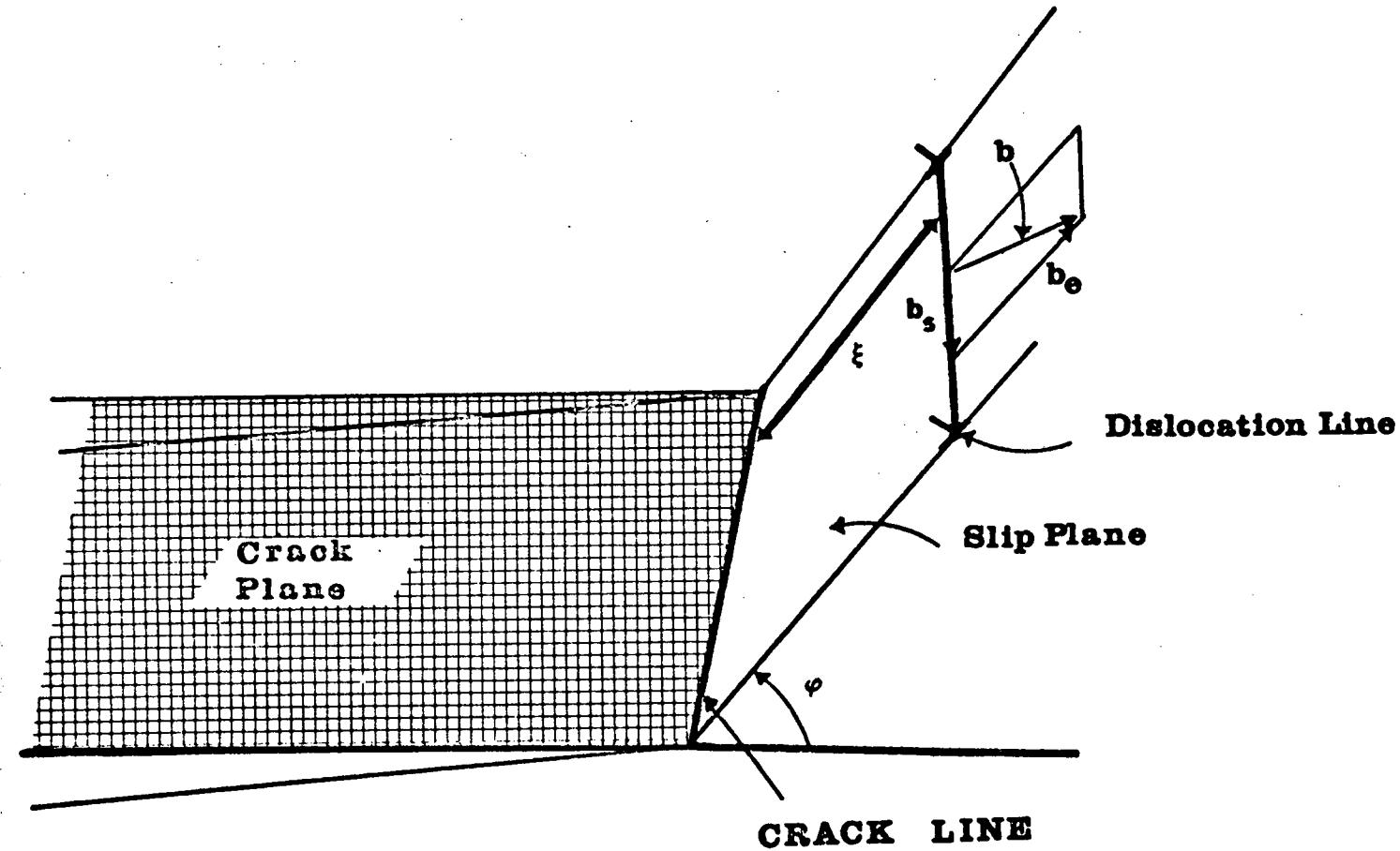


Fig. 2

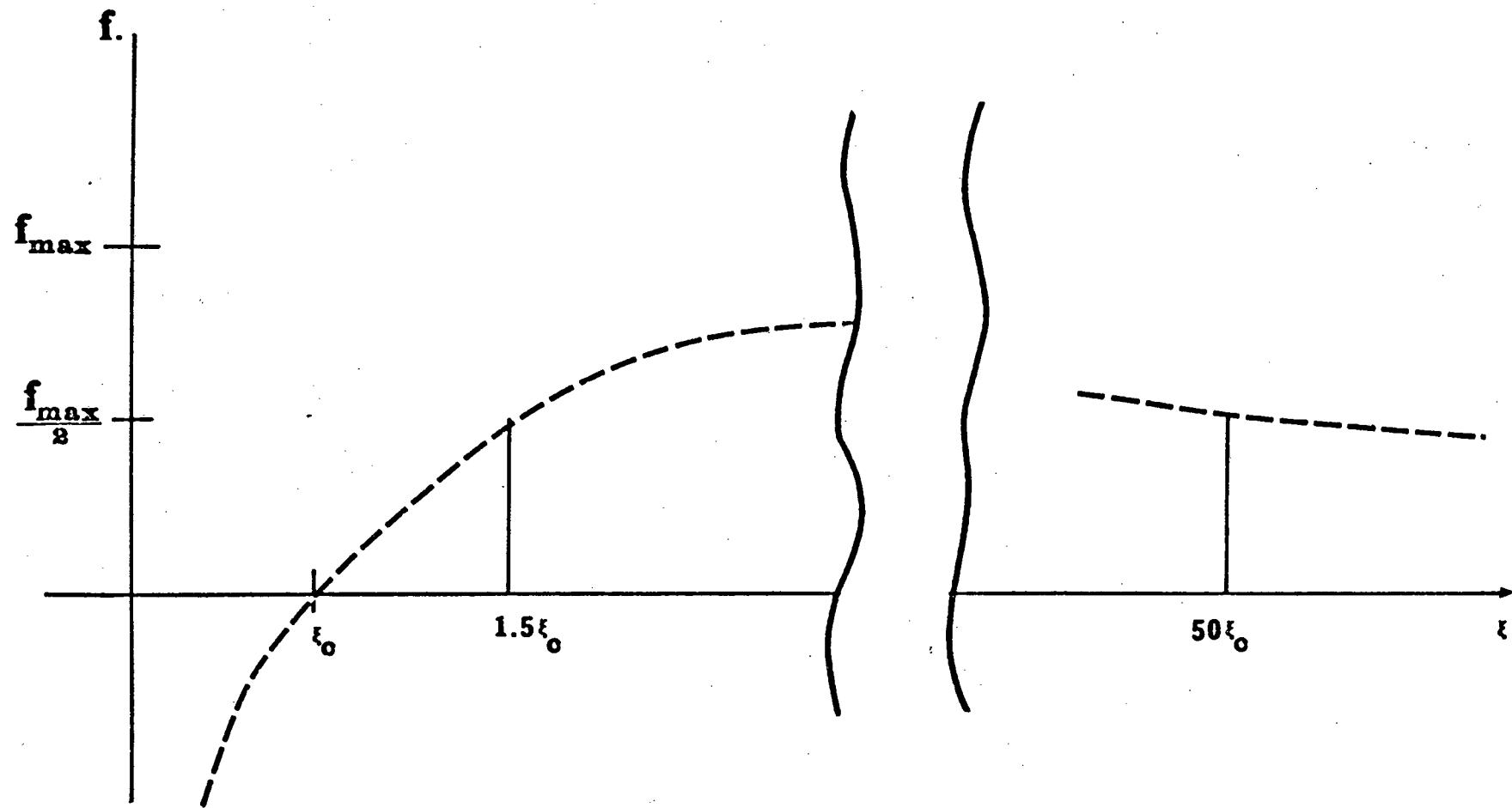


Fig. 3

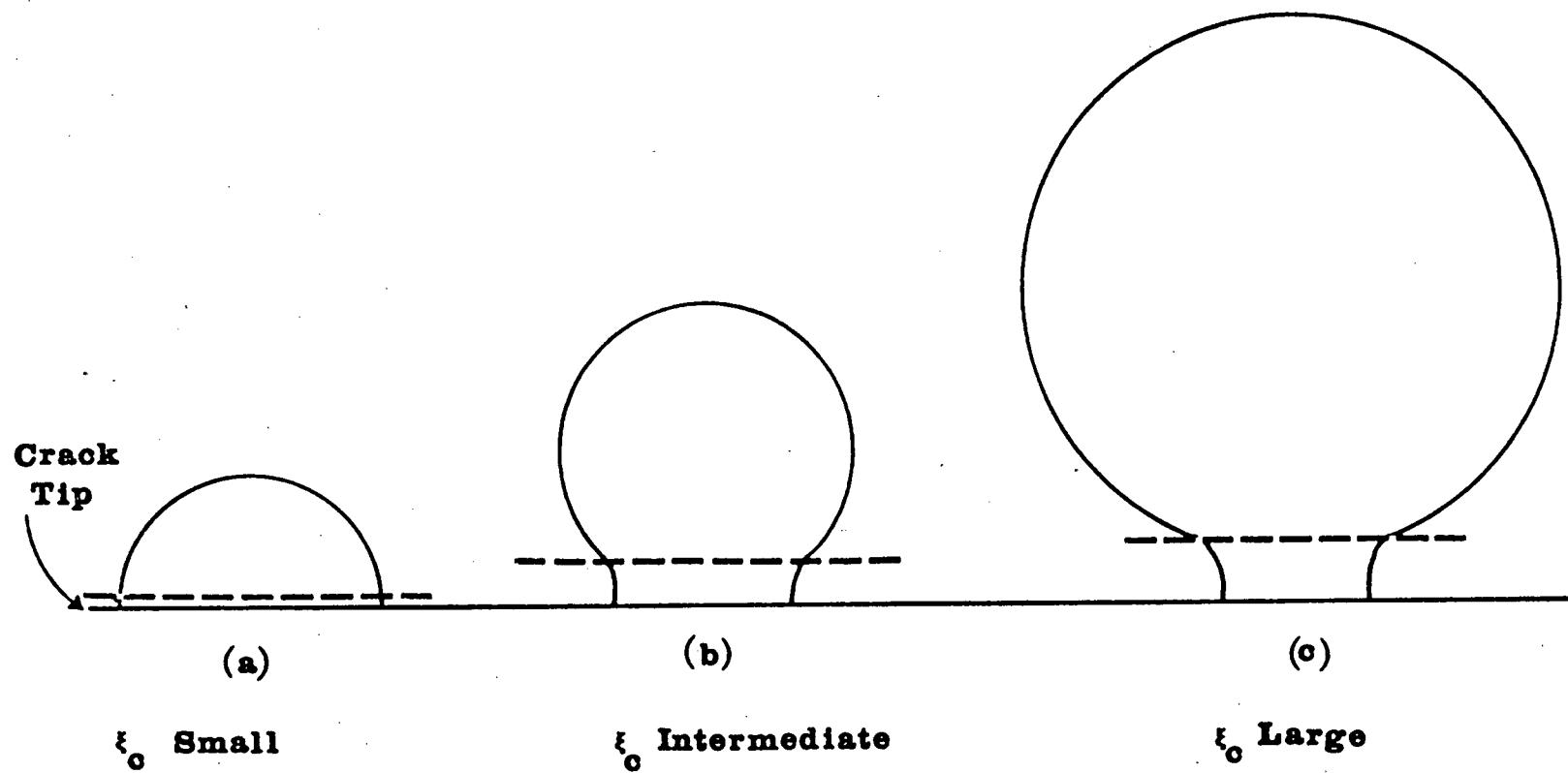


Fig. 4

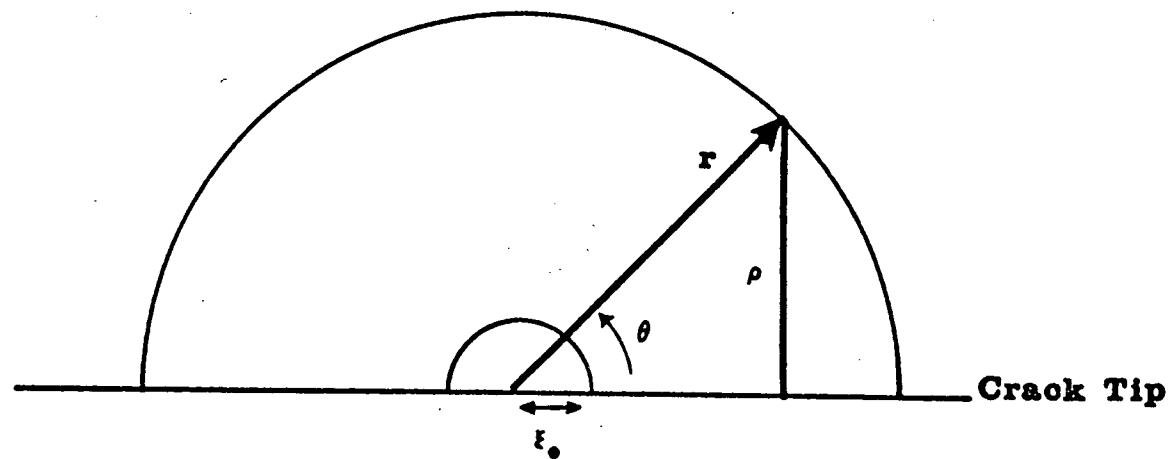


Fig. 5

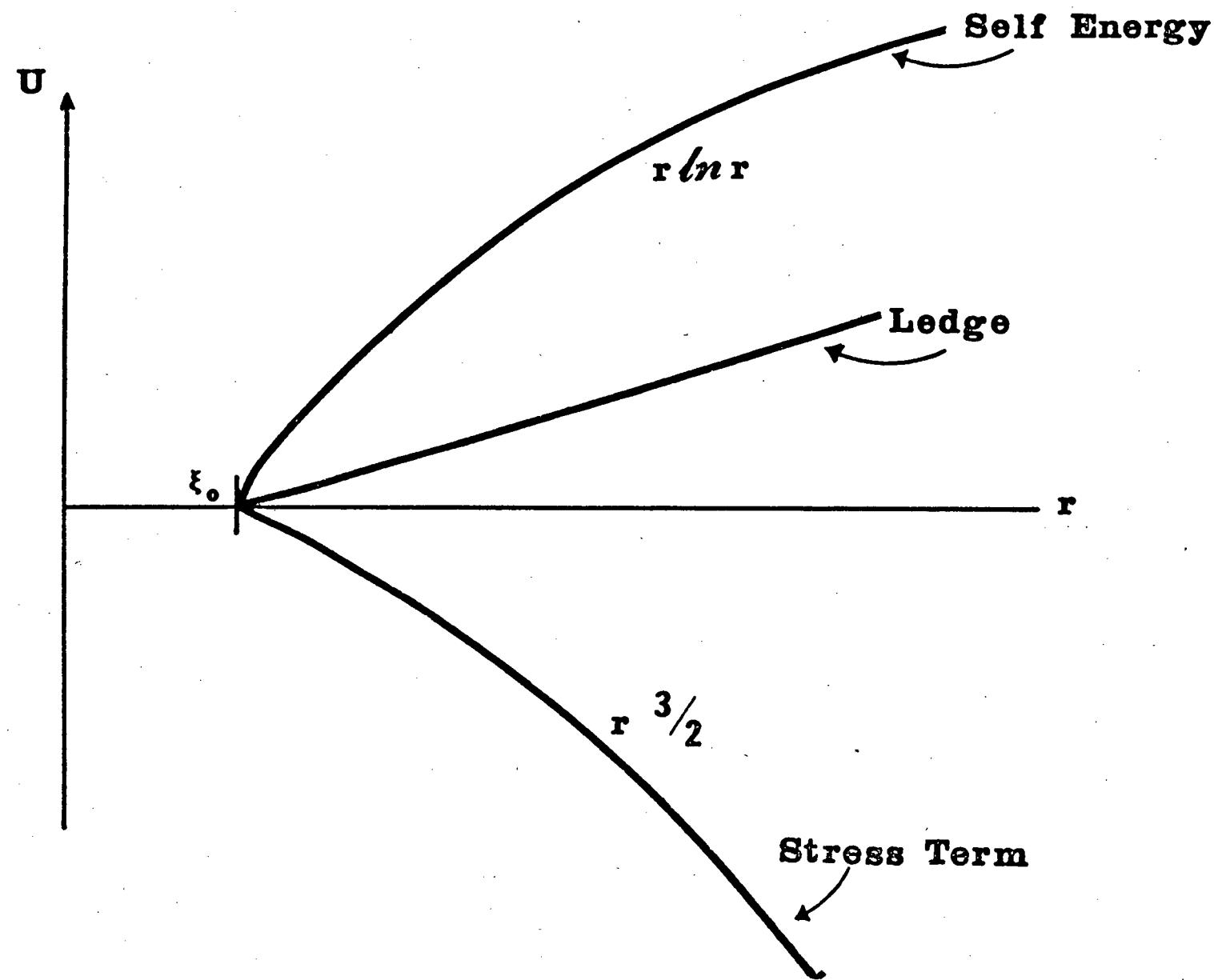


Fig. 6

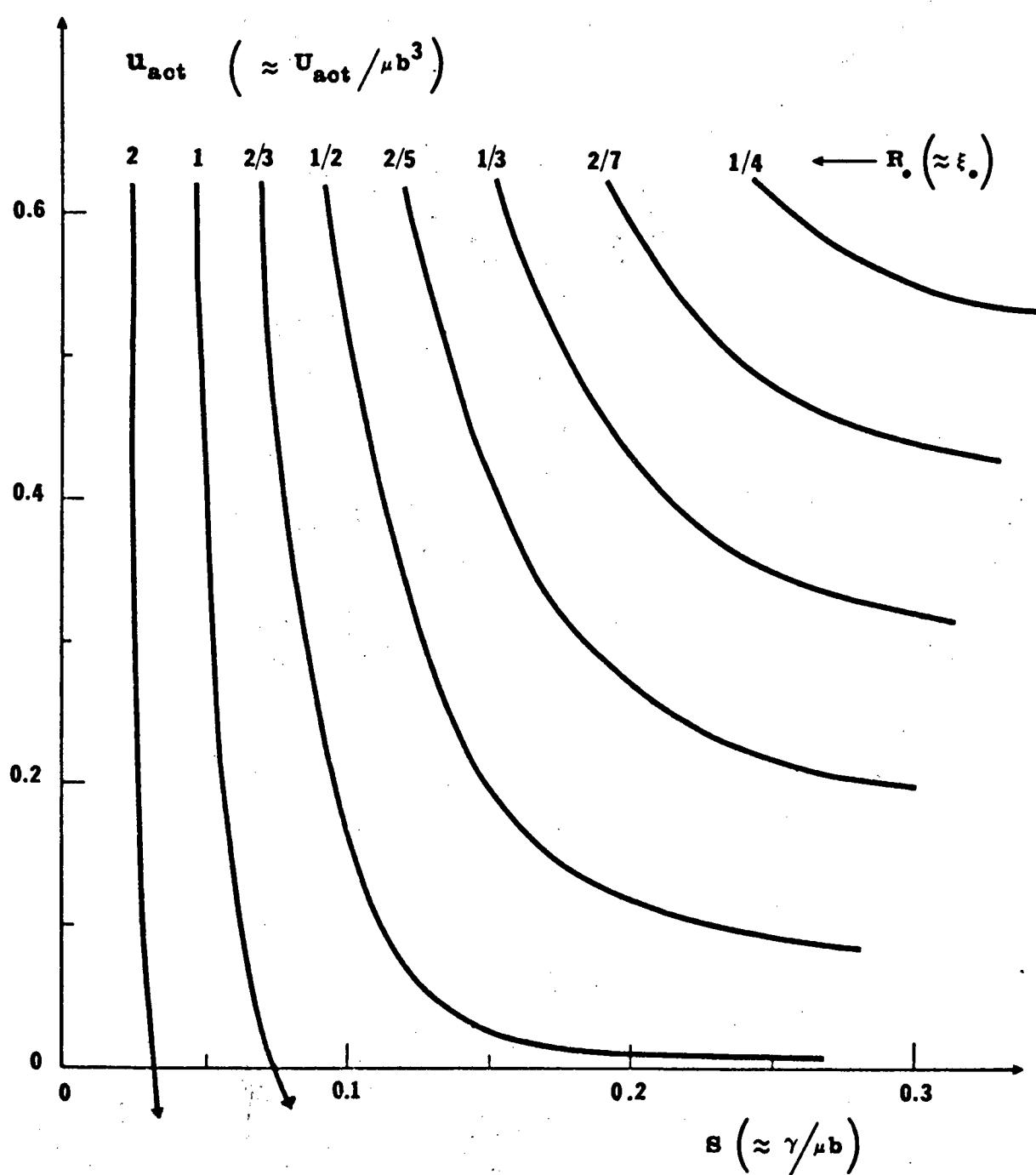


Fig. 7

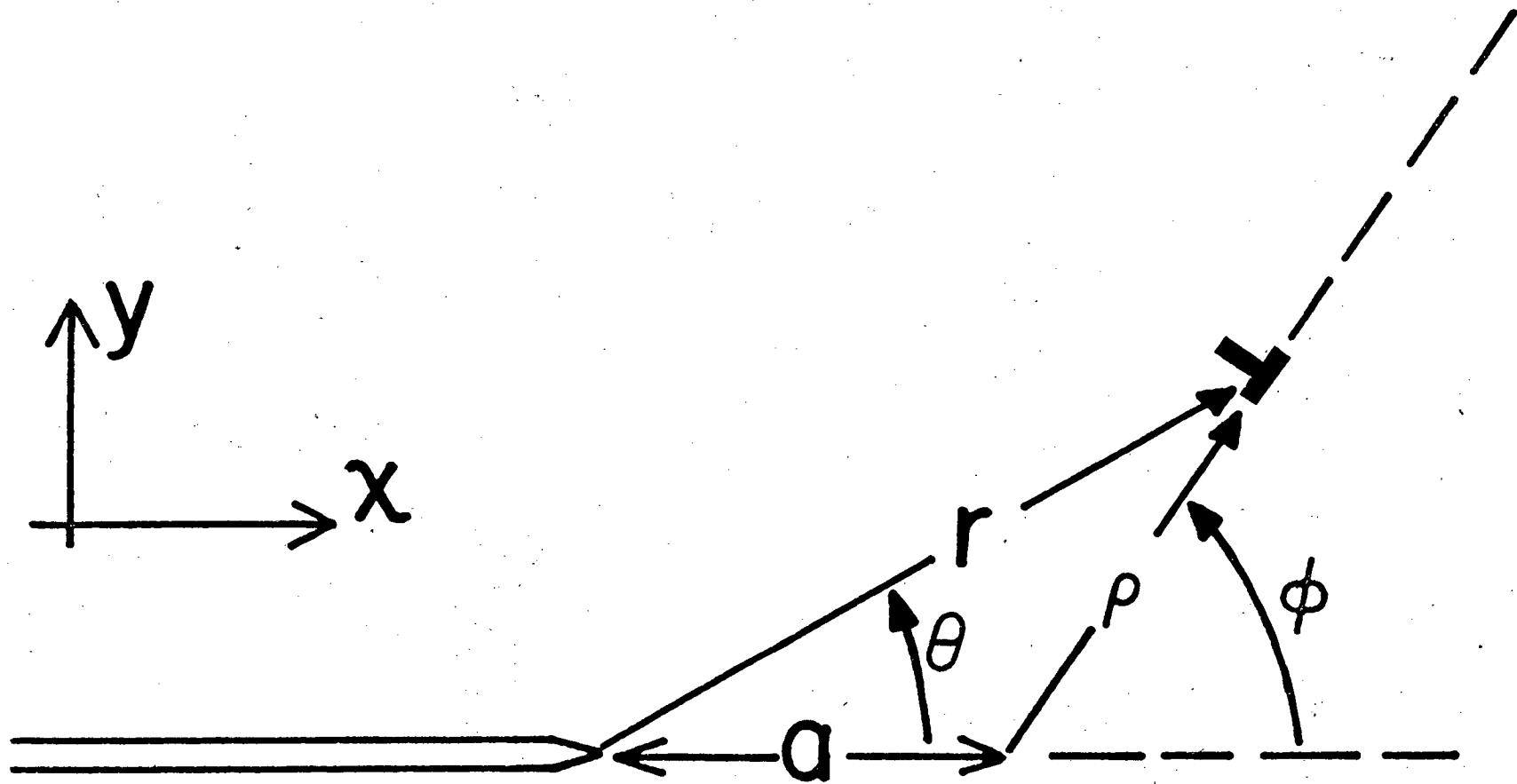


Fig. 8